

# Random vectors and estimation theory

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \text{ where } x_i \text{ are RVs / RANDOM VECTOR}$$

$$Y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

mean  $\begin{bmatrix} E[x_1] \\ \vdots \\ E[x_n] \end{bmatrix}$

Two important matrices associated with RV's

- { Correlation matrix :  $E[XX^T]$   $i, j^{\text{th}}$  entry  $E[x_i x_j]$
- { Cross-correlation :  $E[XY^T]$   $i, j^{\text{th}}$  entry  $E[x_i y_j]$
- { Covariance matrix :  $E[(X-E[X])(X-E[X])^T]$   $i, j^{\text{th}}$  entry  $\text{Cov}(x_i, x_j)$
- { Cross-covariance matrix :  $E[(X-E[X])(Y-E[Y])^T]$   $i, j^{\text{th}}$  entry  $\text{Cov}(x_i, y_j)$

Claim Correlation and covariance matrices are symmetric, positive semidefinite matrices. If  $K$  is positive semidefinite, then there exists a zero-mean random vector  $X$  with  $K$  as its correlation matrix.

Proof If  $K$  is a correlation matrix, then

$$K = E[XX^T] \text{ for some RV } X$$

$$\alpha^T K \alpha = \alpha^T E[XX^T] \alpha = E[(\alpha^T X)(X^T \alpha)] = E[(\alpha^T X)^2] \geq 0$$

$\downarrow$   
non-random,  $\alpha \in \mathbb{R}^n$

For the second claim, suppose that  $K$  is positive semidefinite

Then,  $K$  has non-negative eigenvalues  $\lambda_1, \dots, \lambda_n$   
 $U$  the orthonormal matrix formed from the eigenvectors

Let  $y_i$  be independent RVs, s.t.  $E[y_i] = 0, E[y_i^2] = \lambda_i$

$$Y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$\text{Then, } \text{Cov}(Y, Y) = \Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{bmatrix}$$

Define  $X = UY$

Then,  $E[X] = UE[Y] = 0$  and

$$\text{Cov}(X, X) = \text{Cov}(UY, UY) = E[U Y Y^T U^T] = U E[Y Y^T] U^T = U \Lambda U^T = K$$

One more definition :

Characteristic function  $\phi_X(u) = E[\exp(j u^T X)]$

# Orthogonality principle

Let us start with the case of scalar RVs.

Let  $X$  be a scalar RV that we cannot observe (directly). We can try to "estimate"  $X$  either via repeated experiments char.  $\hat{X}$ , or via the observation of some other RV  $Y$ .

Say, have complicated formula, do not want to drag RV in it, prefer to have a const.  $b$  be a "proxy" for  $X$

What is the best choice for  $b$ ?

Intuitively, mean should be a "good" proxy. Formally, if we seek to find const.  $b$  that minimizes MSE = mean square error  $E[(X-b)^2]$ , we get

$$E[(X-b)^2] = E[(X-E[X] + E[X]-b)^2] = E[(X-E[X])^2] + 2E[(X-E[X])(E[X]-b)] + (E[X]-b)^2 = \text{var}(X) + (E[X]-b)^2$$

$b^* = E[X]$

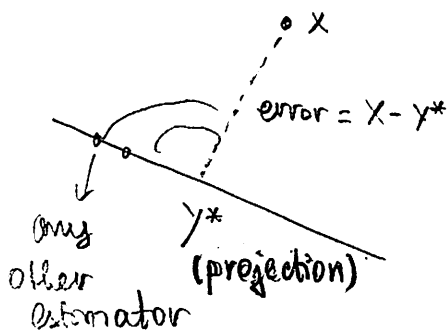
minimizes the error, which in that case equals the variance

Key to the simple proof was

$$E[(X-E[X])a] = 0 \quad \text{any estimator}$$

$$\text{i.e. } E[(X-b^*)a] = 0 \quad \forall a \in \mathbb{R}, \text{ const.}$$

error of optimal estimator



Formally:

Recall that  $X, Y$  are said to be uncorrelated if  $E[XY] = E[X]E[Y]$

$X, Y$  are orthogonal if

$$E[XY] = 0, \quad X \perp Y$$

Above orthogonality principle asserts that  $(X - E[X]) \perp C$

$L^2(\Omega, \mathcal{F}, P)$  : set of all RV's on given PS with finite second moment (why finite - will use MSE)

$\mathcal{V} \subseteq L^2(\Omega, \mathcal{F}, P)$  s.t.

a)  $\mathcal{V}$  linear class: If  $z_1 \in \mathcal{V}, z_2 \in \mathcal{V}$ , then  $a_1 z_1 + a_2 z_2 \in \mathcal{V}, \forall \text{ const. } a_1, a_2$

b)  $\mathcal{V}$  is closed in HS sense:  $z_1, z_2, \dots \in \mathcal{V}, z_n \xrightarrow{\text{m.s.}} z_\infty \Rightarrow z_\infty \in \mathcal{V}$

Let  $\mathcal{V}$  be as above

- a)  $\exists z^* \in \mathcal{V}$  such that  $E[(X-z^*)^2] \leq E[(X-z)^2] \quad \forall z \in \mathcal{V}$  :  $z^*$  is unique
- b)  $W = z^*$  <sup>iff</sup>  
 $W \in \mathcal{V}, (X-W) \perp Z \quad \forall Z \in \mathcal{V}$
- c)  $MMSE = E[(X-z^*)^2] = E[X^2] - E[(z^*)^2]$

Proof b) Assume that  $W \in \mathcal{V}, (X-W) \perp Z \quad \forall Z \in \mathcal{V}$  Assume  $W \perp$  every  $Z \in \mathcal{V}$   
 $\Rightarrow$  it will have smallest MSE  
 $W-Z \in \mathcal{V}$  (linearity) hence  $(X-W) \perp (W-Z)$   
 Then  $E[(X-Z)^2] = E[(X-W+W-Z)^2] = E[(X-W)^2] + E[(W-Z)^2]$   
i.e.  $\downarrow$   $\uparrow$   
 $E[(X-W)^2]$  due to orthogonality

Assume has smallest MSE  
 show orthogonality

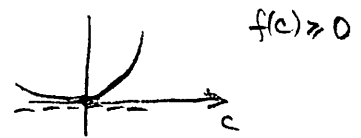
Assume that  $W = z^*$ . Clearly,  $W \in \mathcal{V}$ . Let  $Z \in \mathcal{V}, c \in \mathbb{R}$ , so that  $z^* + cZ \in \mathcal{V}$ . Since  $z^*$  is optimal,  $E[(X-(z^*+cZ))^2] \geq E[(X-z^*)^2]$  \*\*

Expanding

$$E[(X-(z^*+cZ))^2] = E[(X-z^*-cZ)^2] = E[(X-z^*)^2] - E[2(X-z^*)cZ] + E[c^2Z^2]$$

$\Rightarrow$  From \*\*

$$0 \leq \underbrace{E[c^2Z^2] - 2cE[(X-z^*)Z]}_{f(c)}$$



$$f'(c) = 0 \quad \Rightarrow$$

$$(c^2 E[Z^2] - 2c E[(X-z^*)Z]) \Big|'_{c=0} = 0$$

$$2c E[Z^2] - 2 E[(X-z^*)Z] \Big|_{c=0} = 0$$

$$\Rightarrow E[(X-z^*)Z] = 0$$

c)  $E[(X-z^*)^2] = E[(X-z^*)X - (X-z^*)z^*] = E[(X-z^*)X] - E[(X-z^*)z^*]$   
 $= E[X^2 - z^*X]$

Easier

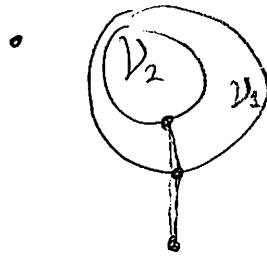
$$E[X^2] = E[(X-z^*+z^*)^2] = E[(X-z^*)^2] + E[z^{*2}] - 2E[(X-z^*)z^*]$$

# Summary of properties of projections

Denote the projection of  $X$  onto  $\mathcal{V}$  as  $\Pi_{\mathcal{V}}(X)$

Then

- $\Pi_{\mathcal{V}}(a_1 X_1 + a_2 X_2) = a_1 \Pi_{\mathcal{V}}(X_1) + a_2 \Pi_{\mathcal{V}}(X_2)$



Both  $\mathcal{V}_2, \mathcal{V}_1$  are closed,  $\mathcal{V}_1 \subseteq \mathcal{V}_2$

$$\Pi_{\mathcal{V}_2}(X) = \Pi_{\mathcal{V}_2}(\Pi_{\mathcal{V}_1}(X))$$

$$E[(X - \Pi_{\mathcal{V}_2}(X))^2] = E[(X - \Pi_{\mathcal{V}_1}(X))^2] + E[(\Pi_{\mathcal{V}_1}(X) - \Pi_{\mathcal{V}_2}(X))^2]$$

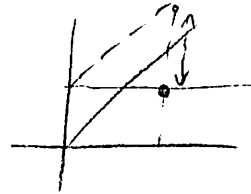
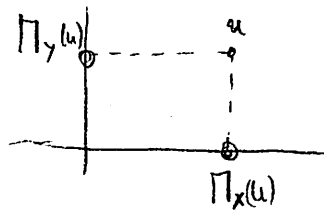
and  $E[(X - \Pi_{\mathcal{V}_2}(X))^2] \geq E[(X - \Pi_{\mathcal{V}_1}(X))^2]$

- Both  $\mathcal{V}_1, \mathcal{V}_2$  are closed,  $\mathcal{V}_1 \perp \mathcal{V}_2$   $\forall z_1 \in \mathcal{V}_1$   
 $\forall z_2 \in \mathcal{V}_2$   $E[z_1 z_2] = 0$

Let  $\mathcal{V} = \mathcal{V}_1 \oplus \mathcal{V}_2 = \{z_1 + z_2 : z_i \in \mathcal{V}_i\}$

$$\Pi_{\mathcal{V}}(X) = \Pi_{\mathcal{V}_1}(X) + \Pi_{\mathcal{V}_2}(X)$$

$$E[(X - \Pi_{\mathcal{V}}(X))^2] = E[X^2] - E[(\Pi_{\mathcal{V}_1}(X))^2] - E[(\Pi_{\mathcal{V}_2}(X))^2]$$



The more important case: Estimating  $X$  based on observations of another variable  $Y$ ? Estimator = function( $Y$ ) =  $f(Y)$

- All functions  $f$
- Linear functions  $f$

1  $\mathcal{V} = \{g(Y) : g: \mathbb{R}^m \rightarrow \mathbb{R}^n, E[g(Y)^T g(Y)] < \infty\}$

$g$  has to be Borel measurable

Assume that  $X, Y$  have a well-defined joint distribution, and in particular, a joint pdf

$$E[(X - g(Y))^2] = \int_{\mathbb{R}^m} E[(X - g(Y))^2 | Y=y] f_Y(y) dy$$

where

$$E[(X - g(Y))^2 | Y=y] = \int_{\mathbb{R}^m} (x - g(y))^2 f_{X|Y}(x) dx$$

Optimal MSE estimator  $E[X|Y]$

Orthogonality principle  $E[(X - E[X|Y])g(Y)] = 0$

Since  $E[\|X - g(Y)\|^2] = \sum_{i=1}^m E[(x_i - g_i(Y))^2]$ , MMSE estimator analysis carries over from the scalar to the vector case in the obvious way - through componentwise estimation. (3)

$$g^*(Y) = E[X|Y] = \begin{pmatrix} E[X_1|Y] \\ E[X_2|Y] \\ \vdots \\ E[X_m|Y] \end{pmatrix}$$

Linear estimators:  $\hat{Y} = c_0 + c_1 Y_1 + c_2 Y_2 + \dots + c_n Y_n$ ;  $c_0, c_1, \dots, c_n \in \mathbb{R}$

$$\hat{X} = AY + b, \quad e = X - AY - b, \quad e_i = (X - AY - b)_i$$

$$E[\|X\|^2] < \infty$$

$$E[\|Y\|^2] < \infty$$

$\Downarrow$

i)  $e_i \perp 1$

ii)  $e_i \perp Y_j \quad \forall i, j$

i)  $\Rightarrow E[e_i] = 0 \Rightarrow E[X] = AE[Y] + b \Rightarrow b = E[X] - AE[Y]$

ii)  $\Rightarrow E[e_i Y_j] = 0$  which is equivalent to  $\text{cov}(e_i, Y_j) = 0$ , since  $E[e_i Y_j] = 0$

$$\text{Cov}(e, Y) = \text{Cov}(X - AY - b, Y) = \text{Cov}(X, Y) - A \text{Cov}(Y, Y) - 0 = 0$$

$$\Rightarrow \text{Cov}(X, Y) = A \text{Cov}(Y, Y)$$

$$A = \text{Cov}(X, Y) \text{Cov}^{-1}(Y, Y)$$

Hence, the optimal estimator from the linear class is

$\hookrightarrow$  if non-singular

$$\hat{E}[X|Y] = E[X] + A(Y - E[Y])$$

$$= E[X] + \text{Cov}(X, Y) \text{Cov}^{-1}(Y, Y) (Y - E[Y])$$

$$\text{Cov}(e) = \text{Cov}(e, e) = \text{Cov}(e, X - g^*(Y)) = \text{Cov}(e, X) - \text{Cov}(e, g^*(Y))$$

$$= \text{Cov}(X - E[X] - \text{Cov}(X, Y) \text{Cov}^{-1}(Y, Y) (Y - E[Y]), X) = \text{Cov}(X) - \text{Cov}(X, Y) \text{Cov}^{-1}(Y, Y) \text{Cov}(Y, X)$$

Estimation error:

$$\text{Cov}(e) = \text{Cov}(X) - \text{Cov}(X, Y) \text{Cov}^{-1}(Y, Y) \text{Cov}(Y, X)$$

### Examples

Let  $Y = X + Z$  where the signal  $X \sim U[-1, 1]$  and noise  $Z \sim \mathcal{N}(0, 1)$  are independent.

Find the MMSE for  $\text{sign}(X)$  - (the sign function)

$$g(y) = E[\text{sign}(X) | Y=y] = \int \text{sign}(x) f_{X|Y}(x|y) dx$$

$$f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x) f_X(x)}{f_Y(y)}$$

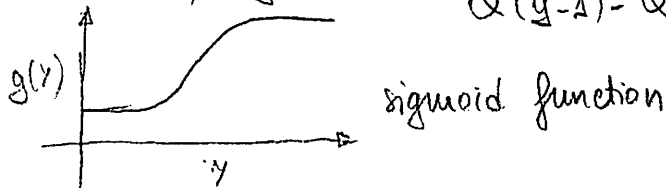
$$f_X(x) = \begin{cases} 1/2, & x \in [-1, 1] \\ 0, & \text{otherwise} \end{cases}$$

Since  $X, Z$  are independent  $Y|X=x \sim N(x, 1)$

$$f_Y(y) = \int_{-\infty}^{+\infty} f_{Y|X}(y|x) f_X(x) dx = \frac{1}{2} \int_{-1}^1 \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} dx$$

$$= \frac{1}{2} (Q(y-1) - Q(y+1))$$

Hence,  $g(y) = \frac{Q(y+1) - 2Q(y) + Q(y-1)}{Q(y-1) - Q(y+1)}$



### Gaussian RVs

$X$  Gaussian with  $f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, x \in \mathbb{R}$   
 $\sigma > 0$

$$\Phi_X(u) = \exp\left(-\frac{u^2\sigma^2}{2} + j\mu u\right)$$

Claim  $X_1, \dots, X_n$  are independent Gaussian RVs, then any  $\sum_{i=1}^n a_i X_i + \dots + a_n X_n$  is Gaussian.

Proof suffices to show that claim is true for  $n=2, a_1=a_2=1$

$$X = X_1 + X_2 \quad X_1 \sim N(\mu_1, \sigma_1^2), X_2 \sim N(\mu_2, \sigma_2^2)$$

$$\Phi_X(u) = E[e^{juX}] = E[e^{juX_1}] E[e^{juX_2}] = \exp\left(-\frac{u^2\sigma_1^2}{2} + j\mu_1 u\right) \exp\left(-\frac{u^2\sigma_2^2}{2} + j\mu_2 u\right)$$

$$= \exp\left(-\frac{u^2(\sigma_1^2 + \sigma_2^2)}{2} + ju(\mu_1 + \mu_2)\right)$$

Def  $(X_i : i \in I)$  is jointly Gaussian if every finite linear combination of variables in the set is Gaussian

$X \sim N(\mu, K)$  mean vector  $\mu$ , covariance  $K$

Theorem 1)  $(X_i : i \in I)$  jointly Gaussian, then each  $X_i$  is Gaussian

2) If  $(X_i : i \in I)$  are Gaussian, and independent (for any finite collection), then  $(X_i : i \in I)$  are jointly Gaussian

3)  $(X_i : i \in I)$  jointly Gaussian

$Y_j$ 's finite linear combinations of  $X_i$ 's;  $Z_k$ 's limits of sequences  $m(Y_j)$  ( $P, o.s., m.s.$ )  
 $(Y_j : j \in J), (Z_k : k \in K)$  are jointly Gaussian RVs

! Proposition 2.8 from the lecture notes

$X_n \in \mathcal{U}$  that is Gaussian,  $\forall n$

$X_n \rightarrow X_\infty$  (a.s., w.s, p, d)  $\Rightarrow \underline{X_\infty \text{ is Gaussian!}}$

(4)

4) Characteristic function of  $X \sim \mathcal{N}(\mu, K)$ ,  $\dim(X) = m$

$$\phi_X(u) = e^{iu^T \mu - \frac{1}{2} u^T K u}$$

5) If  $K$  is diagonal, then components of  $X$  are independent

$X, Y$  are jointly Gaussian vectors; they are independent if  $\text{Cov}(X, Y) = 0$

$$6) f_X(x) = \frac{1}{(2\pi)^{m/2} |K|^{1/2}} \exp\left(-\frac{(x-\mu)^T K^{-1} (x-\mu)}{2}\right)$$

Problem Suppose that  $X, Y$  are jointly Gaussian, with parameters  $E[X] = \mu_x$ ,  $E[Y] = \mu_y$ ,  $\text{Var}(X) = \sigma_x^2$ ,  $\text{Var}(Y) = \sigma_y^2$ ,  $E[XY] = \rho_{xy}$ . Are the following claims true or false:

1.  $X, Y$  are Gaussian. ✓

2.  $X \sim \mathcal{N}(\mu_x, \sigma_x^2)$ ,  $Y \sim \mathcal{N}(\mu_y, \sigma_y^2)$  ✓

3.  $Z = aX + bY$ ,  $a, b \in \mathbb{R}$ , is Gaussian with mean  $a\mu_x + b\mu_y$ . ✓

4.  $\rho_{xy} = 0 \Rightarrow X, Y$  independent ✓

5.  $Z = aX + bY$ ,  $a, b \in \mathbb{R}$ , is Gaussian with variance  $a^2 \sigma_x^2 + b^2 \sigma_y^2$ . ✗

$$\text{Cov}(Z, Z) = \text{Cov}(aX + bY, aX + bY) = a^2 \text{Var}(X) + 2ab \text{Cov}(X, Y) + b^2 \text{Var}(Y)$$

6. The linear MMSE of  $X$  given  $Y$  is

$$X_L = \mu_x + \rho_{xy} \frac{\sigma_x}{\sigma_y} (Y - \mu_y) \quad \checkmark$$

Linear MMSE = unrestricted MMSE

$$E[X|Y] = E[X] + \text{Cov}(X, Y) \text{Cov}(Y, Y)^{-1} (Y - E[Y])$$

$$= \mu_x + \frac{\text{Cov}(X, Y)}{\sigma_y^2 \sigma_y} \sigma_y (Y - \mu_y) = \mu_x + \rho_{xy} \frac{\sigma_x}{\sigma_y} (Y - \mu_y) \quad \checkmark$$

$$\text{Recall that } \rho_{xy} = \frac{\text{Cov}(X, Y)}{\sqrt{\sigma_x^2 \sigma_y^2}} = \frac{\text{Cov}(X, Y)}{\sigma_x \sigma_y}$$

7. The conditional distribution of  $Y|X$  is Gaussian. ✓

True

### Example (Extra)

Let  $X$  be an unobservable RV with  $E[X]=0$ ,  $\text{var}(X)=4$ . We observe

$$Y_1 = X + W_1$$

$$E[W_1] = E[W_2] = 0$$

$$Y_2 = X + W_2$$

$$\text{Var}(W_1) = 1, \text{Var}(W_2) = 4$$

$W_1, W_2, X$  are independent

Find the linear MMSE estimator of  $X$  given  $Y_1, Y_2$

$$\hat{X}_L = aY_1 + bY_2 + c$$

Orthogonality principle

$$1) E[(X - aY_1 - bY_2 - c)] = 0 \Rightarrow c = 0$$

$$2) E[(X - aY_1 - bY_2)Y_1] = 0, E[(X - aY_1 - bY_2)Y_2] = 0$$

$$\Rightarrow E[XY_1] - aE[Y_1^2] - bE[Y_1Y_2] = 0$$

$$E[X(X+W_1)] - aE[(X+W_1)^2] - bE[(X+W_1)(X+W_2)] = 0$$

$$E[X^2] + E[XW_1] - a(E[X^2] + E[W_1^2]) - b(E[X^2] + E[W_1W_2]) = 0$$

$$4 - 5a - 4b = 0$$

$$5a + 4b = 4$$

Similarly, ...

$$4a + 8b = 4$$

$$\Rightarrow a = \frac{2}{3}, b = \frac{1}{6}$$

$$\hat{X}_L = \frac{2}{3}Y_1 + \frac{1}{6}Y_2$$

Example Suppose  $X, Y$  are jointly Gaussian, zero mean,  $K = \begin{pmatrix} 4 & 3 \\ 3 & 9 \end{pmatrix}$

$$E[X^2|Y] = ?$$

Observe the following:  $X, Y$  jointly Gaussian vectors,  $y \in \mathbb{R}$

$$X|Y=y \sim \mathcal{N}(X_L(y), \text{Cov}(e))$$

$$\text{and } X_L(y) = E[X|Y=y]$$

If  $\text{Cov}(Y)$  is non-singular

$$E[X|Y=y] = X_L(y) = E[X] + \text{Cov}(X, Y) \text{Cov}(Y)^{-1} (y - E[Y])$$

$$\text{Cov}(e) = \text{Cov}(X) - \text{Cov}(X, Y) \text{Cov}(Y)^{-1} \text{Cov}(Y, X)$$

and if  $\text{Cov}(e)$  is non-singular

$$f_{X|Y}(x|y) = \frac{1}{(2\pi)^{n/2} |\text{Cov}(e)|^{1/2}} \exp\left(-\frac{1}{2} (x - X_L(y))^T \text{Cov}^{-1}(e) (x - X_L(y))\right)$$



Proof Consider  $X_L(Y) =$  linear function of  $Y$

$$e = X - X_L(Y) = \text{linear function of } X, Y$$

Orthogonality principle  $E[e] = 0$   
 $\text{Cov}(e, Y) = 0 \Rightarrow Y, e$  are jointly Gaussian, independent

Next, rewrite  $X = e + X_L(Y)$

$$\text{given } Y=y, e|Y=y \sim \mathcal{N}(0, \text{Cov}(e))$$

$$\text{Hence } X|Y=y \sim \mathcal{N}(X_L(y), \text{Cov}(e))$$

$$\text{Also, } E[X|Y] = X_L(Y)$$

Example solution  $X, Y$  are jointly Gaussian, zero mean,  $K = \begin{pmatrix} 4 & 3 \\ 3 & 3 \end{pmatrix}$

Given  $Y=y$ , the conditional distribution of  $X$  is

$$\mathcal{N}\left(\frac{\text{Cov}(X, Y)}{\text{Var}(Y)} y, \text{Cov}(X) - \frac{\text{Cov}^2(X, Y)}{\text{Var}(Y)}\right)$$

$$\text{||}$$

$$\mathcal{N}\left(\frac{y}{3}, 3\right)$$

$$E[X^2|Y=y] = \left(\frac{y}{3}\right)^2 + 3$$

• Suppose  $X$  is a RV with  $E[X^4] = 30$

• Derive an upper bound on  $P\{|X| \geq 10\}$

• Find a distribution for  $X$  s.t. that the upper bound holds with equality

$$P\{|X| \geq 10\} \leq \frac{E[f(X)]}{f(10)}$$

$$\text{take } f(x) = x^4$$

$$P\{|X| \geq 10\} \leq \frac{E[X^4]}{10^4} = \frac{30}{10^4} = 0.003$$

$$P\{X = 10\} = 0.003$$

$$P\{X = 0\} = 1 - 0.003$$

•• Let  $U_1, U_2, \dots$  be a sequence of independent random variables, each uniformly distributed in  $[0, 1]$

For what values of  $c \geq 0$  does there exist a  $b > 0$  (depending on  $c$ ) s.t.  $P\{U_1 + \dots + U_n \geq cn\} \leq e^{-bn} \quad \forall n \geq 1$

$$E[U_1] = 1/2 \quad E[U_1 + \dots + U_n] = \frac{n}{2}$$

$$\text{want } cn > 1/2n \quad c > 1/2 \quad \text{If } c = 1/2, \text{ prob is exactly } 0.5$$

$$\therefore (*) P\{U_1 + \dots + U_n \geq c(U_{n+1} + \dots + U_{2n})\} \leq e^{-bn} \quad \forall n \geq 1$$

$$\text{Define } X_i = U_i - cU_{n+i}$$

$$X_i \text{'s are iid, } E[X_i] = \frac{1}{2} - c \frac{1}{2} = \frac{1-c}{2}$$

$$(*) = P\{X_1 + \dots + X_n \geq 0\}$$

$$\Downarrow \text{ want } 0 > \frac{1-c}{2} \Rightarrow \boxed{c < 1}$$