

## Solutions to Practice final

ECS 534

spring 2005

Problem 1

a) False  $\begin{vmatrix} 2 & r \\ r & 3 \end{vmatrix} \geq 0 \Rightarrow |r| \leq \sqrt{6}$

b) True.  $E[z_t] = \mu_x \mu_y$   
 $\text{cov}_z(t,s) = \text{cov}_x(t,s) \text{cov}_y(t,s)$

c) False  $S_x(\omega) \leq 0 \quad \forall \omega \geq 1$ .  
 PSD has always be positive.

d) True.

e) True.

f) True.

g) False.  $\tan^{-1}(\cdot)$  is a concave function, thus it won't satisfy Jensen's Inequality.

h) True

i) False  $|R_x(t,s)| \leq \sqrt{R_x(t,t) R_x(s,s)}$

j). False  $R_x(\tau) \leq R_x(0)$ ,  $\forall \tau \neq 0$ . The slope @  $\tau=0$  has to be 0.

k) False  $2R_{xy}(\tau) \stackrel{?}{\leq} R_x(0) R_y(0)$ . No.

l) ~~So~~ True  $S_w(0) = \frac{4}{2} = \int_0^{\pi} R_x(\tau) d\tau \leq \pi$

Problem 2

a)  $X = |Y|$   
 $\hat{X}_{MMSE} = E[X|Y] = |Y|$

$MSE_1 = 0$

b)  $\hat{X}_{LMMSE} = E[X] + \frac{cov(X,Y)}{cov(Y,Y)} (Y - E[Y])$

$E[Y] = 0$

$E[X] = E[|Y|] = 0.8$

$cov(Y,Y) = 1$

$cov(X,Y) = E[XY] = E[|Y|Y] = 0.$

$\hat{X}_{LMMSE} = 0.8$

$MSE_2 = E[(X - 0.8)^2] = E[X^2] - 1.6 E[X] + 0.64 = 0.32$

c)  $\hat{X}(y) = a + by + cy^2$

$MSE = E[(X - (a + by + cy^2))^2]$

$0 = \frac{\partial}{\partial a} E[\quad]$

$0 = \frac{\partial}{\partial b} E[\quad]$

$0 = \frac{\partial}{\partial c} E[\quad]$

$\Rightarrow a = c = 0.4, b = 0.$

$\hat{X}(y) = 0.4 + 0.4 y^2$

Problem 3  $Y_n = \frac{1}{\sqrt{n}} X_n - 9\sqrt{n}$ .

A 
$$= \frac{1}{\sqrt{n}} \underbrace{(X_n - 9n)}_{Z_n} = \frac{1}{\sqrt{n}} Z_n = \frac{1}{\sqrt{n}} \sum_{i=1}^n Z_i - Z_{i-1}$$

$(Z_0 = X_0 = 0)$ .

Because  $X_n$  is Poisson w/ independent increments,  $\{Z_i - Z_{i-1}\}_{i=1}^n$  are iid. Each term has 0-mean, and variance  $(Z_i - Z_{i-1}) = 1 = 9$ .

By central limit theorem,  $Y_n$  converges to a Gaussian.

$$\lim_{n \rightarrow \infty} Y_n = \lim_{n \rightarrow \infty} \frac{1}{\sqrt{n}} \sum_{i=1}^n Z_i - Z_{i-1} \xrightarrow{d} N(0, 9).$$

B)  $E[\omega_n | \omega_{n-1}, \omega_{n-2}, \dots, \omega_1] = \omega_{n-1}$

$$E[\alpha \cdot \omega_{n-1} \cdot X_n] = \alpha \omega_{n-1} \cdot E[X_n] = \omega_{n-1}$$

$$\alpha \cdot E[X_n] = 1$$

$$\alpha = \frac{1}{E[X_n]} = \frac{1}{4}.$$

Problem 4. A.  $R_X(\tau) = 2e^{-|\tau|} - e^{-2|\tau|}$

$$\begin{aligned} R_X(t-s) &= 2e^{-(t-s)} - e^{-2(t-s)} & \tau \geq 0 \Rightarrow t \geq s. \\ &= 2e^{+(t-s)} - e^{2(t-s)} & t < s. \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial s} R_X(t-s) &= 2e^{-(t-s)} - 2e^{-2(t-s)} & t \geq s \\ &= -2e^{(t-s)} + 2e^{2(t-s)} & t < s. \end{aligned}$$

The first partial is continuous @  $t=s$ . ✓

$$\begin{aligned} \frac{\partial}{\partial t} \frac{\partial}{\partial s} R_X(t-s) &= -2e^{-(t-s)} + 4e^{-2(t-s)} & t \geq s \\ &= -2e^{t-s} + 4e^{2(t-s)} & t < s. \end{aligned}$$

The 2<sup>nd</sup> mixed partial is also continuous @  $t=s$

$$\begin{aligned} \frac{\partial}{\partial s} \frac{\partial}{\partial t} \frac{\partial}{\partial s} R_X(t-s) &= -2e^{-(t-s)} + 8e^{-2(t-s)} & t \geq s \\ &= 2e^{t-s} - 8e^{2(t-s)} & t < s. \end{aligned}$$

$$\left. \begin{array}{l} = 8 - 2 = 6 \\ \left|_{t=s} \right. \quad \quad \quad 2 - 8 = -6 \end{array} \right\} \begin{array}{l} t \geq s \\ t < s. \end{array}$$

The 3<sup>rd</sup> mixed partial has a discontinuity @  $t=s$ .  
 $\Rightarrow$  doesn't exist!

Since  $X$  is WSS,  $R_X(\tau)$ ,  $R_X'(\tau)$  &  $R_X''(\tau)$  exist & continuous, then  $X'_t$  exists in the mean-square sense.

$\Rightarrow k=1$ .

Part B.

$X_0$  &  $X_{\frac{\pi}{2}}$  are jointly Gaussian.

$$\mu_{X_0} = 1 \quad \sigma_{X_0}^2 = 4$$

$$\mu_{X_{\frac{\pi}{2}}} = 0 \quad \sigma_{X_{\frac{\pi}{2}}}^2 = 4$$

$$\text{cov}(X_0, X_{\frac{\pi}{2}}) = E[X_0 X_{\frac{\pi}{2}}] = 4e^{-\frac{\pi}{2}}$$

$$\begin{bmatrix} X_0 \\ X_{\frac{\pi}{2}} \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 & 4e^{-\frac{\pi}{2}} \\ 4e^{-\frac{\pi}{2}} & 4 \end{bmatrix} \right)$$

$$f_{X_{\frac{\pi}{2}} | X_0}(x | x_0 = 1) = \frac{f_{X_{\frac{\pi}{2}}, X_0}(x_{\frac{\pi}{2}}, x_0)}{f_{X_0}(x_0)}$$

$$\sim \mathcal{N}(e^{-\frac{\pi}{2}}, 4(1 - e^{-\pi}))$$

Problem 5.

a)  $\phi_1(t) = s(t)$ .

$$Y_t = \sum_{i=1}^{\infty} (Y_t, \phi_i(t)) \phi_i(t)$$

$$= (Y_t, \phi_1(t)) \phi_1(t) + \sum_{i=2}^{\infty} (Y_t, \phi_i(t)) \phi_i(t)$$

$$(Y_t, \phi_1(t)) = \int (Xs(t) + N_t) \overline{s(t)} dt = X \int \|s(t)\|^2 dt + \int N_t \overline{s(t)} dt$$

$$= X + n_1, \text{ where } n_1 \sim \mathcal{N}(0, \sigma^2)$$

$i \geq 2$   $(Y_t, \phi_i(t)) = \int (Xs(t) + N_t) \overline{\phi_i(t)} dt$ ,  $s(t) = \phi_1(t) \perp \phi_i(t)$ ,  $i \geq 2$ .

$$= X \int \overbrace{s(t) \phi_i(t)}^{=0} dt + n_i$$

Sufficient statistics of  $Y_t$

$$\begin{cases} (Y_t, \phi_1(t)) = X + n_1 \\ (Y_t, \phi_i(t)) = n_i, \quad i = 2, 3, 4, \dots \end{cases}$$

b)  $\hat{X}_{\text{MMSE}} = E[X | Y_t, 0 \leq t \leq T]$

$$= E[X | X + n_1, n_2, n_3, \dots]$$

$$= E[X | X + n_1]$$

$$\hat{X}_{\text{MMSE}} = \frac{1}{1 + \sigma^2} (Y_t, \phi_1(t))$$

} By KL Expansion of part a).

Problem 6  $S_x(\omega) = \frac{2}{1+\omega^2}$ .

a)  $S_y(\omega) = S_x(\omega) |H(\omega)|^2 = \left(\frac{2}{1+\omega^2}\right) \left(\frac{2b}{b^2+\omega^2}\right)$ .

b)  $R_{yx}(\tau) = R_x(\tau) * h(\tau)$ .

$S_{yx}(\omega) = S_x(\omega) H(\omega) = \left(\frac{2}{1+\omega^2}\right) \left(\frac{1}{1+j\omega} - \frac{2}{2+j\omega} + \frac{1}{3+j\omega}\right)$

$H(\omega) = \frac{S_{yx}(\omega)}{S_x(\omega)}$

It's unique, because the system is stable & causal.

Problem 7. a)

$S_x(\omega) = \frac{2A}{A^2+\omega^2}$ .

$S_y(\omega) = S_n(\omega) + S_x(\omega) |G(\omega)|^2$ .

$= G^2 + \frac{2A}{A^2+\omega^2} \frac{\pi}{\alpha} e^{-\frac{\omega^2}{2\alpha}}$ .

$S_{xy}(\omega) = S_x(\omega) \overline{G(\omega)}$   
 $= \frac{2A}{A^2+\omega^2} \sqrt{\frac{\pi}{\alpha}} e^{-\frac{\omega^2}{2\alpha}}$ .

$H(\omega) = \frac{S_{xy}(\omega)}{S_y(\omega)}$

Problem 8.

$$a). \quad [X(\omega) + Y(\omega) H_2(\omega)] H_1(\omega) + N(\omega) = Y(\omega).$$

$$G_1(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{H_1(\omega)}{1 - H_1(\omega) H_2(\omega)} = \frac{2}{1 - \frac{4}{5+j\omega}} = \frac{2(5+j\omega)}{1+j\omega}.$$

$$G_2(\omega) = \frac{Y(\omega)}{N(\omega)} = \frac{1}{1 - H_1(\omega) H_2(\omega)} = \frac{1}{1 - \frac{4}{5+j\omega}} = \frac{5+j\omega}{1+j\omega}.$$

$$S_y(\omega) = S_x(\omega) |G_1(\omega)|^2 + S_N(\omega) |G_2(\omega)|^2.$$

$$S_{xy}(\omega) = S_x(\omega) \overline{G_1(\omega)}.$$

$$H(\omega) = \frac{S_{xy}(\omega)}{S_y(\omega)}.$$