



Announcements

- Morning Office Hours: Mon/Wed, 9–10am in MEB 220H
- Quiz 2 sign-ups are now open
 - The scope of the exam will cover up to the end of today's lecture (Lecture 7)
 - Same format as Quiz 1
- Upcoming deadlines:
 - Thursday (9/14)
 - ME HW5
 - Tuesday (9/19)
 - PL HW6
 - Due next week
 - Writing Assignment 1

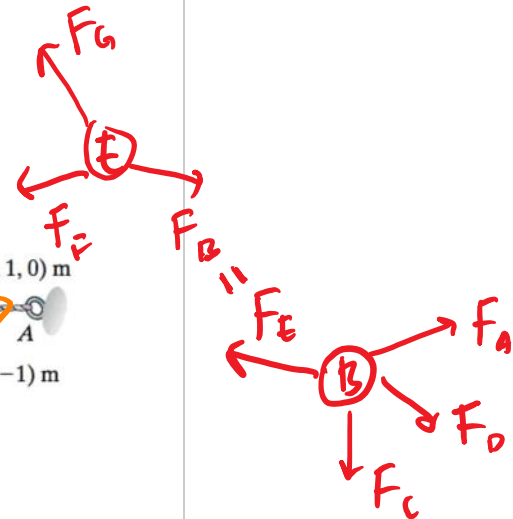
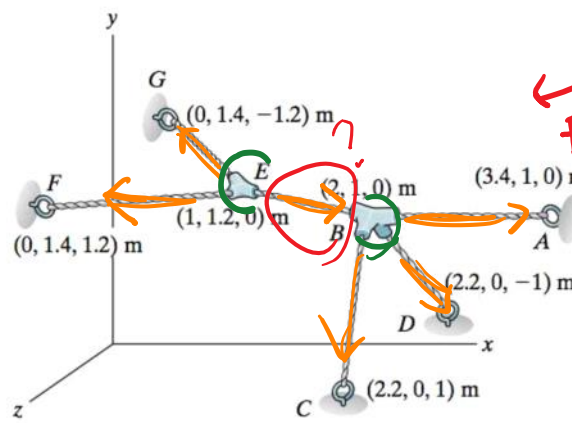


Recap

- Equilibrium of a particle in 2D and 3D
- Equilibrium of a system of particles
- Free body diagram
- Equation of equilibrium

2D: $\sum F_x = 0$
 $\sum F_y = 0$

2 $\textcircled{2}$ 3D: $\sum F_x = 0$
 $\sum F_y = 0$
 $\sum F_z = 0$

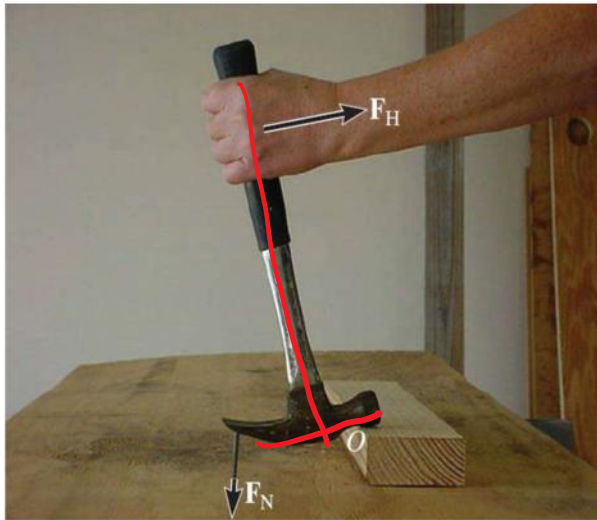


Chapter 4: Force System Resultants

Goals and Objectives

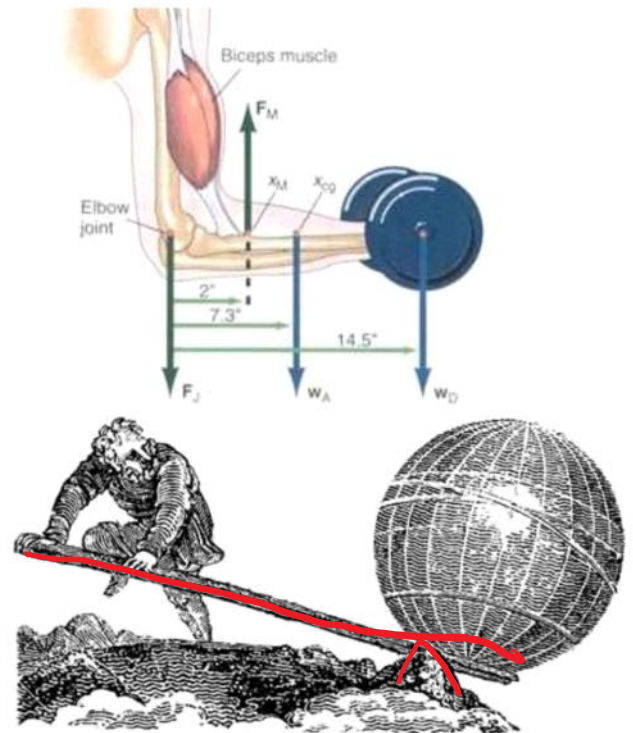
- Discuss the concept of the moment of a force and show how to calculate it in two and three dimensions ✓
- How to find the moment about a specified axis ✓
- Define the moment of a couple
- Finding equivalence force and moment systems
- Reduction of distributed loading

Applications



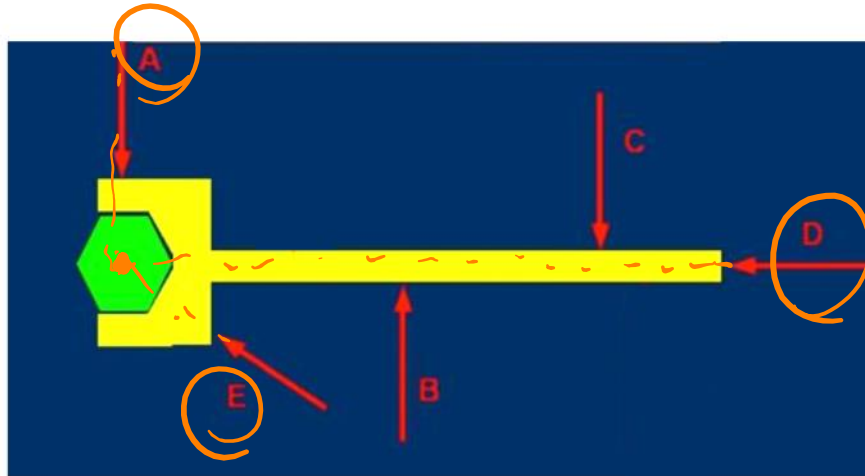
Carpenters often use a hammer in this way to pull a stubborn nail. Through what sort of action does the force F_H at the handle pull the nail? How can you mathematically model the effect of force F_H at point O?

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Moment 1. a very brief period of time. An Exact point in time. 2. importance. 3. A turning Effect produced by a force acting at a distance on An object.

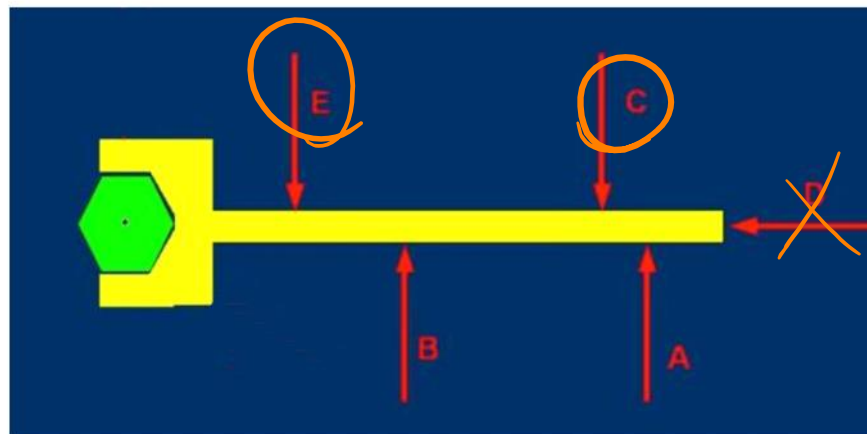
Moment of a Force



Which force(s) have NO turning effect?

A, D, E

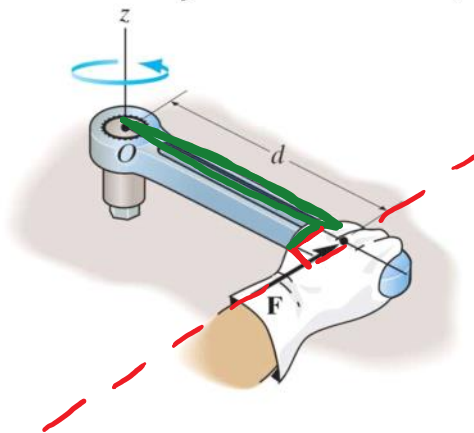
Moment of a Force



- 1) Which force(s) yields a “tighty” effect? C, E
- =
- 2) Which force(s) yields a “loosey” effect? A, B

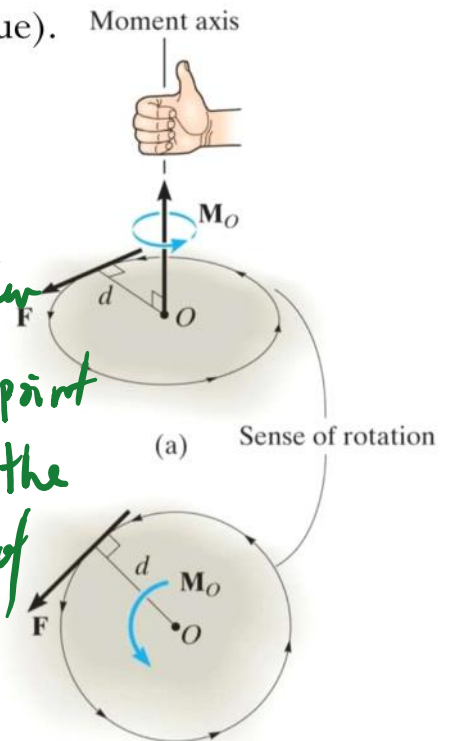
Moment of a force – scalar formulation

The **moment of a force about a point** provides a measure of the **tendency for rotation** (sometimes called a torque).



$$M = Fd$$

d : perpendicular distance from point of reference to the line of action of force.

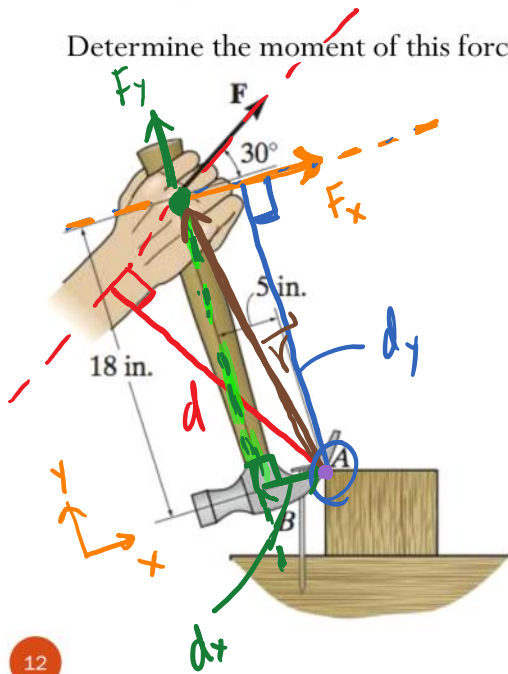


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Direction of \vec{M} : \perp to both \vec{d} and \vec{F} .

Example – Scalar Formulation

Determine the moment of this force about the point A as a function of F.



$$M_A = Fd$$

$$\vec{r} = d_x \hat{i} + d_y \hat{j} = -5\hat{i} + 18\hat{j} \text{ in.}$$

$$M_{Ax} = F_x d_y = -F \cos 30^\circ (18)$$

$$M_{Ay} = F_y d_x = -F \sin 30^\circ (5)$$

$$\text{CCW} = (+)$$

$$\text{CW} = (-)$$

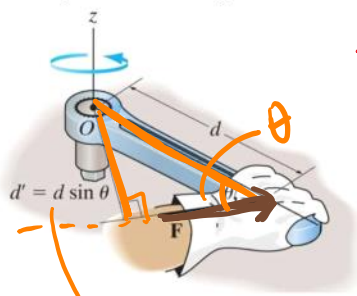
$$\text{CW} = (-)$$

$$\text{CW} = (-)$$

$$M_A = M_{Ax} + M_{Ay} = -F \cos 30^\circ (18) - F \sin 30^\circ (5)$$

Moment of a force – vector formulation

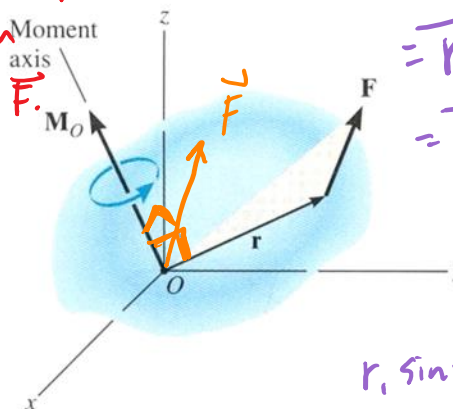
The moment of a force \mathbf{F} about point \mathbf{O} , or actually about the moment axis passing through \mathbf{O} and perpendicular to the plane containing \mathbf{O} and \mathbf{F} , can be expressed using the cross (vector) product, namely:



$$d_{\perp} = d \sin \theta$$

$$M = F d \sin \theta = |\vec{r} \times \vec{F}|$$

\vec{r} : position vector from reference point to line of action of force \mathbf{F} .



$$\vec{M} = \vec{r} \times \vec{F}$$

$$= \vec{r}_1 \times \vec{F}$$

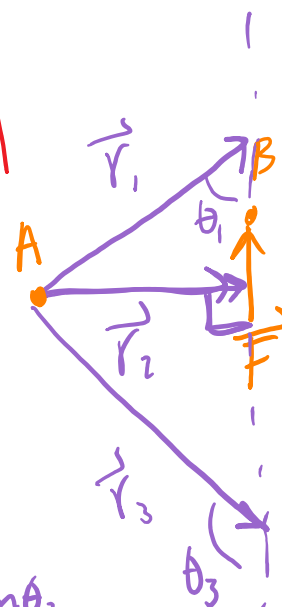
$$= \vec{r}_2 \times \vec{F}$$

$$= \vec{r}_3 \times \vec{F}$$

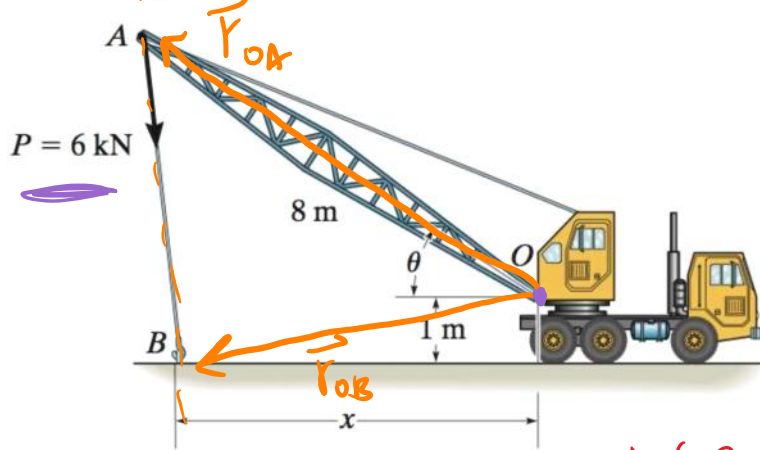
$$\vdots$$

$$r_1 \sin \theta_1 = r_2 \sin \theta_2$$

$$= r_3 \sin \theta_3 = \dots$$



Example – Vector Formulation



Given: The angle $\theta = 30^\circ$ and $x = 10$ m.

Find: The moment by \mathbf{P} about point O.

$$\vec{M}_O = \vec{r} \times \vec{P} = \begin{cases} \vec{r}_{OA} \times \vec{P} \\ \vec{r}_{OB} \times \vec{P} \end{cases}$$

$$\vec{r}_{OA} \times \vec{P} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ r_{OAx} & r_{OAy} & 0 \\ P_x & P_y & 0 \end{vmatrix} = (r_{OAx} P_y - r_{OAy} P_x) \hat{k} = (r_{OAx} P \sin\theta - r_{OAy} P \cos\theta) \hat{k}$$

$$\vec{r}_{OA} = (-8 \cos\theta \hat{i} + 8 \sin\theta \hat{j}) \text{ m}$$

$$\vec{r}_{OB} = (-10 \hat{i} - \hat{j}) \text{ m}$$

$$\vec{P} = P \hat{u}_{AB}$$

$$\hat{u}_{AB} = \frac{\vec{r}_B - \vec{r}_A}{|\vec{r}_{AB}|} = \frac{(-10 + 8 \cos\theta) \hat{i} - (-1 - 8 \sin\theta) \hat{j}}{r_{AB}} = \frac{(-3.07 \hat{i} - 5 \hat{j}) \text{ m}}{5.87 \text{ m}}$$

$$\Rightarrow M_O \approx 48.0 \text{ kN}\cdot\text{m}$$

$$\vec{r}_{OB} \times \vec{P} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ r_{OBx} & r_{OBy} & 0 \\ P_x & P_y & 0 \end{vmatrix} = (r_{OBx} P_y - r_{OBy} P_x) \hat{k} = r_{OBx} P \sin\theta - r_{OBy} P \cos\theta$$

$$\Rightarrow M_O \approx 48.0 \text{ kN}\cdot\text{m}$$

Same!