



UNIVERSITY OF
ILLINOIS
URBANA-CHAMPAIGN

Electronic Page Turner

ECE 445 Presentation

Team 7

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Problem

- Reading and multitasking can be difficult
 - Cooking using a cookbook
 - Playing an instrument

Problems of Existing Solutions

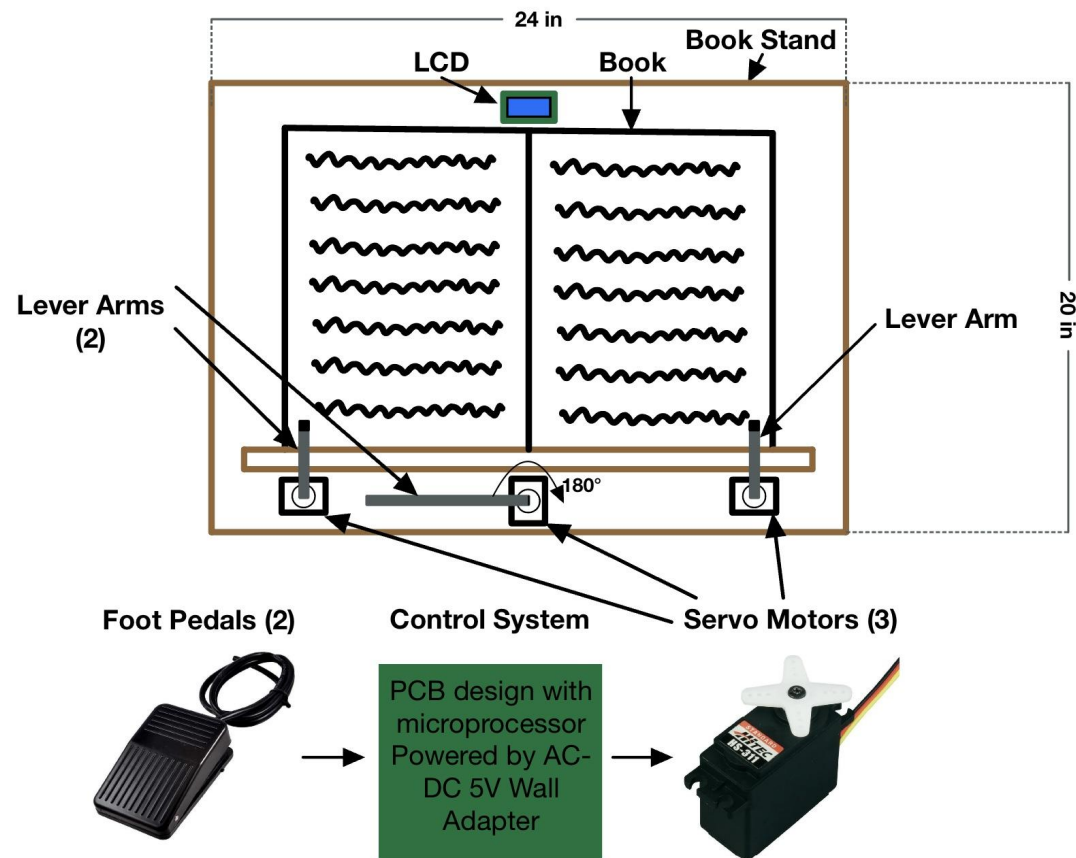
- Limited pages
 - Only turns 10 pages in one direction
- Extensive setup
 - Must attach individual pages to the device
- Expensive
 - Can exceed over \$500



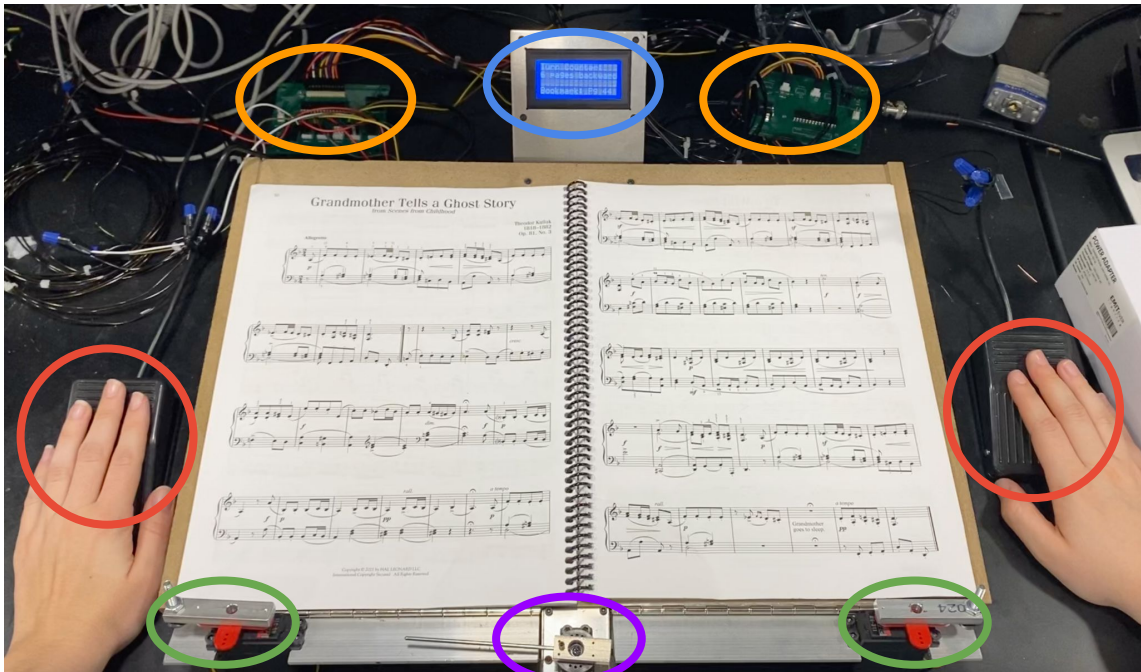
High Level Requirements

- The device must be able to turn one page within 5 seconds \pm 2 seconds. This motion should be repeatable for turning a page backward.
- The device must be able to turn at least ten consecutive pages, with 95% \pm 5% accuracy, and take at most 1 minute \pm 10 seconds when the foot pedal is pressed consecutively.
- The device must be able to store the total number of pages turned in a single sitting, with 95% \pm 5% accuracy, and display this information to the reader.

Design Sketch



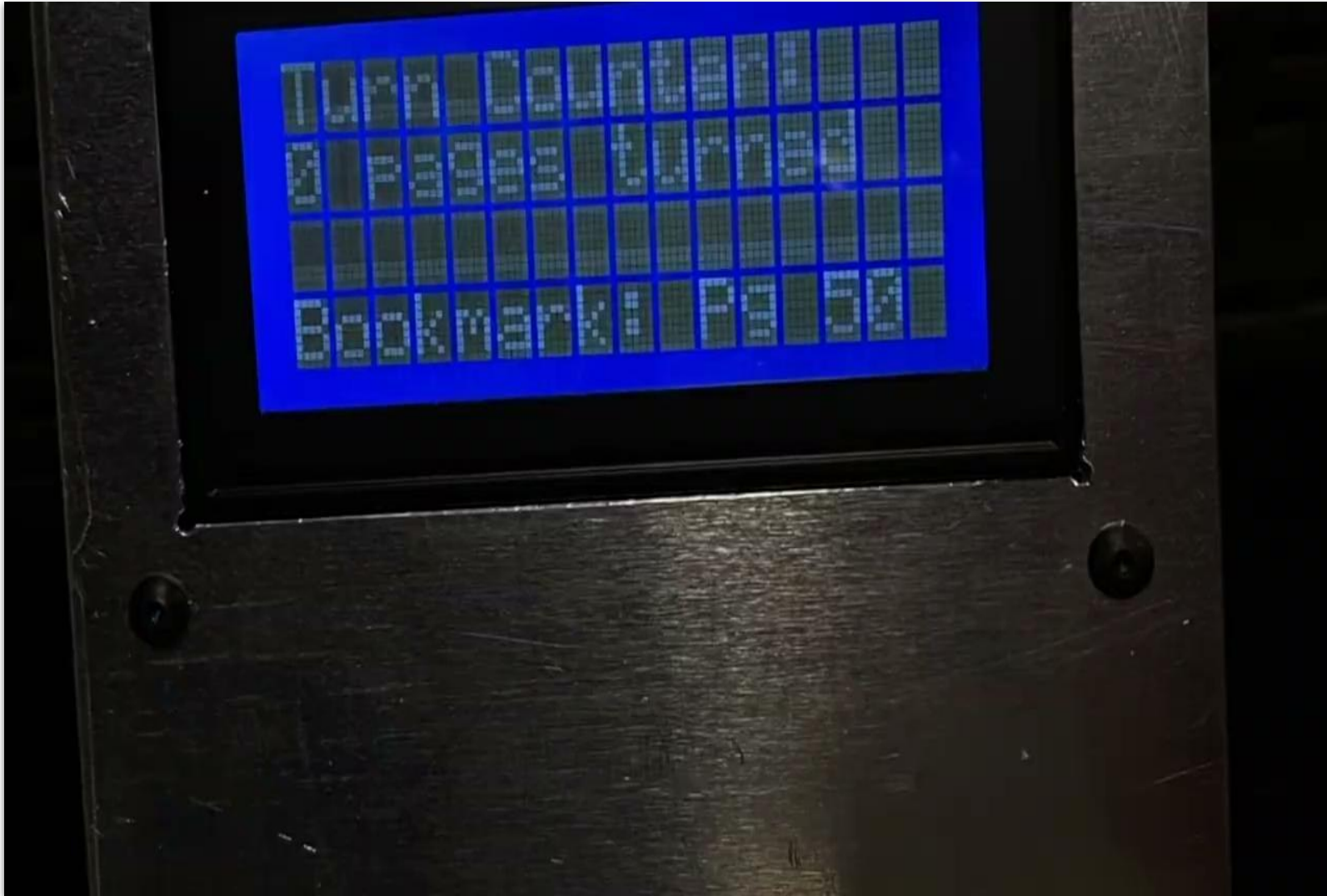
Physical Device



Foot Pedals User Interface PCB'S Lifting Motors Turning Motor



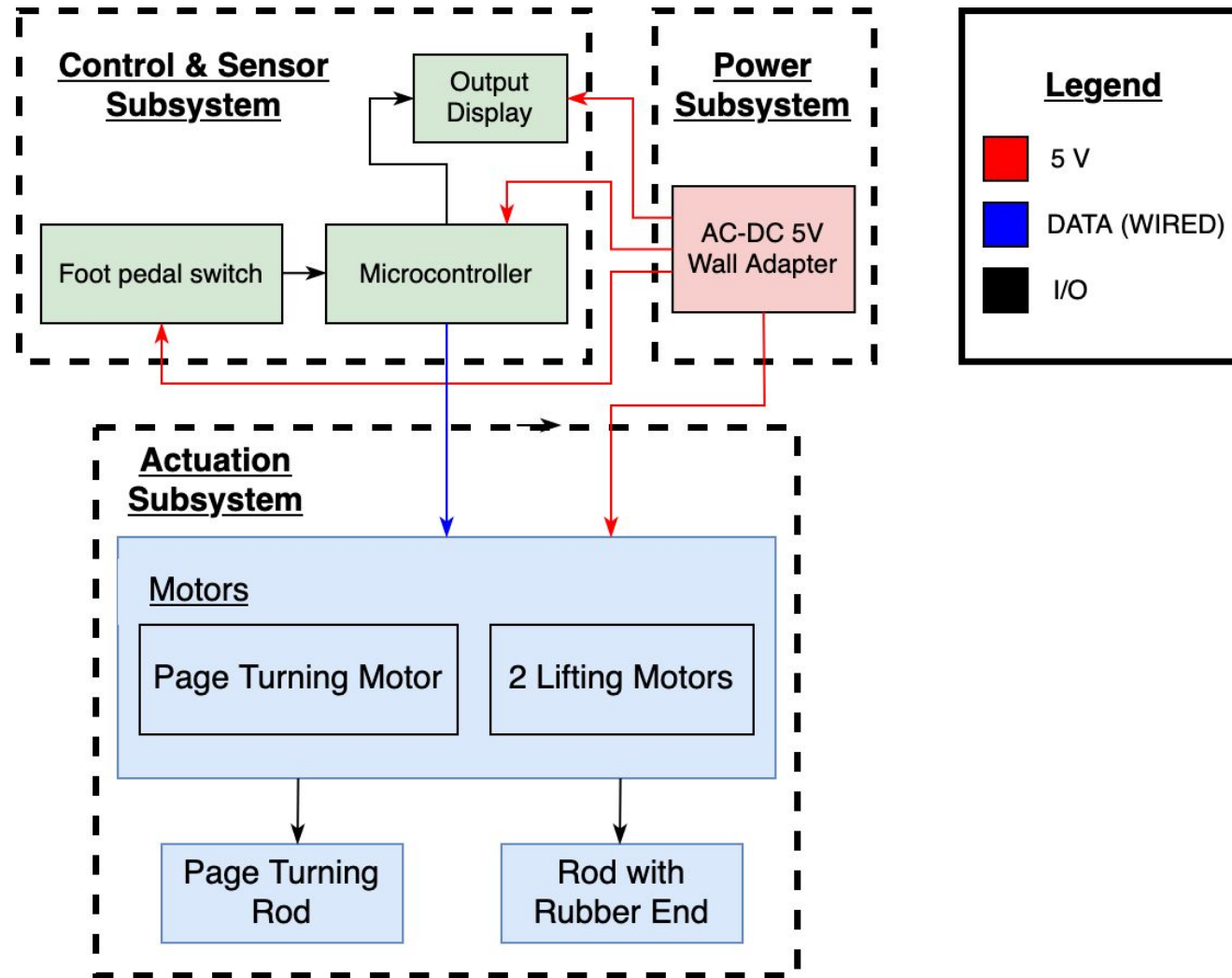
One Page Forward and One Page Backward



LCD Output



10 Consecutive Pages in 1 Minute



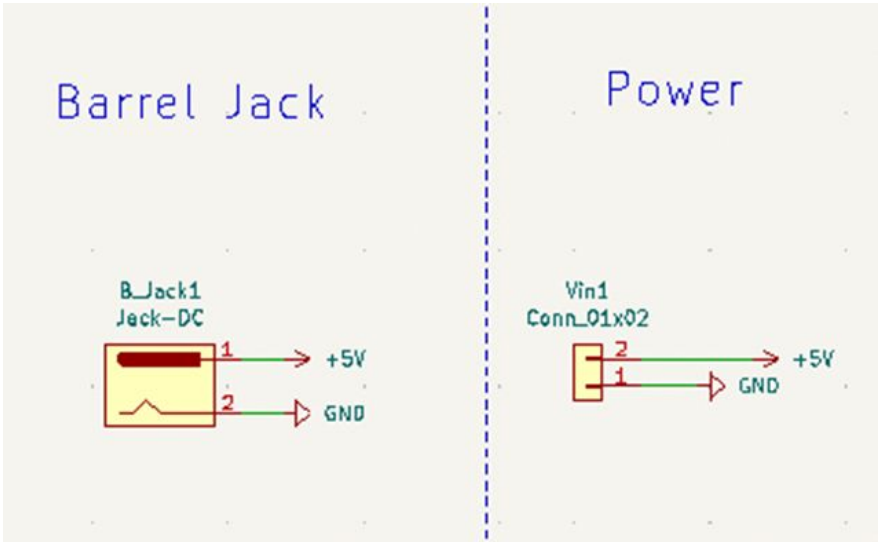
Three Subsystems: Power, Actuation, and Control & Sensors



Power Subsystem

Adia Radecka

Power Subsystem



Requirements	Verification
<ul style="list-style-type: none">● Must have a 5V wall adapter that plugs into a wall outlet.● All components on the PCB must be supplied with $5\text{ V} \pm 5\%$, when the device is idle and active.	<ul style="list-style-type: none">● Use a multimeter to check that the wall adapter barrel jack is supplying $5\text{ V} \pm 5\%$.● Measure the voltage across each component using an oscilloscope. Repeat this process when a foot pedal is pressed.

5V AC-DC Wall Adapter

- Supplied $5V \pm 5\%$ DC to all components

Component	Mean Idle Voltage (V)	Mean Active Voltage (V)
Power Adapter	5.215	5.185
Left Motor	5.215	5.175
Center Motor	5.140	5.120
Right Motor	5.130	5.130
Microcontroller	5.200	5.150
Left Foot Pedal	5.200	5.170
Right Foot Pedal	5.145	5.135
Liquid Crystal Display (LCD)	5.200	5.140

Oscilloscope Testing Data



Challenges

9V Li-ion Batteries

- Batteries have internal resistance
- Active motors drain more current
- Causes the actual voltage supplied to drop

Buck Converter (DC-DC converter)

- Originally using a 12V wall adapter
 - Foot pedals needed 12V
 - Motors needed 6V
 - Microcontroller needed 3.3V

Solution

- 5V wall adapter and chose components that operate at 5V





Actuation Subsystem

Alyssa Bradshaw

HiTEC HS-311 Servo Motors (3)

Operating Voltage Range	4.8 - 6.0 V
Range of Motion	0-180°



Lifting Motor(2)

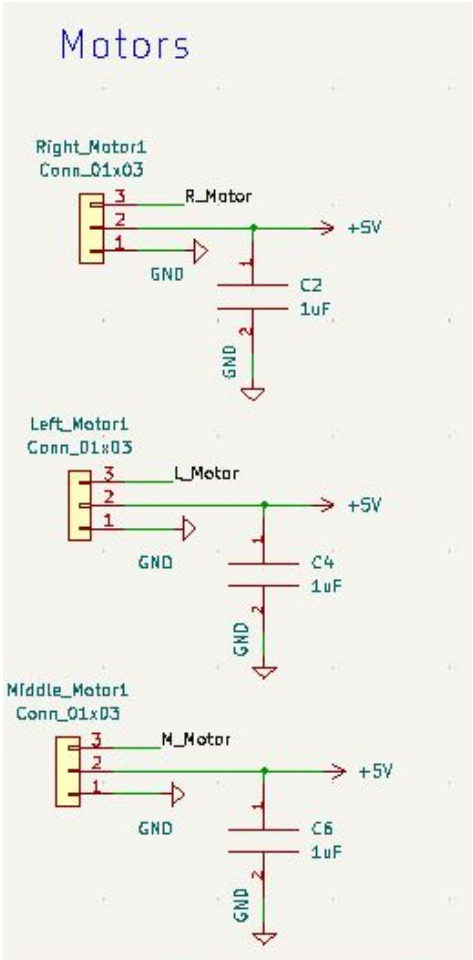


Sweeping Motor



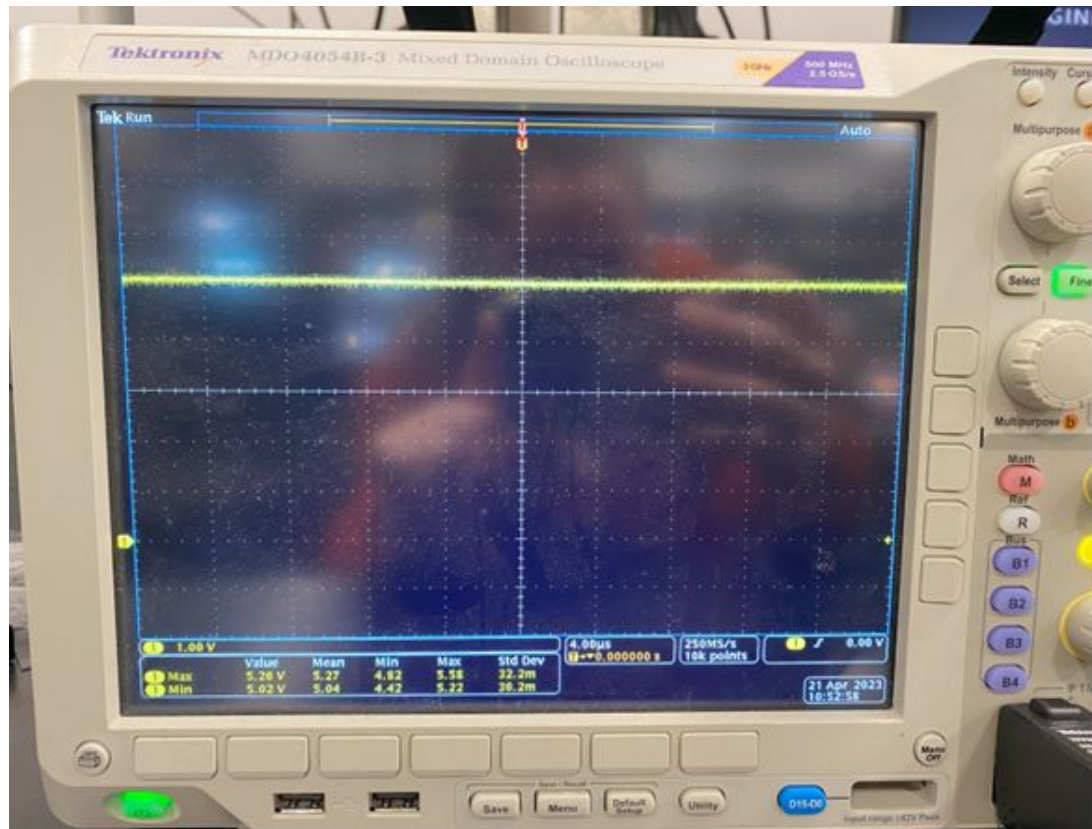
Actuation Subsystem

Requirement	Verification
<ul style="list-style-type: none">• The servo motors must create negligible backwards EMF.• The motors should cause minimal to no damage or tearing to the pages in the book.	<ul style="list-style-type: none">• Use an oscilloscope to plot the voltage of a motor when idle and when active. If the voltage spike is less than $1V \pm 0.5V$, we can consider the backwards EMF from the motor to be negligible.• Run 10 test trials to find the best angle and speed for each motor.

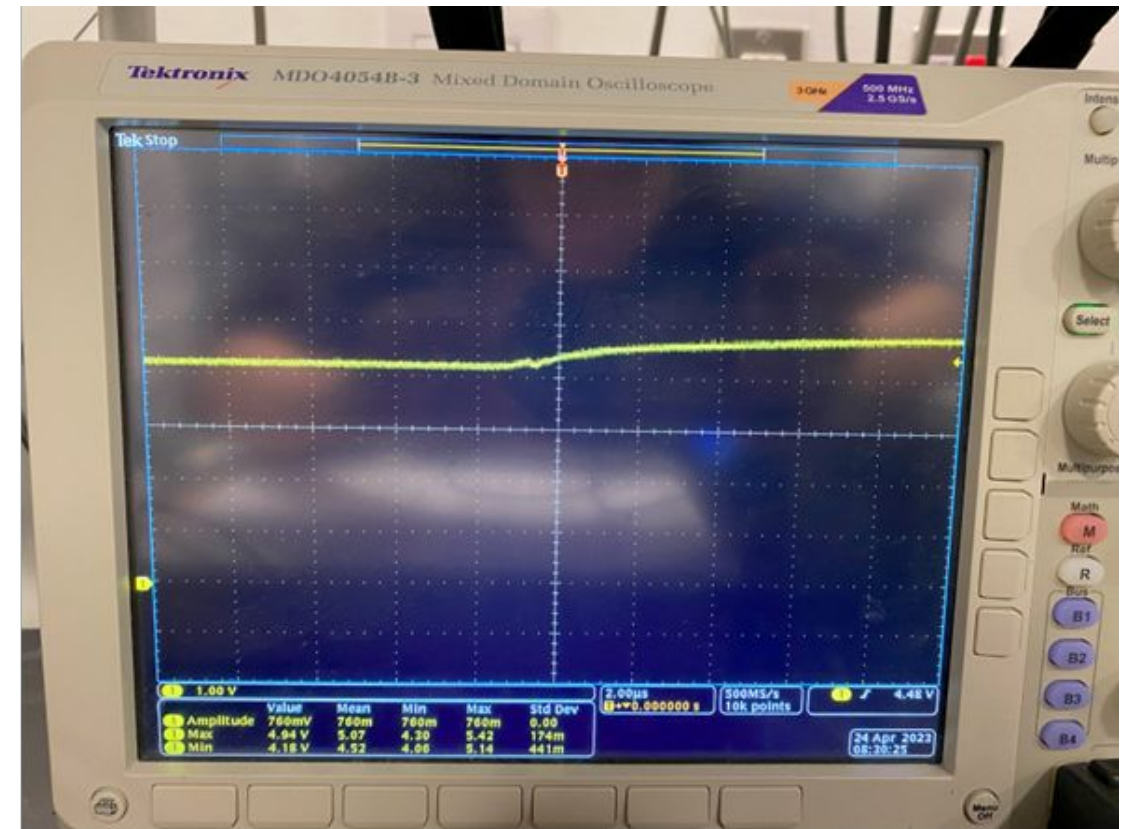


Oscilloscope Testing - Negligible Backwards EMF

Steady 5 Volts



Voltage Drop of 760 mV





Challenges

PCB Issue (1)

- Initially right motor would not work when connecting all components to one PCB

Solution

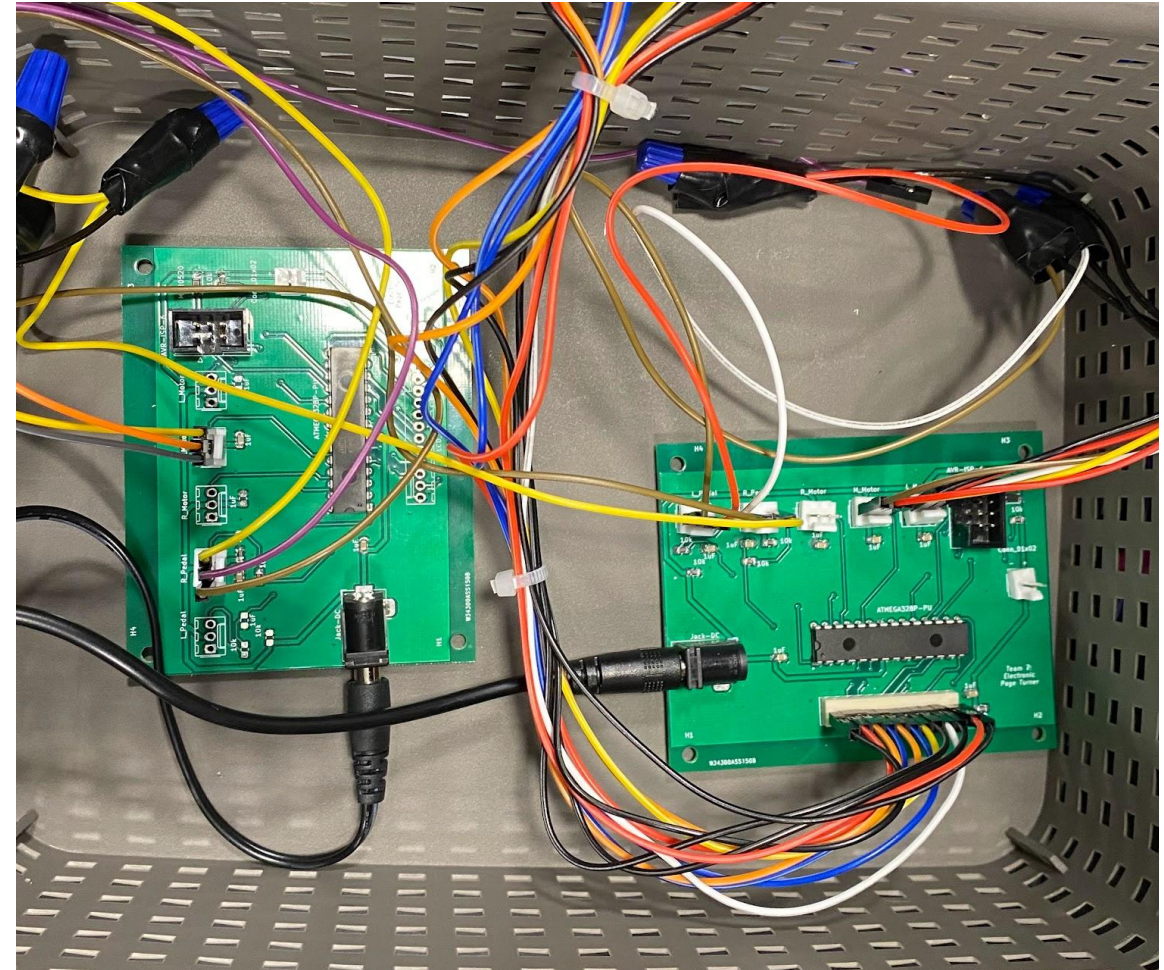
- Used a second PCB to control this motor
 - Two separate programs for each MCU
 - Center and right motor had to be in sync
- Better approach
 - 1 PCB with two Microcontrollers

PCB Issue (2)

- Right motor stopped working on 2nd PCB

Solution

- Rewired all connections
- Soldered a new 2nd PCB



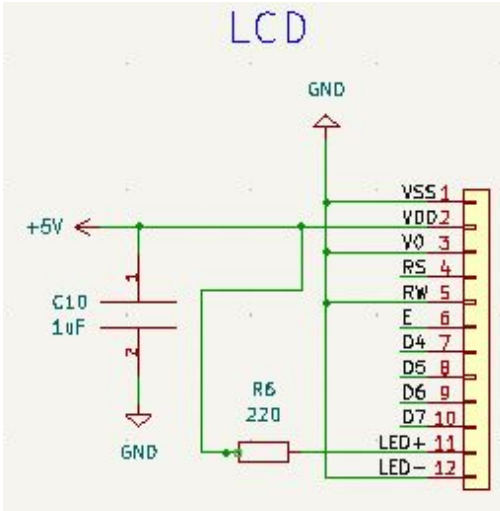
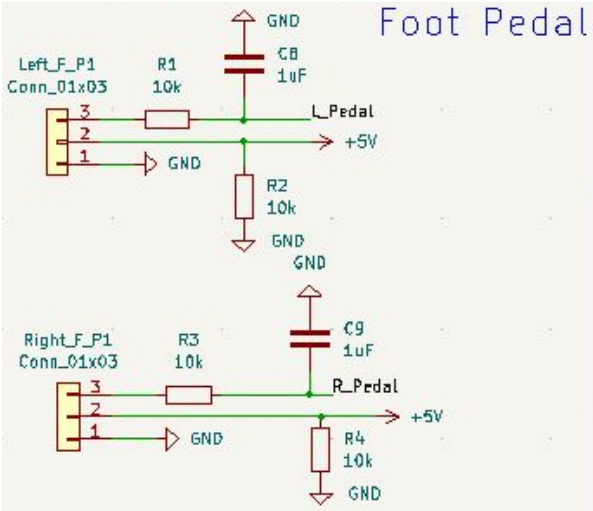
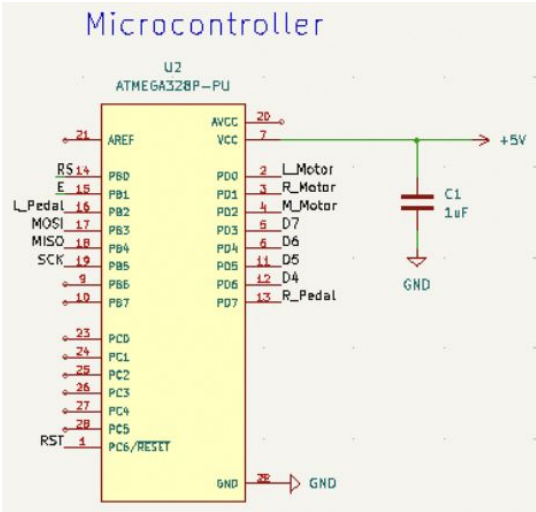


Control & Sensor Subsystem

Javi Cardenas

R&V Table

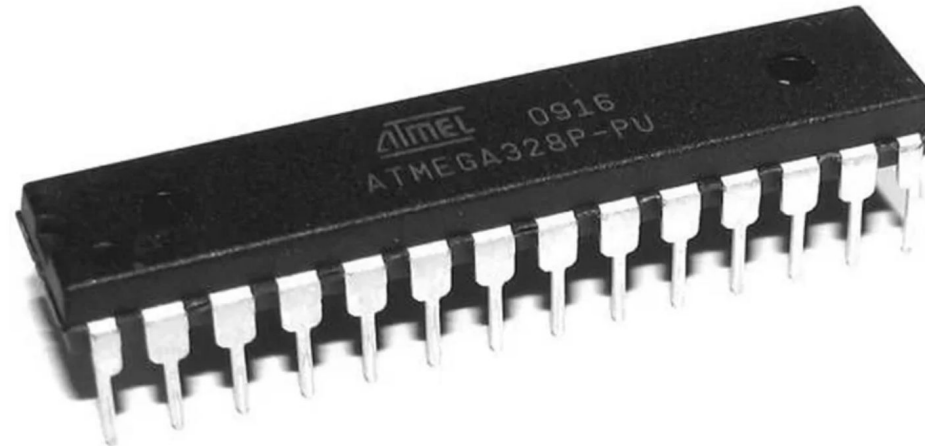
Requirements	Verification
<ul style="list-style-type: none">When the left foot pedal is pressed, the motors should turn a page backward. When the right foot pedal is pressed, the motors should turn a page forward.The LCD should track the number of pages turned forward.	<ul style="list-style-type: none">Ensure that the left motor rotates 45°-135°-45° and the center motor rotates 0°-90°-180° when the left pedal is pressed. Ensure that the right motor rotates 135°-45°-135° and the center motor rotates 180°-90°-0° when the right pedal is pressed.When the right foot pedal is pressed, the count should increase by 1. If the left foot pedal is pressed, the count should decrease by 1.



**Twidec Foot Pedal
Switches**



**ATMEGA328P
Microcontroller**



**Focus 16x4 Liquid
Crystal Display
(LCD)**

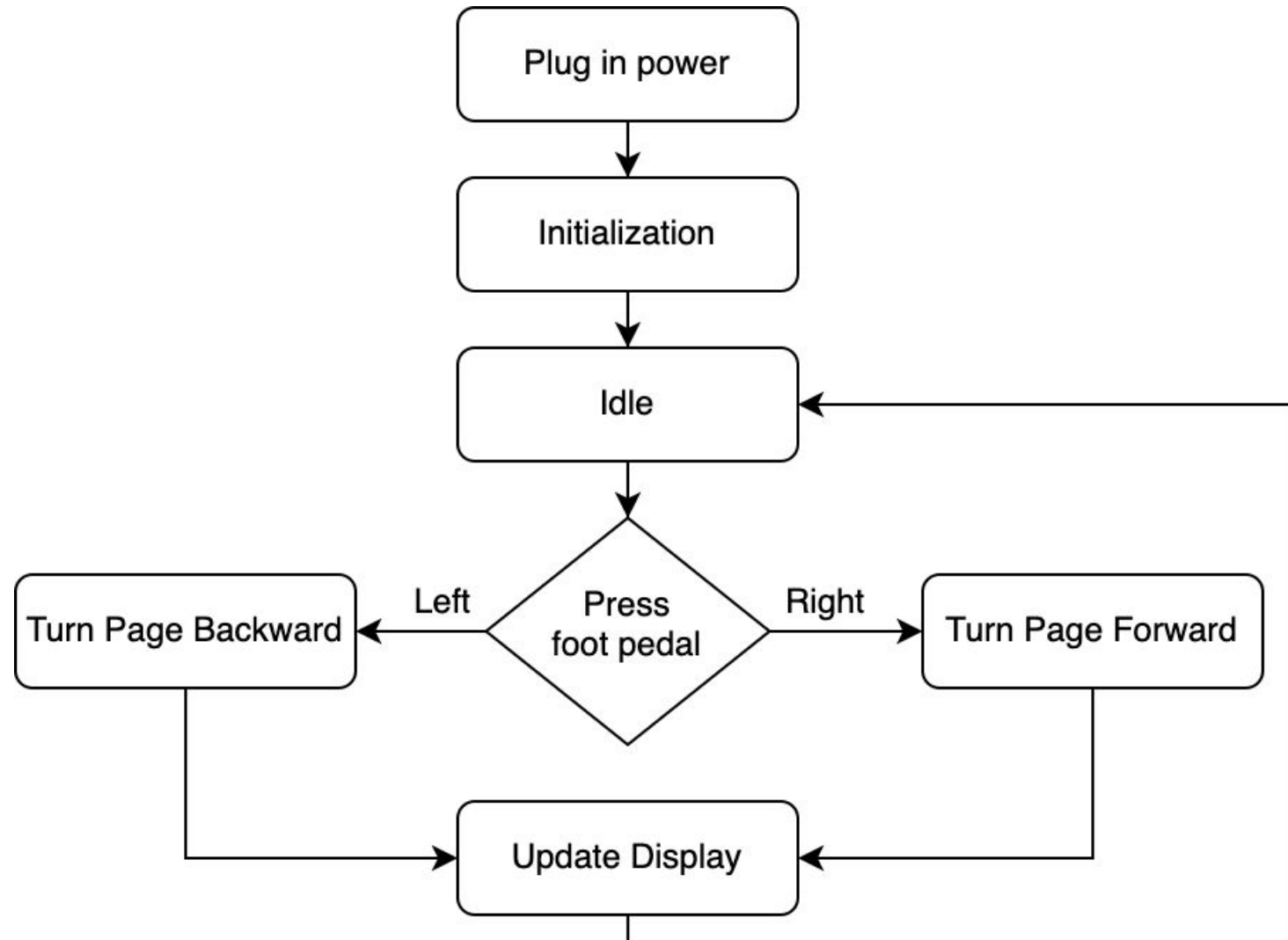


Input

- Foot pedal switches

Output

- Motor actuation
- LCD





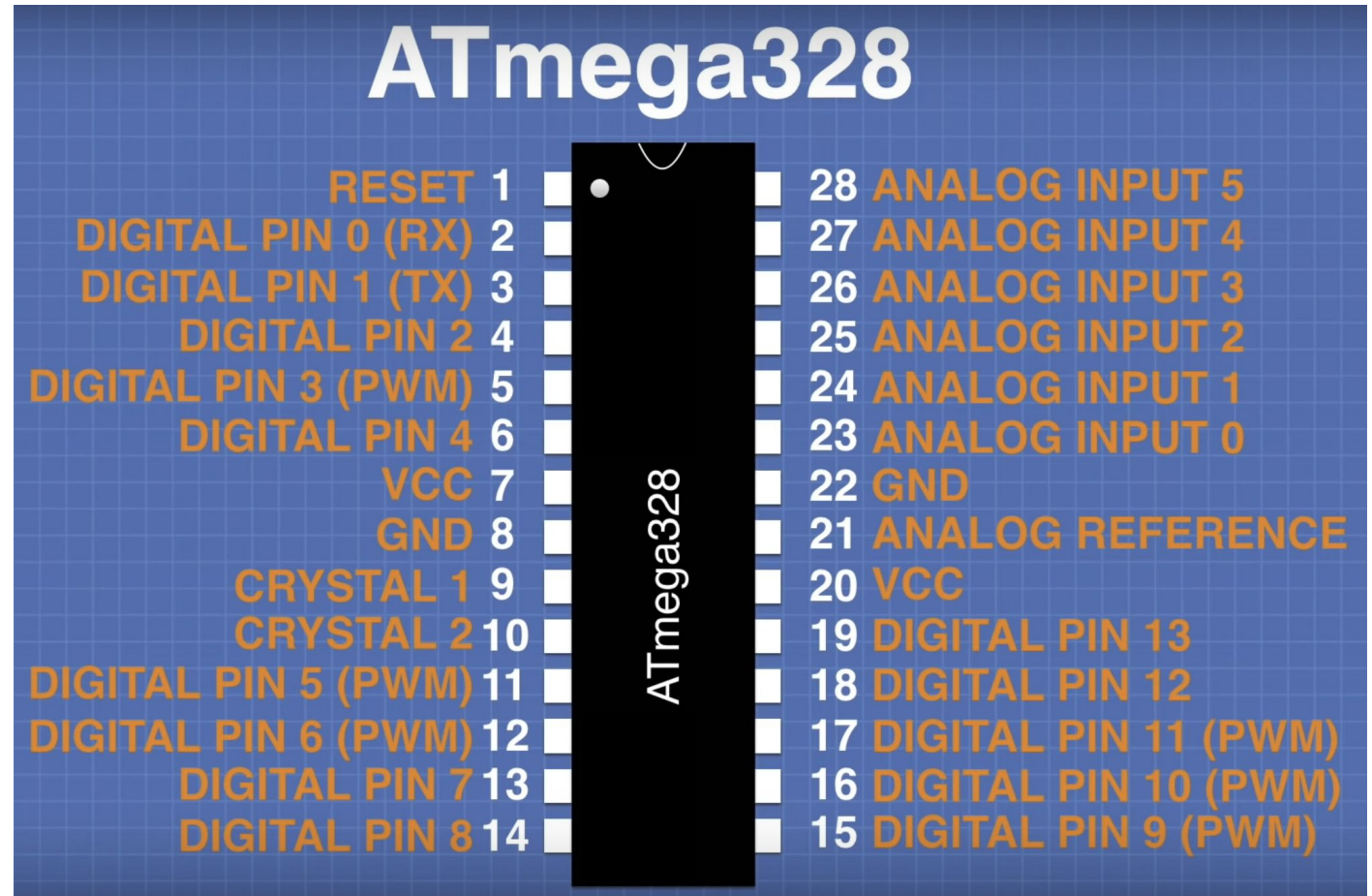
Challenges

Burning Bootloader

- Original MCU had issues

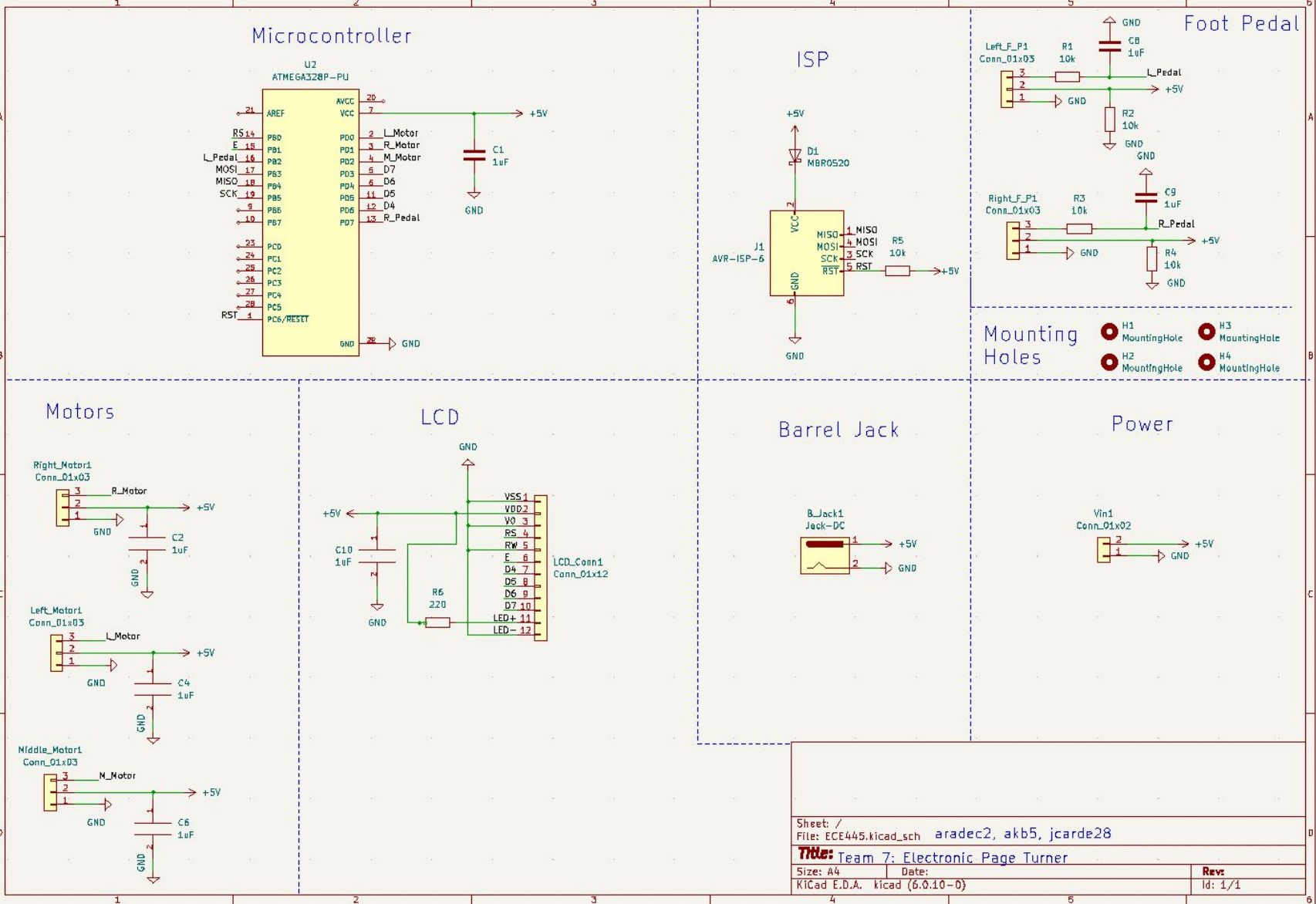
Hardware vs Software

- Arduino software uses digital pins
- Pin 2 maps to pin 0 in software

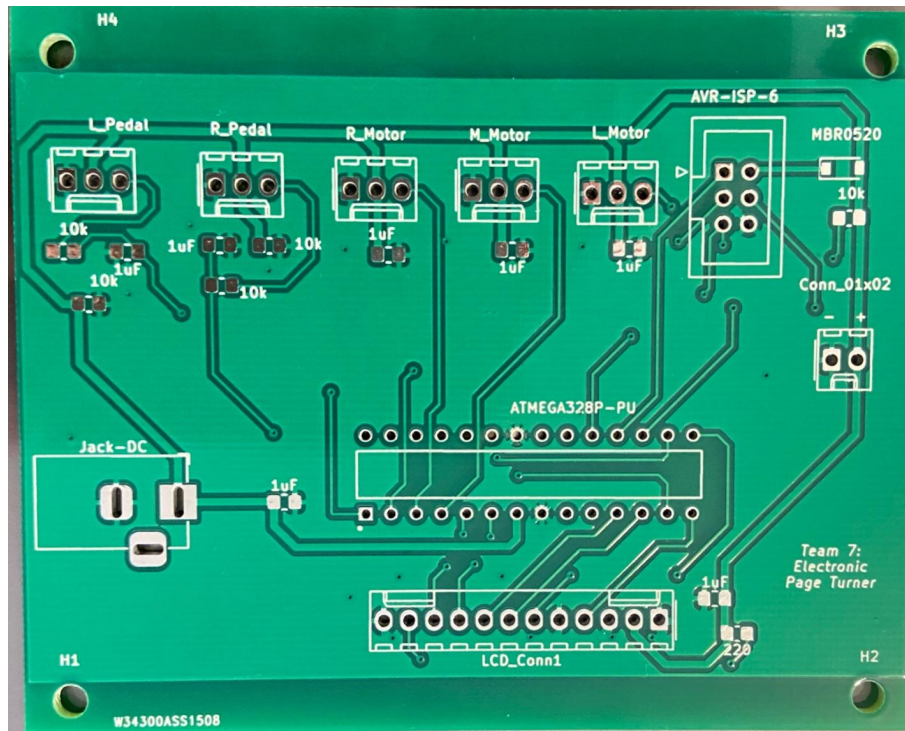




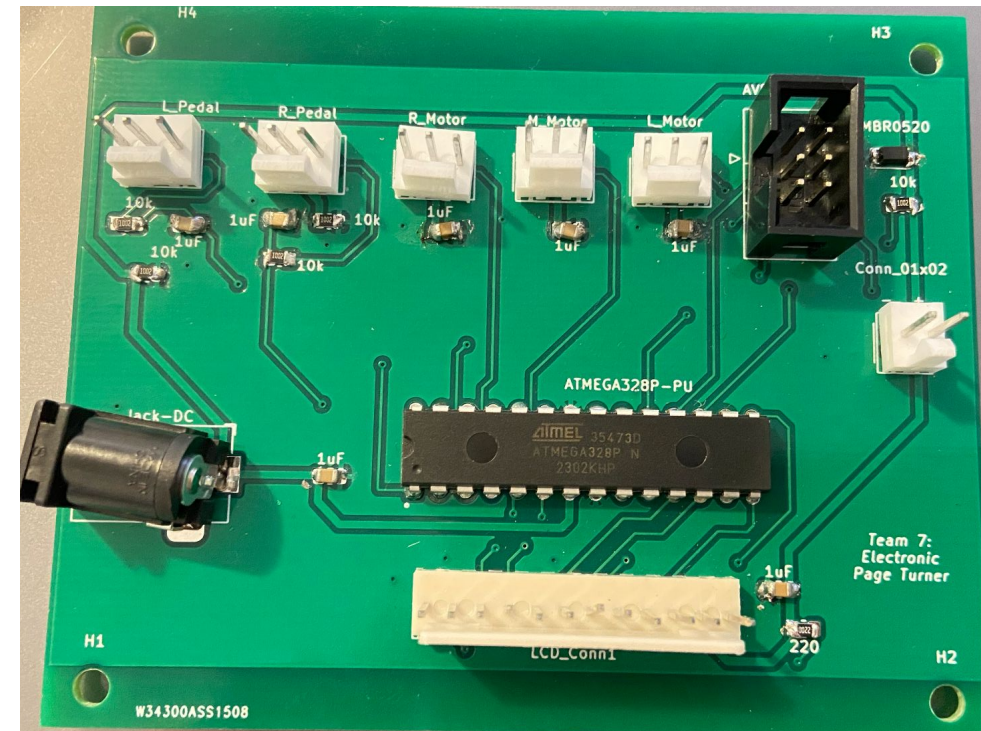
Physical Design



PCB Layout



Unsoldered PCB



Front Side of PCB



Challenges

Foot Pedal

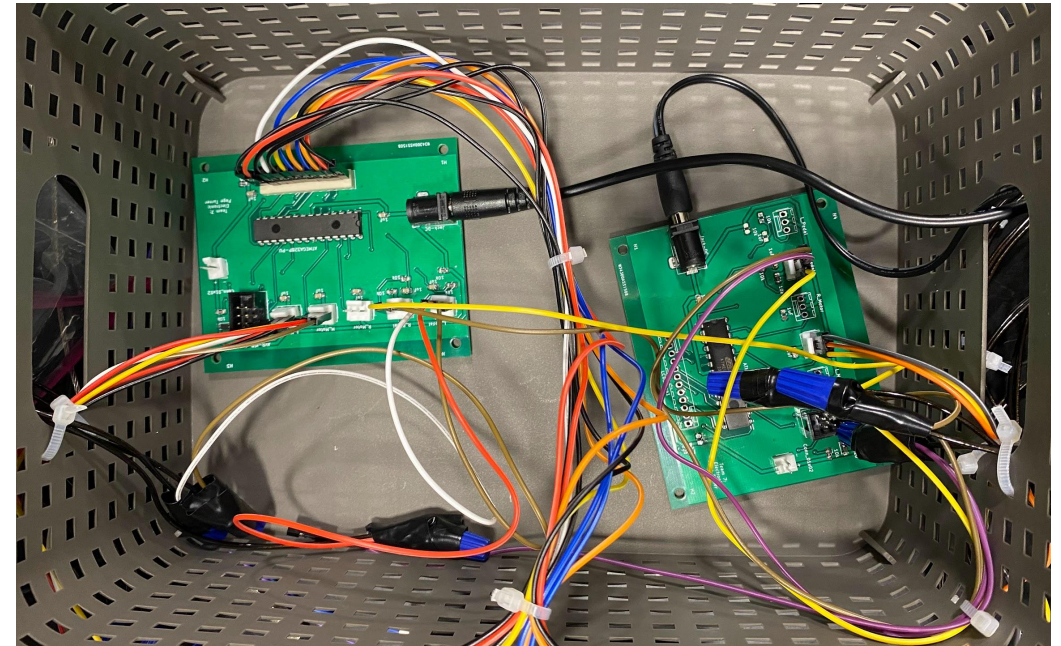
- Pull-Up resistor on voltage line
 - Originally on data line

Microcontroller

- Connect pin 3 to power
- Instead of a via, draw the ground wire on pin 7

Motors

- Add two capacitors for each motor
 - Helps with noise



Conclusion

What we learned and improvements to our device

Cost Analysis

Part	Part Number	Unit Price	Quantity	Total					
					3 Pin Header	WM4201-ND	\$0.27	7	\$1.89
Microcontroller	ATMEGA328P-PU	\$7.21	2	\$14.42	LCD Display	2632-C162A-BW-LW 65-ND	\$6.27	1	\$6.27
Foot Pedal	n/a	\$10.43	2	\$20.86					
Servo Motor	HS-311	\$14.76	3	\$44.28	10k Resistor	2197-294-10-RC-ND	\$0.15	8	\$1.20
PCB Manufacture	n/a	\$30.00	1	\$30.00	1uF Capacitor	478-1836-ND	\$0.82	9	\$7.38
Barrel Jack	PJ-102AH	\$0.82	1	\$0.82	2 pin header	900-0022232021-ND	\$0.15	2	\$0.30
5V Wall Adapter	1470-2771-ND	\$6.50	1	\$6.50	12 pin header	2057-LHA-12-TS-ND	\$0.26	1	\$0.26
ISP Header	1597-114020164-ND	\$2.80	2	\$5.60	Diode	1N4148W-13-F	\$0.19	2	\$0.38
					Machine Shop Parts	n/a	\$50.00	1	\$50.00
					Total Cost				\$190.16

Accomplishments

- Met all high-level requirements
- Affordable compared to existing devices
- Hands-Free

Recommendations for Further Work

- Reset Button or Feedback loop to deal with page jamming
- Force sensor to determine thickness of pages
- Use only one PCB





Questions?



The Grainger College of Engineering

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