

# Wireless Midi Controller



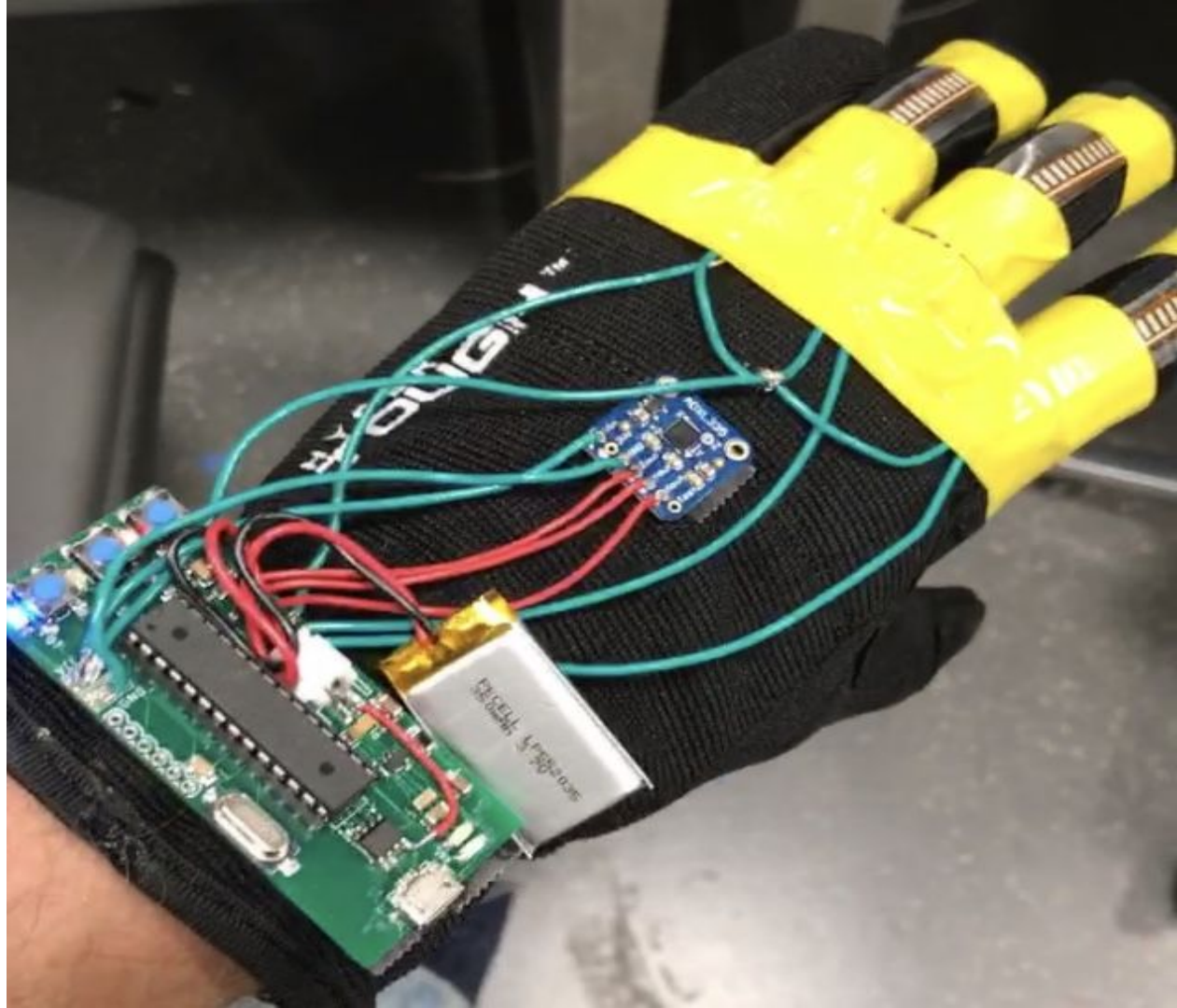
By: Michael Brady, Sarah Palecki, Allan Belfort  
Group 57  
TA: Anthony Caton

# Introduction



- Wireless MIDI Glove Instrument
- For DJs or artists
  - Eliminates need to stand by soundboard or computer
- Uses simple gestures
  - Flex of a finger
  - Tilt of your wrist

# Wireless MIDI Glove



# Presentation Outline

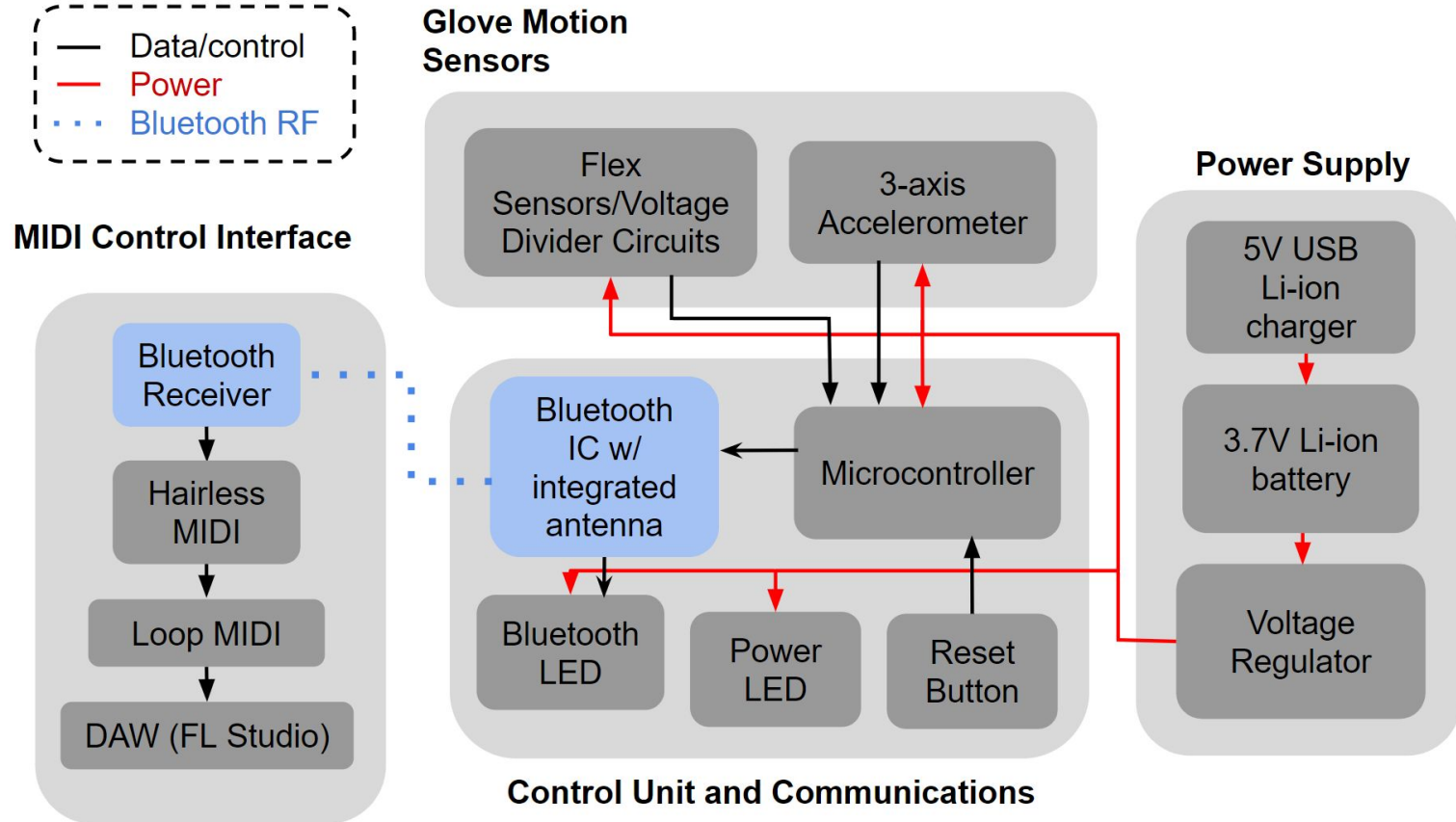
- System Overview and Block Diagram
- Hardware used
  - Sensors
  - Control Unit and Communications
  - Power Supply
- Software Used
  - MIDI Control Interface
  - MIDI Code
- Future Work/Acknowledgements/Thank You

# System Overview

- Hardware:
  - Microcontroller: Atmega328
  - Bluetooth: RN-41
  - 2.2" flex sensors x3
  - 3-axis analog accelerometer
- Software
  - Sensor mapping/MIDI outputting/Microcontroller code
  - Hairless MIDI
  - Loop MIDI
  - FL Studio



# Block Diagram



# Glove Motion Sensors- 3-axis accelerometer

- Adafruit Adxl335 3-axis analog accelerometer
  - Full sensing range of +/- 3G
  - Runs on 3.3V
- X-axis tilt = sound panning
- Y-axis tilt = volume control
- Output directly to the microcontroller



# Glove Motion Sensors- Flex Sensors

- Sparkfun 2.2" Flex Sensors
- 3 sensors:
  - Index, middle, ring finger
- Voltage divider circuit
- Output of voltage divider circuits are read as analog inputs to microcontroller

$$V_{out} = V_{in} \frac{(R_{flex})}{(R_{flex} + R_2)}$$





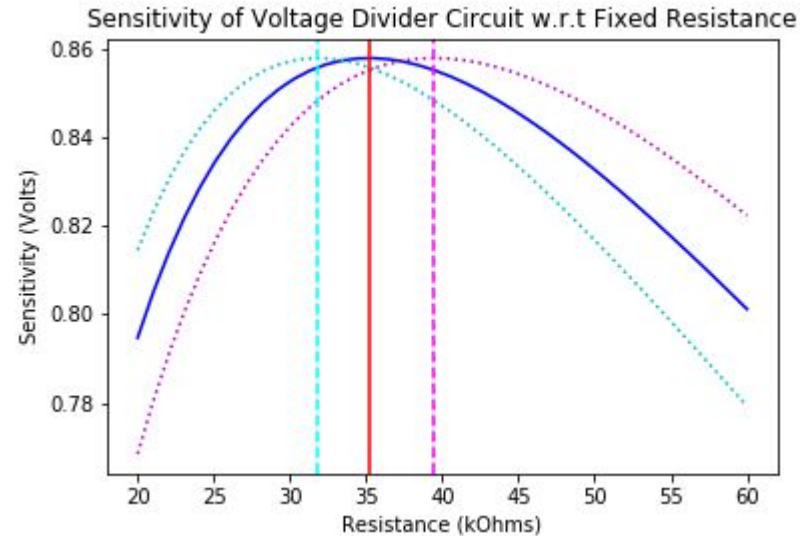
# Analog Sensor Mapping

$$\text{Output} = \frac{\text{Max} - \text{Input}}{\text{Max} - \text{Min}} * 127$$

<i>pppp</i>	= 8
<i>ppp</i>	= 20
<i>pp</i>	= 31
<i>p</i>	= 42
<i>mp</i>	= 53
<i>mf</i>	= 64
<i>f</i>	= 80
<i>ff</i>	= 96
<i>fff</i>	= 112
<i>ffff</i>	= 127

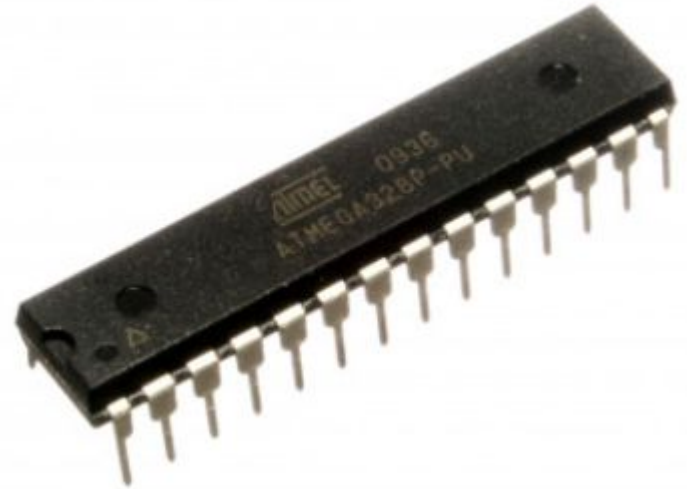
# Flex Sensors Voltage Divider Data and Tolerance Analysis

- Maximize sensitivity of voltage divider circuit
- Looked for fixed resistance
- Modeled the errors
  - Due to inconsistencies in sensors

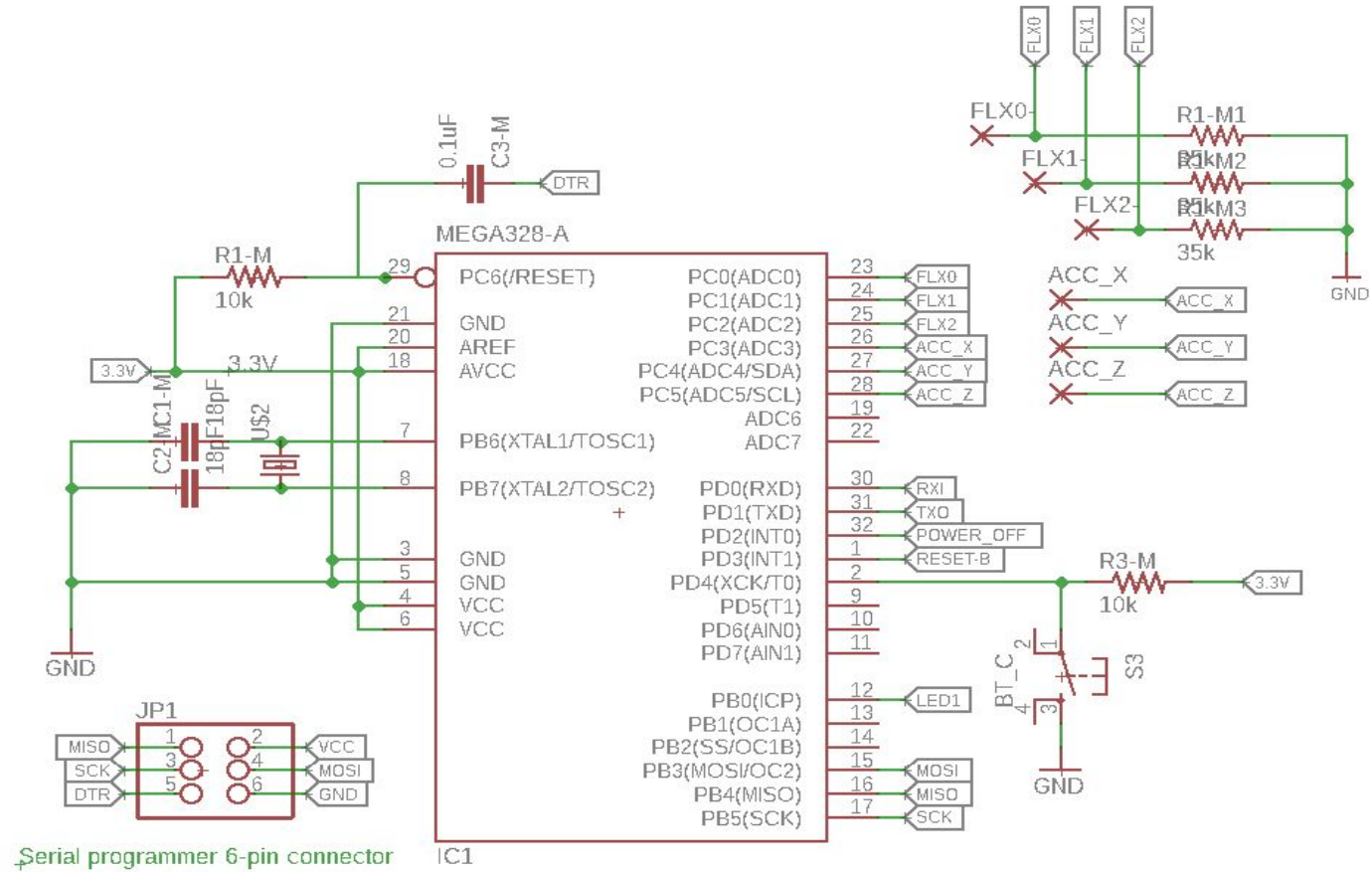


# Control Unit and Communications- Microcontroller

- Atmega328p
  - 8-bit AVR RISC based
  - 32KB ISP Flash memory
  - Operating at 3.3V
  - 8 MHz clock



# Microcontroller: Atmega328 Schematic



Connections needed for communications are TXD, RXD, & GND. 3.3V is internally regulated

# Microcontroller: Programming (Pin map to Arduino map)

ATmega328 Pin Mapping

Arduino function						Arduino function
reset	(PCINT14/RESET) PC6	1	28	PC5 (ADC5/SCL/PCINT13)		analog input 5
digital pin 0 (RX)	(PCINT16/RXD) PD0	2	27	PC4 (ADC4/SDA/PCINT12)		analog input 4
digital pin 1 (TX)	(PCINT17/TXD) PD1	3	26	PC3 (ADC3/PCINT11)		analog input 3
digital pin 2	(PCINT18/INT0) PD2	4	25	PC2 (ADC2/PCINT10)		analog input 2
digital pin 3 (PWM)	(PCINT19/OC2B/INT1) PD3	5	24	PC1 (ADC1/PCINT9)		analog input 1
digital pin 4	(PCINT20/XCK/T0) PD4	6	23	PC0 (ADC0/PCINT8)		analog input 0
VCC	VCC	7	22	GND		GND
GND	GND	8	21	AREF		analog reference
crystal	(PCINT6/XTAL1/TOSC1) PB6	9	20	AVCC		VCC
crystal	(PCINT7/XTAL2/TOSC2) PB7	10	19	PB5 (SCK/PCINT5)		digital pin 13
digital pin 5 (PWM)	(PCINT21/OC0B/T1) PD5	11	18	PB4 (MISO/PCINT4)		digital pin 12
digital pin 6 (PWM)	(PCINT22/OC0A/AIN0) PD6	12	17	PB3 (MOSI/OC2A/PCINT3)		digital pin 11 (PWM)
digital pin 7	(PCINT23/AIN1) PD7	13	16	PB2 (SS/OC1B/PCINT2)		digital pin 10 (PWM)
digital pin 8	(PCINT0/CLKO/ICP1) PB0	14	15	PB1 (OC1A/PCINT1)		digital pin 9 (PWM)

Digital Pins 11, 12 & 13 are used by the ICSP header for MISO, MOSI, SCK connections (Atmega 168 pins 17, 18 & 19). Avoid low-impedance loads on these pins when using the ICSP header.

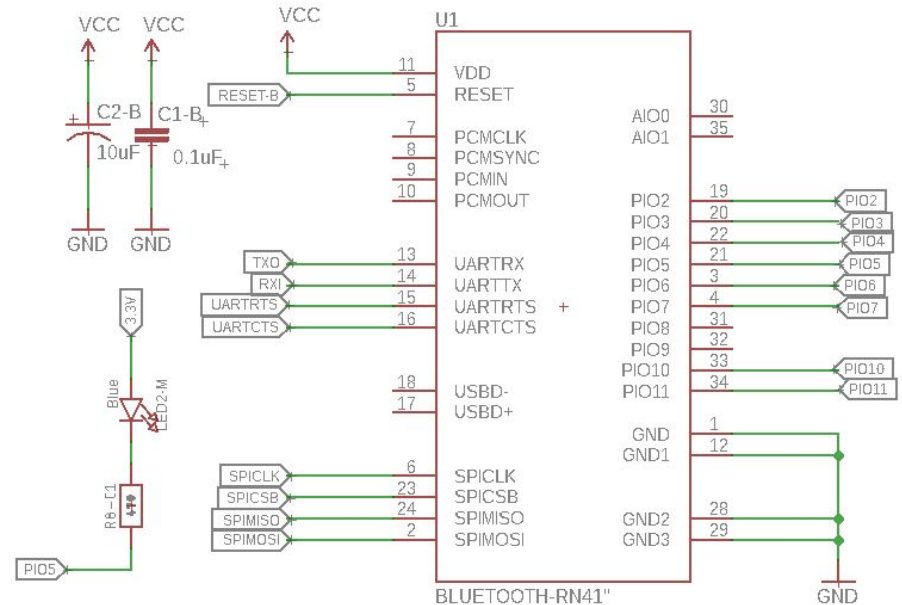
# Control Unit and Communications: Bluetooth Transceiver

- Model RN-41
  - Fully certified class 1 Bluetooth
  - Used in transmitting mode
  - 115,200 baud
  - Bluetooth receiver is built in to computer or added via bluetooth-usb receiver
  - Blue LED for debugging

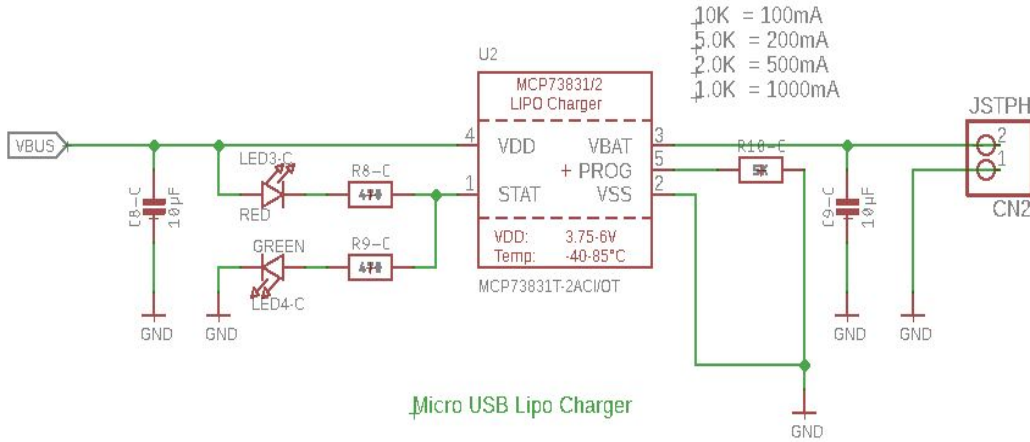


# Bluetooth Transceiver: Programming

- Necessary to pair the transmitting RN-41 Bluetooth module with the Bluetooth module located inside a laptop
- Easy first-time setup through computer
- LED on PIO5 (Status) pin to show connection state



## Power Supply: Li-Ion Battery & USB Charger

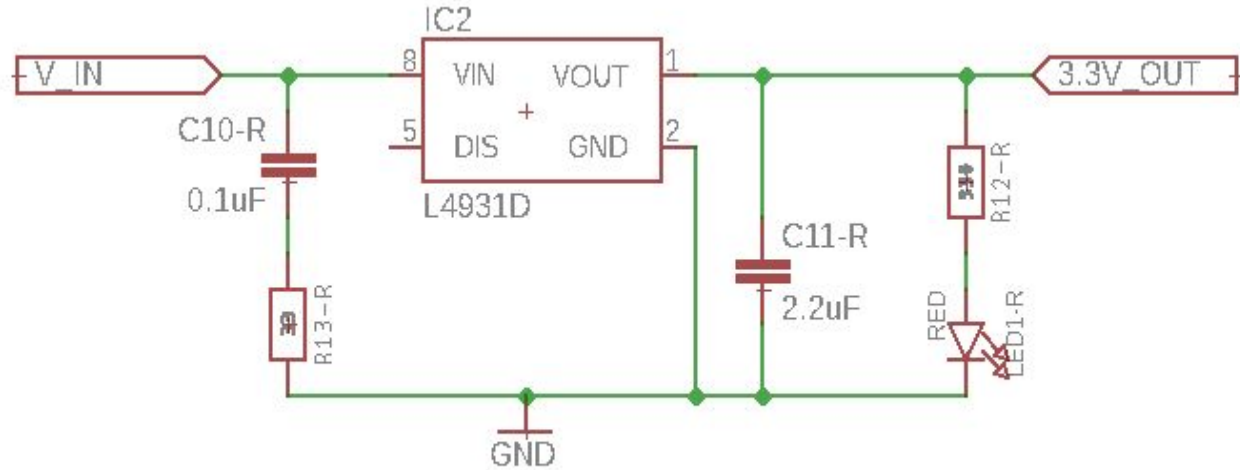


- MCP73831T charging IC
  - 5V micro USB input
  - Variable charge rate
    - Optimal charging speed
    - Extended battery life
  - Full charge in 1-2 hours
  - Charge status LEDs
    - Red- charging
    - Green- charge complete
- 350 mAh Li-Ion battery
  - 3.7-4.2V output depending on charge
  - Device run time > 6 hours



# Power Supply: Voltage Regulator

- L4931 very low dropout regulator
  - Input 3.7-4.2V from battery
  - Output 3.3V +/- 1%
  - 4-6 mA current draw



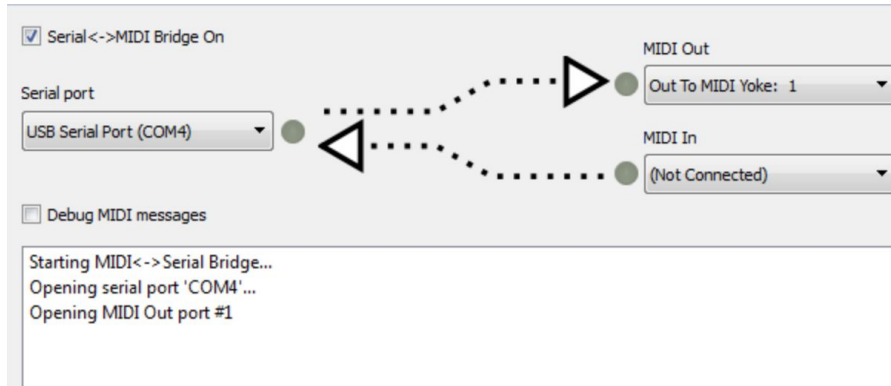
Very Low Dropout Voltage Regulator

# MIDI Control Interface: Bluetooth Receiver

- Located inside of most laptops
  - External bluetooth-USB receiver can be used if needed
- Simple pairing procedure
- We used the software “Tera Term” to debug the Bluetooth output
- Settings used:
  - Baud rate of 115200 bits/second
  - Line ending: CR-LF

# MIDI Control Interface: Hairless MIDI

- Serial <-> MIDI Bridge
- Debug tool for MIDI messages

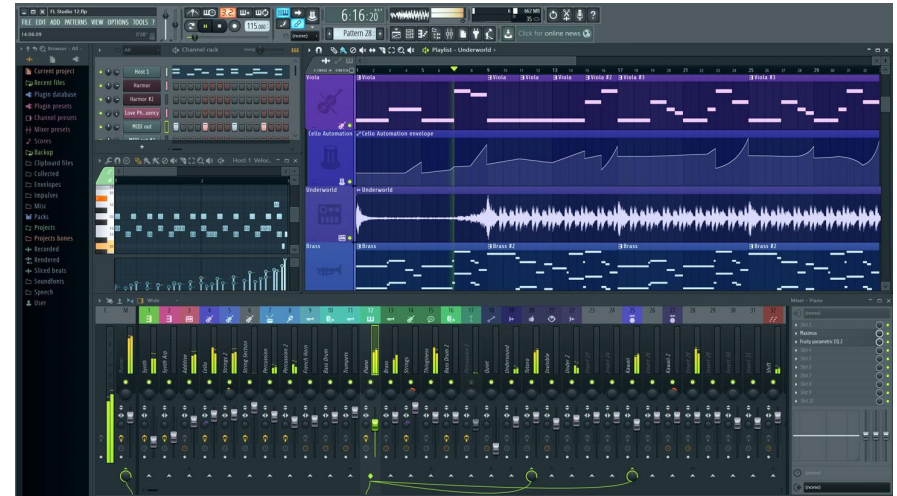


# MIDI Control Interface: Loop MIDI

- Create virtual MIDI ports on the computer
  - Free
  - Easy to download
- Input from Hairless MIDI
- Output to DAW
  - Lets DAW recognize data as MIDI

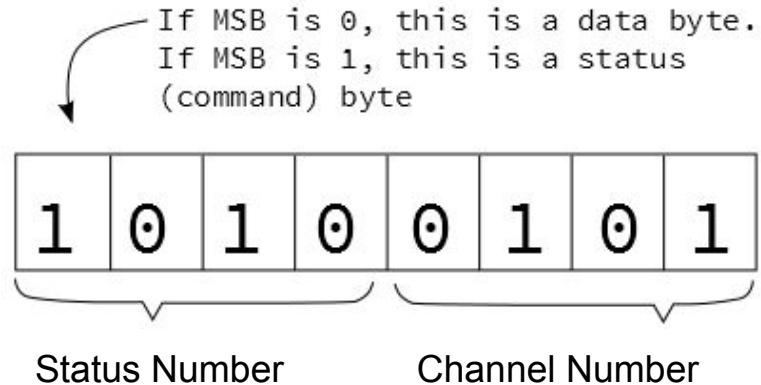
# MIDI Control Interface: DAW

- FLStudio
- Allows musicians to create, edit, record or arrange their music
- Works with MIDI protocol to record and play MIDI files
- Received the glove's codes and processed them to create/modify sounds



# MIDI Control Interface: MIDI Code

- Used the Arduino Midi Library by FortySevenEffects on Github
  - Allows for use of `Midi.SendNoteOn(note, channel, velocity);`
    - Cleans up the code
- MIDI Code Format
  - Status Bytes
  - Data Bytes
- Two types of MIDI messages:
  - “Note On”
  - “Control Change”
  - Made up of Status + Data Bytes



# MIDI “Note On”

- A “Note On” Midi message contains 3 bytes:
  - 1 “Status Byte”: 0x9?
    - ? = Channel
  - 2 “Data Bytes”: 0x?? + 0x??
    - 1st Byte ?? = note value (60 = middle C)
    - 2nd Byte ?? = velocity value
- Velocity value is used to change volume

MIDI Status Messages					
Message Type	MS Nybble*	LS Nybble*	Number of Data Bytes	Data Byte 1	Data Byte 2
Note On	0x9	Channel	2	Note Number	Velocity

\* A Nybble is equivalent to 4 bits

# MIDI “Control Change”

- A “Control Change” Midi message contains 2 bytes:
  - 1 “Status Byte”: 0xB?
    - ? = Channel
  - 1 “Data Byte”: 0x??
    - ?? = Controller Number
- Used to change effects
  - Pan
  - Vibrato
  - Pitch Bend

MIDI Status Messages				
Message Type	MS Nybble*	LS Nybble*	Number of Data Bytes	Data Byte 1
Control Change	0xB	Channel	1	Control Number

\* A Nybble is equivalent to 4 bits



# Future Hardware Development

- Power Button
  - Turn device On/Off
- LEDs
  - In fingers with flex sensors
  - Change intensity
- Pressure sensors
  - In fingertips
  - Control different sounds
- Better materials
- Slimmed down package

# Future Software Development

- Enable a “tapping” feature on the accelerometer
  - Uses sudden acceleration along z-axis
  - “Single tap” vs. “Double tap”
  - Change programs
  - Control separate functions
- Change the sensor mapping algorithm
  - Simple linear algorithm vs. specifically designed algorithm for each sensor

# Overall Analysis of Wireless MIDI Glove

## Strengths:

- Can be used at a range of ~50 feet from computer
- Low-latency

## Threats:

- Global DJ Tornado Gloves
- Remidi Glove and Controller

## Weaknesses:

- Possible difficulty in user setup
- Only produces sounds, does not edit them

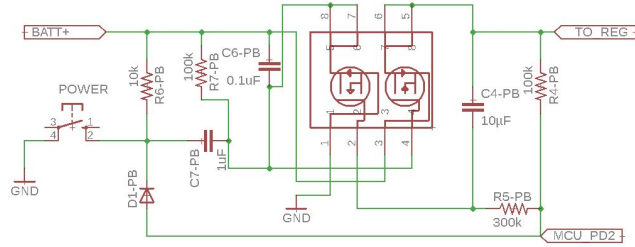
## Opportunities:

- Innovative performance wear
- Can use in addition to supplement a different instrument

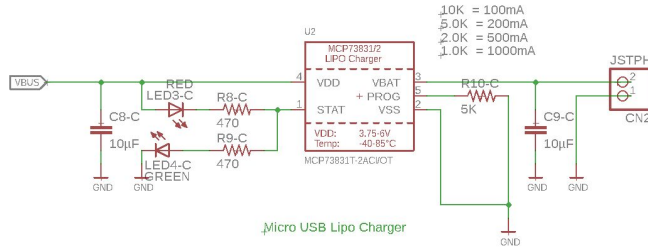
# Acknowledgements

- Professor Lippold Haken, ECE 402
- Mr. Anthony Caton

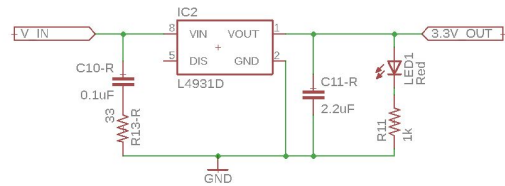
**Thank you!**



Push Button Power Circuit



Micro USB Lipo Charger



Very Low Dropout Voltage Regulator

