

## High-Level Requirements

- The devices must be able to control at least three different physical sound sources.
- Latency variation must be kept to a minimum. Latency itself is not a concern, but latency must not vary by more than 30 milliseconds.
- Devices must function with at least six feet of distance between devices for simulating real-world environments and circumstances.

## R&V Summary

Module Name	Requirements	Points
Relay Module	<ul style="list-style-type: none"><li>• This module should successfully make a sound from various devices that are connected to wall power using the python module.</li></ul>	15
Servo Module	<ul style="list-style-type: none"><li>• This module should successfully rotate the motor from 0 degree to 180 degree and comeback to 0 degree continuously using the python module.</li></ul>	15
Ringling Module	<ul style="list-style-type: none"><li>• This module should successfully ring the bell using the python module using battery power.</li></ul>	5
Jitter Buffer	<ul style="list-style-type: none"><li>• Network jitter minimizes latency variation to within 30 ms with variable latency.</li></ul>	10
Display Module	<ul style="list-style-type: none"><li>• Display IP and Port for connecting devices</li><li>• Display battery status using backlight</li><li>• Display most recent command</li></ul>	5
	<b>Total</b>	50