UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN Department of Electrical and Computer Engineering

ECE 544NA PATTERN RECOGNITION Fall 2016

SAMPLE EXAM 3

- $\bullet\,$ This is a CLOSED BOOK exam. You may use one page, both sides, of handwritten notes.
- There are a total of 100 points in the exam. Plan your work accordingly.
- You must SHOW YOUR WORK to get full credit.

Problem	Score
1	
2	
3	
4	
5	
6	
Total	

Name: _____

Problem 1 (20 points)

An RNN has output $\hat{y}(t)$ defined for $0 \leq t < \infty$, input x(t), error E_t , network weights a_t and b_t , and scalar nonlinearity $g(\cdot)$ related by

$$\hat{y}(t) = g(a_t \hat{y}(t-1) + b_t x(t))$$
 (1)

$$E_t = \frac{1}{2} (y(t) - \hat{y}(t))^2$$
(2)

$$a_0 = b_0 = 0$$
 (3)

$$a_{t+1} = a_t - 0.02 \sum_{k=0}^t \frac{\partial E_t}{\partial a_k}$$

$$\tag{4}$$

(a) Prove that, even if E_t is bounded, $\sum_{k=0}^{t} \frac{\partial E_t}{\partial a_k}$ might grow without bound.

(b) Modify the update equation to

$$a_{t+1} = \max\left(-a_{MAX}, \min\left(a_{MAX}, a_t - 0.02\sum_{k=0}^t \frac{\partial E_t}{\partial a_k}\right)\right)$$

Find sufficient conditions on a_{MAX} and $g(\cdot)$ such that $\sum_{k=0}^{t} \frac{\partial E_t}{\partial a_k}$ is guaranteed to remain bounded as $t \to \infty$.

Problem 2 (10 points)

Consider a two-layer RNN, one node per layer, with input x(t), hidden layer h(t), output $\hat{y}(t)$, error E_t , scalar nonlinearity $g(\cdot)$, and coefficients a, b, α, β related by

$$h(t) = g(ah(t-1) + bx(t))$$
 (5)

$$\hat{y}(t) = (\alpha \hat{y}(t-1) + \beta h(t)) \tag{6}$$

$$E_t = y(t)\log(\hat{y}(t)) + (1 - y(t))\log(1 - \hat{y}(t))$$
(7)

Find $\frac{\partial E_t}{\partial \beta}$ and $\frac{\partial E_t}{\partial b}$.

Problem 3 (20 points)

A simplified LSTM with inputs x(t) is defined by

$$c(t) = i(t)x(t) + m(t)c(t-1)$$
(8)

$$i(t) = u\left(w^{i}x(t) + b^{i}\right) \tag{9}$$

$$m(t) = u(w^{m}x(t) + b^{m})$$
(10)

where $u(\cdot)$ is the unit step function, defined as $u(z) = \frac{1}{2} (\operatorname{sign}(z) + 1)$.

(a) Choose w^i, b^i, w^m and b^m so that

$$c(t) = \begin{cases} x(t) & x(t) > 2\\ c(t-1) & x(t) < 2 \end{cases}$$
(11)

(b) Suppose x(t) = s(t) + v(t), where s(t) is the desired signal,

$$s(t) = \begin{cases} 10 & t = 0\\ 0 & \text{otherwise} \end{cases}$$

and v(t) is a random noise process with distribution given by

$$\Phi(z) = \Pr\{v(t) \le z\} = \int_{-\infty}^{z} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}u^2} du$$

Define the "memory" of the network you designed in part (a) to be the expected number of time steps for which c(t) = x(0). Find the memory of your network, as a function of $\Phi(z)$.

Problem 4 (25 points)

Define $c_t = i$ to be the event that the i^{th} coin is flipped at time t, where $1 \leq i \leq 3$. The possible observations are $x_t \in \{H, T\}$. Two of the coins are unfair; the heads probabilities of the three coins are given by $p(x_t = H | c_t = i) = i/4$. Coin $c_1 = 1$ is always the first one flipped. After each coin flip, the coin is changed with probability $\frac{1}{2}$; if the coin is changed, both of the other coins are equally likely.

- (a) What is $p(c_1 = 1, c_2 = 1, c_3 = 2)$?
- (b) What is the probability of getting three heads in a row?
- (c) Suppose you observe two heads in a row. You know that the first flip was coin $c_1 = 1$. Which coin was most probably the second one flipped?

Problem 5 (15 points)

Suppose that an HMM has 6 states with transition probabilities arranged into a matrix A, whose $(i, j)^{\text{th}}$ element is $a_{ij} = \Pr\{s_t = j | s_{t-1} = i\}$. The a_{ij} are initialized randomly, but because of a programming error, a_{34} is accidentally set to $a_{34} = 0$. New transition probabilities \hat{a}_{ij} are estimated as

$$\hat{a}_{ij} = \frac{\sum_{t=1}^{T} \xi_t(i,j)}{\sum_{t=1}^{T} \sum_{j=1}^{6} \xi_t(i,j)}$$
(12)

$$\xi_t(i,j) = p(s_{t-1} = i, s_t = j | A, X)$$
(13)

where $X = [x_1, \ldots, x_T]$ is a sequence of observations whose details you do not need to know. Prove that, under these circumstances, $\hat{a}_{34} = 0$.

Problem 6 (10 points)

A NN-HMM hybrid has known observations $X = [x_1, \ldots, x_T]$, and unknown state sequence $S = [s_1, \ldots, s_T]$. Its initialization probabilities are $\pi_i = \Pr\{s_1 = i\}$, and its transition probabilities are $a_{ij} = \Pr\{s_t = j | s_{t-1} = i\}$. Its observation probabilities are computed by the softmax

layer of a neural network; they are $b_j(x_t) = \Pr\{s_t = j | x_t\} / \Pr\{s_t = j\}$. Consider the following algorithm:

$$\alpha_1(i) = \pi_i b_i(x_1), \quad 1 \le i \le N \tag{14}$$

$$\alpha_{t+1}(j) = \sum_{i=1}^{N} \alpha_t(i) a_{ij} b_j(x_t), \quad 1 \le i, j \le N, \quad 1 \le t \le T - 1$$
(15)

$$P_{final} = \sum_{j=1}^{N} \alpha_T(j) \tag{16}$$

Express $P_{final} = \ldots$, where the right-hand side of the equation contains some sort of arithmetic combination of joint, conditional, and marginal probability mass functions of the random variables x_t . No other variables should appear on the right-hand side.