



Boeing's Laser Multiplex System

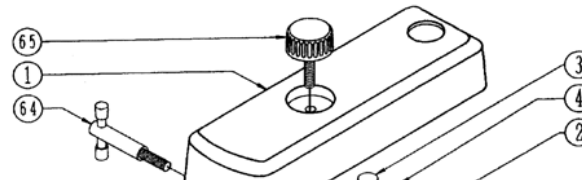
Group 34

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ECE445 Senior Design

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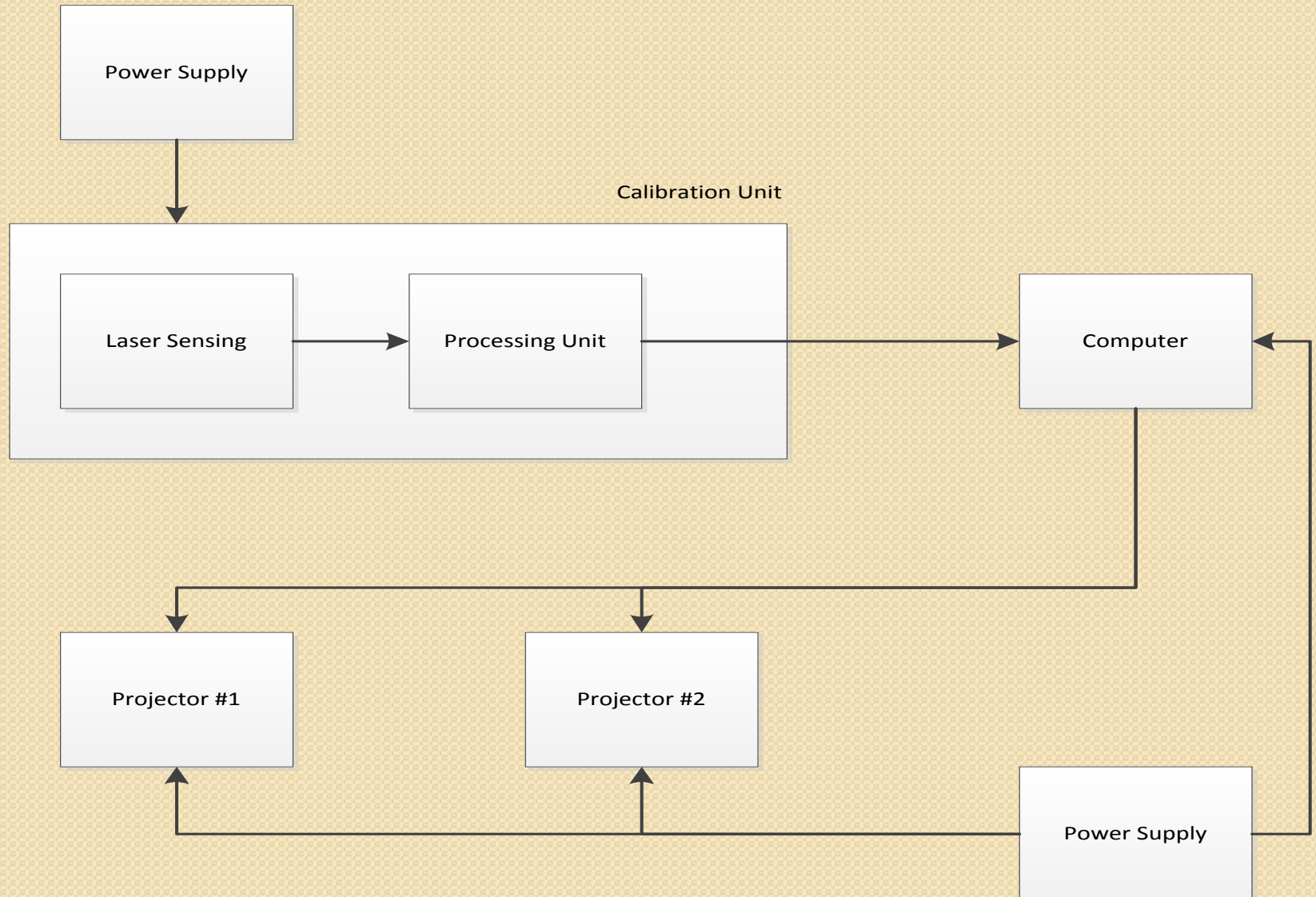
Motivation



Objective

- The system can have both the accuracy of laser projectors and the speed of optical projectors
- A projection system that uses two laser projectors to display animation
- A calibration system to detect correct alignment of the two projectors

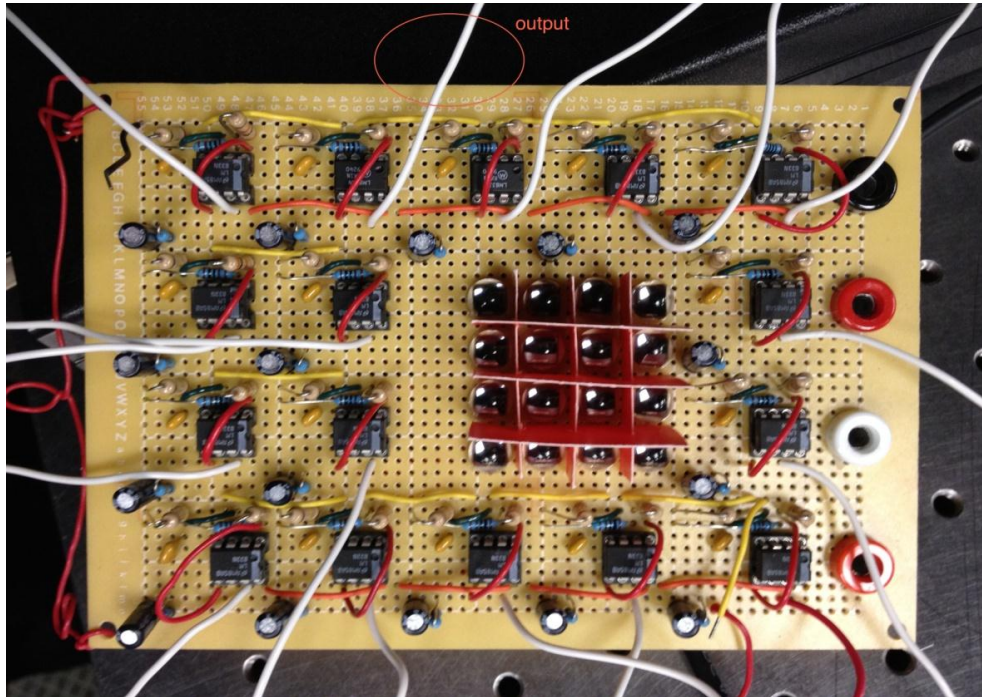
Block Diagram



Calibration Unit

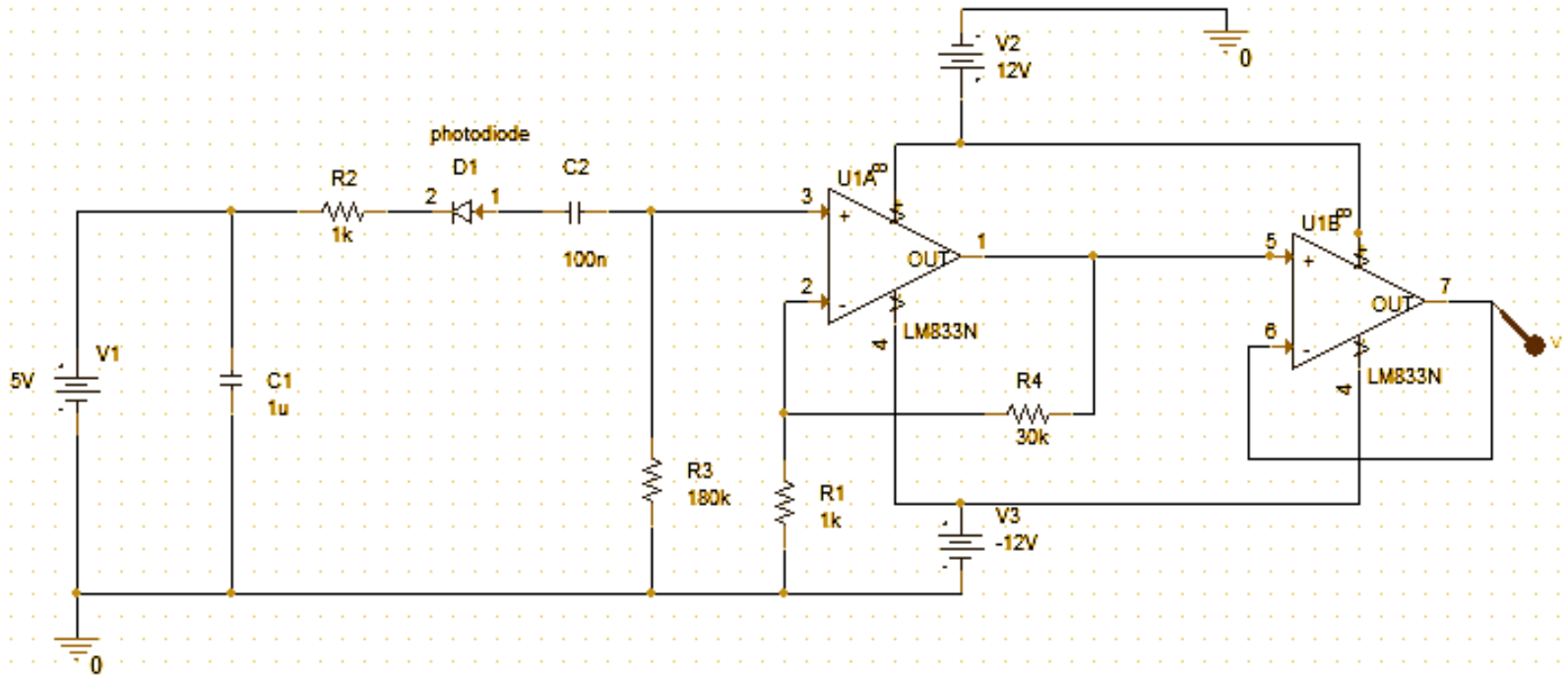
- Test pattern sent to projectors
- Shine laser on sensing circuit
- Signal output to the microcontroller
- Analyzed data to the computer
- Results display on the monitor

Photodiode Sensing Circuit



- 5V, 12V and -12V power in
- Photodiodes produce current
- 16 analog signals send to microcontroller

Photodiode Circuit Schematic

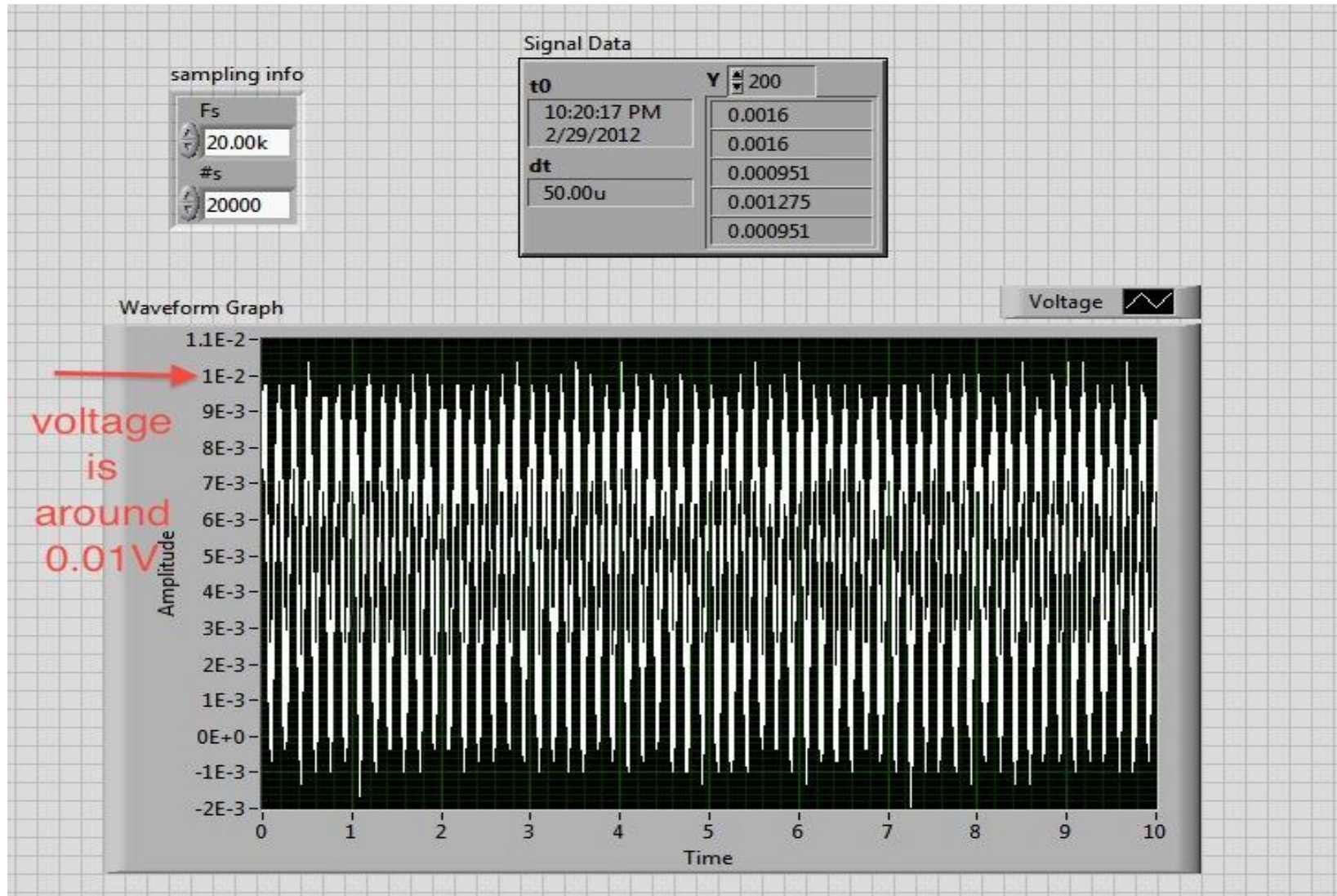


- Decoupling capacitor = 1μF
- 1k resistor protecting photodiode
- Cut-off frequency 8.8 Hz
- Voltage amplifier with DC gain = 30
- Buffer stage

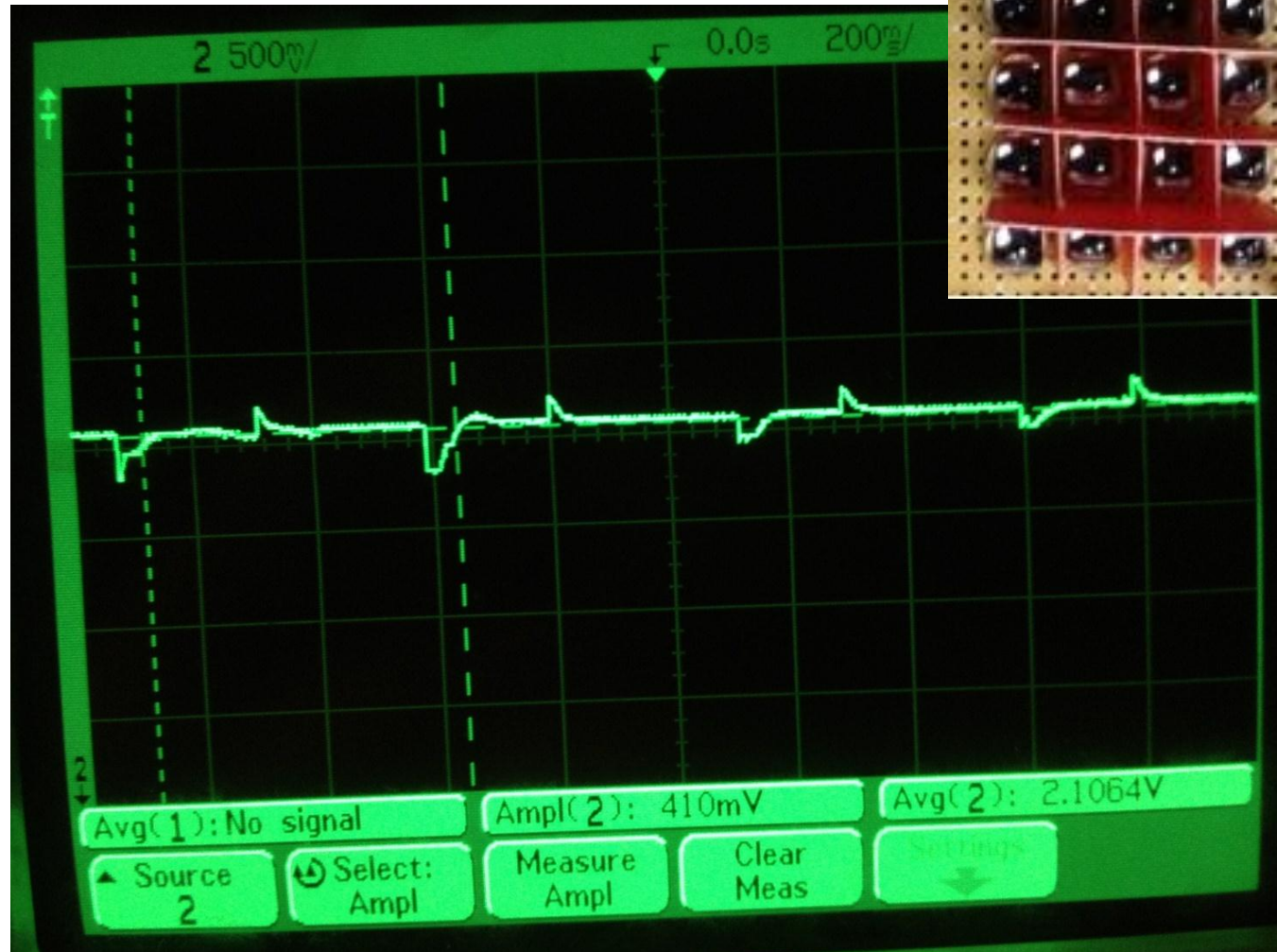
Limitation-Resolution

- Minimum detected length is 0.4 inch
- Maximum detected area is
 $0.4 \text{ inch} \times 0.4 \text{ inch} = 0.16 \text{ inch}^2$

Voltage Output under Natural Light with DC Block



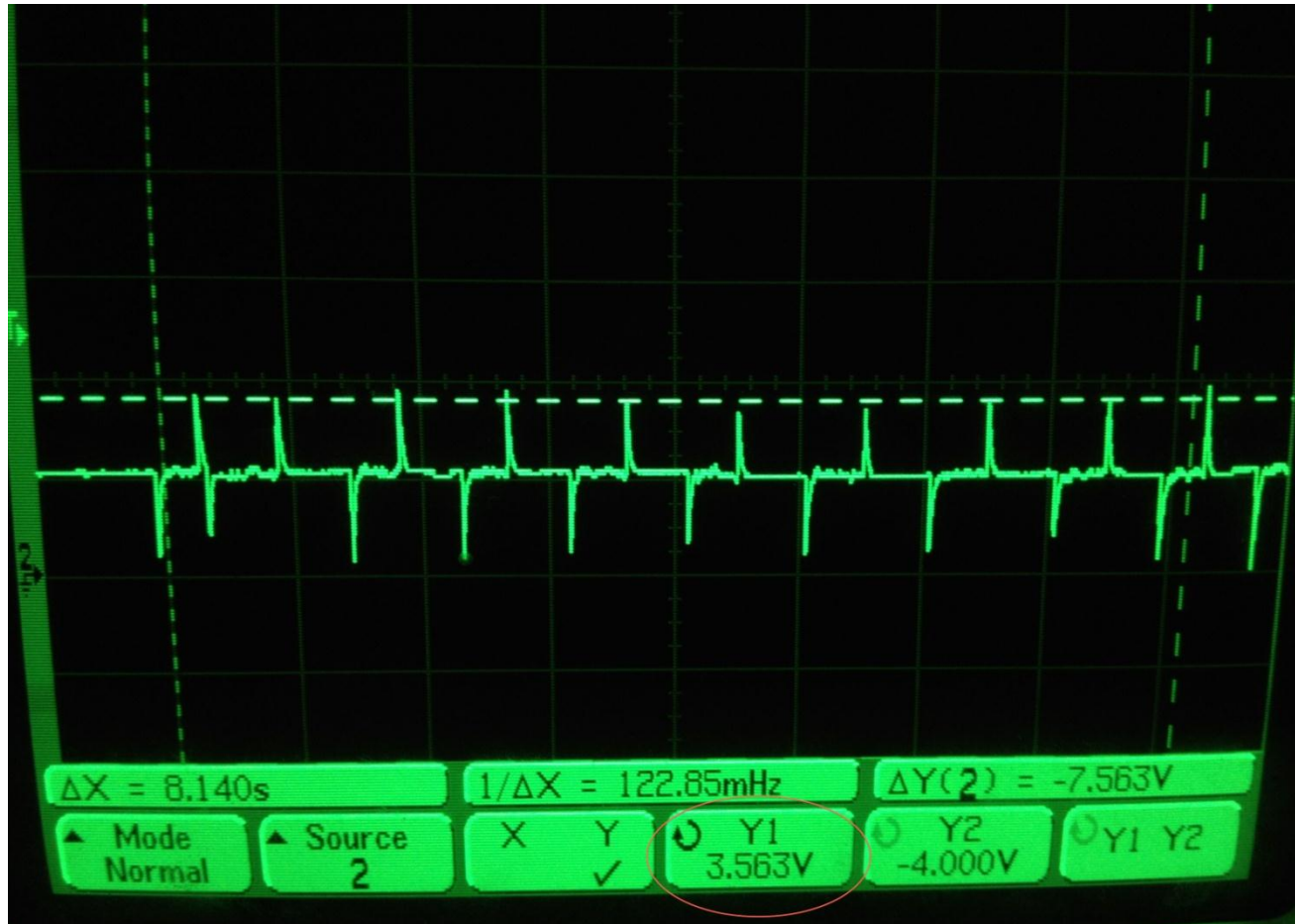
Cross-Section Boards Reduce Laser Effect



$$V_{affect} = 2.5V$$

$$V_{affect-new} = 0.41V$$

Voltage Output When Laser Shining On



$$V_{laser} = 3.563V$$

Processing Unit

- Consists of three PIC18F4550 chips
- The 16 analog outputs are connected to two of the PICs (13 outputs to 1st PIC; 3 outputs to 2nd PIC)
- The 3rd PIC – provides a square wave with a frequency of 0.25Hz (named Clk) to the two PICs

Cont.

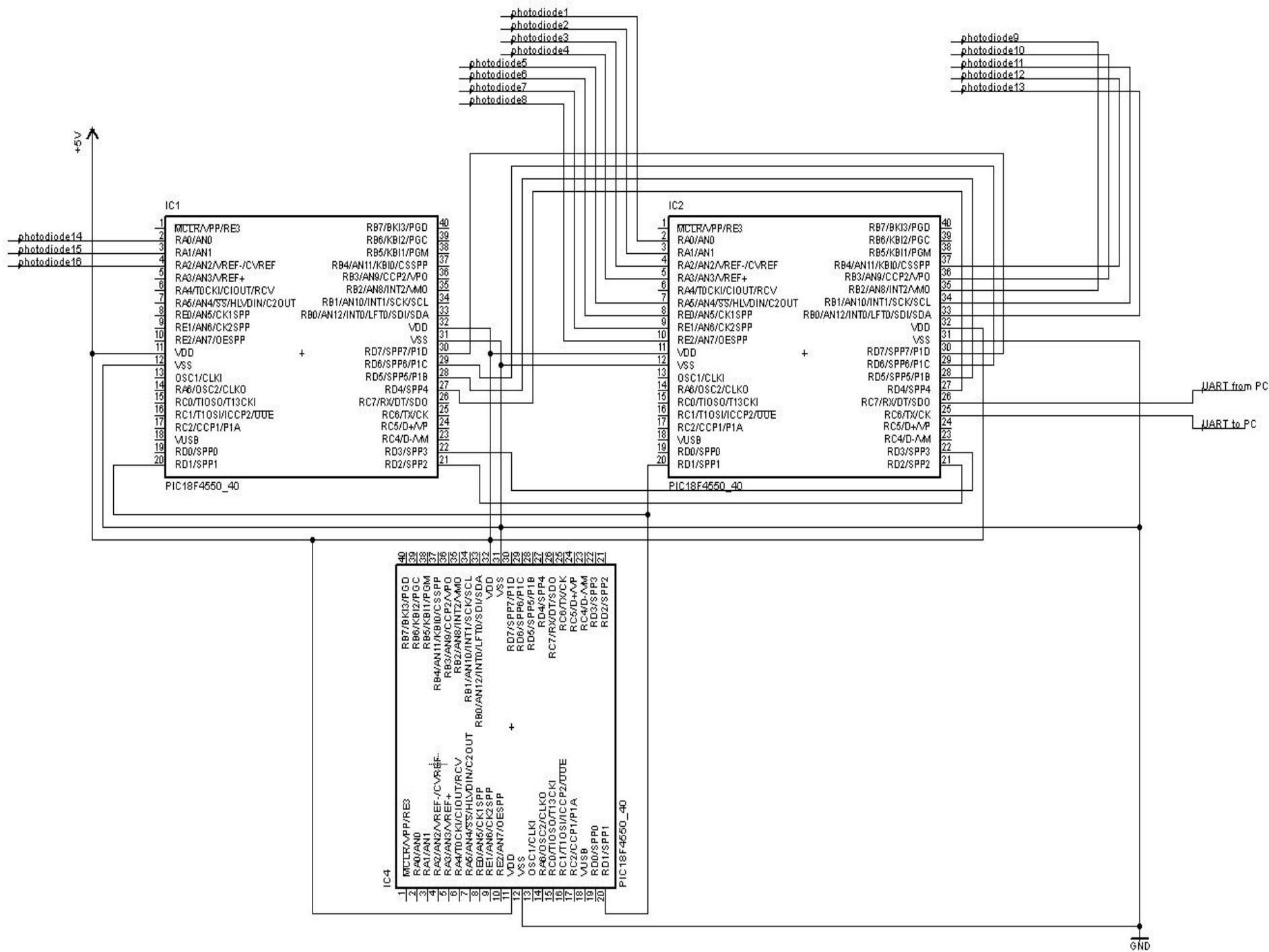
- The PICs count the total number of transitions from logic 0 to logic 1 when Clk is high for each analog input.
- Threshold voltage were all set at 3.4 V
- However, each output from photodiodes has different voltage level (with laser presence or without laser)

Why count transitions?

- Because the lasers will be tracing a pattern at some frequency
- In order for this to work:
 - The two lasers should trace a same pattern
 - One of the lasers should trace at a frequency which is a multiple of the other laser's frequency
 - They should start tracing at different starting coordinates

Cont.

- After number of transitions are known, the corresponding case is determined
 - Case 1: laser 1 traced through
 - Case 2: laser 2 traced through
 - Case 3: both lasers traced through
 - Case 4: no laser traced through
- A variable is used to store the result for each photodiode



Between Processing Unit and PC

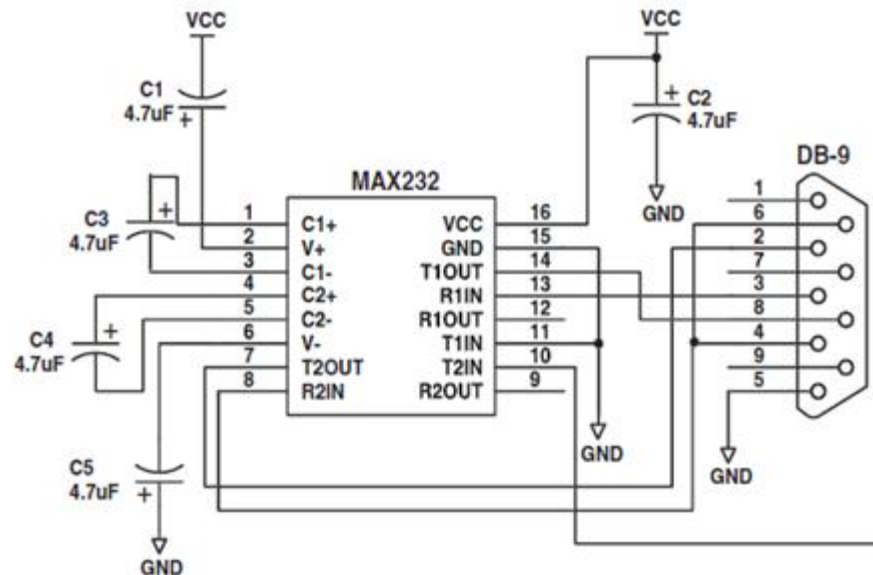
- 8 bit/ asynchronous mode
- 9600 baud rate
- 19 bytes of data
- Start byte: 0xff

Next 16 bytes: 4 bits(coordinates)
4 bits(case result)

18th byte: 0x00 or 0x01 (indicate if aligned)

Last byte: 0xff

- MAX232 is used to convert UART data such that the data can be read by a standard RS232-port



Serial Port Data Convention

Start Byte	Color Byte 1 to 16	Status Byte	Stop Byte
0xff	*See Interpretation *	0x01 or 0x00	0xff

Color Byte Interpretation:

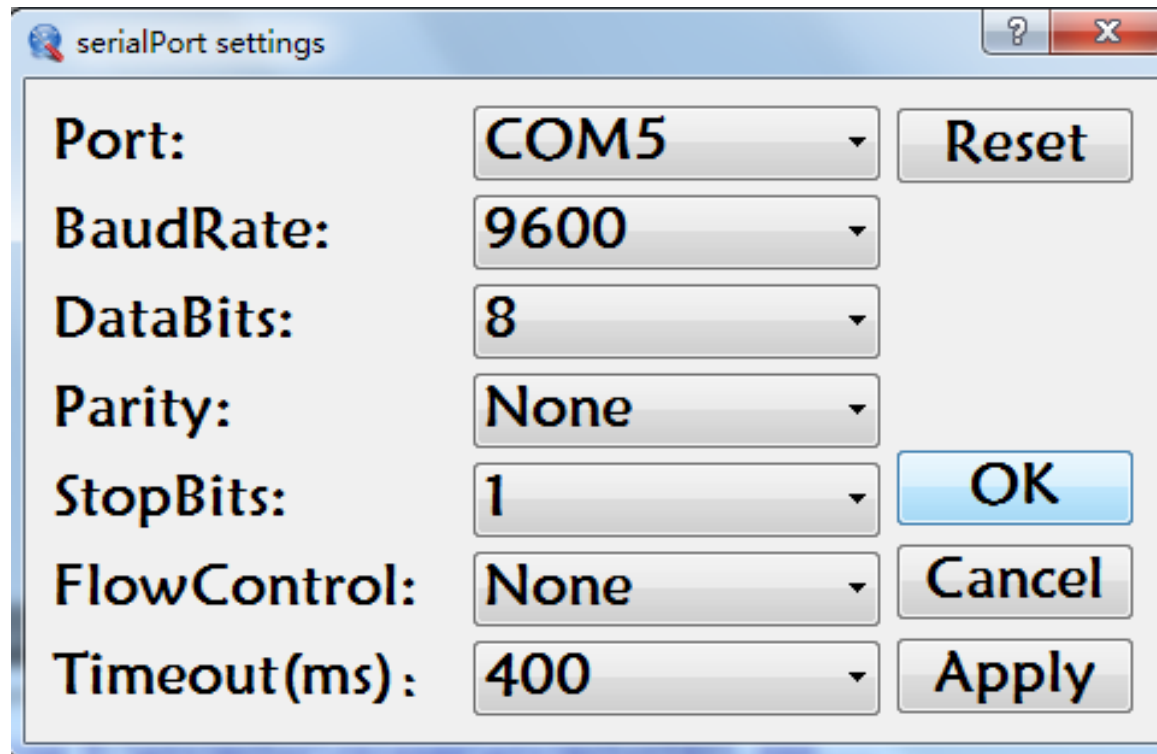
- Higher 4 bits represents the number of photodiode
- Lower 4 bits represents the lighting condition of the current photodiode
 - 0000 = Grey : No laser light is shining on the current photodiode
 - 0010 = Green: Both lasers are projecting on the current photodiode
 - 0100 = Blue: Only laser 2 is projecting on the current photodiode
 - 1000 = Red: Only laser 1 is projecting on the current photodiode

Limitation

- Cannot precisely control the scanning frequency of the Laser projector by software
- Each laser projector does not exhibit identical refresh rate at each time
- One of the newer model have significantly larger refresh rate than the older one

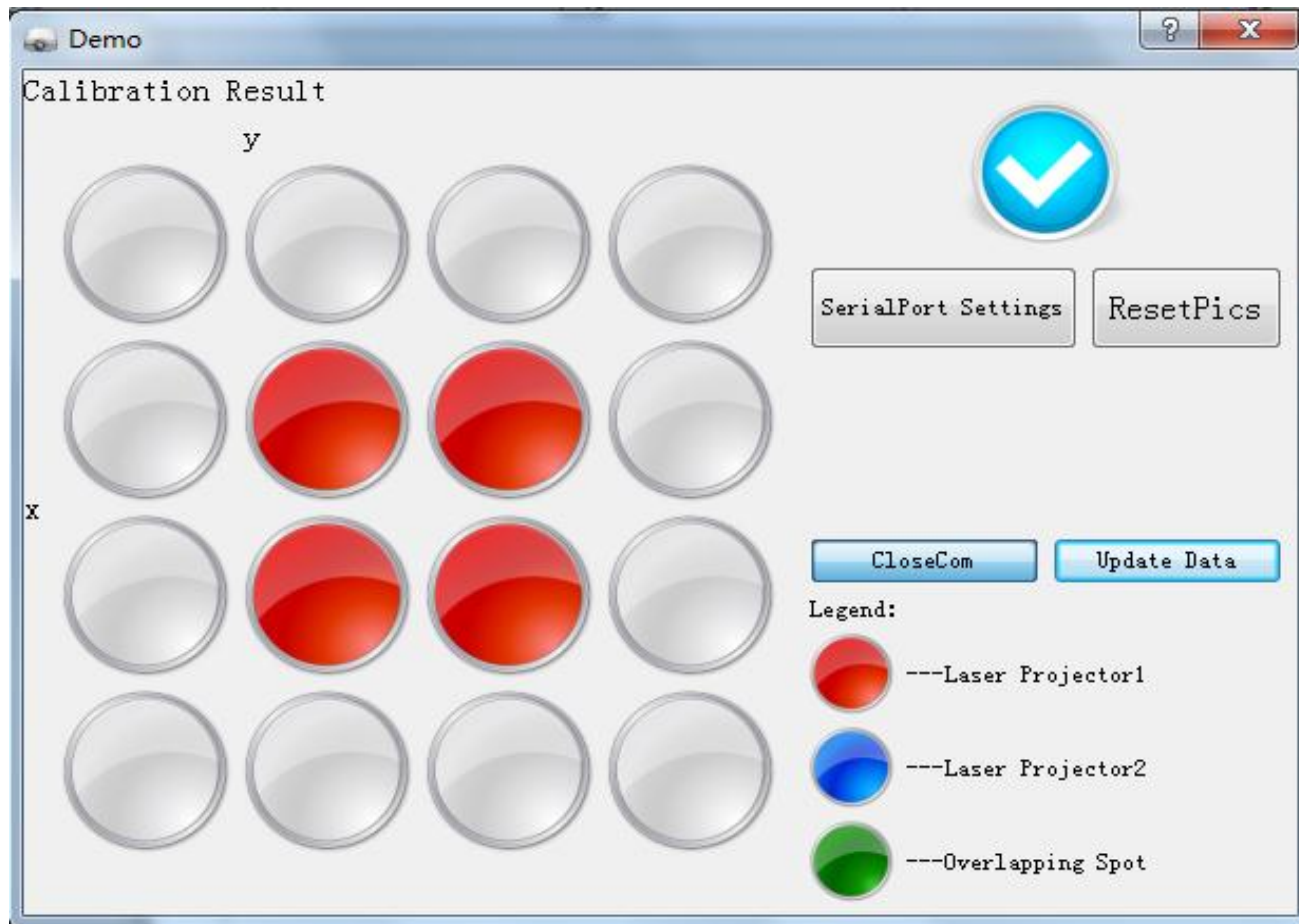
Therefore, two laser projectors have to be calibrated separately.

Graphical User Interface



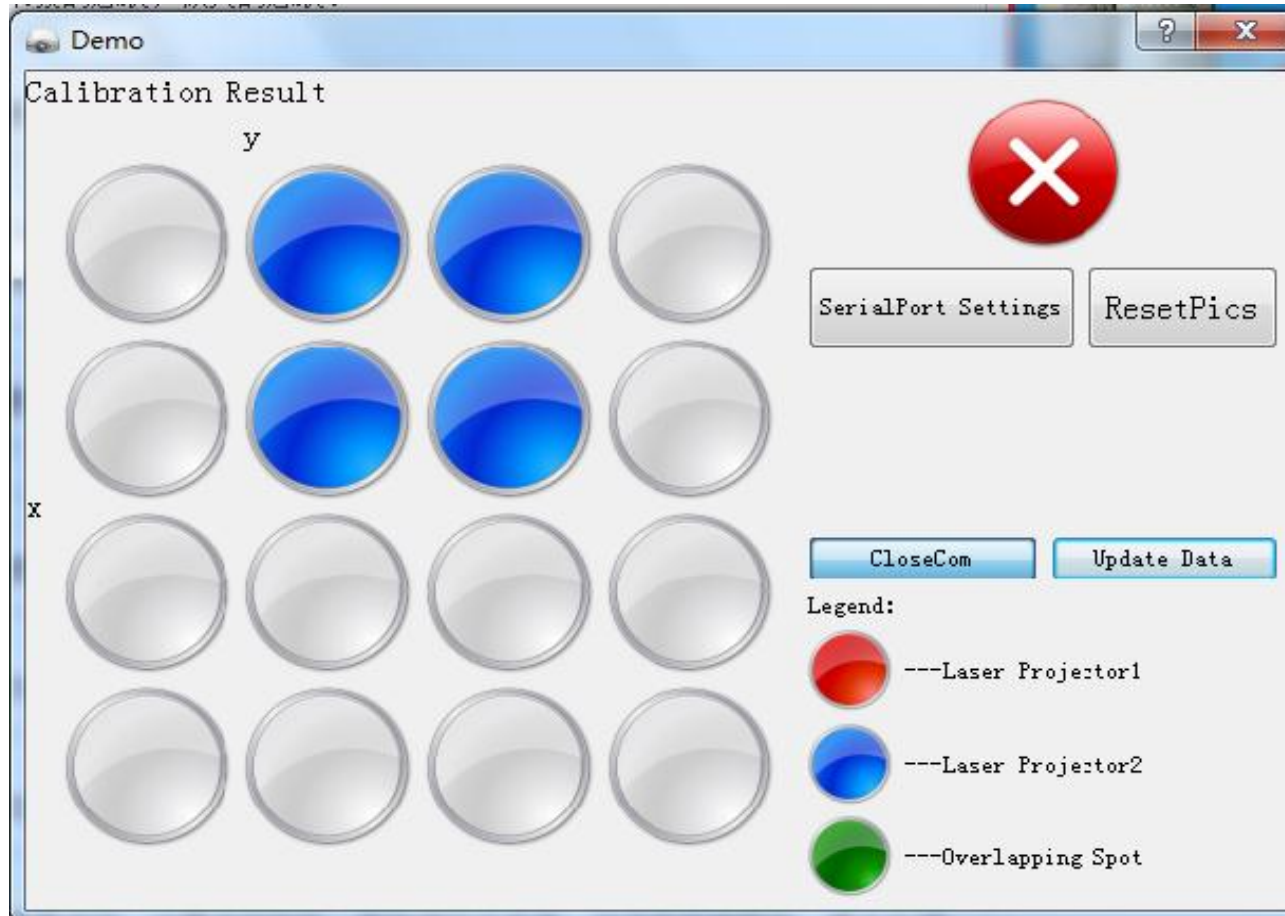
Setting up Serial Port Connection

Graphical User Interface

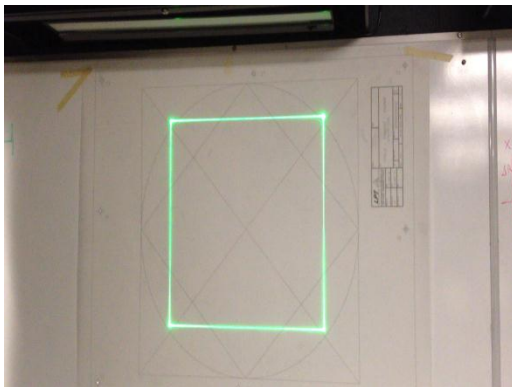
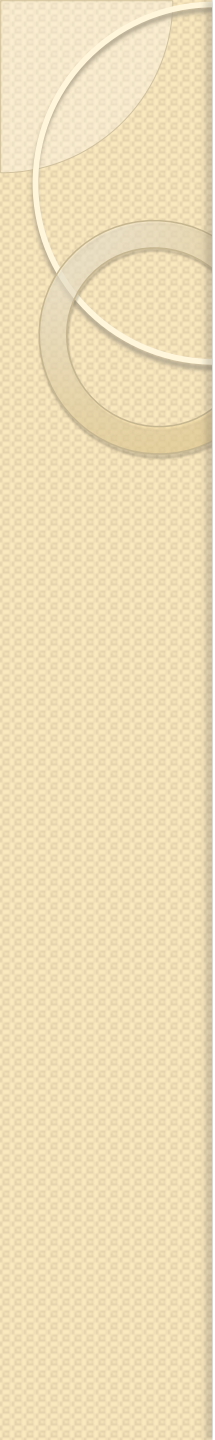


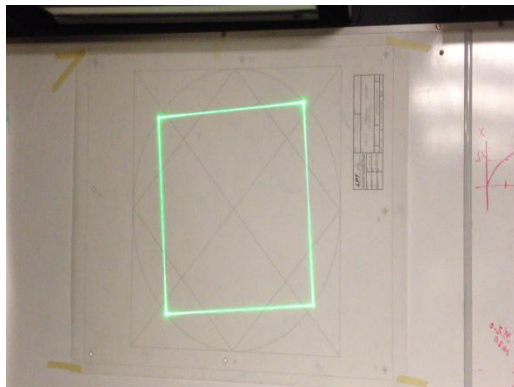
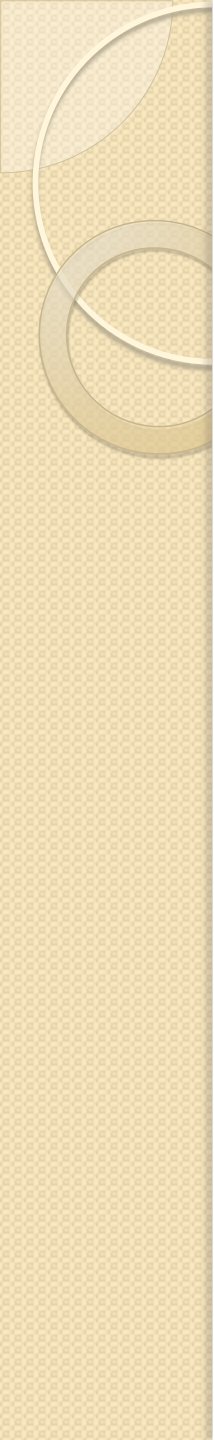
Laser Projector 1 is aligned correctly

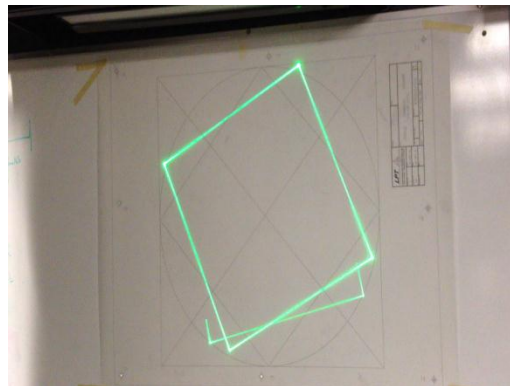
Graphical User Interface



Laser Projector 2 is misaligned



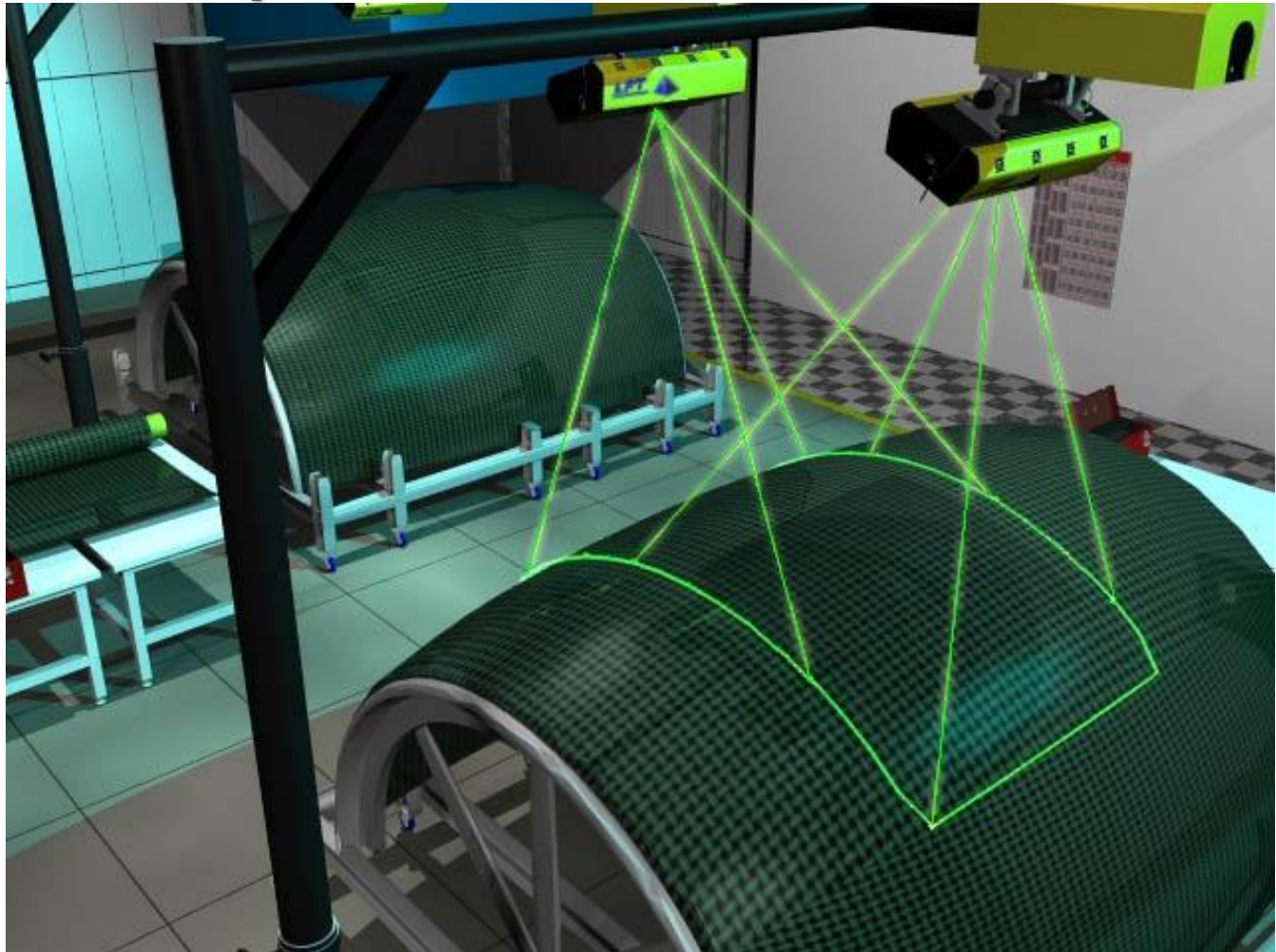




Accomplishments

- A Calibration unit that helps align two laser projectors
- Control the laser projectors through a PC using a JAVA API

Application: Assembly Instruction Animation



Credits

- Professor P. Scott Carney
- Jane Tu
- Parts Shop Personnel
- Alex Suchko
- Philip Freeman, Phillip Tillman & Kenneth Owens from the Boeing Company

