

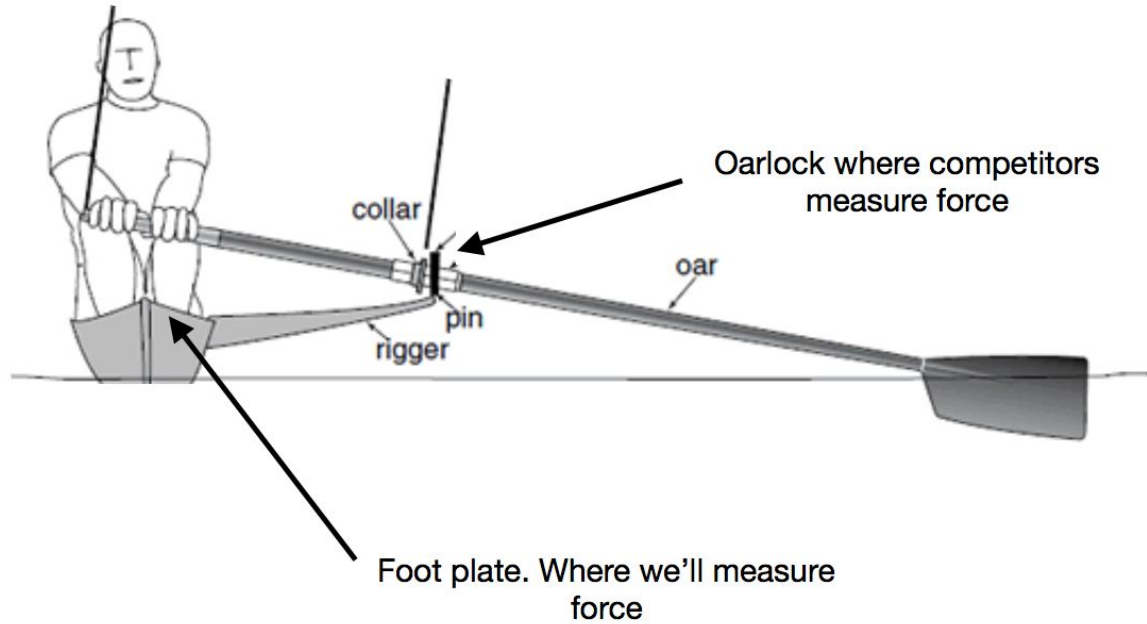


# Rowing Tracker

Group #47: Jai Agarwal, Nathan  
Zurcher, Kerem Gulpinar



# Introduction

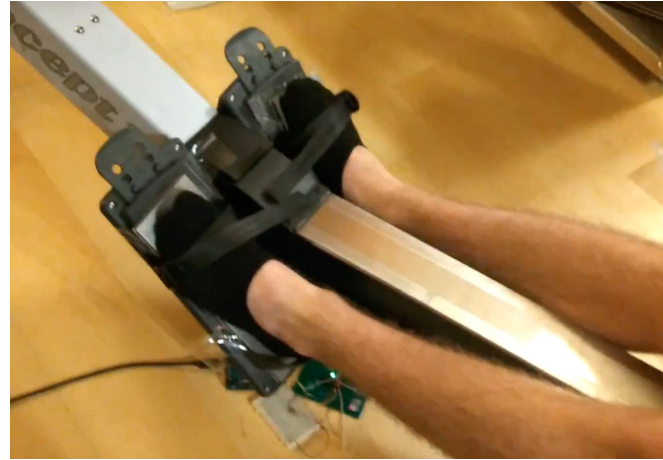


# Introduction

- New method to measure an individual rower's effort on the water
- Existing solutions are extremely costly

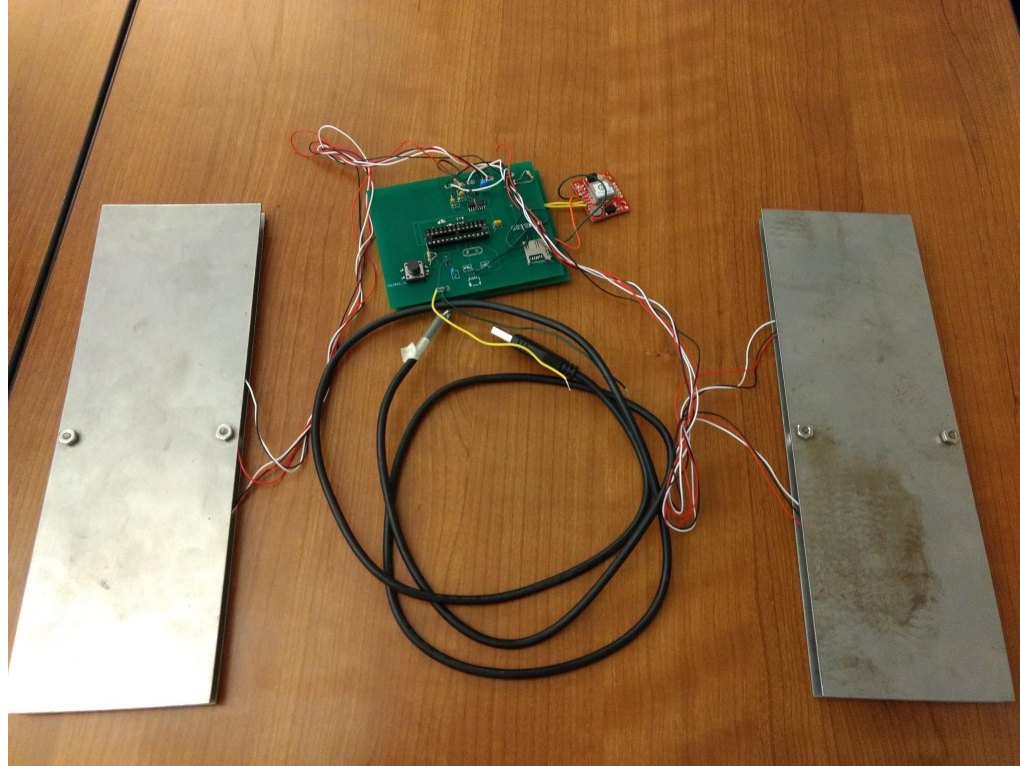


Peach Innovations Solution  
costs \$8370 to outfit an 8



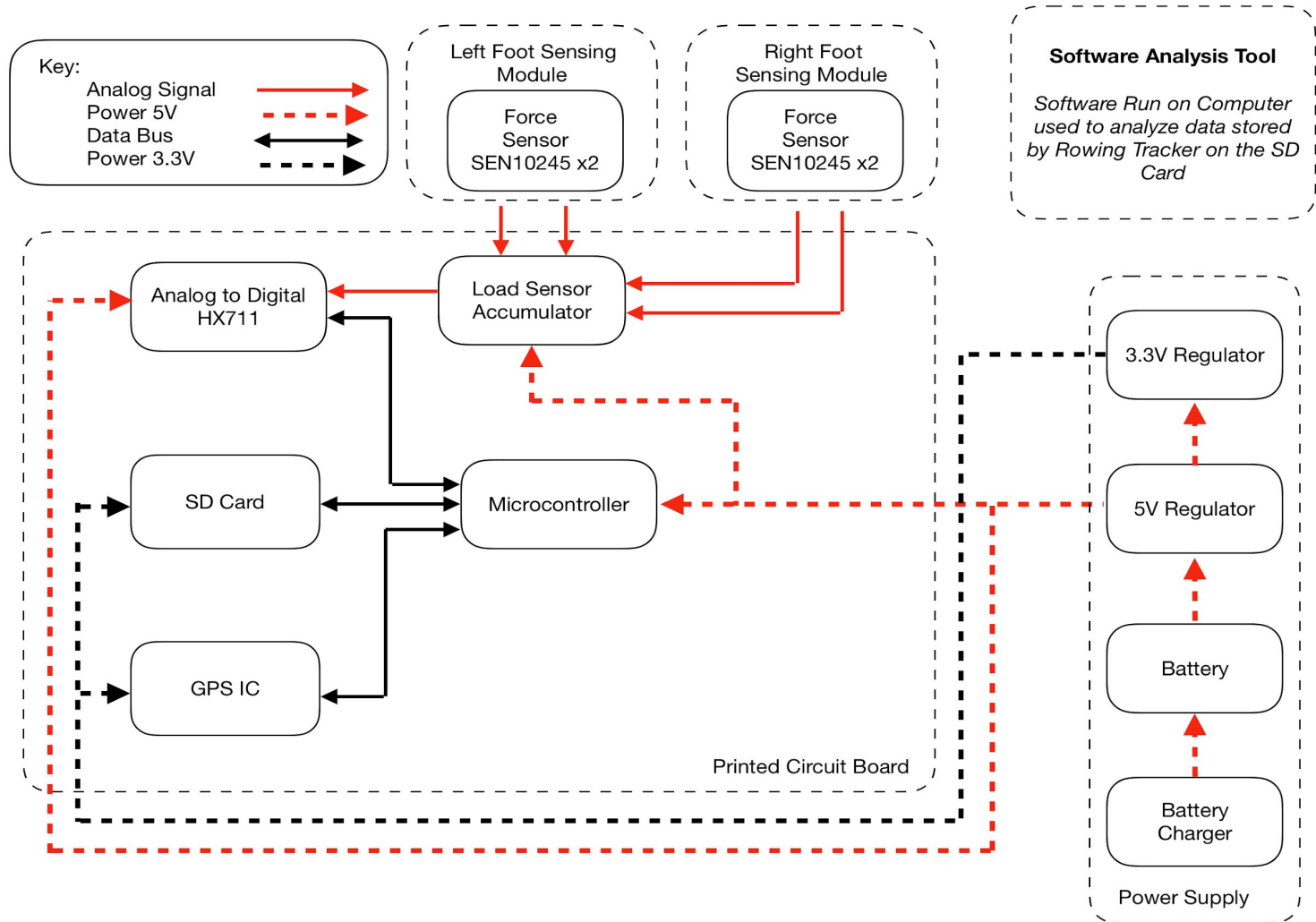
Our solution would cost  
\$1016 to outfit an 8 in parts.

# Rowing Tracker



# Objectives

- Create a cheaper alternative
- Measure through the feet
- Be able to provide all information a Rowing Machine would provide
  - Including wattage, strokes per minute, and pace(time/500 meters)



# Components

## Hardware:

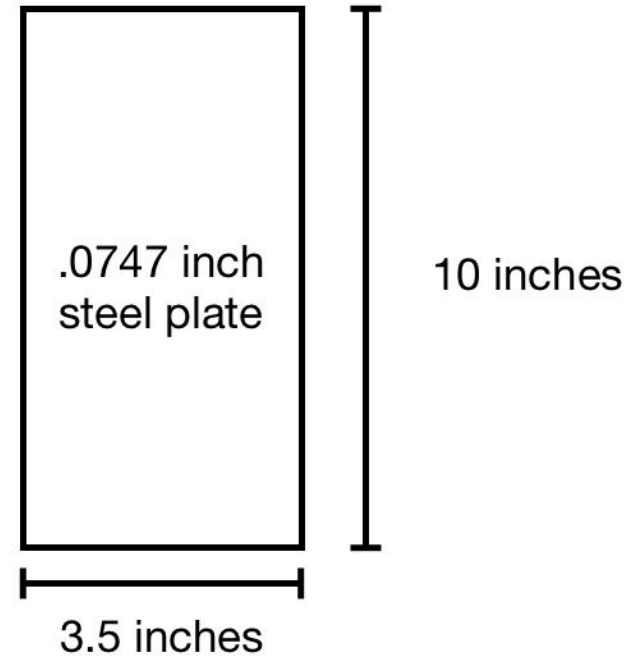
- Foot Sensing Module
- Control Unit / Printed Circuit Board
- Power Supply

## Software:

- Microcontroller Program
- Software Analysis Tool

# Foot Sensing Module

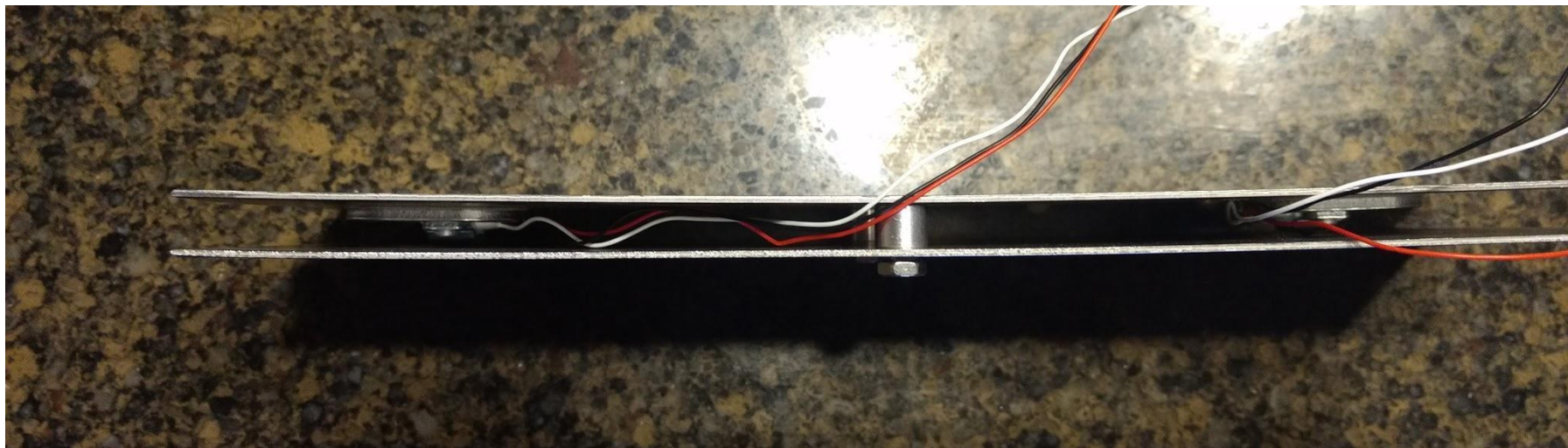
- Detect force up to 100kg (220.4lbs) per foot
- Compatible with existing boat footwear
- Robust - steel plates
- 2 3-wire strain gauges per foot
  - Capable of carrying 50kg (110.2lbs) each
- 1.19lbs per foot module





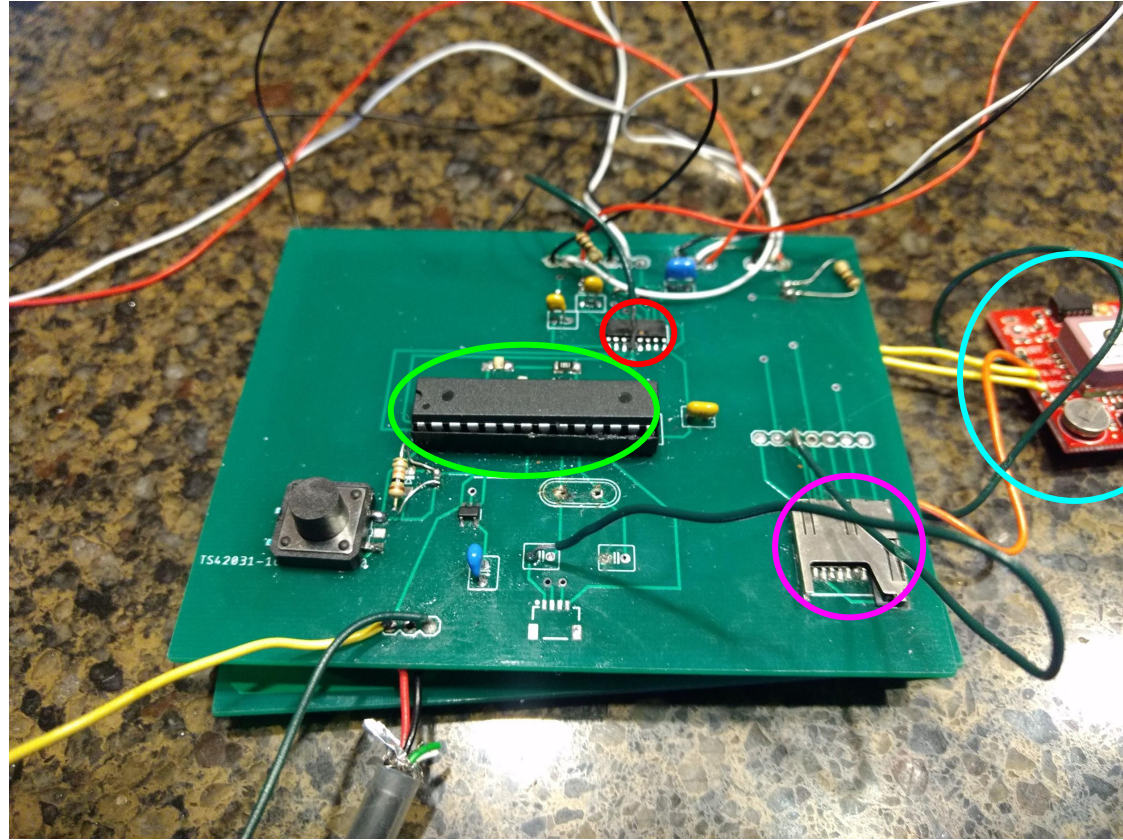
# Force Sensing Module - Final Product





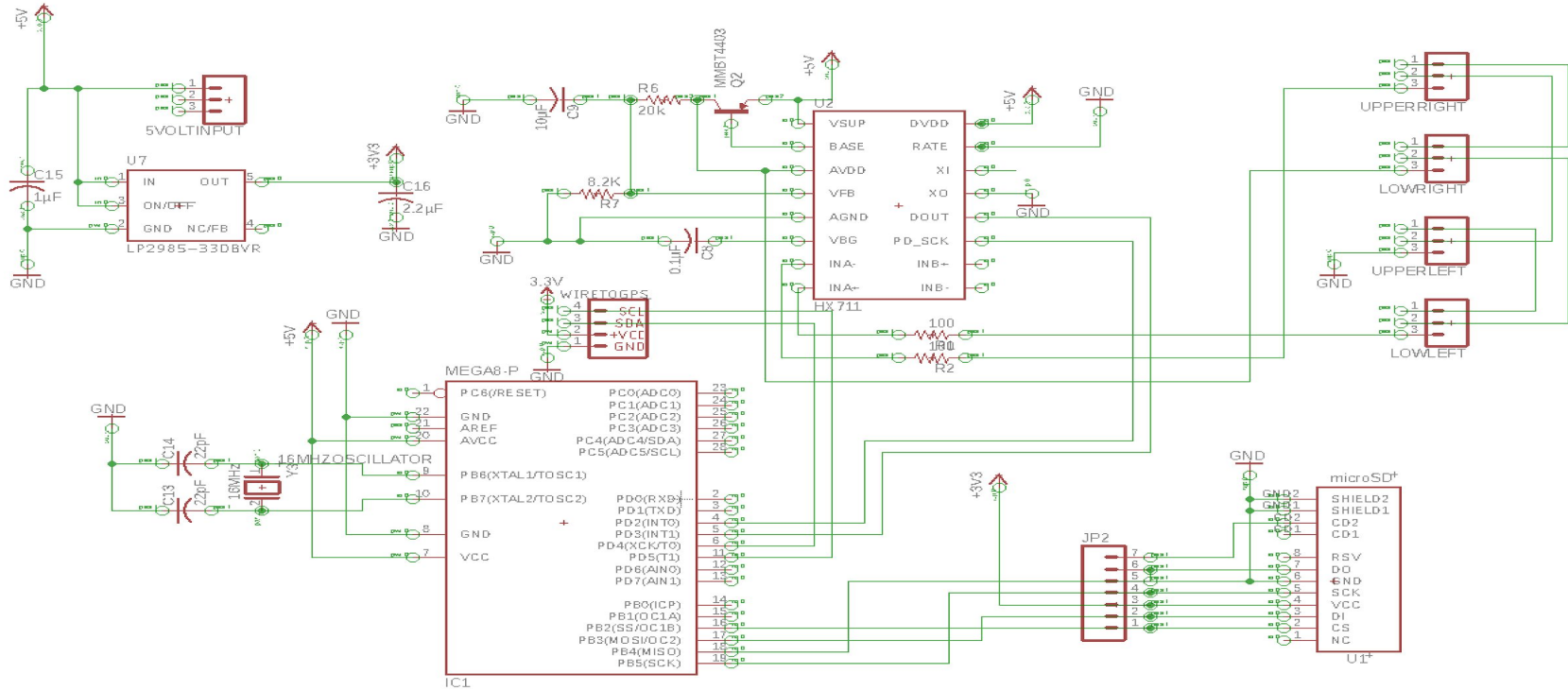
# Control Unit

- Components
  - ATmega328 Microcontroller
  - HX711 Analog to Digital Converter
  - SanDisk 8GB microSD Card
  - XA1110 GPS (external)
- Inputs
  - 4 3-wire strain gauge inputs (analog)
  - GPS via I2C
  - Reset button
  - 5 Volts
- Outputs
  - Red and Green LED
  - SD card





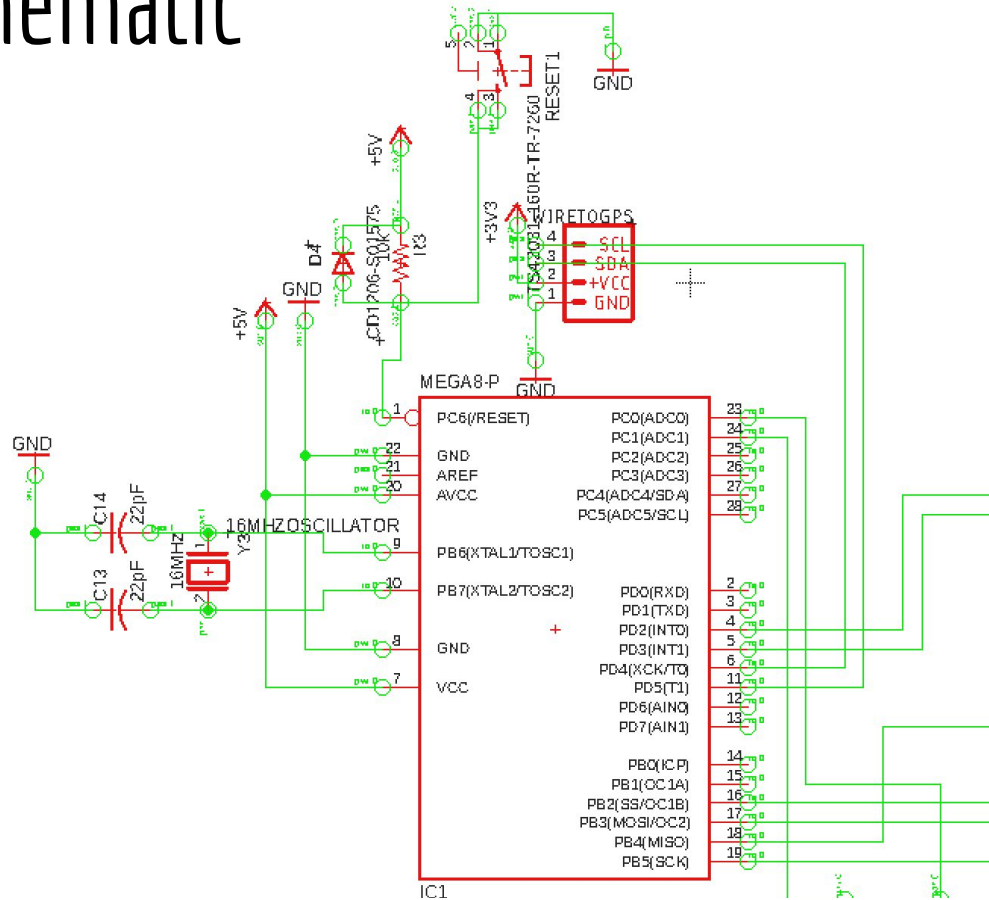
# Control Unit - Schematic



# ATMega328 Process

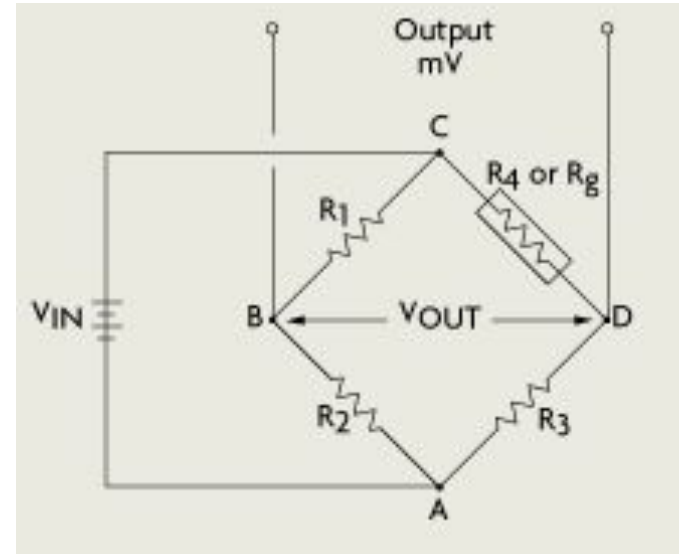
- Activate microSD Card
- Generate new CSV file with unique name
- Receive serial input from A to D
- Receive I2C input from GPS
- Record CSV lines with GPS time stamp and force input

# ATMega328 Schematic

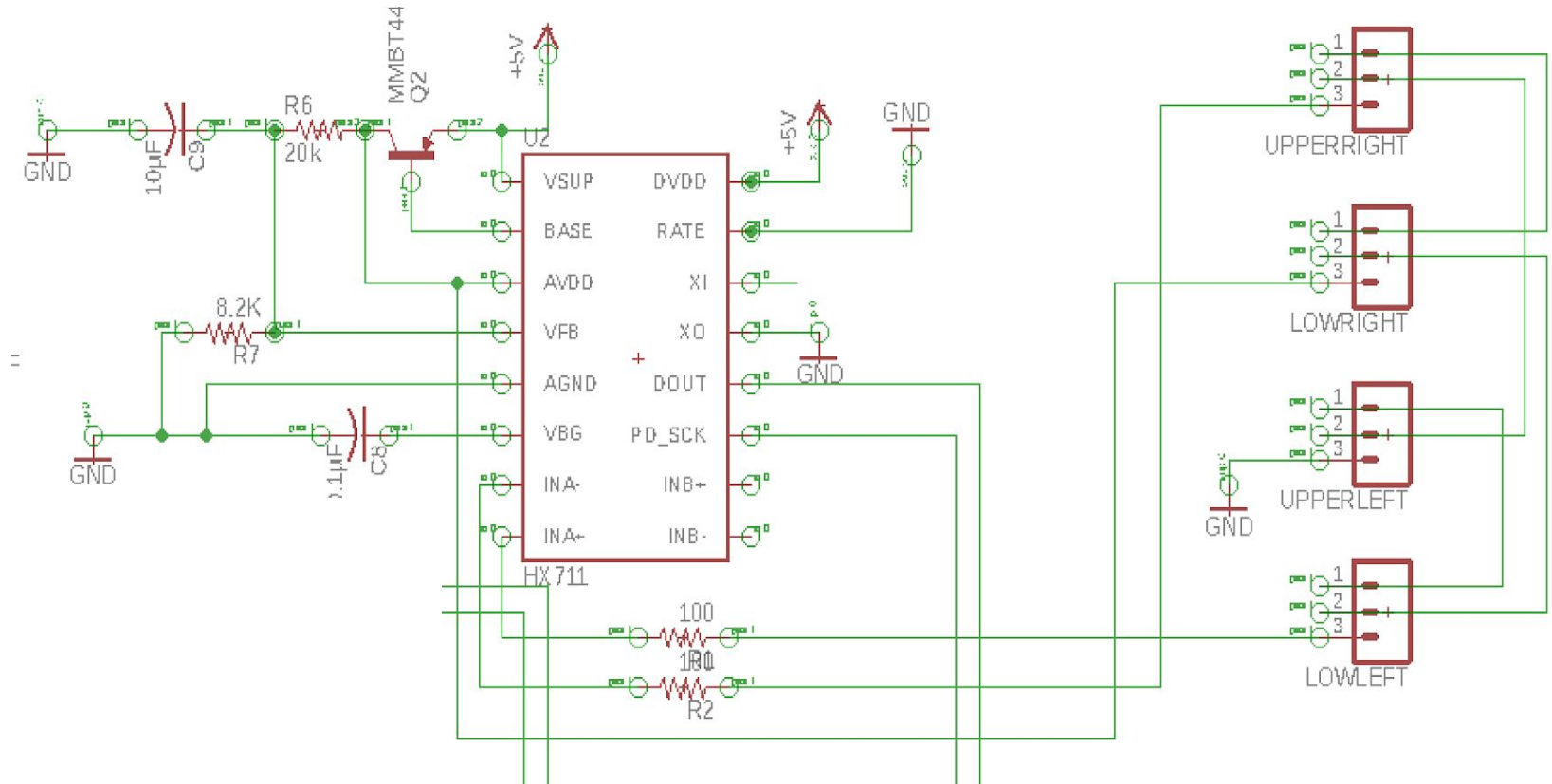


# Control Unit - Analog to Digital Converter

- No need for individual sensor values
- Wheatstone Bridge sums 4 different strain gauge inputs
- Allows use of only one A to D converter
- 24 bit converter generates large range



# Control Unit - Analog to Digital Converter(Schematic)



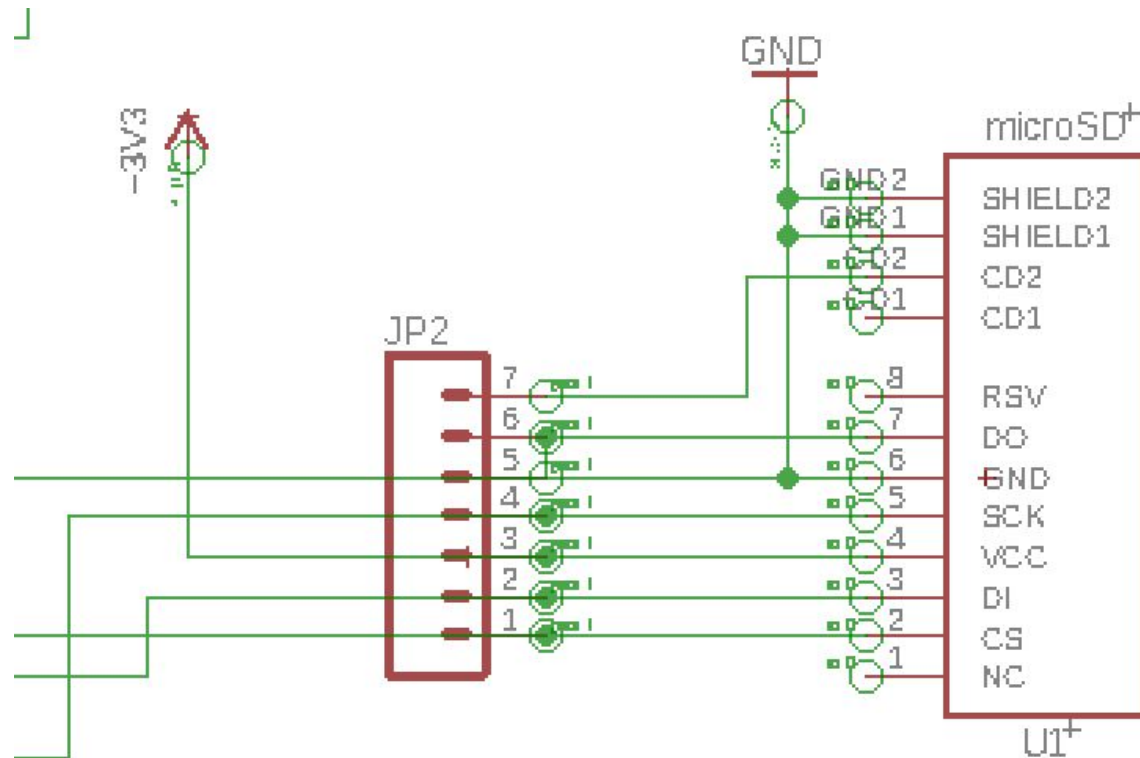


# Control Unit - microSD Card

- SanDisk Ultra 8GB Class 10 UHS-I
- Listed write speed of 100 Mbits/second in SPI mode
- 8GB card allows for ~652 hours of constant recording

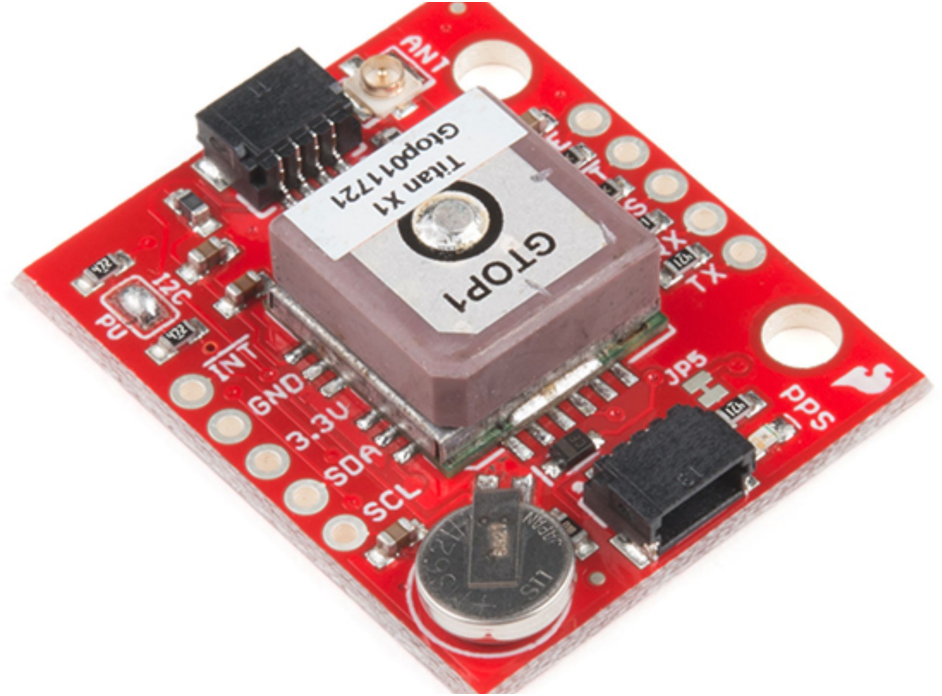


# Control Unit - SD Card(Schematic)



# Control Unit - Outsourced Components

- XA1110 - GPS Module
  - Backup battery -- Quicker Fix
  - Small Profile
  - Very sensitive
- Battery Pack/5V Supply



# 5 Volt Power Supply (Eliminated)

- 5V output
- 2500 mAh to allow 6-10 hours of operation
- Sustained loads of 200mA; peaks of 250mA
- Requirements are easily met by readily available product
  - Save time and money

# Power Supply

- 5500 mAh allows more than 20 hours of operation assuming total load of 200mA
- 5 Volt 1 Amp output greatly exceeds requirements



# Software Analysis Tool

- Input: Data from SD card
- Output: Rowing Machine outputs and further statistics
- Smooth Data
- Calculate Rowing Machine values
  - wattage, strokes per minute, and pace(time/500 meters)

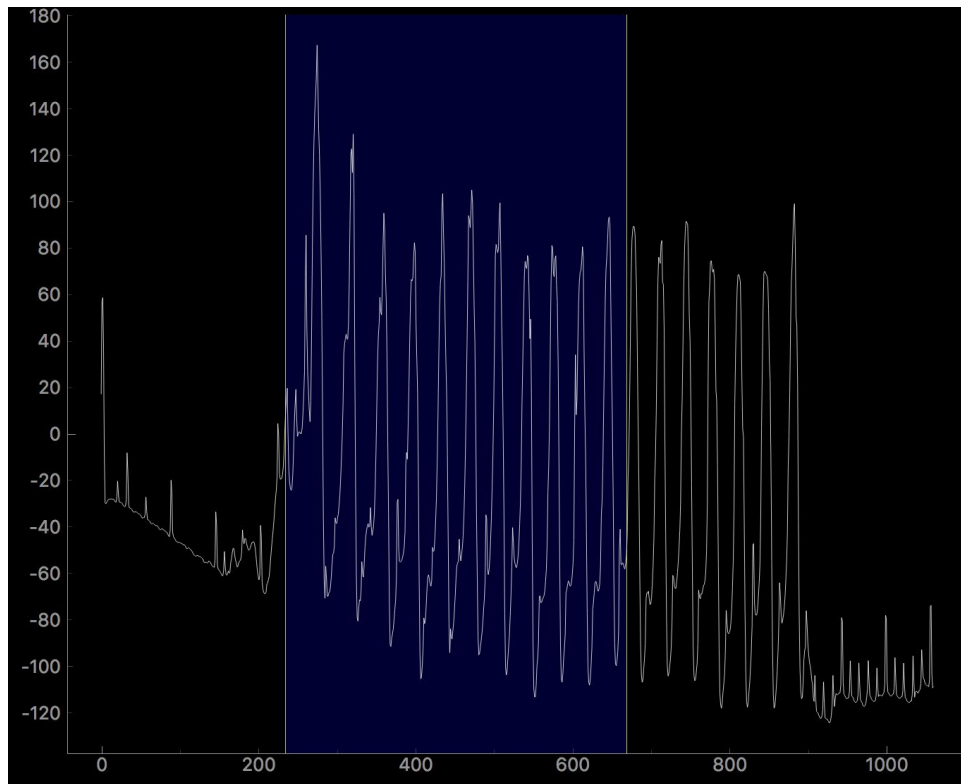
# Data:

## TEST9

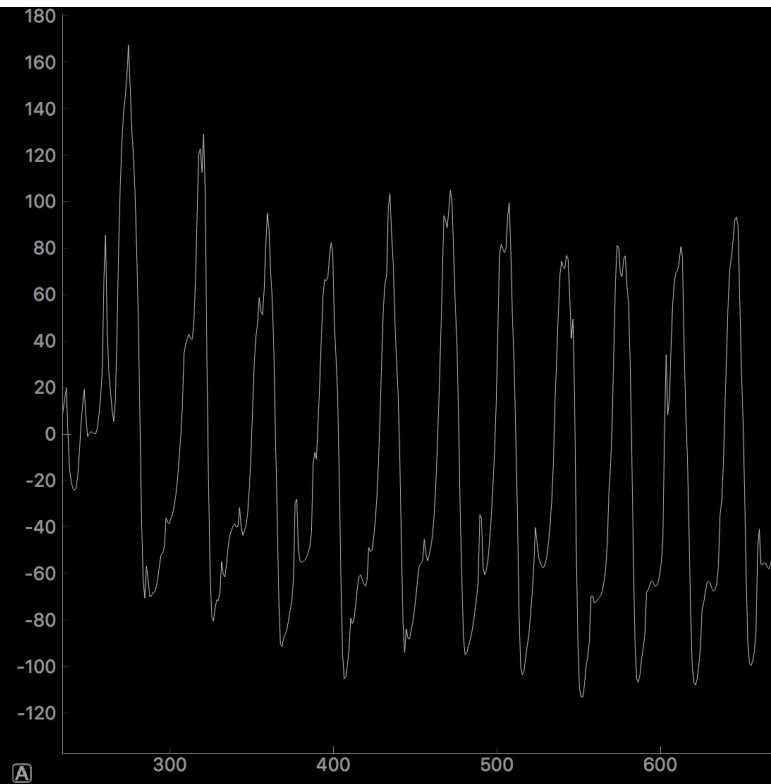
dd/mm/yy	hours	minutes	seconds	lbs of force	latitude	longitude	speed
210418	1	47	1	31.76	40.091823	-88.238594	2.1298
210418	1	47	1	30.99	40.091823	-88.238594	2.1298
210418	1	47	1	30.09	40.091823	-88.238594	2.1298
210418	1	47	1	31.51	40.091823	-88.238594	2.1298
210418	1	47	1	34.86	40.091823	-88.238594	2.1298
210418	1	47	1	37.14	40.091823	-88.238594	2.1298
210418	1	47	1	39.92	40.091823	-88.238594	2.1298
210418	1	47	1	44.24	40.091823	-88.238594	2.1298
210418	1	47	2	49.42	40.091823	-88.238594	2.1298
210418	1	47	2	52.81	40.091823	-88.238594	2.1298
210418	1	47	2	54.94	40.091823	-88.238594	2.1298
210418	1	47	2	58.14	40.091823	-88.238594	2.1298
210418	1	47	2	62.98	40.091823	-88.238594	2.1298

# Interface

Region Selection



Zoomed Selection

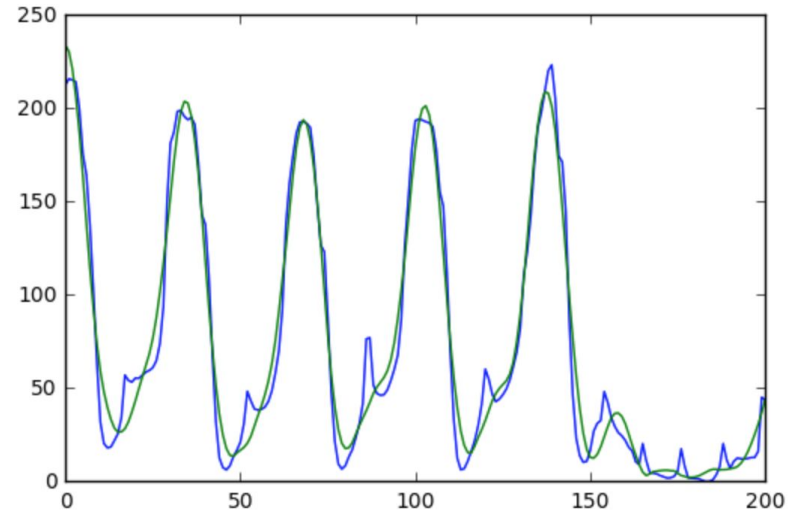




# Data Analysis

- Provides:
  - Graphical representation (smoothed)
    - Savitzky-Golay Filter
  - Rowing Machine Information

time: 18.0 seconds  
average force: 325.048171277 N  
number of strokes: 4 strokes  
number of strokes per minute: 13.3333333333 strokes/min  
average speed of boat: 0.638023168317 km/hr  
approximate distance of boat : 3.19011839368 m  
approximate pace of boat: 47 minute(s) 1 second(s)  
approximate pace of boat: 3 minute(s) 2 second(s)  
watts: 57.6078972235 W



# Requirements and Verifications -Force Sensing Module

- Footplate can accurately record a stroke
  - Force sensors did max at any point throughout the stroke
  - Enough samples taken to clearly define force curve

# Requirements and Verification - Power Module

- PCB low power consumption.
  - Wired PCB through ammeter found total current draw of 70mA
  - Slightly greater than expected 52mA
- Resistor Load test of 500mA on battery pack
  - Voltage sag of less than 0.15 volts
  - No overheating of battery pack or vias
- Resistor Load test of 350mA on 3.3V regulator
  - Voltage sag of .10 volts
  - Regulator did not overheat throughout 15 minutes of load
- Ran device on battery pack for 6 hours
  - Device charge indicator showed no change

# Requirements and Verification - PCB Components

- SD Card
  - Capable of recording CSV data as generated without slowing system
    - 138 second test generated 47KB = 340.5KB/second
    - 340.5KB/second  $\rightarrow$  2.7Mbits/second  $<$  100Mbits/second max
- GPS Unit
  - Generate 1 sample/second of date, time, latitude, longitude, and speed
    - Data was printed to serial out and displayed on computer
    - Time/Date was accurate within 5 seconds
    - Position/speed accurate within 10 seconds(outdoors)
  - Low power usage
    - Consumed 60mA while seeking
    - Consumed only 40mA once lock
    - Well within design parameters for battery life

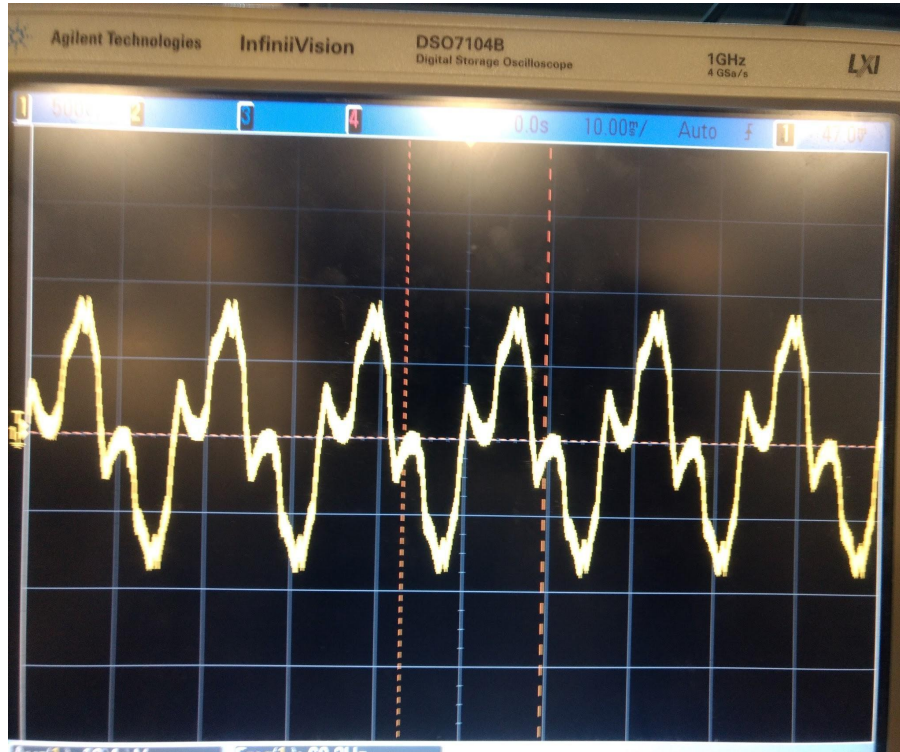
# Requirements and Verification - Software Module

- Have an interface that would be easy for users to use
- Presents information that Rowing Machine would
  - wattage, strokes per minute, and pace(time/500 meters)

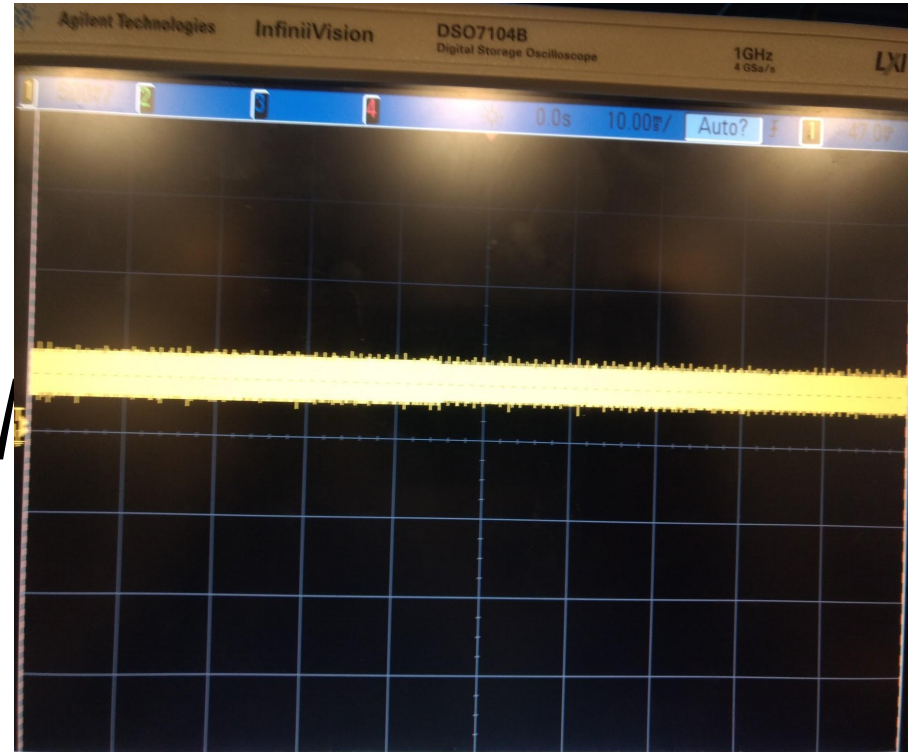
# RV-Troubleshooting

- Unstable behavior
- Worked perfectly on Arduino Uno
- Isolated Issue to External Clock using Oscilloscope

# RV-Troubleshooting



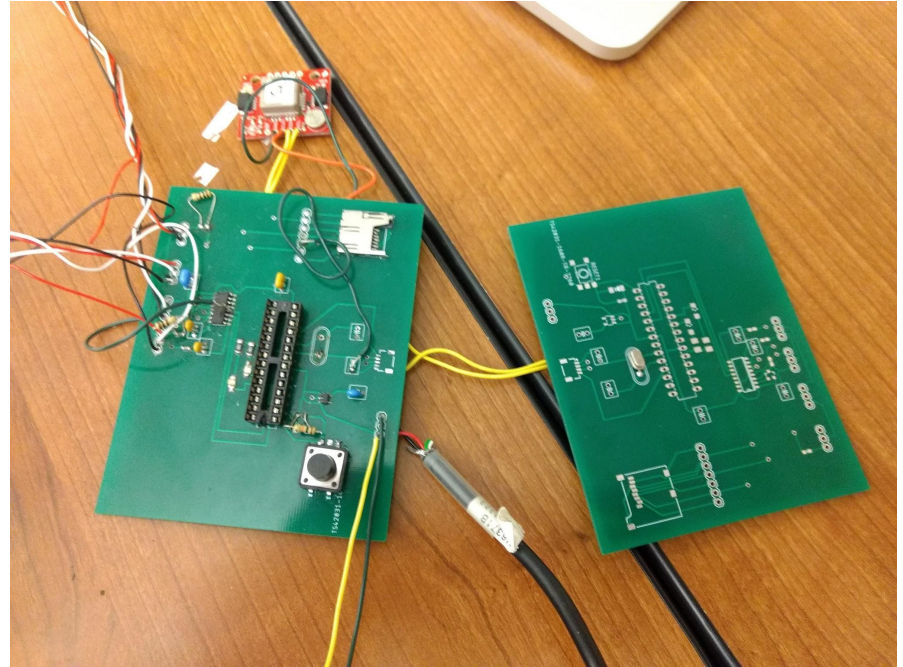
Oscillator Pins Arduino



Oscillator Pins PCB

# RV-Troubleshooting

- Moved new oscillator to proto board
- PCB leads for oscillator thought to be faulty
- Wire distance too great led to intermittent faults





# Component Cost

Component	Cost
Load Sensors -50kg (x4)	\$39.90
Steel Plates	\$12.00
XA1110 GPS	\$44.95
PCB parts	\$30.71
Total	\$127.56

# Future Work

- Expand system to outfit an entire boat
- Improve accuracy through more quantitative analysis
- Improve system waterproofing
- Easy connect/disconnect of foot plates from control unit



VO2 Mask

Questions?