

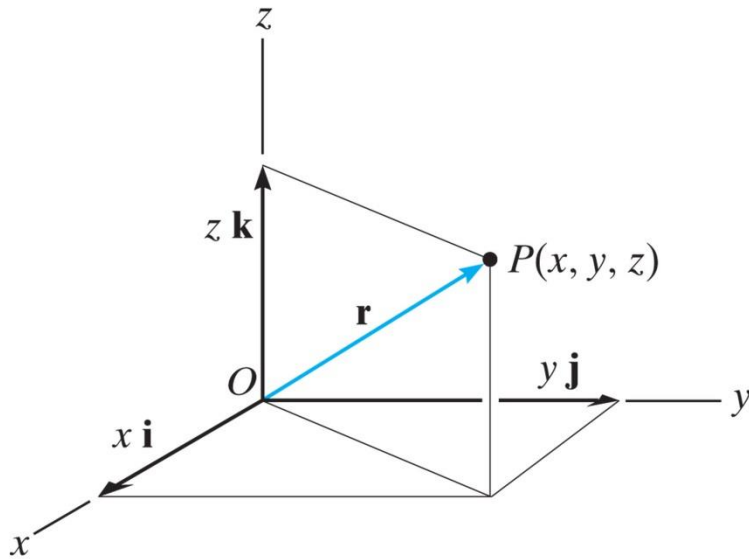
# To do ...

- **Quiz 1** sign up now!
  - Tues – Fri of next week (Sept 12 – 15)
  - “Practice” quiz available
- HW3 due **Thurs**
- HW4 PL due **Tues**
- **Quiz 2** (Sept 19 – 22)
- Written assignment coming soon

# Recap

- A force can be treated as a vector since forces obey all the rules that vectors do
- Vector representations
  - Rectangular components
  - Cartesian components
  - Unit vector
  - Directional cosines
- Position vectors

# Position vectors

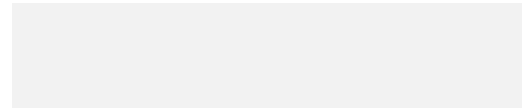


A position vector  $\mathbf{r}$  is defined as a fixed vector which locates a point in space relative to another point. For example,

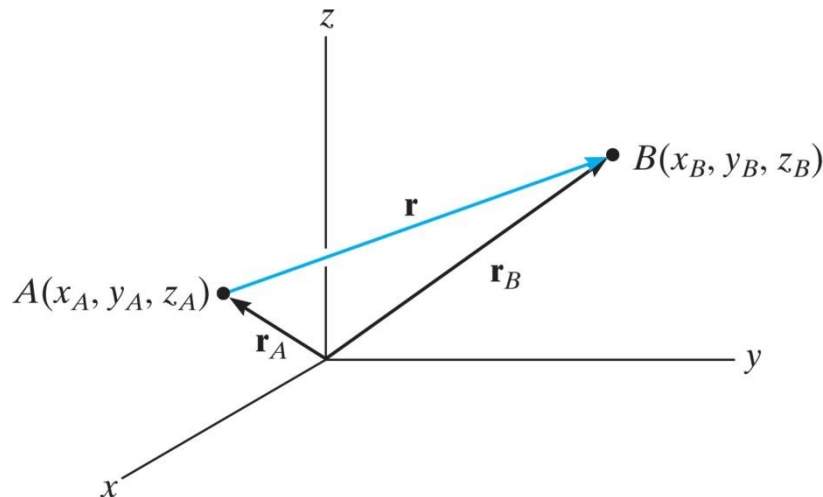
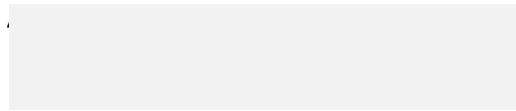
$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

expresses the position of point  $P(x, y, z)$  with respect to the origin  $O$ .

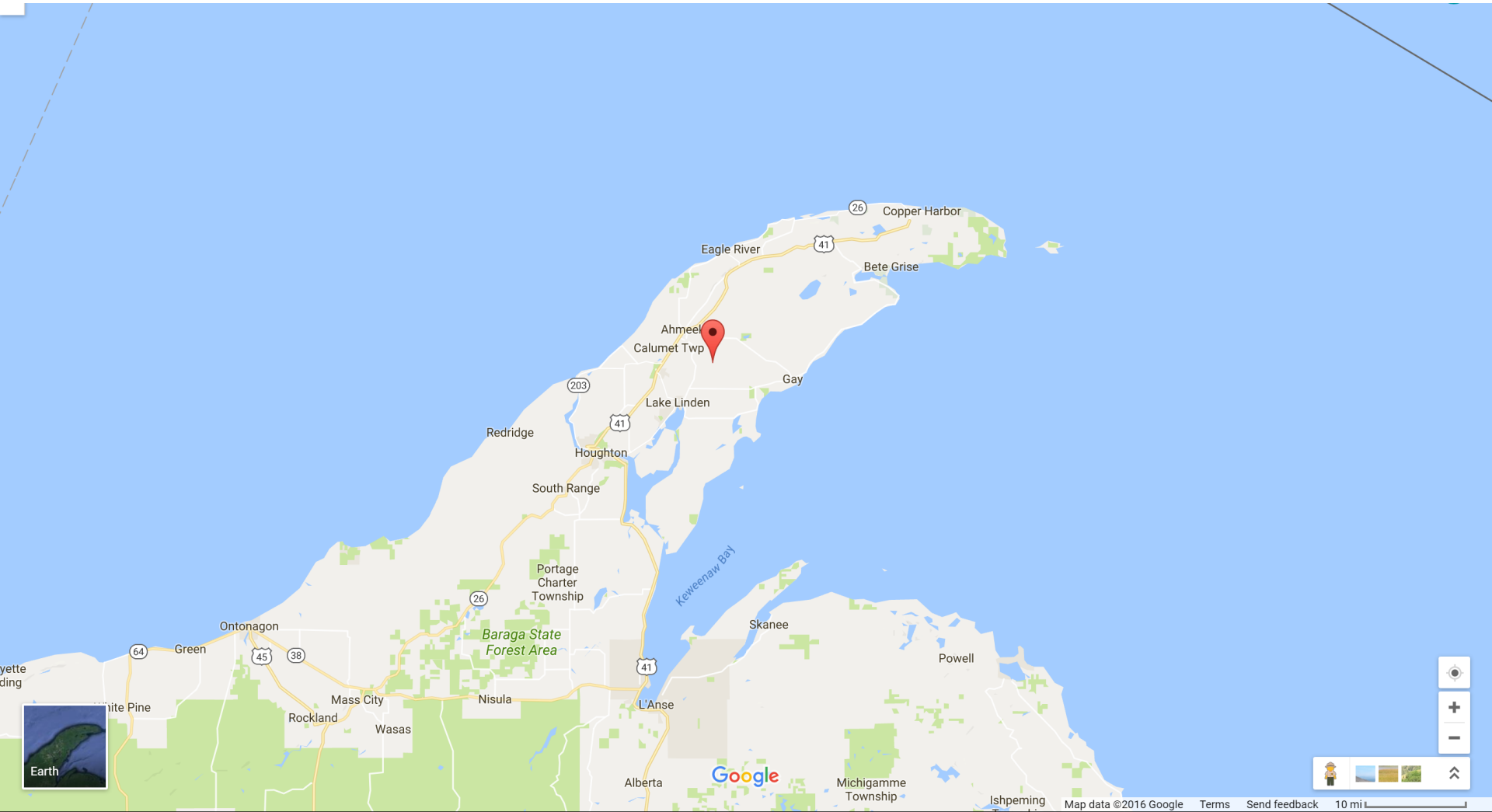
The position vector  $\mathbf{r}$  of point  $\mathbf{B}$  with respect to point  $\mathbf{A}$  is obtained from



Hence,

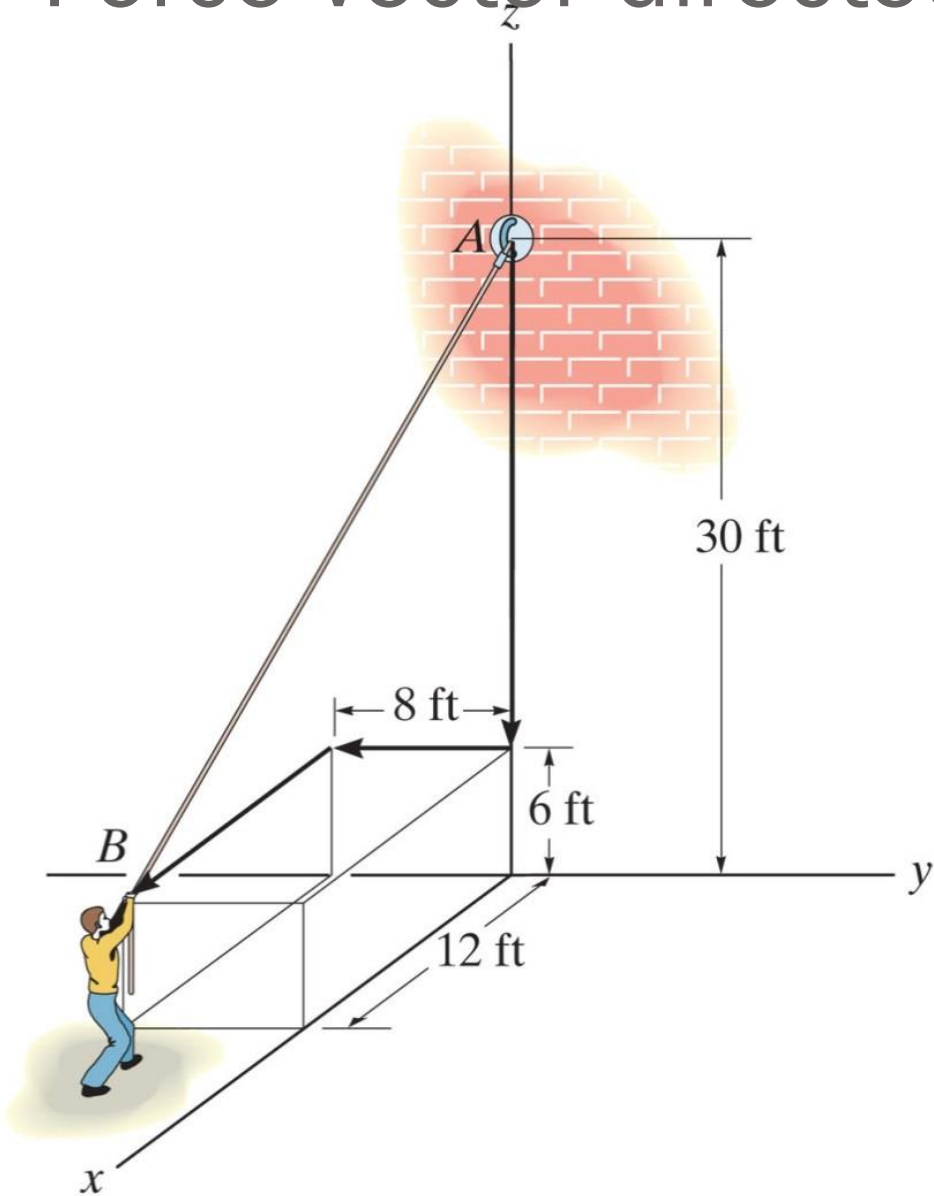


Thus, the  $(\mathbf{i}, \mathbf{j}, \mathbf{k})$  components of the position vector  $\mathbf{r}$  may be formed by taking the coordinates of the tail (point  $A$ ) and subtracting them from the corresponding coordinates of the head (point  $B$ ).

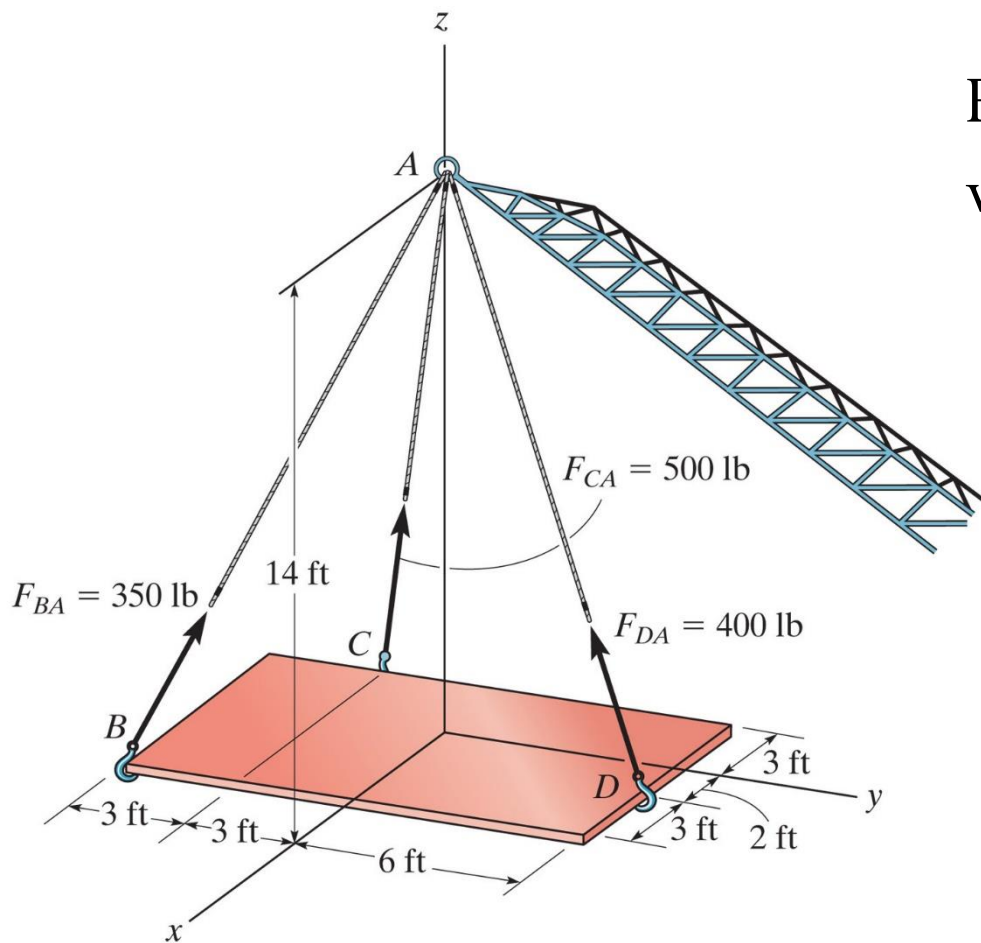


# Force vector directed along a line

The man pulls on the cord with a force of 70 lb. Represent the force  $F$  as a Cartesian vector.



Express each force as a Cartesian vector



# Why do we care?

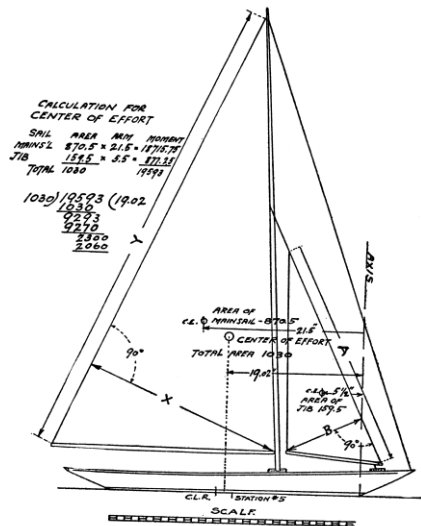
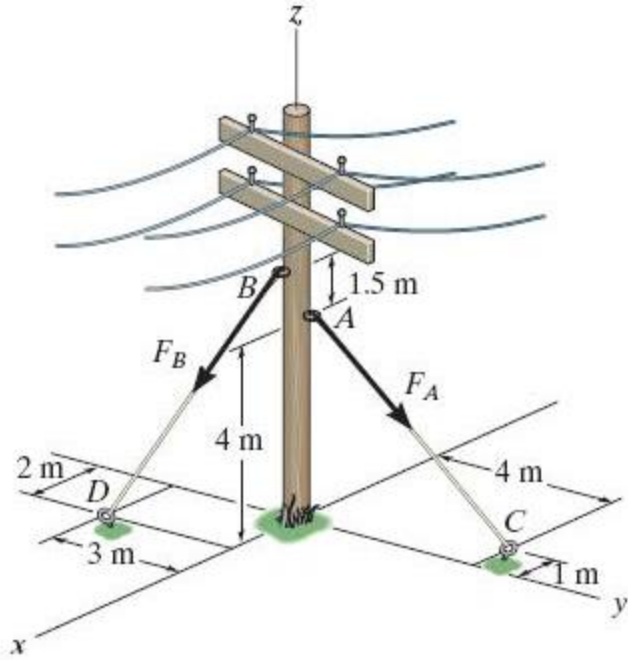


FIGURE 15.





# Force vector directed along a line



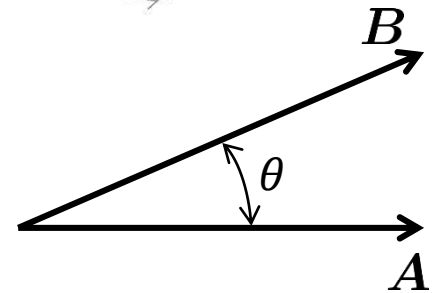
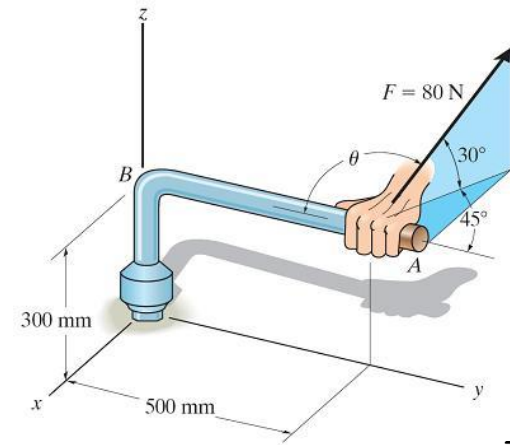
Don't look up!



# Dot (or scalar) product

The dot product of vectors **A** and **B** is defined as such

$$\mathbf{A} \cdot \mathbf{B} =$$

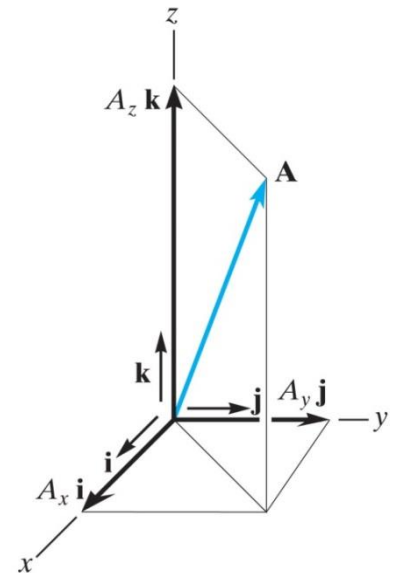


Cartesian vector formulation:

$$\mathbf{A} \cdot \mathbf{B} =$$

Note that:

$$\begin{array}{c} \mathbf{j} \\ \uparrow \\ \mathbf{i} \end{array} \quad \mathbf{i} \cdot \mathbf{j} = 0 \quad \mathbf{i} \cdot \mathbf{i} = 1 \quad \longrightarrow \quad \mathbf{i}$$



# Cross (or vector) product

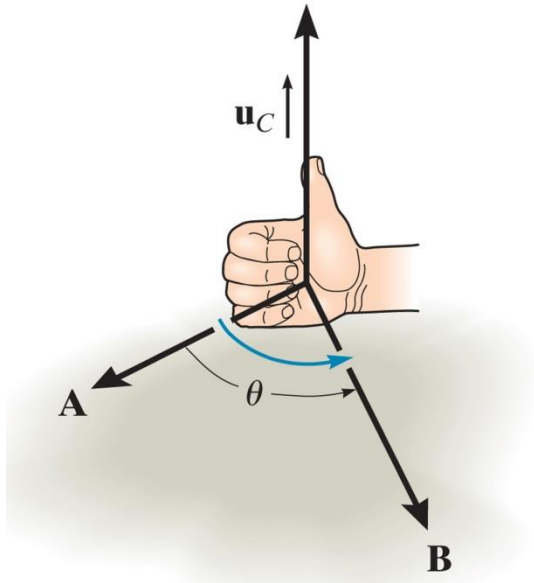
The cross product of vectors **A** and **B** yields the vector **C**, which is written

$$\mathbf{C} = \mathbf{A} \times \mathbf{B}$$

The magnitude of vector **C** is given by:

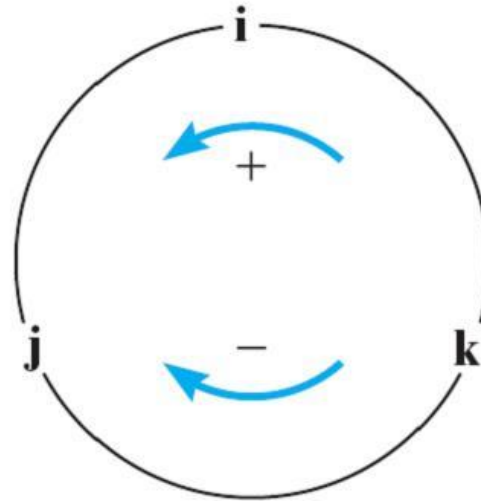
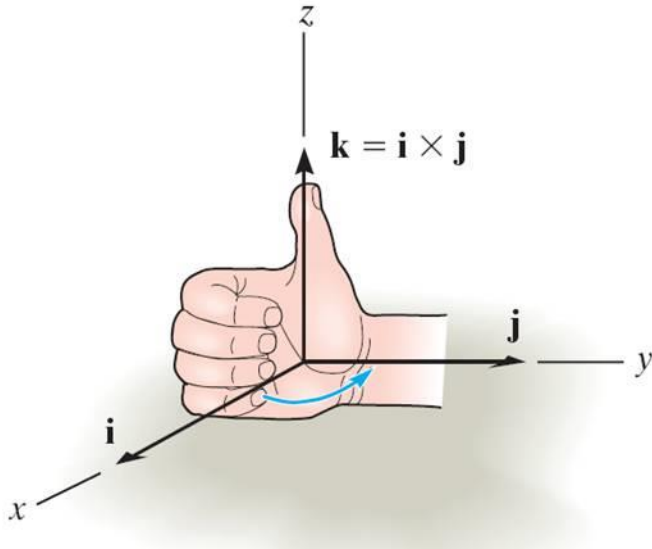
The vector **C** is perpendicular to the plane containing **A** and **B** (specified by the **right-hand rule**). Hence,

$$C =$$



# Cross (or vector) product

The right-hand rule is a useful tool for determining the direction of the vector resulting from a cross product. Note that a vector crossed into itself is zero, e.g.,  $\mathbf{i} \times \mathbf{i} = \mathbf{0}$



Considering the cross product in Cartesian coordinates

$$\mathbf{A} \times \mathbf{B} = (A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}) \times (B_x \mathbf{i} + B_y \mathbf{j} + B_z \mathbf{k})$$

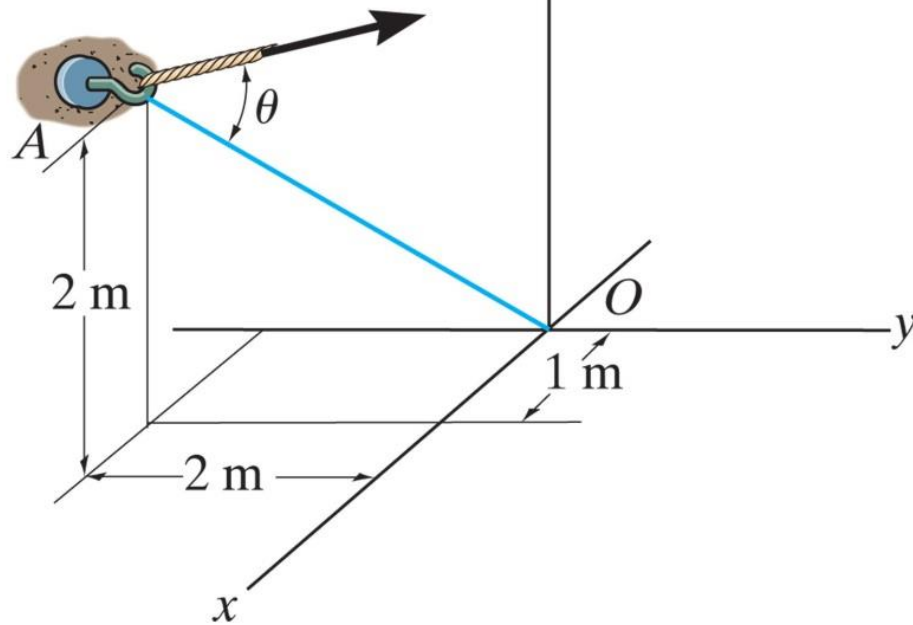
# Cross (or vector) product

Also, the cross product can be written as a determinant.

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Each component can be determined using  $2 \times 2$  determinants.

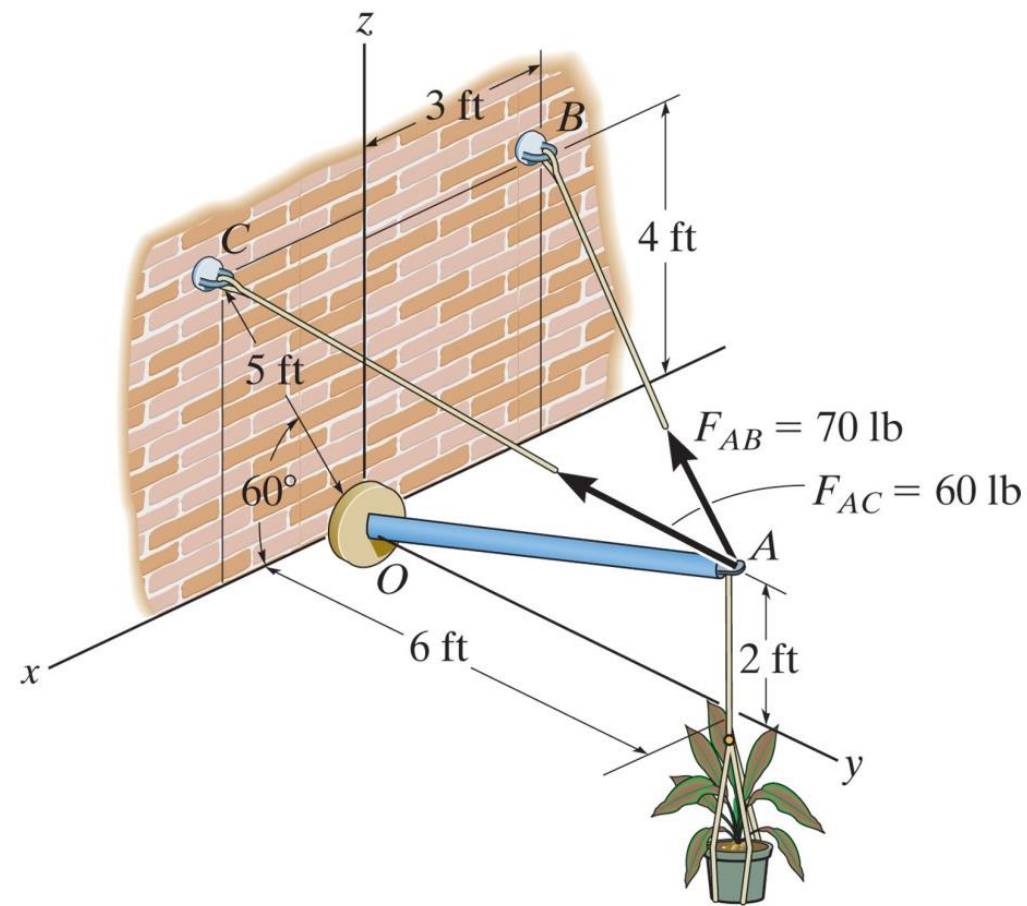
$$\mathbf{F} = \{-6\mathbf{i} + 9\mathbf{j} + 3\mathbf{k}\} \text{ kN}$$



**Given:** The force acting on the hook at point A.

**Find:** The angle between the force vector and the line  $\mathbf{AO}$ , and the magnitude of the projection of the force along the line  $\mathbf{AO}$ .

Determine the projected component of the force vector  $F_{AC}$  along the axis of strut AO. Express your result as a Cartesian vector



# Chapter 3: Equilibrium of a particle

## Main goals and learning objectives

- Introduce the concept of a free-body diagram for an object modelled as a particle
- Solve particle equilibrium problems using the equations of equilibrium



# Applications



For a spool of given weight, how would you find the forces in cables AB and AC? If designing a spreader bar (BC) like this one, you need to know the forces to make sure the rigging (A) doesn't fail.



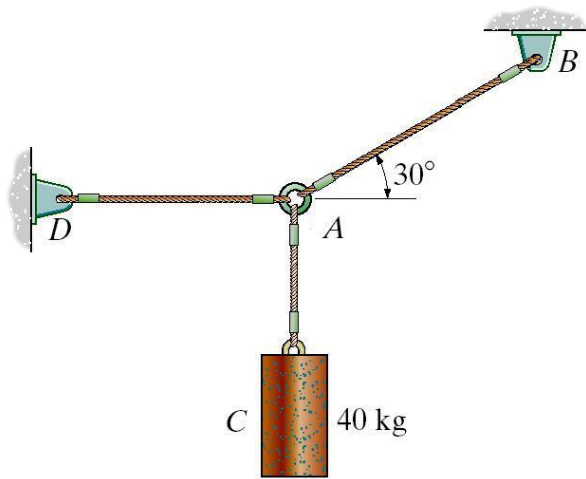
# Equilibrium of a particle

According to Newton's first law of motion , a particle will be in **equilibrium** (that is, it will remain at rest or continue to move with constant velocity) if and only if

$$\sum \mathbf{F} = \mathbf{0}$$

where  $\sum \mathbf{F} = \mathbf{0}$  is the resultant force vector of all forces acting on a particle.

In three dimensions, equilibrium requires:



Free body diagram

# Equilibrium of a particle (cont.)

**Contact force in smooth surface:**

