



## Announcements

- In-class Quiz 3 next Monday!

### □ Upcoming deadlines:

- Tuesday (9/26)
  - PL HW8
- Thursday (9/28)
  - ME HW9



## Recap

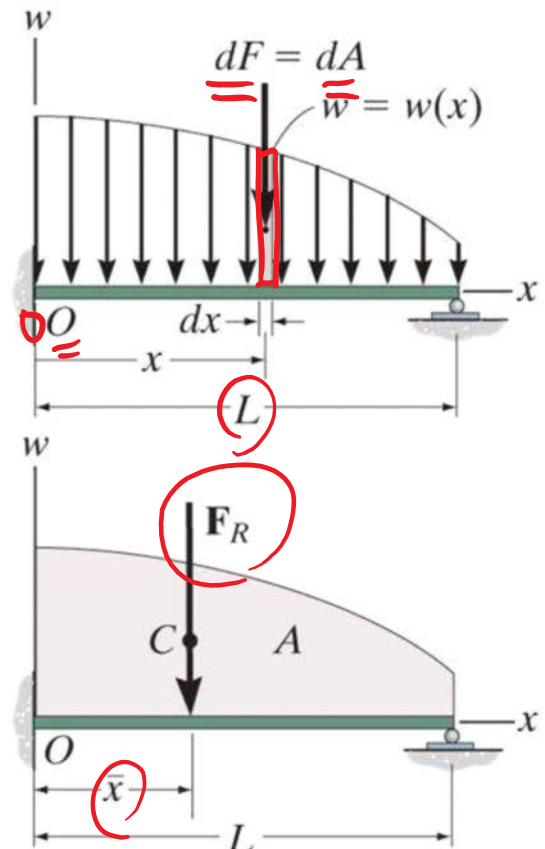
- Equivalent force system for distributed loading

$$F_R = \int dF = \int_0^L w(x) dx$$

$$M_o = \int_0^L x w(x) dx$$

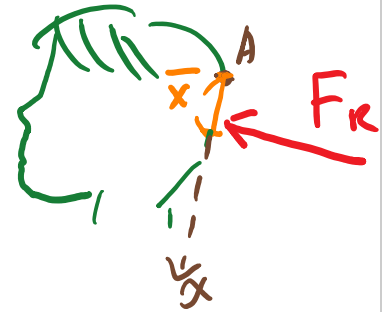
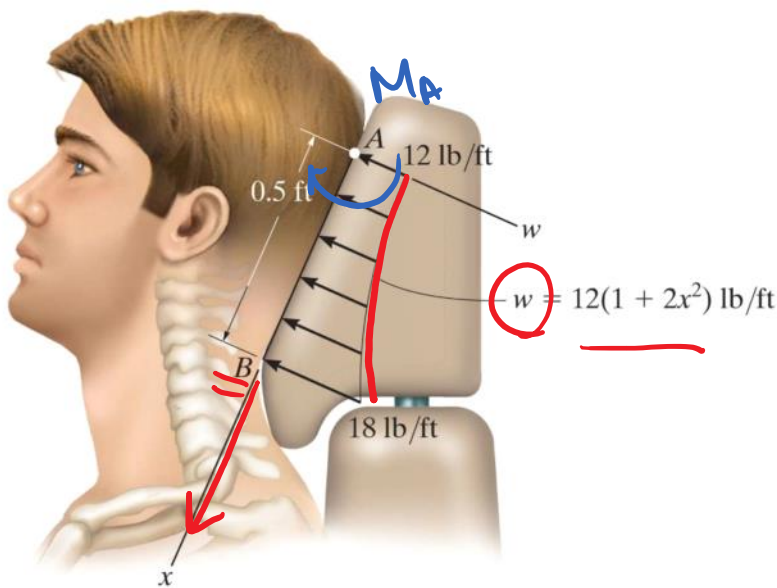
$\uparrow$        $\uparrow$   
 $d$        $F$

2  $M_o = \bar{x} F_R \Rightarrow \bar{x} = \frac{M_o}{F_R}$



## Example

Find the equivalent force and its location from point A for the loading on the headrest as shown.



$$F_R = \int_0^L w(x) dx$$

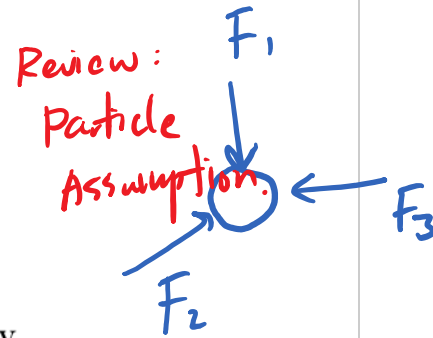
$$= \int_0^{0.5} 12(1 + 2x^2) dx$$

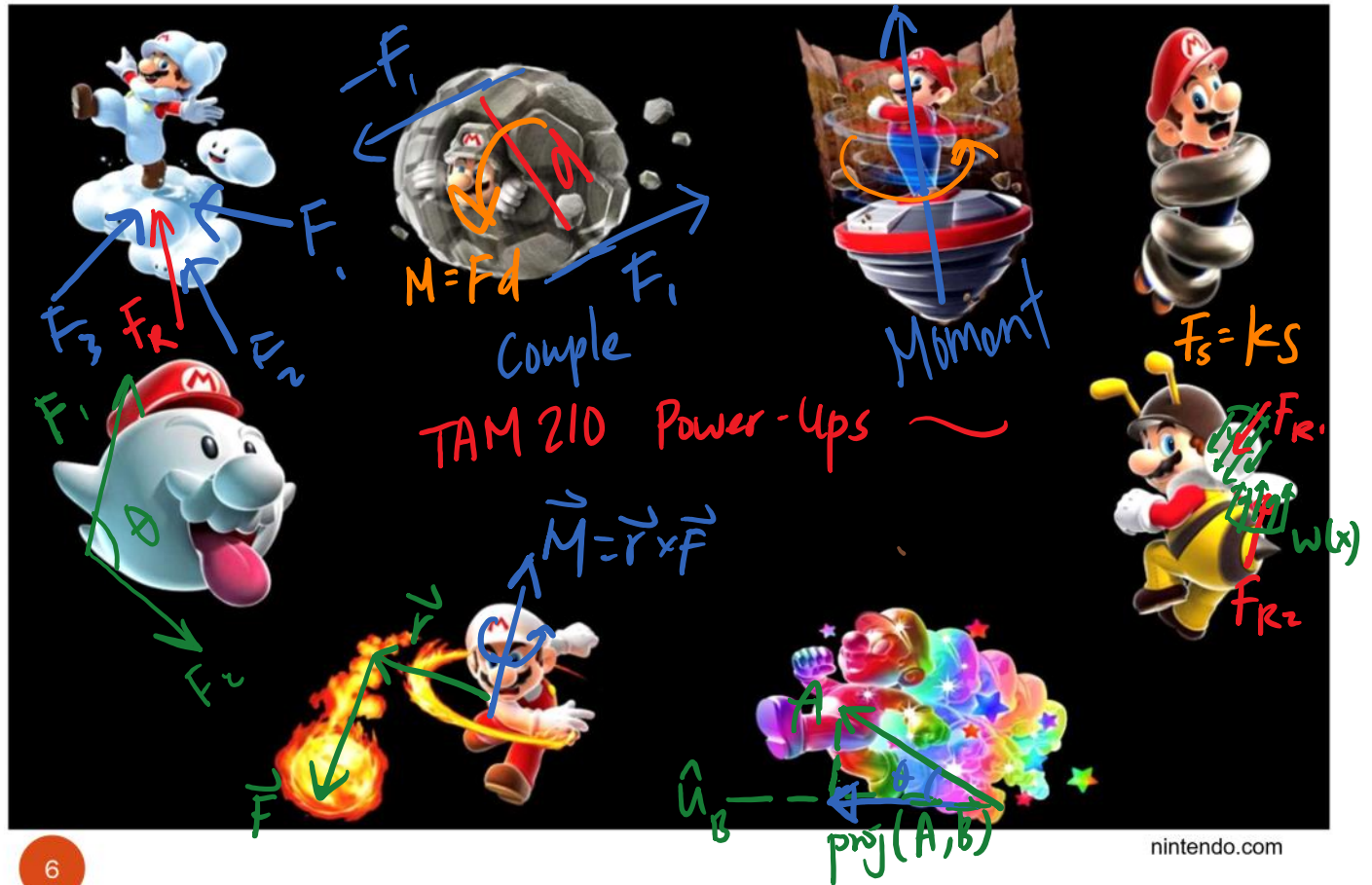
$$\bar{x} = \frac{M_A}{F_R} = \frac{\int_0^L x w(x) dx}{\int_0^L w(x) dx} = \frac{\int_0^{0.5} x [12(1 + 2x^2)] dx}{\int_0^{0.5} [12(1 + 2x^2)] dx}$$

## Chapter 5: Equilibrium of Rigid Bodies

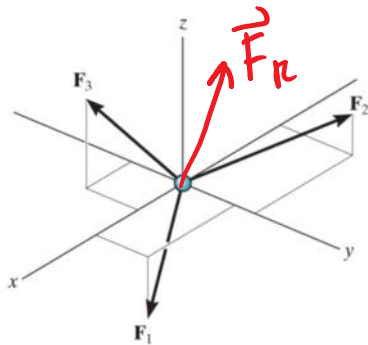
## Goals and Objectives

- Introduce the free-body diagram for a rigid body
- Develop the equations of equilibrium for a rigid body
- Solve rigid body equilibrium problems using the equations of equilibrium

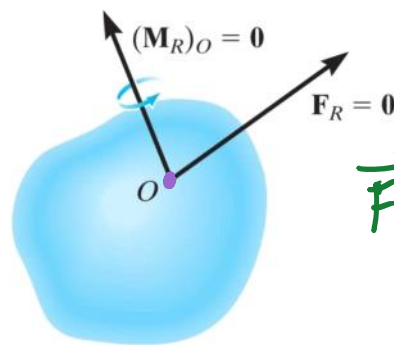
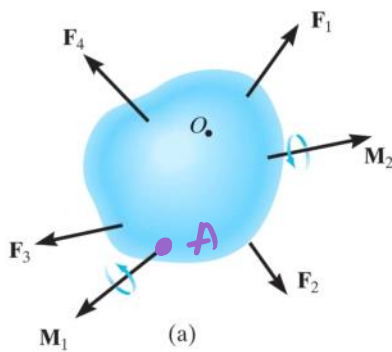




# Equilibrium of a Rigid Body



In contrast to the forces on a particle, the forces on a rigid-body are not usually concurrent and may cause rotation of the body. We can reduce the force and couple moment system acting on a body to an equivalent resultant force and a resultant couple moment at an arbitrary point O.



$$\vec{F}_R = \sum \vec{F} \quad \left\{ \begin{array}{l} \sum F_x = F_{Rx} \\ \sum F_y = F_{Ry} \\ \sum F_z = F_{Rz} \end{array} \right.$$

$$\vec{M}_{R0} = \sum \vec{r} \times \vec{F} + \sum M$$

# Equilibrium of a Rigid Body

Static equilibrium:

$$\sum \vec{F} = 0 \Rightarrow \text{No translation}$$

$$\sum \vec{M} = 0 \Rightarrow \text{No rotation}$$

Maintained by reaction forces and moments

- Support & constraint that provide the necessary forces/moments to keep body at equilibrium.

Assumption of rigid body

- Body doesn't deform or break under the load.

8

- Only consider external forces



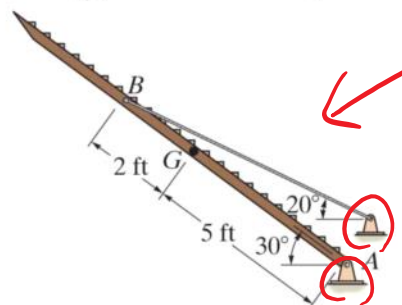


## Process of solving rigid body equilibrium problems

The uniform truck ramp has weight 400 lb and is pinned to the body of the truck at each side and held in the position shown by the two side cables. Determine the reaction forces at the pins and the tension in the cables.



1. Create idealized model (modeling and assumptions)



3. Apply eqns of equilibrium

2. Draw free body diagram showing ALL the external (applied loads and supports)

9

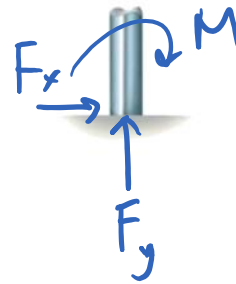
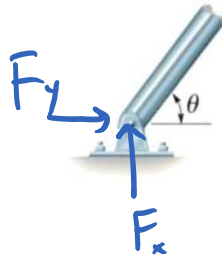
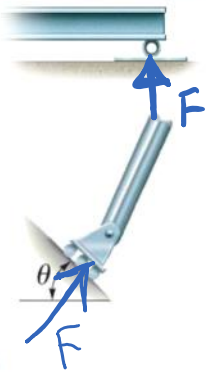
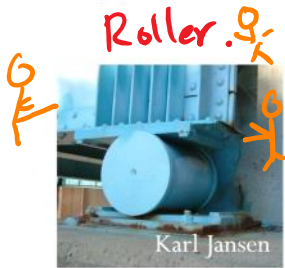


$$\sum \vec{F} = 0$$

$$\sum \vec{M}_O = 0.$$

## Equilibrium in two-dimensional bodies

### Support reactions

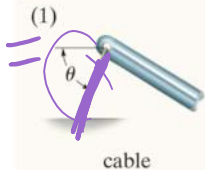
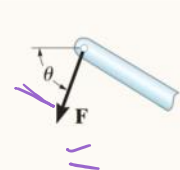
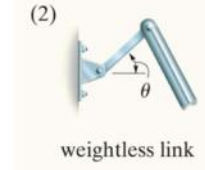
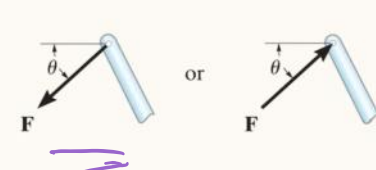
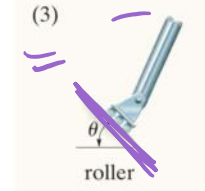
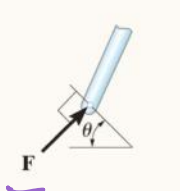
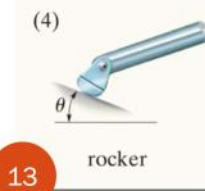
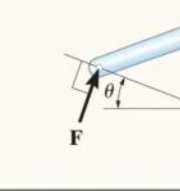


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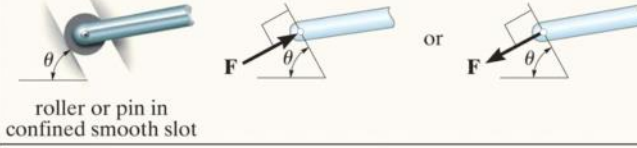
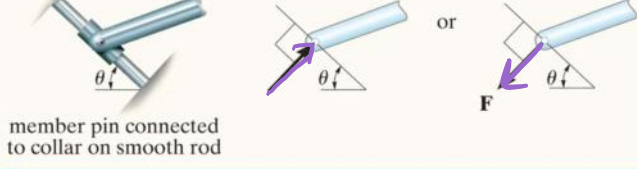
$\Rightarrow$  Support Reaction = constraints on the system.

## Types of connectors

**TABLE 5-1 Supports for Rigid Bodies Subjected to Two-Dimensional Force Systems**

Types of Connection	Reaction	Number of Unknowns
<p>(1)</p>  <p>cable</p>		<p>One unknown. The reaction is a tension force which acts away from the member in the direction of the cable.</p>
<p>(2)</p>  <p>weightless link</p>		<p>One unknown. The reaction is a force which acts along the axis of the link.</p>
<p>(3)</p>  <p>roller</p>		<p>One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.</p>
<p>(4)</p>  <p>rocker</p>		<p>One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.</p>

# Types of connectors

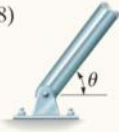
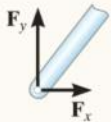




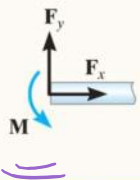
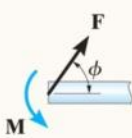
TABLE 5-1 Supports for Rigid Bodies Subjected to Two-Dimensional Force Systems		
Types of Connection	Reaction	Number of Unknowns
(5)  smooth contacting surface		One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.
(6)  roller or pin in confined smooth slot		One unknown. The reaction is a force which acts perpendicular to the slot.
(7)  member pin connected to collar on smooth rod		One unknown. The reaction is a force which acts perpendicular to the rod.

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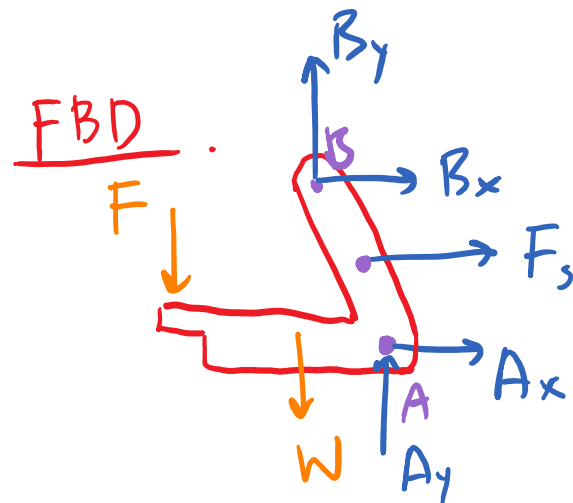
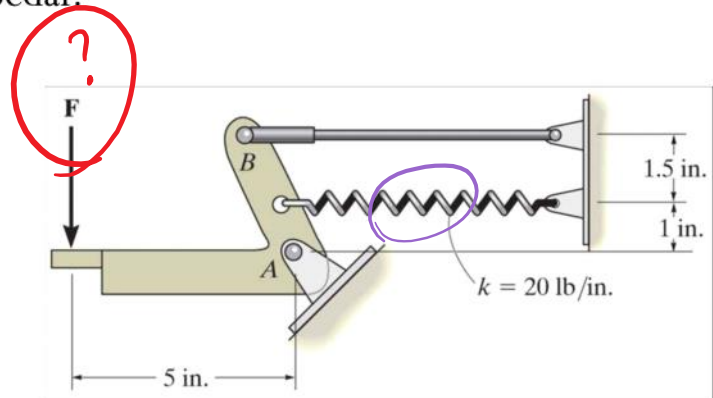
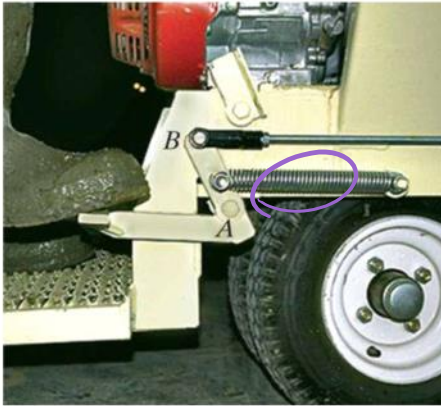
## Types of connectors

TABLE 5-1 Continued

Types of Connection	Reaction	Number of Unknowns
(8)  smooth pin or hinge	 or 	Two unknowns. The reactions are two components of force, or the magnitude and direction $\phi$ of the resultant force. Note that $\phi$ and $\theta$ are not necessarily equal [usually not, unless the rod shown is a link as in (2)].
(9)  <u>member fixed connected to collar on smooth rod</u>		Two unknowns. The reactions are the couple moment and the force which acts perpendicular to the rod.
(10)  fixed support	 or 	Three unknowns. The reactions are the couple moment and the two force components, or the couple moment and the magnitude and direction $\phi$ of the resultant force.

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The operator applies a vertical force to the pedal so that the spring is stretched 1.5 in. and the force in the short link at B is 20 lb. Determine the vertical force applied to the pedal.



Find the tension in cable B given the weight of the cage.

