

Section (Check One) MWF 10am \_\_\_\_\_ TR 12:30pm \_\_\_\_\_

1. \_\_\_\_\_ / 25    2. \_\_\_\_\_ / 25

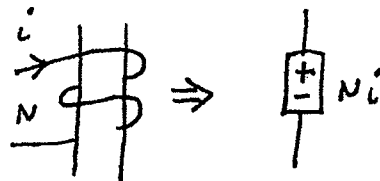
3. \_\_\_\_\_ / 25    4. \_\_\_\_\_ / 25    Total \_\_\_\_\_ / 100  
30    20

Useful information

$\sin(x) = \cos(x - 90^\circ)$      $\bar{V} = \bar{Z}\bar{I}$      $\bar{S} = \bar{V}\bar{I}^*$      $\mu_0 = 4\pi \cdot 10^{-7} \text{ H/m}$

$\int_C \mathbf{H} \cdot d\mathbf{l} = \int_S \mathbf{J} \cdot \mathbf{n} da$      $\int_C \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot \mathbf{n} da$      $\mathfrak{R} = \frac{l}{\mu A}$      $MMF = Ni = \phi \mathfrak{R}$

$\mathfrak{R} = \frac{l}{\mu A}$      $B = \mu H$      $\phi = BA$      $\lambda = N\phi$      $\lambda = Li$  (if linear)



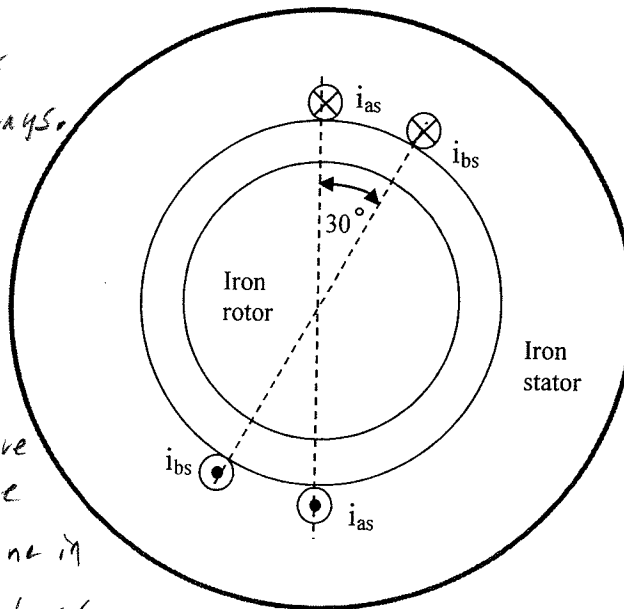
$W_m = \int_0^\lambda i d\hat{\lambda}$      $W_m' = \int_0^i \lambda d\hat{i}$      $W_m + W_m' = \lambda i$      $f^e = \frac{\partial W_m'}{\partial x} = -\frac{\partial W_m}{\partial x}$      $x \rightarrow \theta$

$f^e \rightarrow T^e$

$EFE = \int_a^b i d\lambda$      $EFM = -\int_a^b f^e dx$      $EFE + EFM = W_{mb} - W_{ma}$      $\lambda = \frac{\partial W_m'}{\partial i}$      $i = \frac{\partial W_m}{\partial \lambda}$

**Problem 1. (25 points)**

The device below has two coils separated by 30 degrees as shown. Find an expression for the torque that must be tolerated by the coil installations (i.e. the torque created by the currents will try to move the coils) if the device radius is 0.01 meters, the depth into the paper is 0.02 meters, the air gap is 0.001 meters, and each current is 10 Amps DC. The coils are identical and each has 50 turns. The air gap permeability is  $\mu_0$  and the permeability of the iron is infinite.



Radius = .01m  
 $l = .02m$   
 $g = .001m$   
 $i_{as} = 10A$   $i_{bs} = 10A$   
 $\theta = 30^\circ$

Could solve this problem two ways. One way would solve for the H quantities in the four areas. This will take a long time and will give a triangle wave for  $L_{asbs}$  as done in the book and class.

An easier way is to use a sinusoidal approximation for the flux linkage for two coils separated by an angle  $\theta$ :

$$\left. \begin{aligned} \lambda_{as} &= L_s i_{as} + m \cos \theta i_{bs} \\ \lambda_{bs} &= m \cos \theta i_{as} + L_s i_{bs} \end{aligned} \right\} (\theta = 30^\circ \text{ in this problem})$$

$$w'_m = \left( \frac{1}{2} L_s i_{as}^2 \right) + (m \cos \theta i_{as} i_{bs} + \frac{1}{2} L_s i_{bs}^2) \Rightarrow T^e = -m \sin \theta i_{as} i_{bs}$$

For  $\theta = 30^\circ$ ,  $i_{as} = 10A$ ,  $i_{bs} = 10A$ ,  $T^e = -50m \text{ N.m.}$

Maximum coupling is when  $\theta = 0^\circ$ . The flux linking the as coil due to  $i_{bs}$  would be  $\Phi = \mu_0 H_{out} \pi R l$  where H is due to  $i_{bs}$ . This would satisfy  $(H_{out, left} - H_{out, right}) g = 50 \times 10$

By conservation of flux,  $\mu_0 H_{out, left} \pi R l + \mu_0 H_{out, right} \pi R l = 0$

$$H_{out, left} = \frac{500}{2g} \text{ so } 50 \mu_0 \frac{500}{2g} \pi R l = 10m$$

$m = .001H$   $T^e = -.05 \text{ N.m.}$

**Problem 2. (25 points.)**

An electromechanical system is described by the following flux-linkage vs current characteristic:

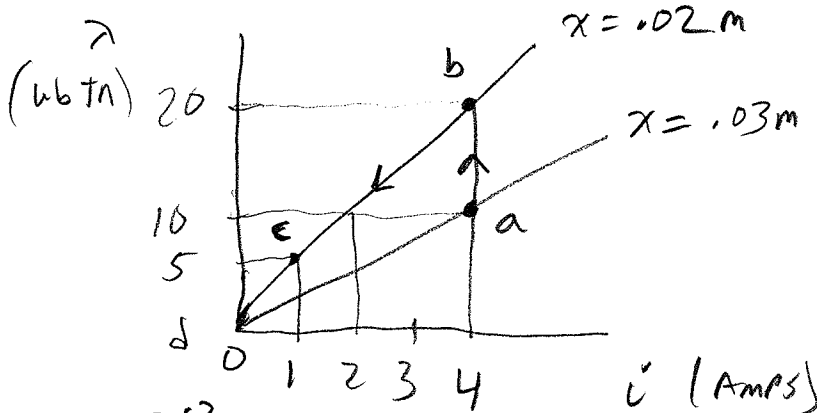
$$\lambda = \frac{.05}{x - .01} i$$

It is operated on the path a - b - c - d as indicated below, with x constant during b - c - d. The current is constant during a - b.

	a	b	c	d
i (Amps)	$i_a$	$i_b$	$i_c$	0
$\lambda$ (Wb turns)	10	$\lambda_b$	5	0
x (meters)	.03	.02	.02	.02

Find the following things:

- $i_a, i_b, i_c$ , and  $\lambda_b$
- The energy stored in the coupling field at points a, b and c.
- The force of electric origin at points a, b and c.
- The Energy From the Electrical system into the coupling field as the system goes from a to b
- The Energy From the Mechanical system into the coupling field as the system goes from a to b



a)  $i_a = 4A = i_b$   
 $\lambda_b = 20 \text{ Wb turns}$   
 $i_c = 1 \text{ Amp}$

b)  $w_{m_a} = \int_0^{10} \lambda di = 20 \text{ J}$

$w_{m_b} = \int_0^{20} \lambda di = 40 \text{ J}$

$w_{m_c} = \int_0^5 \lambda di = 2.5 \text{ J}$

c)  $w_m^l = \frac{.025 i^2}{(x - .01)}$

$f_e = -\frac{.025 i^2}{(x - .01)^2}$

$f_a^e = -1600 \text{ N}$      $f_b^e = -4000 \text{ N}$      $f_c^e = -250 \text{ N}$

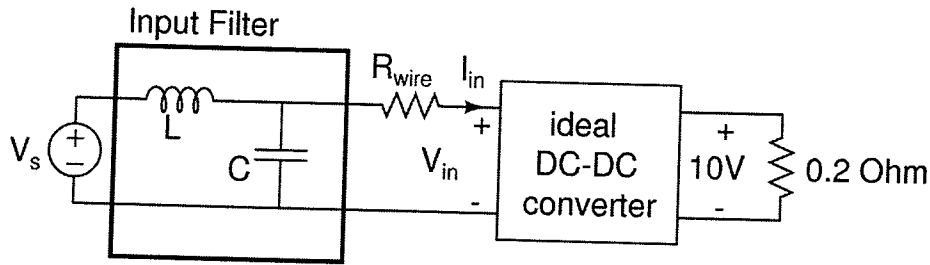
d)  $E_{FE} = \int_{10}^{20} 4 d\lambda = 40 \text{ J}$   
 a-b

$E_{PM} = w_{m_b} - w_{m_a} - E_{FE} = 40 - 20 - 40 = -20 \text{ J}$   
 a-b

check  $E_{PM} = -\int_{.03}^{.02} \left( -\frac{.025 \times 4^2}{(x - .01)^2} \right) dx = -\frac{.025 \times 16}{(x - .01)} \Big|_{.03}^{.02} = -.4(160 - 50) = -20 \text{ J}$

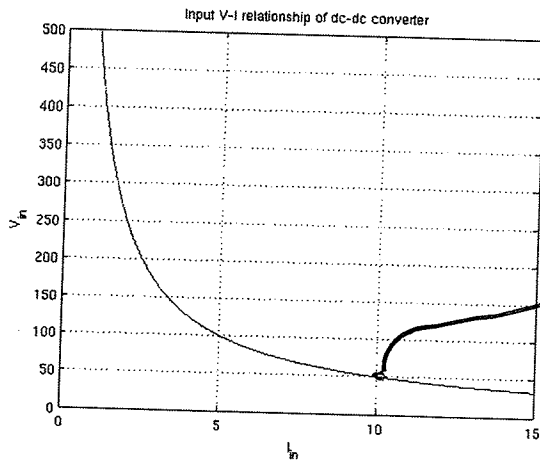


**Problem 3. (30 points.)**



A dc-dc converter with input filter

Shown above is an ideal (100% efficient) dc-dc converter with an L-C input filter and constant source voltage  $V_s$ . In this problem we will analyze the small-signal stability of this circuit. The following component values are used in the problem:  $L = 1 \text{ mH}$ ,  $C = 1 \text{ mF}$ ,  $R_{\text{wire}} = 1 \text{ Ohm}$ . The ideal DC-DC converter provides a constant output power of  $P_{\text{out}} = 500 \text{ W}$  to the load. The **input** voltage and current of the dc-dc converter are related by the equation:  $P_{\text{in}} = P_{\text{out}} = V_{\text{in}} \times I_{\text{in}}$  (as shown below).



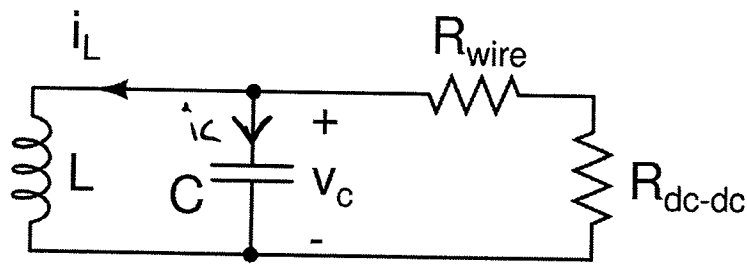
operating point  
note negative slope  $\frac{dV_{\text{in}}}{dI_{\text{in}}}$

- a) Find an expression for the small signal input resistance ( $R_{\text{dc-dc}} = dV_{\text{in}}/dI_{\text{in}}$ ) as a function of  $P_{\text{in}}$  and  $I_{\text{in}}$ , and evaluate it at the operating point ( $I_{\text{in}} = 10 \text{ A}$ ,  $P_{\text{in}} = 500 \text{ W}$ ).

$$P_{\text{in}} = V_{\text{in}} I_{\text{in}} \Rightarrow V_{\text{in}} = \frac{P_{\text{in}}}{I_{\text{in}}}$$

$$R_{\text{DC-DC}} = \frac{dV_{\text{in}}}{dI_{\text{in}}} = - \frac{P_{\text{in}}}{I_{\text{in}}^2} \Big|_{\substack{P_{\text{in}}=500\text{W} \\ I_{\text{in}}=10\text{A}}} = -5 \Omega$$

Shown below is the small-signal (linearized) circuit of the input filter and dc-dc converter, together with the wire resistance  $R_{\text{wire}}$ . Note that the component  $R_{\text{dc-dc}}$  is a small-signal linearized resistance of the dc-dc converter and the load, and has the value that you found in (a).



Small signal circuit of input filter, wire resistance and the dc-dc converter with load.

$$\dot{i}_C = C \frac{dv_C}{dt}$$

↑ note direction of current in figure

The circuit above can be expressed in a state-space representation as

$$R_T = R_{\text{wire}} + R_{\text{dc-dc}} = 1 - 5 = -4$$

b) Find the matrix A.

$$\begin{bmatrix} \frac{dv_C}{dt} \\ \frac{di_L}{dt} \end{bmatrix} = A \times \begin{bmatrix} v_C \\ i_L \end{bmatrix}$$

$$\text{KVL: } L \frac{di_L}{dt} = v_L$$

$$A = \begin{bmatrix} 250 & -1000 \\ 1000 & 0 \end{bmatrix}$$

$$\text{KCL: } i_L + C \frac{dv_C}{dt} + \frac{v_C}{R_T} = 0$$

$$\frac{dv_C}{dt} = \frac{-v_C}{CR_T} - \frac{i_L}{C}$$

$$\frac{di_L}{dt} = \frac{v_C}{L}$$

c) Find the eigenvalues of A.

$$\Rightarrow \begin{bmatrix} \frac{dv_C}{dt} \\ \frac{di_L}{dt} \end{bmatrix} = \underbrace{\begin{bmatrix} \frac{-1}{C(R_T)} & -\frac{1}{C} \\ \frac{1}{L} & 0 \end{bmatrix}}_A \begin{bmatrix} v_C \\ i_L \end{bmatrix}$$

$$(\lambda I - A) = 0$$

$$\begin{vmatrix} \lambda + \frac{1}{R_T C} & \frac{1}{C} \\ -\frac{1}{L} & \lambda \end{vmatrix} = \lambda^2 + \frac{\lambda}{R_T C} + \frac{1}{LC} = 0$$

$$\lambda = -\frac{1}{2R_T C} \pm \frac{1}{2} \sqrt{\left(\frac{1}{R_T C}\right)^2 - \frac{4}{LC}}$$

$$= 125 \pm 992j$$

d) Is the system stable? Explain your answer.

The system is unstable

$$\operatorname{Re}\{\lambda\} > 0$$

**Problem 4. (20 points.)**

Consider the following nonlinear equations:

$$\frac{dx_1}{dt} = 3x_1 - x_1x_2$$

$$\frac{dx_2}{dt} = 2x_1x_2 + x_2$$

The system has initial conditions  $x_1(0) = 1$  and  $x_2(0) = 2$

a) Find all equilibrium points of the system

$$\begin{aligned} 0 &= 3x_1^e - x_1^e x_2^e \Rightarrow 0 = x_1^e (3 - x_2^e) & x_1^e &= 0 \text{ or } x_2^e = 3 \\ 0 &= 2x_1^e x_2^e + x_2^e \Rightarrow 0 = x_2^e (2x_1^e + 1) & x_2^e &= 0 \text{ or } x_1^e = -\frac{1}{2} \end{aligned}$$

If  $x_1^e = 0$ ,  $x_2^e$  must be zero  $\Rightarrow x_1^e = 0, x_2^e = 0$  is one soln.

other soln  $\Rightarrow x_1^e = -\frac{1}{2}, x_2^e = 3$

b) Using Euler's method with a timestep  $\Delta t = 0.01$  sec, determine the state values at  $t = 0.01$  sec and  $t = 0.02$  sec.

$$x_1(0.1) = x_1(0) + \left. \frac{dx_1}{dt} \right|_{t=0} \Delta t$$

$$x_1(0.1) = 1 + (3 \cdot 1 - 1 \cdot 2) \cdot 0.01 = 1.01$$

$$x_2(0.1) = 2 + (2 \cdot 1 \cdot 2 + 2) \cdot 0.01 = 2.06$$

$$x_1(0.2) = 1.01 + (3 \cdot 1.01 - 1.01 \cdot 2.06) \cdot 0.01 = 1.0195$$

$$x_2(0.2) = 2.06 + (2 \cdot 1.01 \cdot 2.06 + 2.06) \cdot 0.01 = 2.1222$$