

System	Module	Requirement	Points
Navigation	Microcontroller	- Interact with all sensors and output modules	10
	GPS	- Provides GPS coordinates within 100m accuracy - Updates at 1 to 2Hz	8
	Compass	- Heading accurate within 5 degrees	8
Steering	Motors	- 15kg pull force each for 150-180 degrees of motion	5
	Parachute	- Holds full weight of payload - Turns as brake strings are pulled	2
Power	Battery/Voltage Regulator	- Supply enough power (voltage and current output) to circuit - Each component properly supplied	8
Display	LCD	- Displays meaningful information	4.45 :^)
Physical	Payload Box	- Can hold all modules while	4.55
<b>TOTAL:</b>			<b>50</b>