

# Bone Conduction Lock

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TA: Jacob Bryan

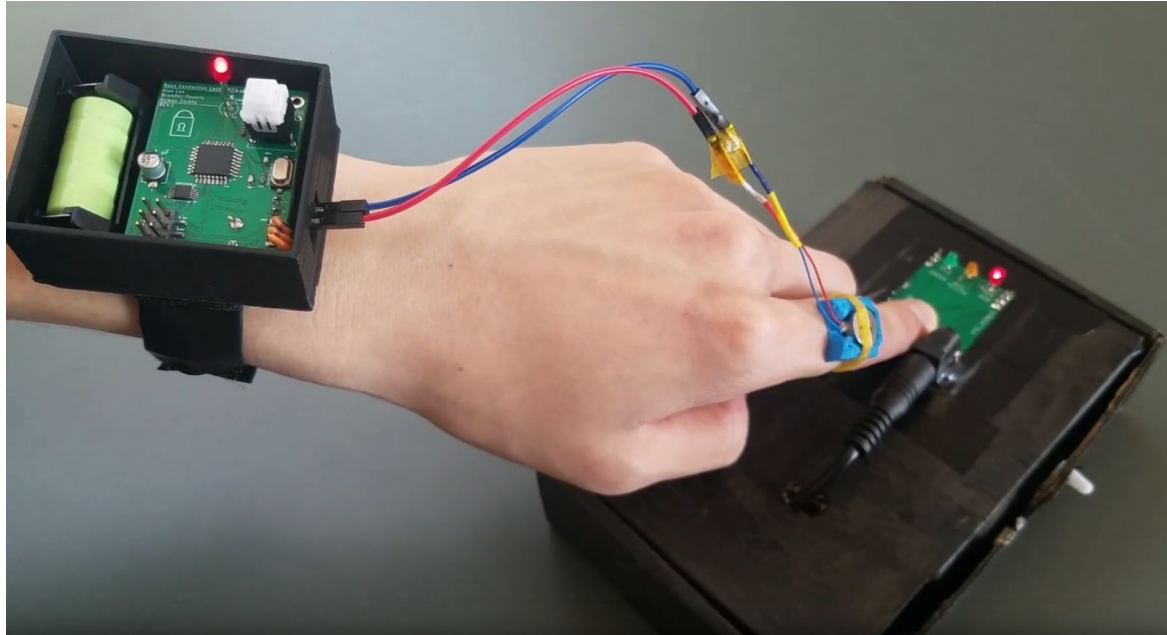
April 30, 2018





# Project Overview

A lock that is unlocked by vibrations conducted through the user's bones.





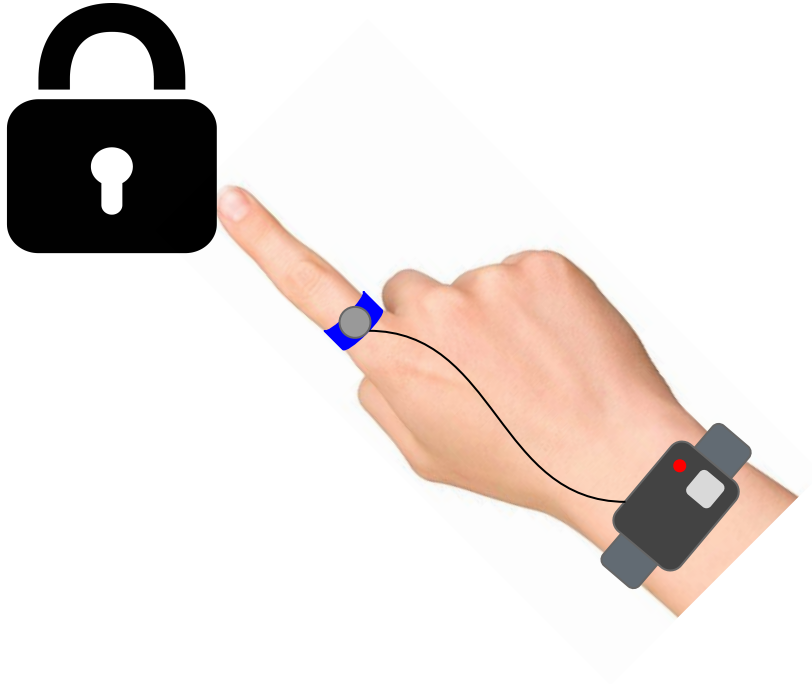
# Objective

- Prove human bone conduction is a viable communication channel
- Provide an efficient and secure way to unlock a door
- Investigate the use of human bone for biometric authentication



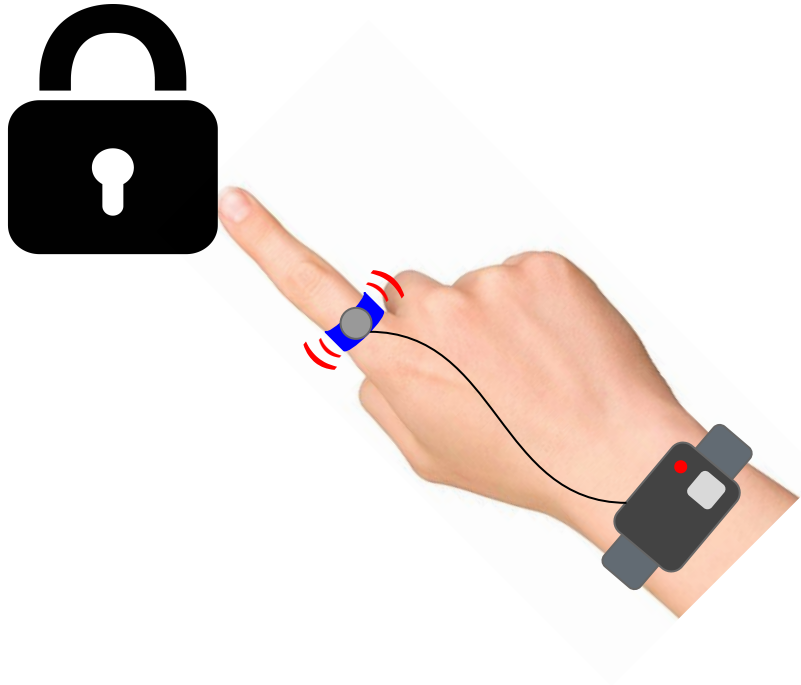
# Bone Conduction Lock Operation (Basic)

User presses their finger to the lock





# Bone Conduction Lock Operation (Basic)

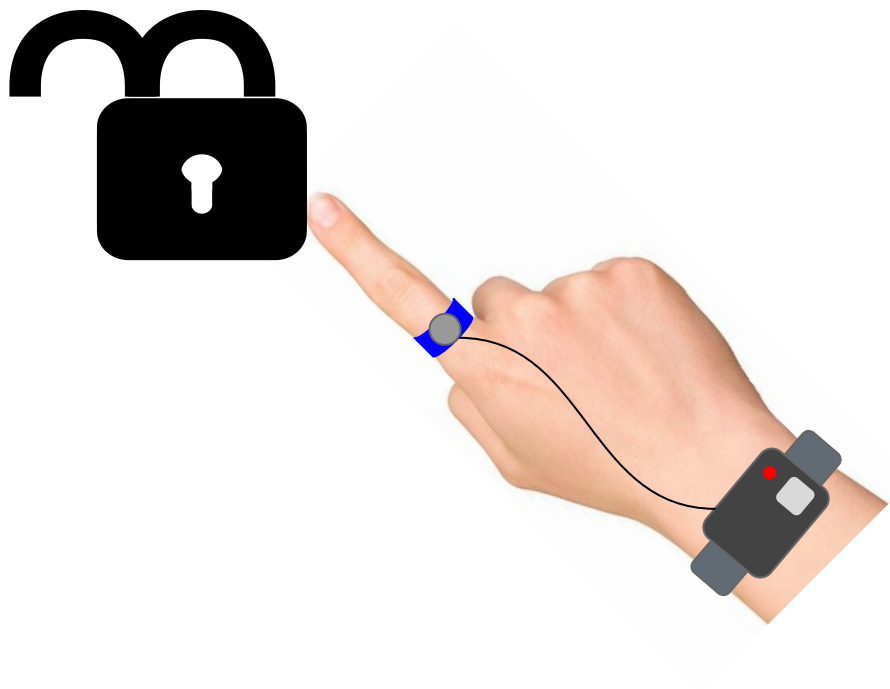


User presses their finger to the lock

User presses button on band to  
generate vibrations



# Bone Conduction Lock Operation (Basic)



User presses their finger to the lock

User presses button on band to generate vibrations

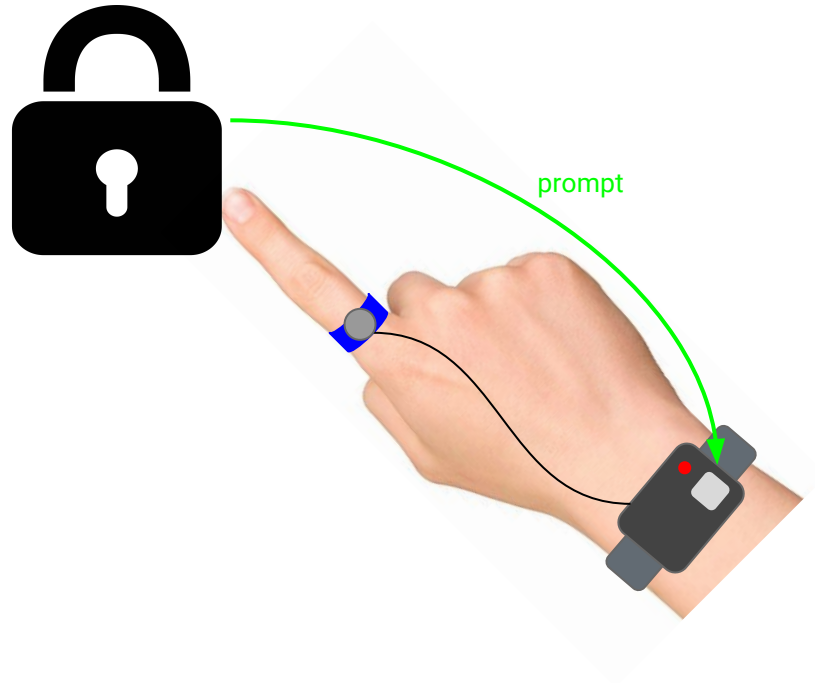
Lock detects and verifies signal  
- if signal is correct, lock unlocks

After predetermined time, lock locks itself

Lock is now ready for the next attempt



# Bone Conduction Lock Operation (Advanced)

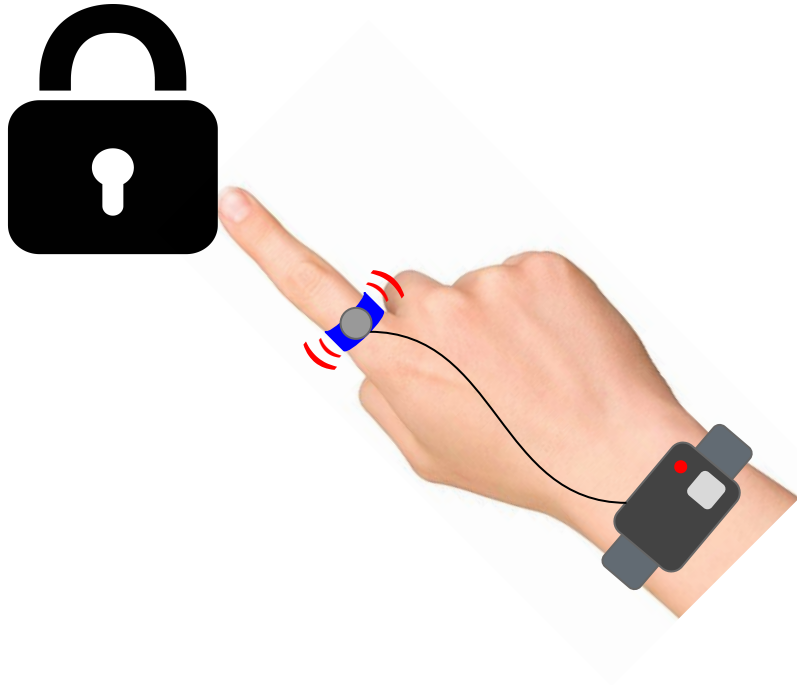


User presses their finger to the lock

Lock detects finger and sends prompt to band wirelessly



# Bone Conduction Lock Operation (Advanced)



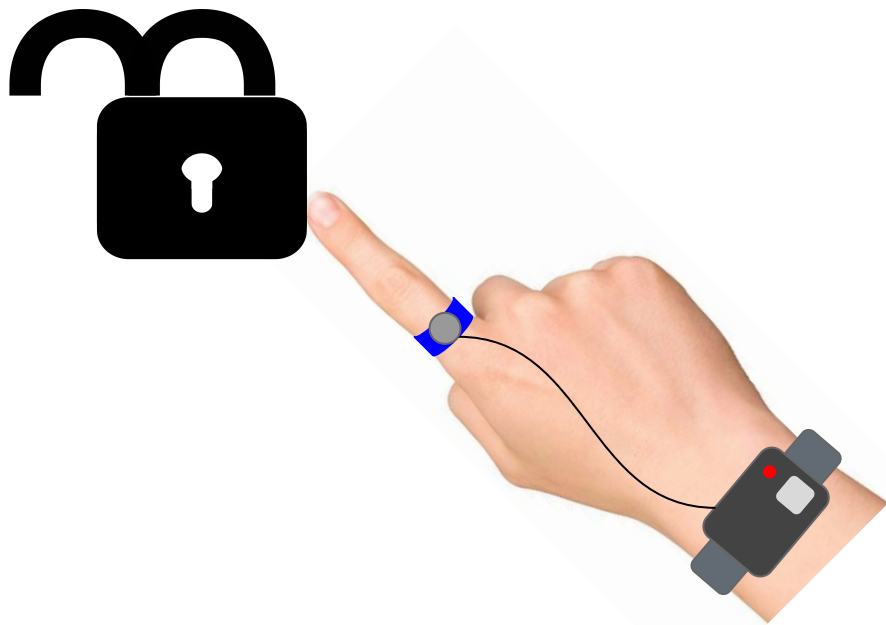
User presses their finger to the lock

Lock detects finger and sends prompt to band wirelessly

Band generates vibrations corresponding to prompt



# Bone Conduction Lock Operation (Advanced)



User presses their finger to the lock

Lock detects finger and sends prompt to band wirelessly

Band generates vibrations corresponding to prompt

Lock detects and verifies signal

- if signal is correct, lock unlocks

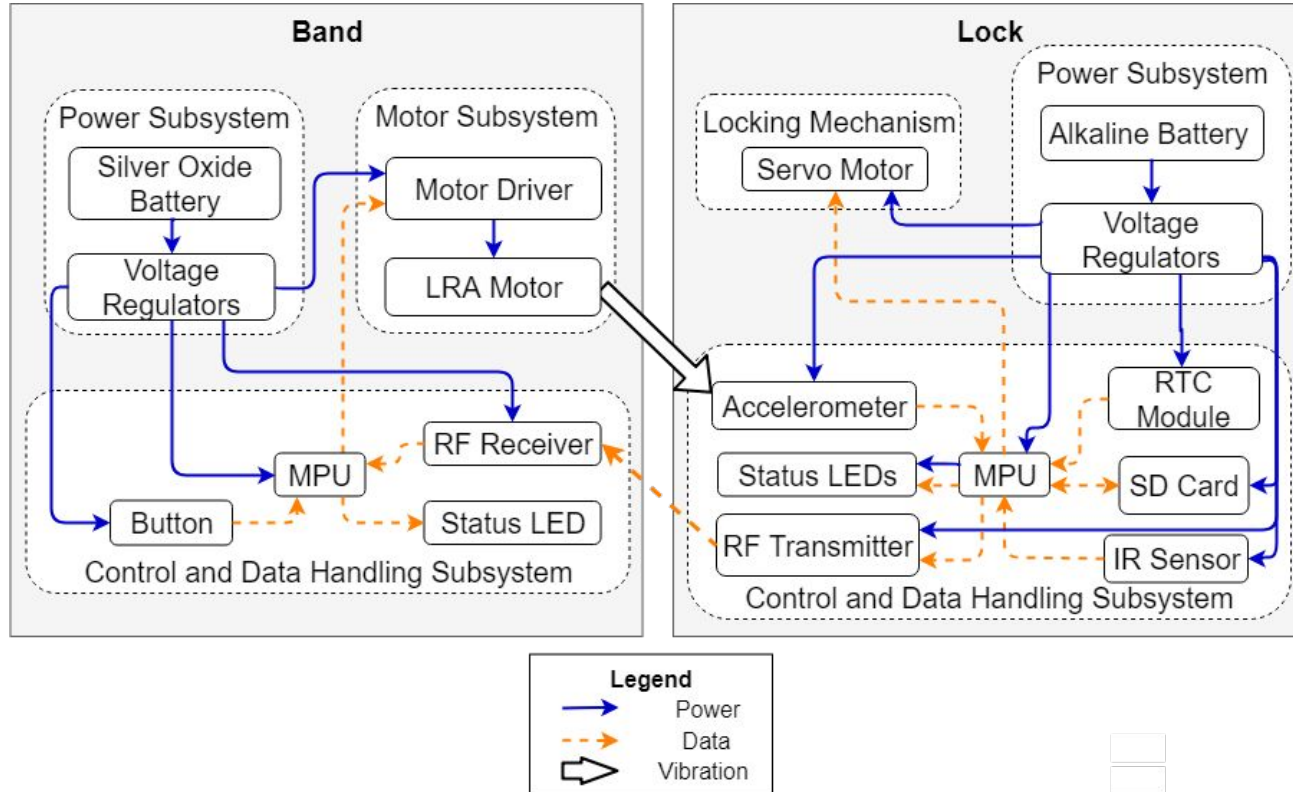
After predetermined time, lock locks itself

Lock stores activity in activity log

Lock is now ready for next attempt

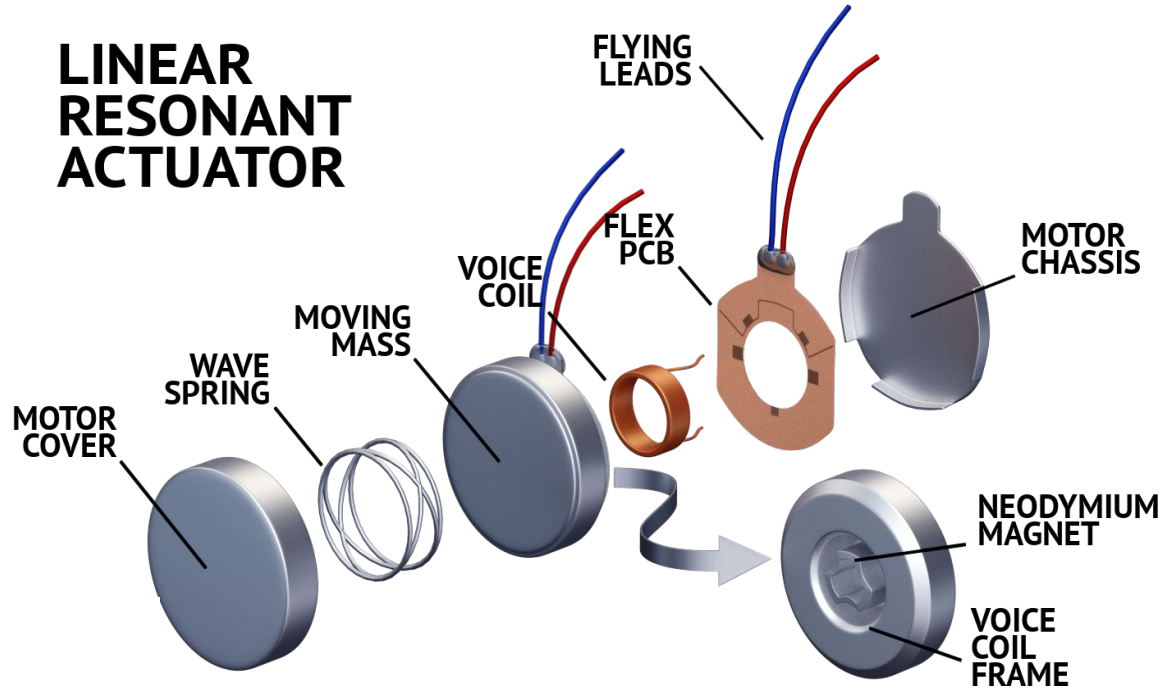


# Block Diagram



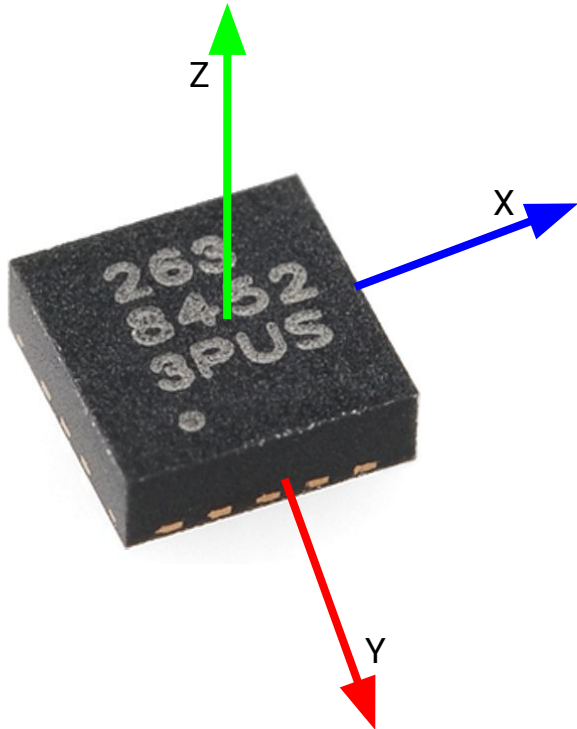


# Motor





# Accelerometer



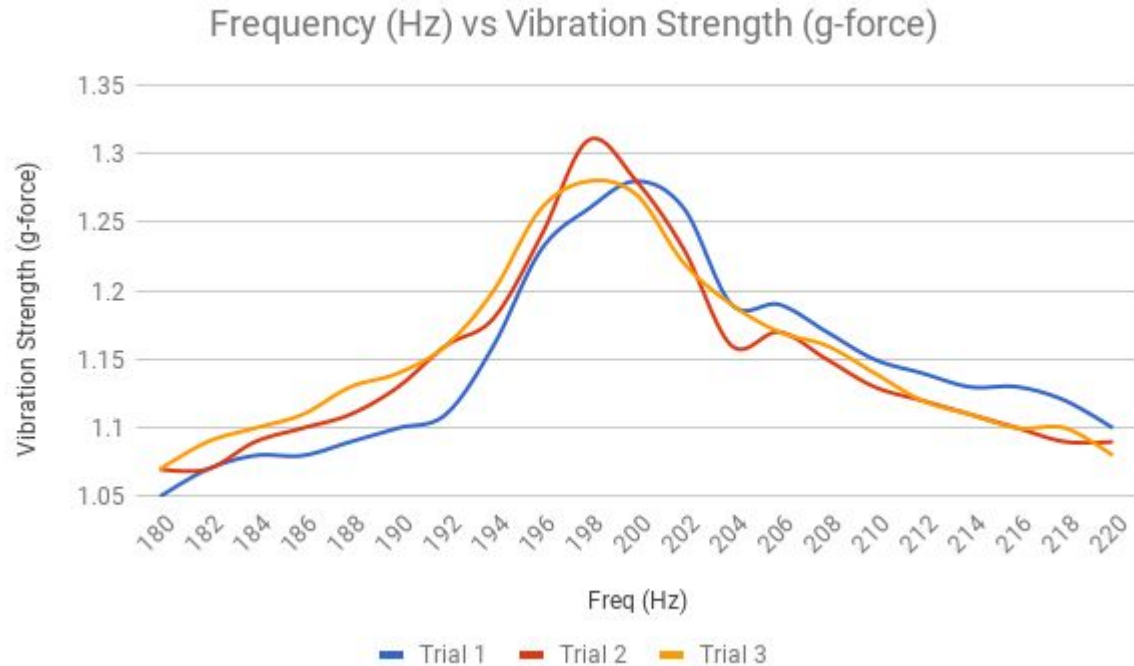
MMA8452 3-axis accelerometer:

- MEMS accelerometer with 12-bit resolution
- Selectable full-scale range:  $\pm 2g$ ,  $\pm 4g$ , or  $\pm 8g$
- Selectable sampling rate: 800, 400, 200, 100, 50, 12.5, 6.25, or 1.56 Hz

We initialized accl with  **$\pm 2g$**  full-scale range and **800 Hz** sampling frequency.

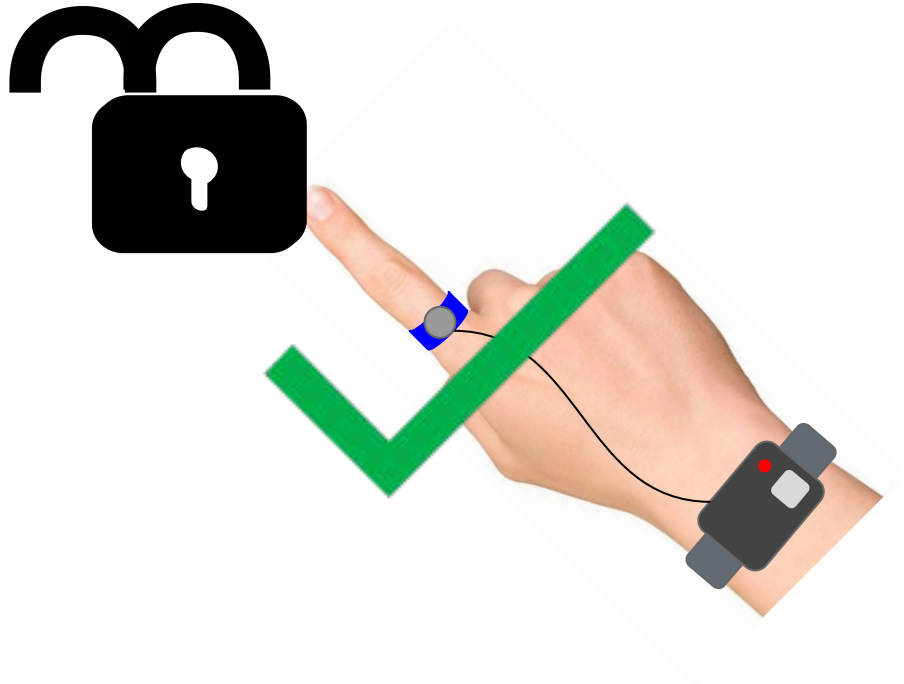


# Resonant Frequency





# Efficiency: Unlock with one motion





# Security

- keys made up of 10 bits transmitted in 3s
- bit = 0 or bit = 1
- total number of possible bit sequences:

$2^{10} = 1024$  possible keys





# Security (cont.)

Dynamic prompts:

- For every attempt, the bone conduction lock is expecting a different key





# Security (cont.)

```
/dev/ttyUSB0

- key length [b]: 128
- encryption time [us]: 1704
- decryption time [us]: 2096
- plain: Team 3: Bone Conduction Lock
- cipher: 5< 5 5 j y<%n4C c f @
- check: Team 3: Bone Conduction Lock
- iv: 936a17793c1125c5843443a4b63c140

=====

- key length [b]: 192
- encryption time [us]: 2000
- decryption time [us]: 2484
- plain: Team 3: Bone Conduction Lock
- cipher: f f f f 0 s f f N & K V $ f ? X h
- check: Team 3: Bone Conduction Lock
- iv: f4b561824db9acf83f58dfb61ac4a7

=====

- key length [b]: 256
- encryption time [us]: 2332
- decryption time [us]: 2896
- plain: Team 3: Bone Conduction Lock
- cipher: V f 5 , b f f " f f f I f f f , k f f m w # ` r ) % f
- check: Team 3: Bone Conduction Lock
- iv: 2c6b9bb6b6d772360dbb482925fee

=====
```



# Security (cont.)

Time penalty:

- penalized for consecutive incorrect keys received by the lock
- Penalty for  $n$  consecutive incorrect key:

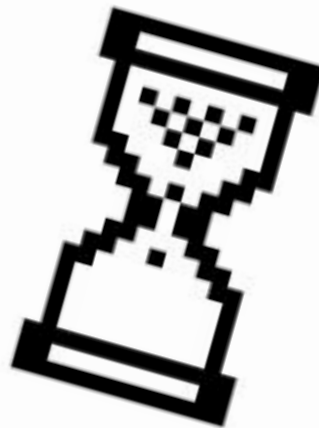
$n = 2 \rightarrow$  wait 10 seconds

$n = 5 \rightarrow$  wait 30 seconds

$n = 10 \rightarrow$  wait 60 seconds

$n > 10 \rightarrow$  wait  $60(n-10)+60$  seconds

To bruteforce all possible keys, ignoring the dynamic prompts, it would take **30916970 seconds = 375 days**





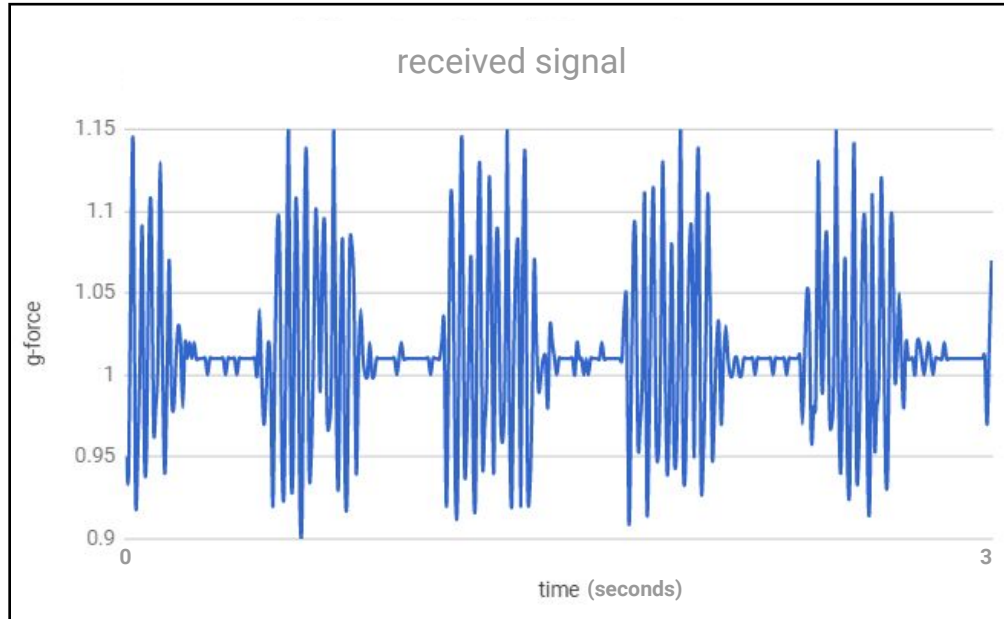
# Security (cont.)

11:08:29 | Tuesday - 2/27/18 LOCK ACTIVITY LOG

11:08:47	Tuesday - 2/27/18	finger detected	
11:08:57	Tuesday - 2/27/18	correct key;	lock UNLOCKED
11:09:01	Tuesday - 2/27/18	finger detected	
11:09:10	Tuesday - 2/27/18	correct key;	lock LOCKED
11:09:14	Tuesday - 2/27/18	finger detected	
11:09:20	Tuesday - 2/27/18	incorrect key;	do nothing
11:09:25	Tuesday - 2/27/18	finger detected	
11:09:29	Tuesday - 2/27/18	finger removed	
11:09:30	Tuesday - 2/27/18	imcomplete key;	do nothing



# Stability

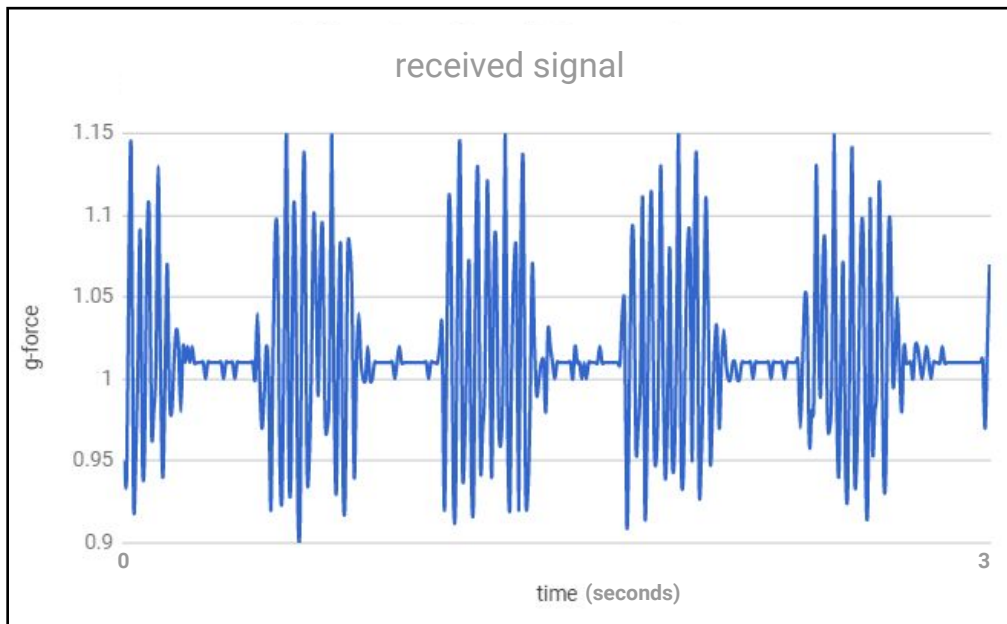


For bit extraction, must consider:

- sampling rate
- downsampling
- ramp up/down of LRA motor



# Stability (cont.)

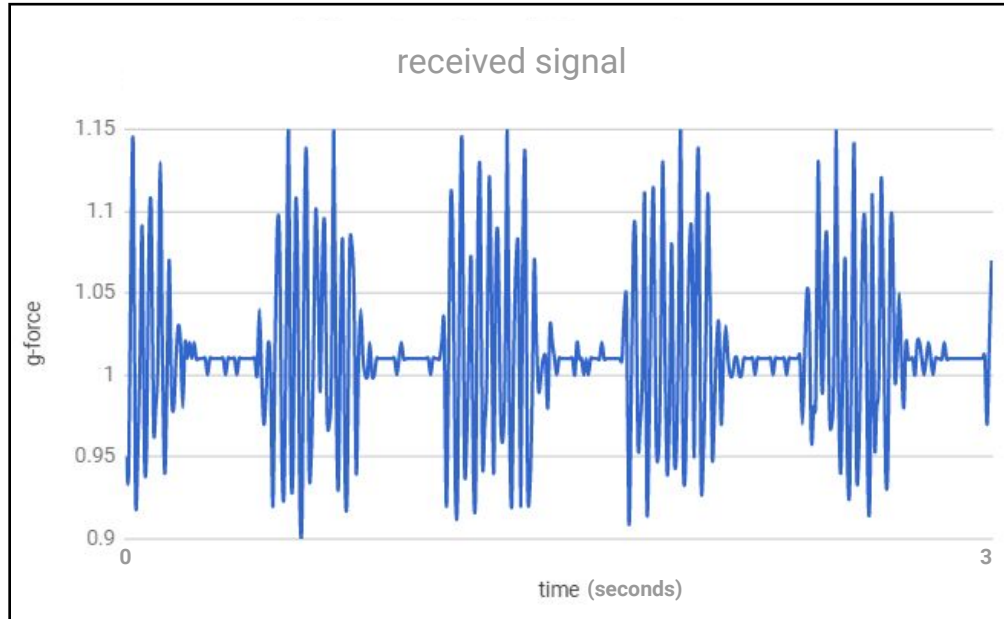


To decrease the time per vibration, implemented following algorithms with the **TI DRV2605L** motor driver:

- resonance frequency finder
- overdrive
- assisted braking



# Stability (cont.)



fastest vibration  $\rightarrow$  100 ms

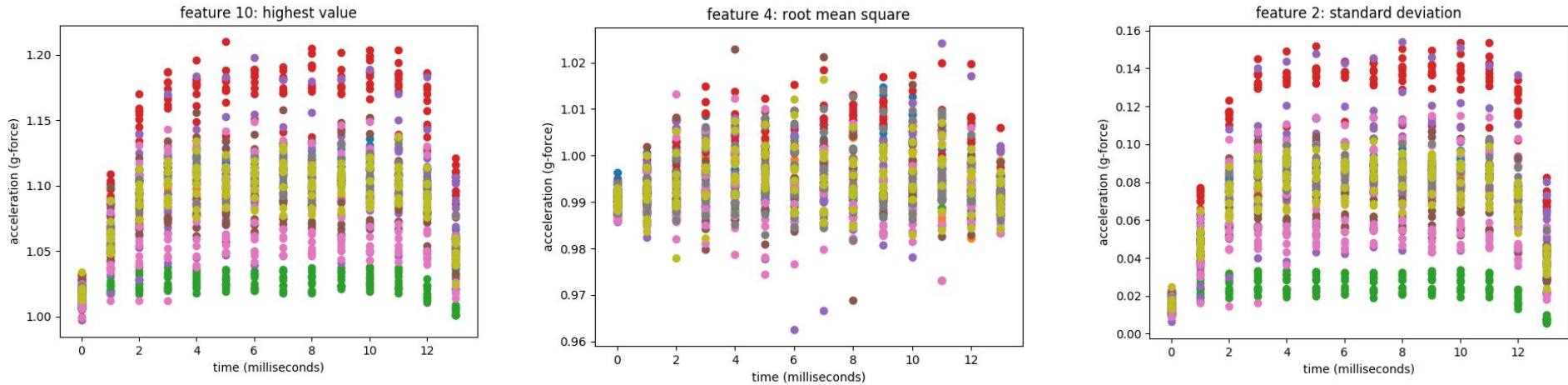
$\uparrow$  number of bits =  $\uparrow$  bit extraction error

false negative < 5% of trials

- use 290 ms vibrations



# Biometric Authentication (time domain analysis)

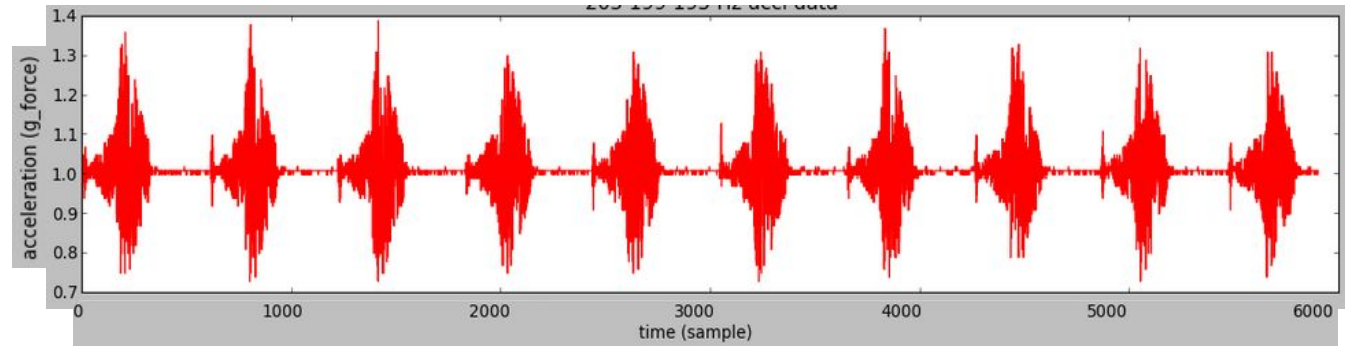


Other features: mean, variance, average deviation, zero-crossings, skewness, Kurtosis, lowest value

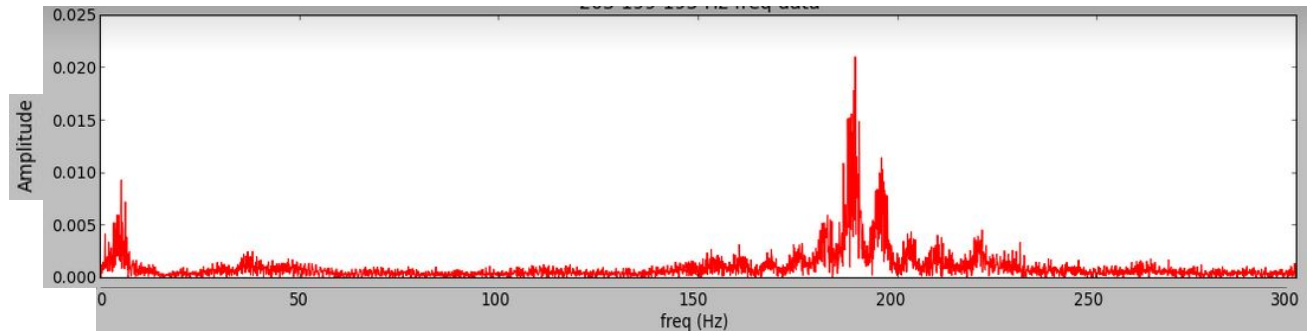


# Biometric Authentication (frequency domain analysis)

Continuous time domain signal reconstructed as discrete signal. Increasing frequency sweep to drive LRA motor.



Frequency response.





# Conclusion:

- Proved human bone is viable channel for communication
- Built hardware platform to use human bone as communication channel
- Showed hardware platform is stable and can operate as a lock
- Used hardware setup for explorations into biometric authentication



# Future Work

Integration with commercial devices



Use biomarkers to generate key





# Ethics



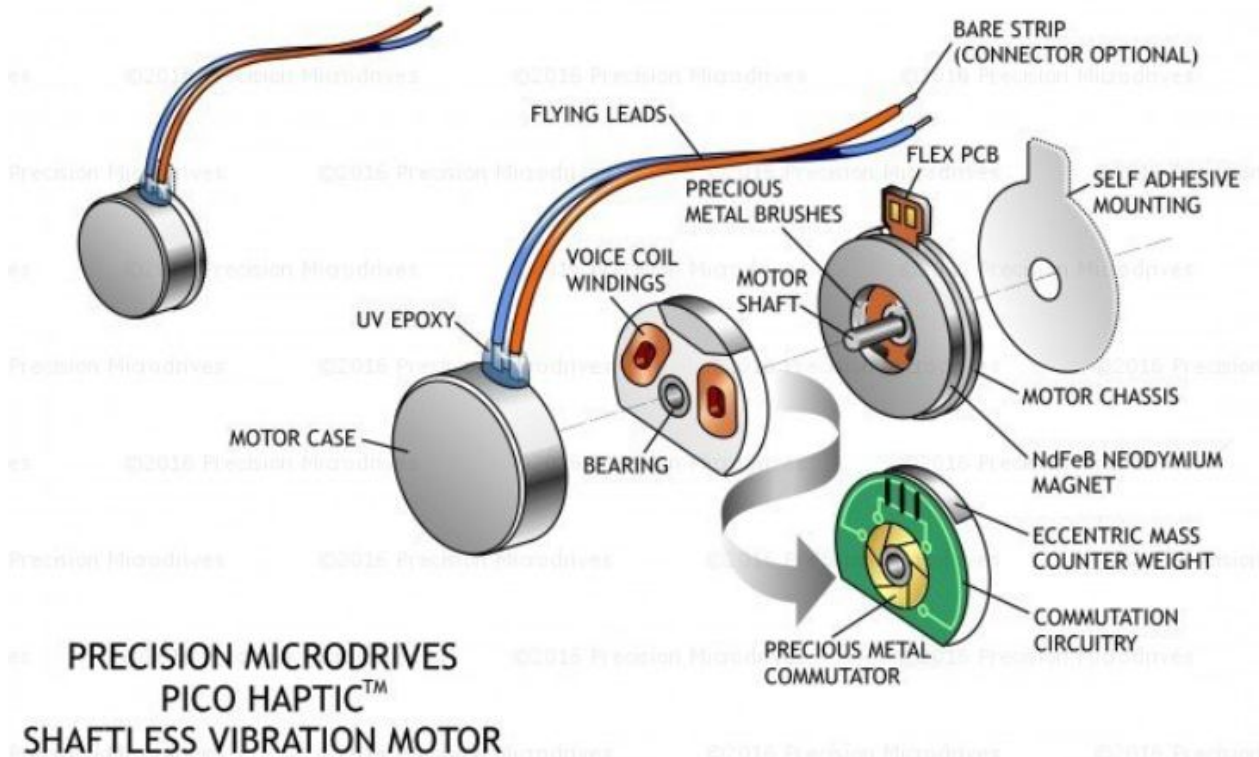


**Thank You!**

**Questions?**

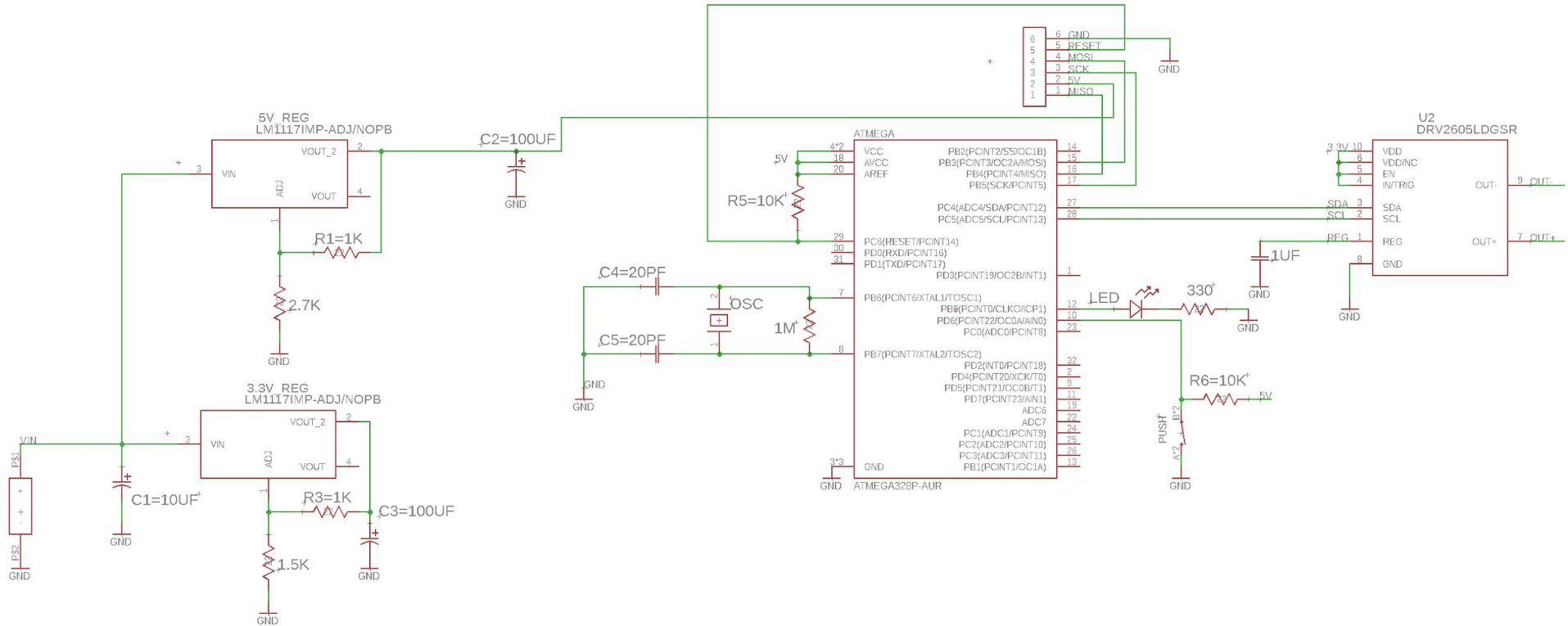


# Design: ERM Motor





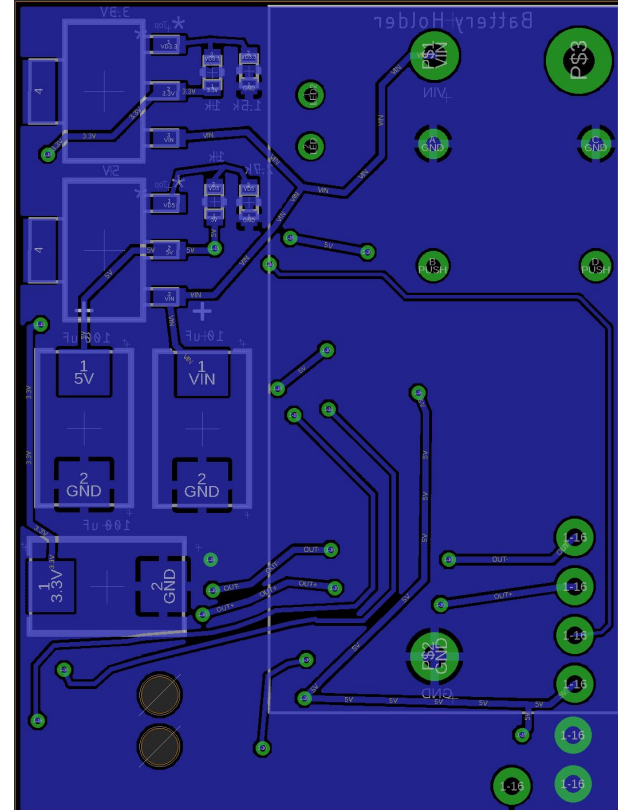
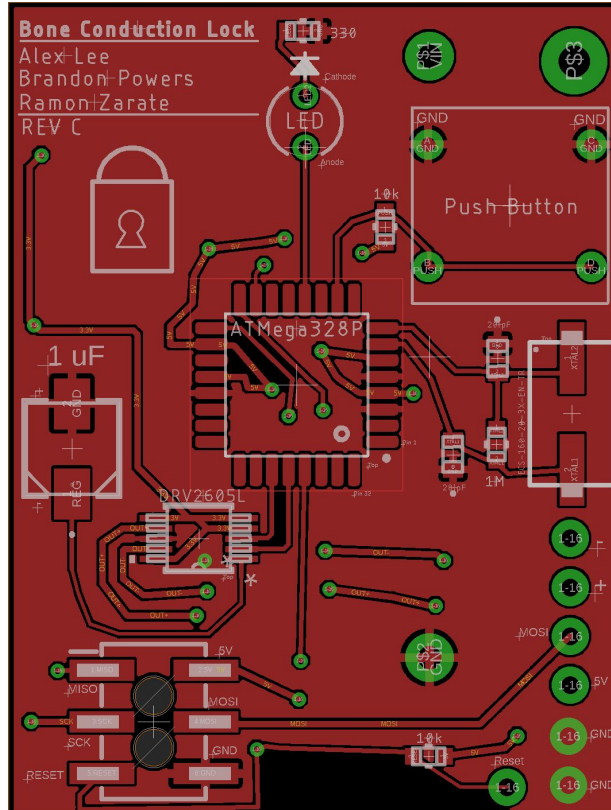
# Design: Band Module Schematic





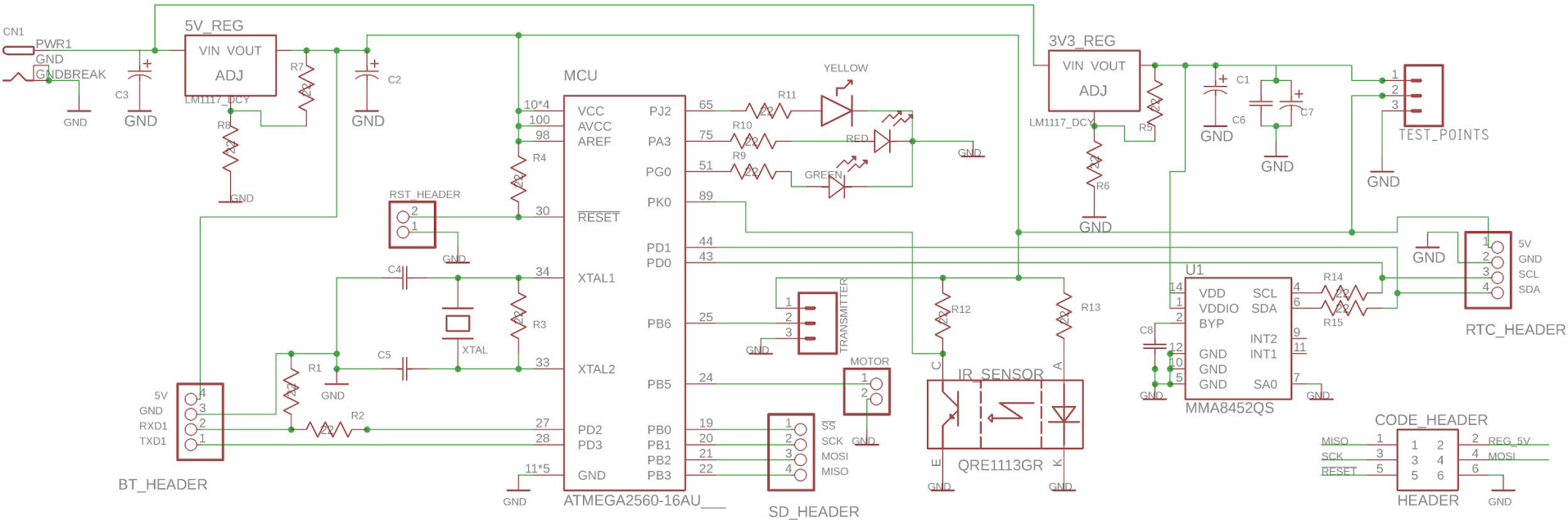
# Design: Band Module PCB Layout

- 30 mm x 40 mm
  - Size of Apple watch
- Power on bottom





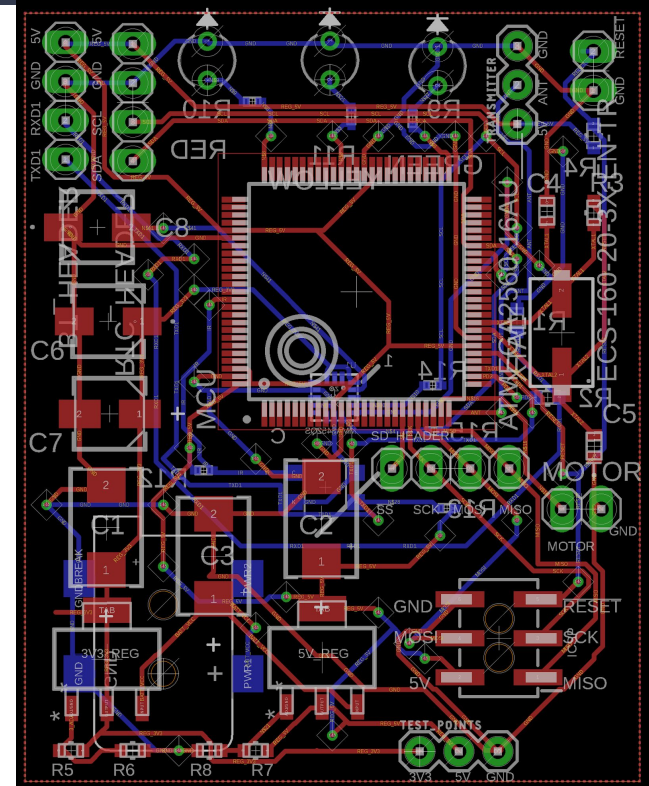
# Design: Lock Module Schematic





# Design: Lock Module PCB Layout

- 40 mm x 50 mm
- Mostly clear on bottom except for IR sensor, accelerometer
- Too dense to effectively display via powerpoint. Evidence visible on right





# Design: Power Supply Schematic

$$R_1 = R_3 = 1 \text{ k}\Omega$$

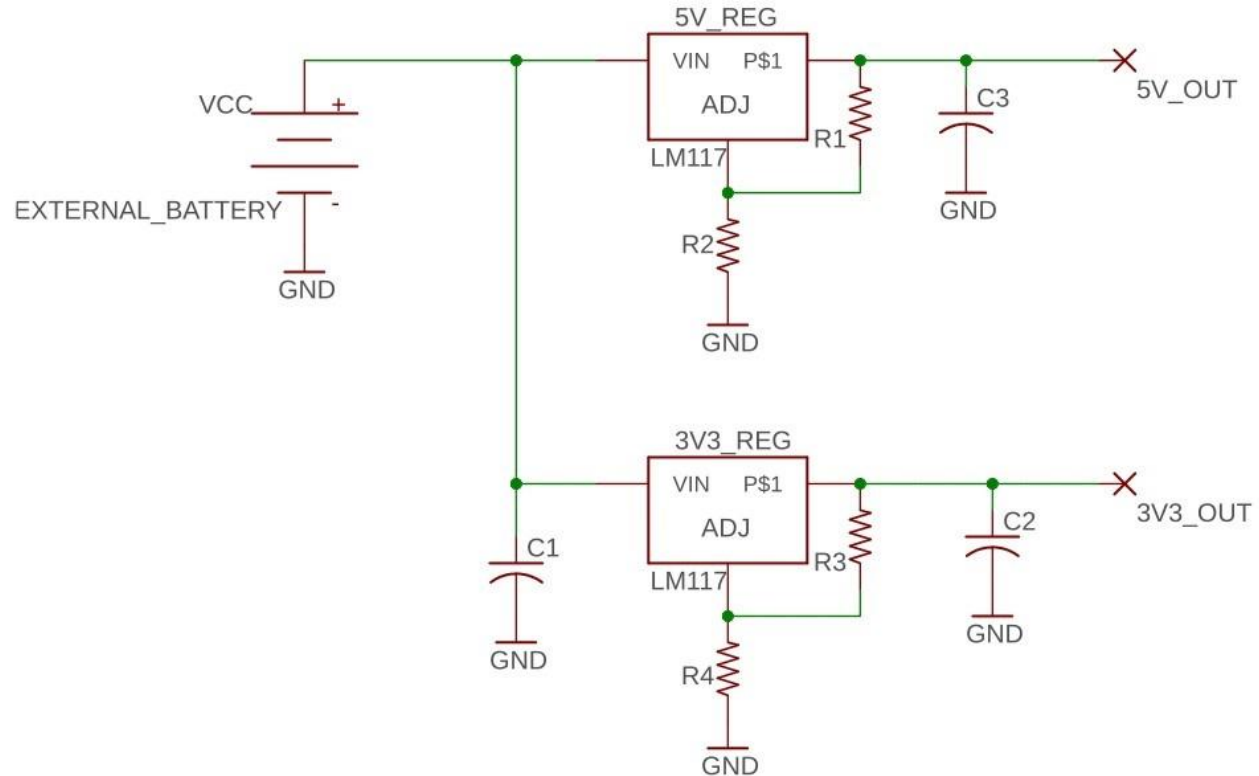
$$R_2 = 2.7 \text{ k}\Omega$$

$$R_4 = 1.5 \text{ k}\Omega$$

$$C_1 = 10 \text{ }\mu\text{F}$$

$$C_2 = C_3 = 100 \text{ }\mu\text{F}$$

$$V_{\text{out}} = 1.25(1 + (R_2/R_1))$$





# Design: Power Consumption Results

## Lock Module

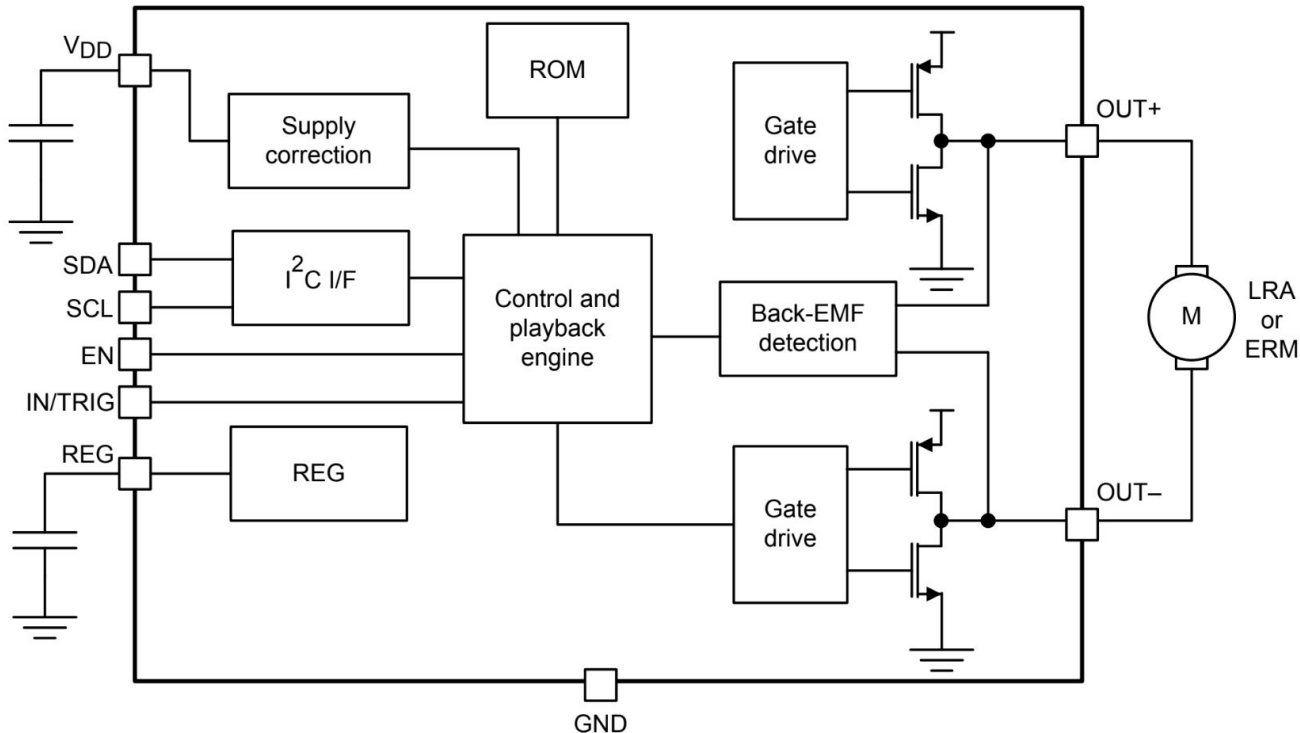
<b>3.3 V Regulator</b>	<b>Output Voltage</b>	<b>Theoretical Idle Current</b>	<b>Input Voltage</b>	<b>9 V</b>
	3.18 V	30 mA	<b>Battery Capacity</b>	<b>310 mAh</b>
<b>5 V Regulator</b>	<b>Output Voltage</b>	<b>Theoretical Output Current</b>	<b>Transmission Time</b>	<b>2 sec</b>
	4.78	100 mA	<b>Battery Life (Idle)</b>	<b>10.3 Hours</b>
			<b>Battery Life (Dynamic)</b>	<b>3.1 Hours</b>
			<b>Transmissions/Battery</b>	<b>5,580</b>

## Band Module

<b>3.3 V Regulator</b>	<b>Output Voltage</b>	<b>Idle Output Current</b>	<b>Input Voltage</b>	<b>7.5 V</b>
	5.48 V	20 mA	<b>Battery Capacity</b>	<b>110 mAh</b>
<b>5 V Regulator</b>	<b>Output Voltage</b>	<b>Output Current</b>	<b>Transmission Time</b>	<b>3 sec</b>
	4.75 V	66 mA	<b>Battery Life (Idle)</b>	<b>5.5 Hours</b>
			<b>Battery Life (Dynamic)</b>	<b>1.6 Hours</b>
			<b>Transmissions/Battery</b>	<b>1,920</b>



# Design: Motor Driver Supply Correction





# Band Module: RV Table Review

Requirements	Verification	Verification Status
1. Signal from push button is momentary	<ul style="list-style-type: none"><li>a. Display output from push button on serial monitor</li><li>b. Show the microcontroller only receives signal when button is pushed.</li></ul>	Yes
2. Pushing the button results in one complete transmission of the "key"	<ul style="list-style-type: none"><li>a. Wait five seconds without pressing the button and show that the motor does not generate a signal.</li><li>b. Push the button and observe the motor generate a complete signal on the serial monitor.</li><li>c. Push the button while the motor is generating a signal and show that it does not affect the completion of the current signal on the serial monitor.</li></ul>	Yes
3. Must be able to generate and transmit multiple complete "keys"	<ul style="list-style-type: none"><li>a. Transmit two consecutive signals by pressing the button once, wait for the first signal to transmit completely, then press the button again to transmit the second complete signal.</li><li>b. Show two complete signals were transmitted on serial monitor.</li></ul>	Yes

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# Lock Module: RV Table Review

Requirements	Verification	Verification Status
1. Accelerometer output has full-scale range of $\pm 2$ g with minimum sampling rate of 800 Hz to be read by microcontroller	<ul style="list-style-type: none"><li>a. Sweep frequency range using function generator to capture frequency response.</li><li>b. Show that frequency response does not get clipped at 2 g on the serial monitor.</li></ul>	Yes
2. Accelerometer output has 0.01 g precision and maximum noise floor of 1.02 g	<ul style="list-style-type: none"><li>a. Show the output has 0.01 g precision on serial monitor.</li><li>b. Show accelerometer has maximum noise floor of 1.02 g on the serial monitor.</li></ul>	Yes
3. IR sensor detects finger when in contact with the lock module target area	<ul style="list-style-type: none"><li>a. Send IR sensor output to microcontroller.</li><li>b. Display sensor output on the serial monitor.</li><li>c. Show change in IR sensor output is a function of proximity of finger when within one inch of the lock module target area.</li></ul>	Yes
4. Status LEDs show state of the lock	<ul style="list-style-type: none"><li>a. When lock is in locked state (<math>0^\circ</math>), the red LED is on.</li><li>b. When lock is in unlocked state (<math>90^\circ</math>), the green LED is on.</li></ul>	Yes



# Power Supply: RV Table Review

Requirements	Verification	Verification Status
3. Must output 3.3 V $\pm$ 5% with a current load of up to 800 mA	<ul style="list-style-type: none"><li>d. Measure the output voltage using a multimeter.</li><li>e. Vary the load current by changing load resistance.</li><li>f. Show on multimeter that voltage stays in its tolerance range as current is varied up to 800 mA.</li></ul>	Yes
4. Must output 5 V $\pm$ 5% with a current load of up to 800 mA	<ul style="list-style-type: none"><li>d. Measure the output voltage using a multimeter.</li><li>e. Vary the load current by changing load resistance.</li><li>f. Show on multimeter that voltage stays in its tolerance range as current is varied up to 800 mA.</li></ul>	Yes
3. Maintain a temperature below 120°C	<ul style="list-style-type: none"><li>b. Use an IR thermometer or IR camera when the IC is in operation to show that the temperature stays below 120°C.</li></ul>	Yes