Name:		
Group members:	 	

## TAM 210/211 - Worksheet 3

Objectives:

- Use free body diagrams and equilibrium equations to determine forces in cables and springs.
- Explore an experimental setup to verify theoretical findings.
- 1) A box of weight W is supported by two springs, as illustrated below.

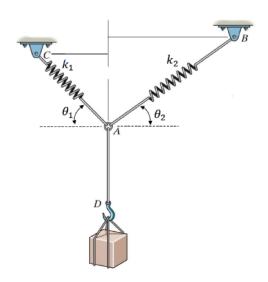
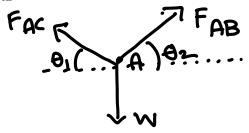


Figure 1: Spring-mass setup.

a) Draw a free body diagram of the forces acting at ring A. Denote the force in spring AC as  $F_{AC}$  and the force in spring AB as  $F_{AB}$ .



b) Use the equilibrium equations  $\sum \mathbf{F} = \mathbf{0}$  to determine  $F_{AC}$  and  $F_{AB}$ . Your answers should be functions of W,  $\theta_1$  and  $\theta_2$ .

$$\Sigma F_{N}=0$$
 $F_{AB} \cos \theta_{Z} - F_{AC} \cos \theta_{1} = 0$ 
 $\Sigma F_{y}=0$ 
 $F_{AB} \sin \theta_{2} + F_{AC} \sin \theta_{1} - W = 0$ 
 $\Gamma \cos \theta_{1}$ 
Using this in  $\Omega$ 
we get

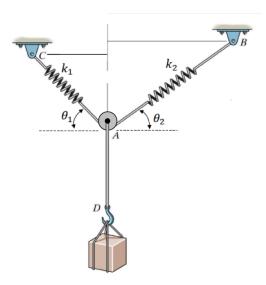
$$F_{AC} = \frac{w\cos\theta_2}{\sin\theta_2\cos\theta_1 + \cos\theta_2\sin\theta_1}$$

$$F_{AB} = \frac{w\cos\theta_1}{\sin\theta_2\cos\theta_1 + \cos\theta_2\sin\theta_1}$$

- 2) Use an experimental setup to validate your findings above. Start by calibrating the springs. Make sure to have the reading mark set to "zero" when the spring is hanging unloaded at a vertical position.
- a) Find the weight of the object in the toolbox by using a single spring. Record the weight.

b) Use the peg-board, spring, ring, bolts and the weight object to reproduce Question 1 setup. Use the angle measurements and the mass of your object to predict your spring reading using your equations from Question 1(b). Check your solution with actual spring readings.

3) In this next experimental setup, the springs are fixed at uneven positions (different heights) again, but the springs are no longer connected to each other via a ring. Instead, connect the springs using a piece of string, to model the cable that goes through the pulley at A. Use a bobbin to represent the frictionless pulley.

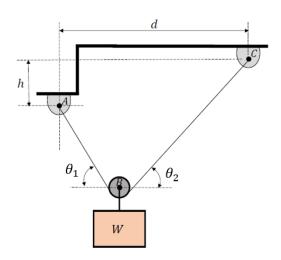


a) After hanging your object, what do you notice about the angles  $\theta_1$  and  $\theta_2$ ? What does this tell you about the forces acting on the two ends of the string?

$$\theta_1 = \theta_2 = 7$$
  $\leq F_N = 0$   $F_{AB}(0S\theta_2 = F_{AC}(0S\theta_1 = 7)$   $= 7$   $F_{AB} = F_{AC}(0S\theta_1 = 7)$ 

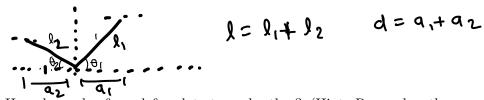
b) Use the angle measurements and the mass of your object to predict your spring reading using your equations from Question 1(b). Check your solution with actual spring readings.

4) An experimental setup is created as illustrated below with string ABC of length L.



a) What happens to angles  $\theta_1$  and  $\theta_2$  when the weight W is changed by changing the object? Why?

$$\theta_1$$
  $\theta_2$  donot change with weight. They memain constant and equal.  $\theta_1 = \theta_2$ 



b) How do angles  $\theta_1$  and  $\theta_2$  relate to each other? (Hint: Remember the assumption we make for the tensions at the two ends of the string that goes over a frictionless pulley.) Express the angles in terms of the given symbolic variables and dimensions (neglect the size of the frictionless pulley B). How does your theoretical expression validate your conclusions in part (a)?

Tension in a string remain, same. FAB = FAC  

$$\Rightarrow \theta_2 = \theta_1 = \theta$$
.  $\theta_1 = \frac{q_1}{\cos \theta_1}$   $\theta_2 = \frac{q_2}{\cos \theta_2} \Rightarrow \theta_1 + \theta_2 = \frac{q_1}{\cos \theta_1}$   
 $\Rightarrow \theta_2 = \theta_1 = \theta$ .  $\theta_1 = \frac{q_1}{\cos \theta_1}$   $\theta_2 = \frac{q_2}{\cos \theta_2} \Rightarrow \theta_1 + \theta_2 = \frac{q_1}{\cos \theta_2}$ 

c) Express the forces along AB and BC as Cartesian vectors in terms of the given symbolic variables and dimensions.

$$F_{AB} = F_{BC} = \frac{w}{2sin\theta}$$

$$F_{AB} = -F_{AB} Cos \theta_1 \hat{i} + F_{AB} Sin \theta_1 \hat{j} = \frac{wd}{2\sqrt{\ell^2 - d^2}} \hat{i} + \frac{w\hat{i}}{2} \hat{j}$$

$$F_{BC} = F_{BC} (os \theta_2 \hat{i}) + F_{BC} Sin \theta_2 \hat{j} = \frac{wd}{2\sqrt{\ell^2 - d^2}} \hat{i} + \frac{w\hat{i}}{2} \hat{j}$$

d) If the string ABC were shorter, how would angles  $\theta_1$  and  $\theta_2$  and the forces along AB and BC change?  $\theta = \cos^{-1}(\frac{d}{4})$ . If I is neduced  $\theta_1 = \theta_2 = \theta$  will neduce  $f_{AB} = f_{BC} = \frac{W}{2 \sin \theta} \Rightarrow \Delta g$  is neduced sing neduced

and as a nesult FAB & FBC Will increase.

e) What implications does part (d) have on the design of systems with different string lengths in terms of the required strengths of the strings?

strings with shorter length should have more strength, as the tengion developed in them will be larger.