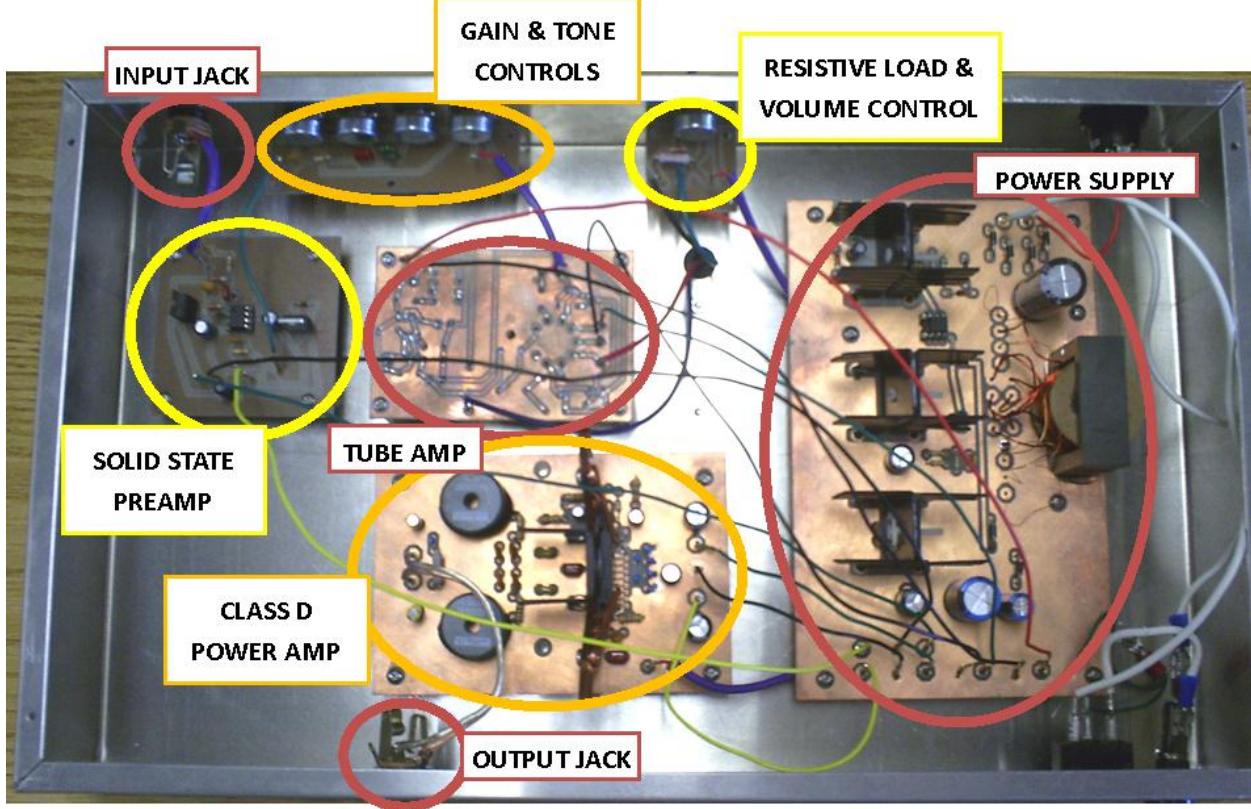


Appendix 2

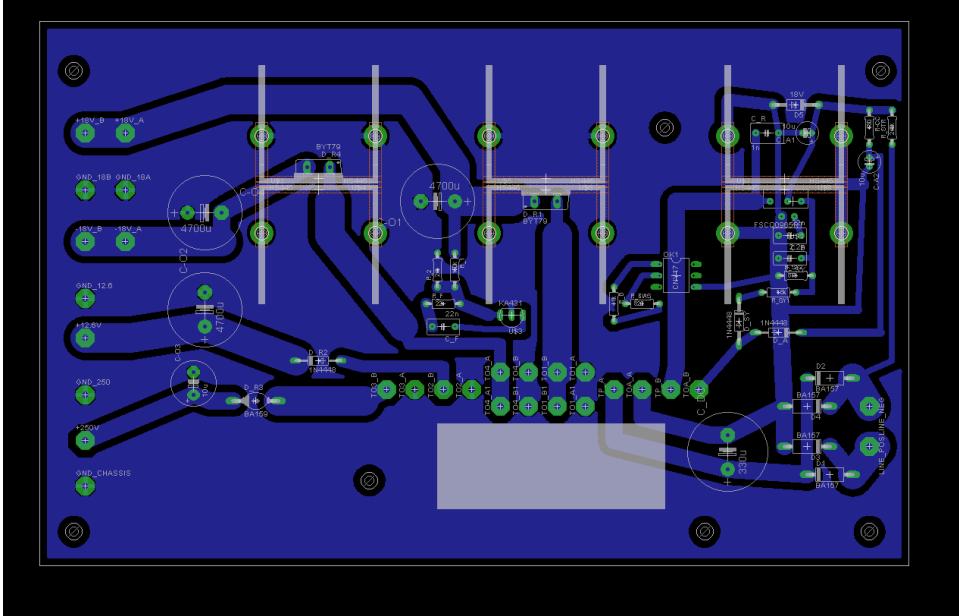
Final Construction of Amplifier Head



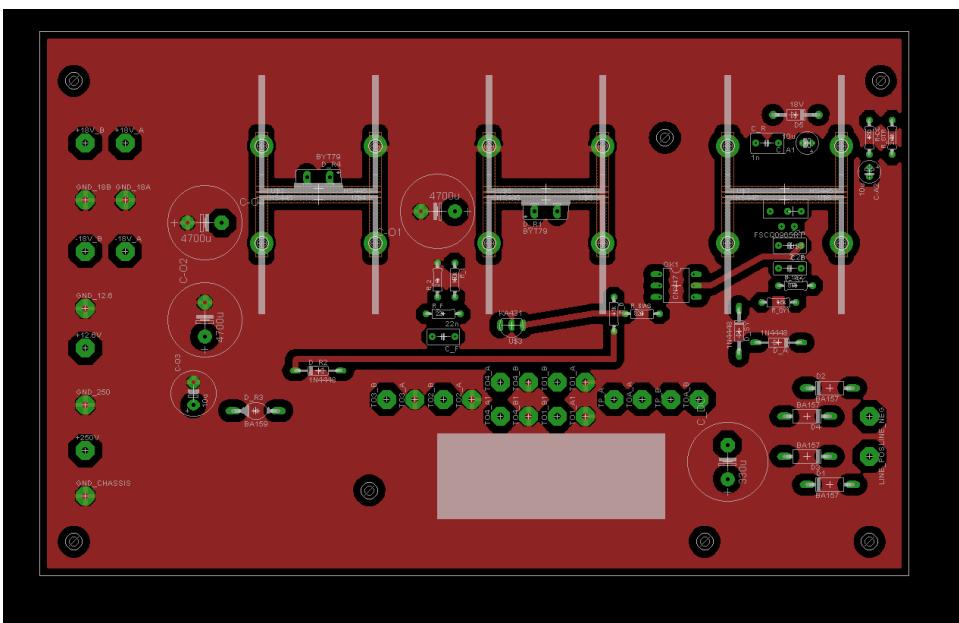
PCB Layouts

Power Supply Board

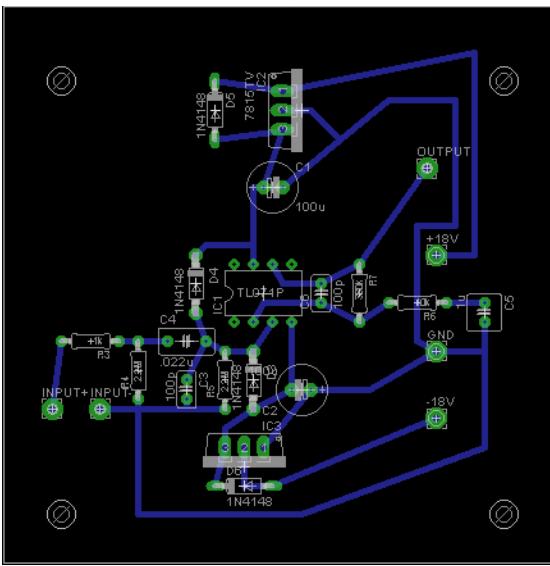
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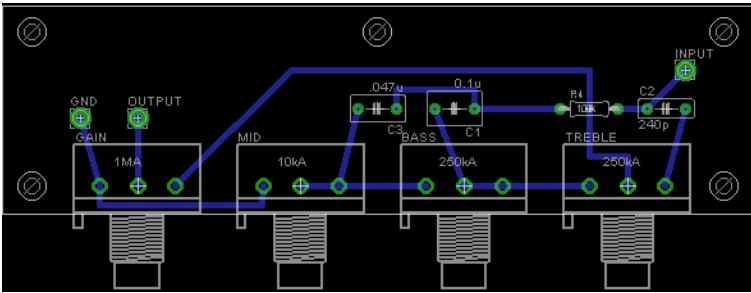
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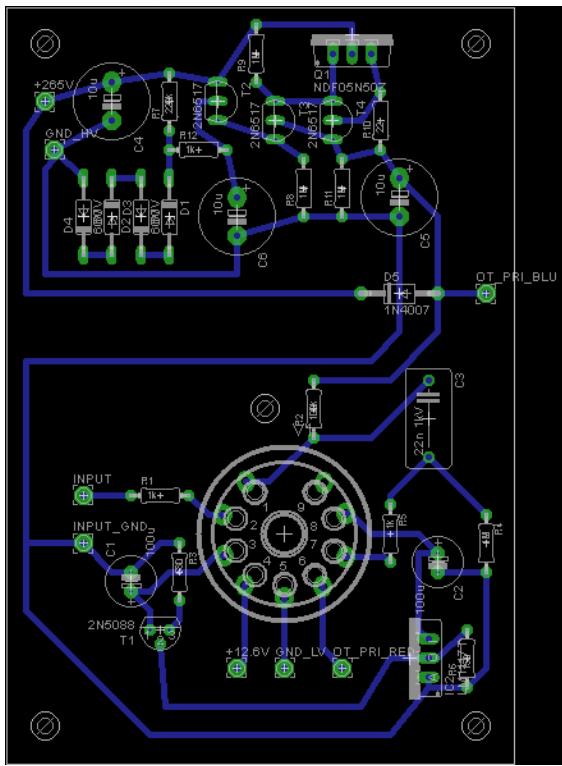
Solid-State Preamplifier



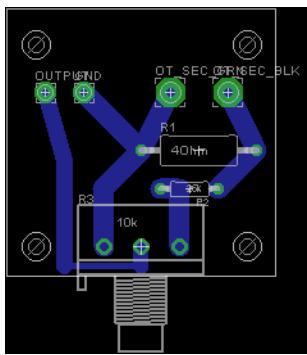
Gain & Tone Controls



Tube Amplifier

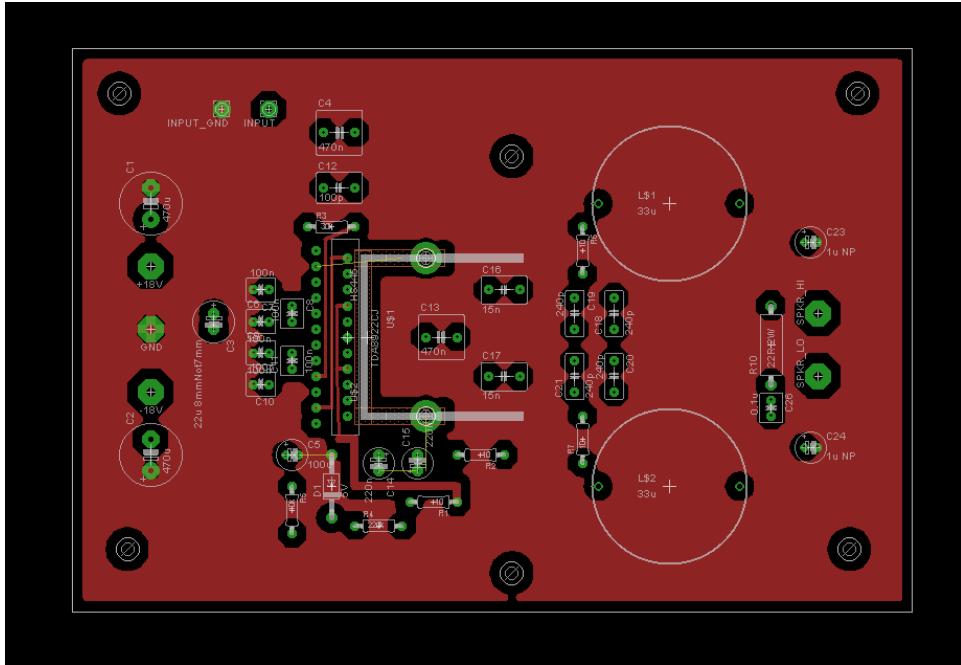


Resistive Load & Volume Control

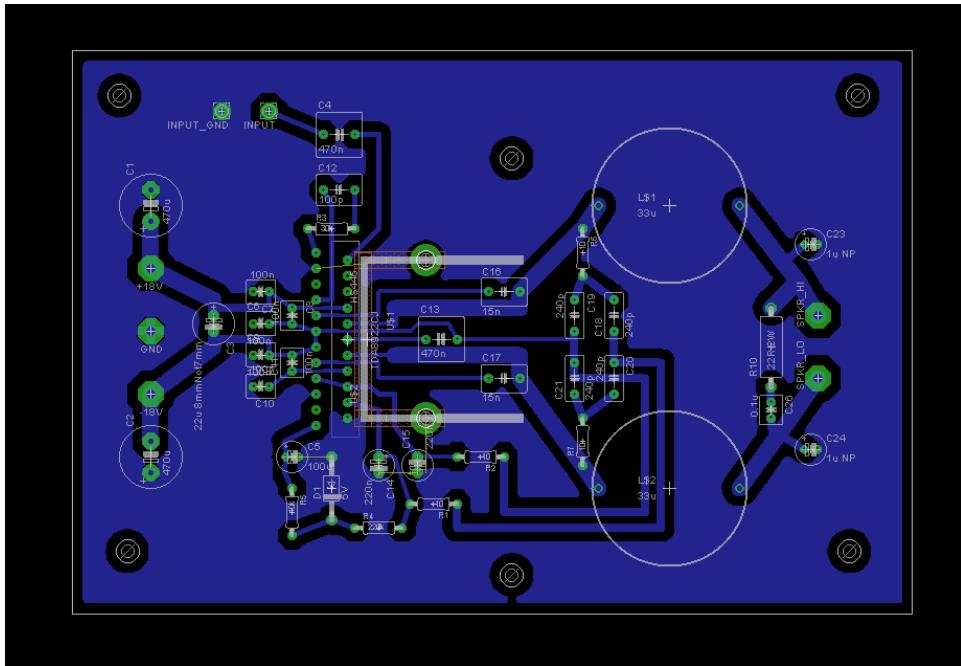


Solid-State Power Amplifier

Top



Bottom



Power Supply Design Sheet



FPS Design Assistant for AN4146
Ver 1.00 by H.S. Choi
Blue cells are the input parameters
Red cells are the output parameters

1. Define the system specifications

Minimum Line voltage (V_{line}^{min})	103.5 V.rms
Maximum Line voltage (V_{line}^{max})	137.5 V.rms
Line frequency (f_L)	60 Hz

	$V_{o(n)}$	$I_{o(n)}$	$P_{o(n)}$	$K_{L(n)}$
1st output (Vo1) ; regulated by feedback	18 V	2.50 A	45 W	46
2nd output (Vo2)	12.6 V	0.15 A	2 W	2
3rd output (Vo3)	260 V	0.03 A	2 W	2
4th output (Vo4)	18 V	2.50 A	45 W	46
5th output (Vo5)	V	A	W	Ω

Maximum output power (P_o) =	98.4 W
Estimated efficiency (E_{eff})	70 %
Maximum input power (P_{in}) =	140.6 W

2. Determine DC link capacitor and DC link voltage range

DC link capacitor (C_{DC})	330 uF
Minimum DC link voltage (V_{DC}^{min}) =	125 V
Maximum DC link voltage (V_{DC}^{max}) =	194 V

3. Determine the reflected output (V_{RO})

Output voltage reflected to primary (V_{RO})	126 V
Maximum nominal Drain voltage (V_{ds}^{nom}) =	320 V

4. Determine transformer primary side inductance (L_m)

Drain voltage falling time (T_F)	2.3 us
Minimum Switching frequency of FPS ($f_{s,min}$)	25 kHz
Maximum duty cycle (D_{max}) =	0.47
Primary side inductance (L_m) =	500 uH
Maximum peak drain current (I_{ds}^{peak}) =	4.74 A
RMS drain current (I_{ds}^{rms}) =	1.88 A

5. Choose the proper FPS considering the input power and current limit

Typical current limit of FPS (I_{LM})	6.00 A
Minimum I_{LM} considering tolerance	5.28 A
	> 4.74 A
	->O.K.

6. Determine the proper core and the minimum primary turns

Maximum flux density swing in normal mode (ΔB_{max})	0.30 T	$\rightarrow N_p > 42.25 T$
Maximum flux density in transient (B_{sat})	0.38 T	$\rightarrow N_p > 42.18 T$
Cross sectional area of core (A_c)	187 mm ²	

Minimum primary turns (N_p^{\min}) =

42.2 T

7. Determine the number of turns for each output and Vcc drop circuit

V_{o2} in standby mode (V_{o2}^{standby}) =

6.3 V

V_{o2} = 13 V in normal mode

V_{cc} auxiliary voltage drop ratio (K_{drop}) =

0.54

Minimum V_a in standby mode (V_a^{standby}) =

13.0 V

V_a in normal mode (V_a^{normal}) =

24.9 V

	$V_{F(n)}$	# of turns
Winding for V_a (24.9V)	1.2 V	9.5 \Rightarrow 10 T
Winding for V_{o1} (18V)	1.2 V	7 \Rightarrow 7 T
Winding for V_{o2} (12.6V)	1.2 V	5.0 \Rightarrow 5 T
Winding for V_{o3} (260V)	1.2 V	95.2 \Rightarrow 95 T
Winding for V_{o4} (18V)	1.2 V	7.0 \Rightarrow 7 T
Winding for V_{o5} (V)	1.2 V	0.0 \Rightarrow 0 T
<u>Number of turns for primary winding (N_p) =</u>	46 T	> 42.2 T

---> enough turns

Ungapped AL value (AL) =

4680 nH/T²

Gap length (G) ; center pole gap =

0.94199 mm

Maximum operating current of FPS (I_{op}) =

8 mA

MOSFET input capacitance (C_{iss}) =

1750 pF

Breakdown voltage of V_{cc} zener diode =

18 V

Current consumed by FPS (I_{cc}) =

10.8 mA

at 90 kHz

V_{cc} drop resistor (R_{cc}) =

0.7 k Ω

< 1 k Ω

Power dissipation of R_{cc} =

0.1 W

8. Determine the startup resistor

Maximum Startup current of FPS (I_{start}) =

50 uA

Startup resistor =

240 k Ω

< 782 k Ω

Effective V_{cc} capacitor (C_e) =

20 uF

Maximum dissipation in startup resistor =

0.03 W

at 137.5 Vac

Maximum startup time (T_{str}^{\max}) =

2.66 s

at 103.5 Vac

9. Determine the wire diameter for each winding

	Diameter	Parallel	$I_{D(n)}^{\text{rms}}$	(A/mm)
Primary winding	0.7 mm	X	1	1.9 A
Winding for V_{cc} (24.9V)	0.3 mm	X	1	0.1 A
Winding for V_{o1} (18V / 2.5A)	0.8 mm	X	2	6.0 A
Winding for V_{o2} (12.6V / 0.15A)	0.4 mm	X	1	0.3 A
Winding for V_{o3} (260V / 0.025A)	0.2 mm	X	1	0.1 A
Winding for V_{o4} (18V / 2.5A)	0.8 mm	X	2	6.0 A
Winding for V_{o5} (V / A)	mm	X	#### A	####

Copper area (A_c) =

36.05 mm²

Fill factor (K_F) =

0.2

Required window area (A_{wp})180.27 mm²**10. Choose the rectifier diode in the secondary side**

	$V_{D(n)}$	$I_{D(n)}^{rms}$
Rectifier diode for Vcc	65 V	0.10 A
Rectifier diode for Vo1 (18V / 2.5A)	48 V	5.97 A
Rectifier diode for Vo2 (12.6V / 0.15A)	34 V	0.35 A
Rectifier diode for Vo3 (260V / 0.025A)	663 V	0.06 A
Rectifier diode for Vo1 (18V / 2.5A)	48 V	5.97 A
Rectifier diode for Vo5 (V / A)	Ω V	##### A

11. Determine the output capacitor

	$C_{o(n)}$	$R_{o(n)}$	$I_{cap(o(n))}$	$\Delta V_{o(n)}$
Output capacitor for Vo1 (18V / 2.5A)	470 uF	110 mΩ	5.4 A	1.7
Output capacitor for Vo2 (12.6V / 0.15A)	4700 uF	100 mΩ	0.3 A	0.1
Output capacitor for Vo3 (260V / 0.025A)	10 uF	100 mΩ	0.1 A	0.1
Output capacitor for Vo4 (18V / 2.5A)	470 uF	110 mΩ	5.4 A	1.7
Output capacitor for Vo5 (V / A)	uF	mΩ	##### A	#####

12. Design the synchronization network

Peak value of Sync voltage (V_{sync}^{pk})	9.0 V	$4.6 < V_{sync}^{pk} < 12V$ (V_{ovp})
Sync voltage divider resistor (R_{sy1})	1500 Ω	
Sync voltage divider resistor (R_{sy2})	848 Ω	
Effective output capacitance of MOSFET	1.1 nF	($C_{oss} + C_r$)
Sync capacitor (C_{sy})	2.2 nF	

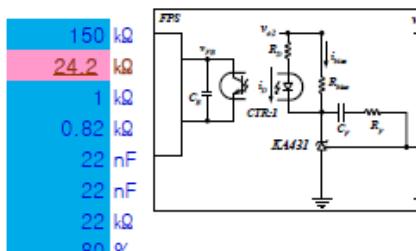
13. Design voltage drop circuit for the burst operation

Vo2 in standby mode (V_{o2}^{stdby})	6.3 V
Breakdown voltage of zener diode, Dz	3.3 V

14. Design the feedback control circuit

Control-to-output DC gain =	9
Control-to-output zero (w_z) =	19.3 krad/s => $f_z = 3.080$ Hz
Control-to-output RHP zero (w_{rz}) =	167.4 krad/s => $f_{rz} = 26.663$ Hz
Control-to-output pole (w_p) =	951 rad/s => $f_p = 151$ Hz

Voltage divider resistor (R_1)	150 kΩ
Voltage divider resistor (R_2)	24.2 kΩ
Opto coupler diode resistor (R_D)	1 kΩ
KA431 Bias resistor (R_{bias})	0.82 kΩ
Feedback pin capacitor (C_B) =	22 nF
Feedback Capacitor (C_F) =	22 nF
Feedback resistor (R_F) =	22 kΩ
Current transfer ratio of opto coupler (CTR)	80 %



$$\text{Feedback integrator gain } (w_i) = \frac{R_F}{R_1} = \frac{22}{150} = 0.147 \text{ rad/s} \Rightarrow f_i = \frac{0.147}{2\pi} = 23 \text{ Hz}$$

Compensator zero (w_{zc}) = 2066 rad/s => $f_{zc} = \frac{329}{\pi}$ Hz
 Compensator pole (w_{pc}) = 16234 rad/s => $f_{pc} = \frac{2.585}{\pi}$ Hz

