

Problem 1 (40 pts.)

10 pts a) Given a two port electrical and one port mechanical system

$$\lambda_1(i_1, i_2, \theta) = 2i_1 + 3i_2 \cos \theta$$

$$\lambda_2(i_1, i_2, \theta) = 3i_1 \cos \theta + i_2 + 5$$

find W_m' and T^e

$$W_m' = i_1^2 + 3i_1 i_2 \cos \theta + \frac{1}{2} i_2^2 + 5i_2$$

$$T^e = \frac{\partial W_m'}{\partial \theta} = -3i_1 i_2 \sin \theta$$

15 pts b) Given the following system

$$\dot{x}_1 = 2x_1 + x_2^2 + 1 \quad x_1(0) = 0$$

$$\dot{x}_2 = x_1 x_2 - x_1^2 + 3x_2 \quad x_2(0) = 1$$

Use the Euler's method with step size $\Delta t = 0.1$ calculate $x_1(t)$ and $x_2(t)$ at $t = 0.1$ and $t = 0.2$

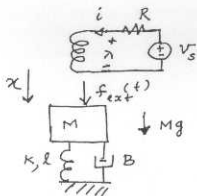
$$x_1(0.1) = 0 + (0 + 1 + 1)0.1 = 0.2$$

$$x_2(0.1) = 1 + (0 - 0 + 3)0.1 = 1.3$$

$$x_1(0.2) = 0.2 + (2 \times 0.2 + 1.3^2 + 1)0.1 = 0.509$$

$$x_2(0.2) = 1.3 + (0.2 \times 1.3 - 0.2^2 + 3 \times 1.3)0.1 = 1.712$$

15pts⁰



ℓ is the value of x for which $f_{spring} = 0$

include gravity

$$\lambda = \frac{10i}{x}$$

If $f_{ext}(t) = 10 \sin t$, write the electromechanical model in state space form.

$$V_S = iR + \frac{d\lambda}{dt} = iR - \frac{10i}{x^2} \frac{dx}{dt} + \frac{10}{x} \frac{di}{dt}$$

$$w_{m1} = \frac{5i^2}{x} \quad f^e = -\frac{5i^2}{x^2}$$

$$m \frac{d^2x}{dt^2} = -k(x-\ell) - B \frac{dx}{dt} + 10 \sin t + mg - \frac{5i^2}{x^2}$$

$$\begin{aligned} x &= x \\ \dot{x} &= v \\ i &= i \end{aligned}$$

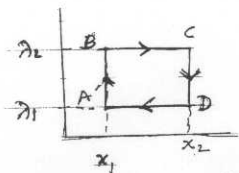
$$\frac{dx}{dt} = v$$

$$\frac{dv}{dt} = \frac{1}{m} \left[-k(x-\ell) - Bv + 10 \sin t + mg - \frac{5i^2}{x^2} \right]$$

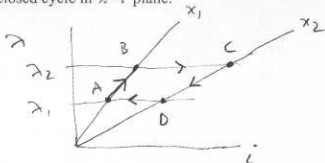
$$\frac{di}{dt} = \frac{x}{10} \left[-iR + \frac{10i}{x^2} v + V_S \right]$$

Problem 2 (30 pts)

Given the $\lambda-i$ relationship of a device as $\lambda = \frac{i}{(1+x)}$. The system traverses in the closed cycle as the following



- a) Sketch the closed cycle in $\lambda-i$ plane.



- b) For the problem above, find $EFE|_{\text{cycle}}$. Is the device acting as a generator or a motor?

$$EFE|_{\text{cycle}} = \int_A^B i d\lambda + \int_{B-C} i d\lambda + \int_{C-D} i d\lambda + \int_{D-A} i d\lambda = \int_A^B i d\lambda + 0 - \int_D^C i d\lambda - 0$$

$$= - \int_A^B i d\lambda$$

Generator

- c) For the problem above, what is the value of $EFM|_{\text{cycle}}$?

$$EFM|_{\text{cycle}} = + \int_A^B i d\lambda$$

OR

$$b) \text{ FFE}_{\text{cycle}} = \int_{\lambda_1}^{\lambda_2} (1+x_1) \lambda d\lambda + 0 + \int_{\lambda_2}^{\lambda_1} (1+x_2) \lambda d\lambda$$

$$= (1+x_1) \frac{(\lambda_2^2 - \lambda_1^2)}{2} + (1+x_2) \frac{(\lambda_1^2 - \lambda_2^2)}{2}$$

$$= \frac{\lambda_2^2 - \lambda_1^2}{2} (1+x_1 - x_2 - 1) = \frac{\lambda_2^2 - \lambda_1^2}{2} (x_1 - x_2) < 0$$

gen

$$c) \text{ EFM}_{\text{cycle}} = \frac{\lambda_2^2 - \lambda_1^2}{2} (x_2 - x_1)$$

Problem 3 (30 pts)

- a) Find the equilibrium of the following system in the interval $0 < x_1 < \pi$

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = -5\sin x_1 - x_2 + 2.5$$

$$x_2 = 0$$

$$5\sin x_1 = 2.5$$

$$x_1^e = \frac{\pi}{6}, \frac{5\pi}{6}$$

- b) Linearize and find eigenvalues of the system around one of them.

$$\Delta \dot{x}_1 = \Delta x_2$$

$$\Delta \dot{x}_2 = -5\cos x_1^e \Delta x_1 - \Delta x_2$$

$$A = \begin{bmatrix} 0 & 1 \\ -5\cos x_1^e & -1 \end{bmatrix}$$

$$A_{e_1} = \begin{bmatrix} 0 & 1 \\ -4.33 & -1 \end{bmatrix}$$

$$|\lambda I - A| = \begin{vmatrix} \lambda & -1 \\ 4.33 & \lambda + 1 \end{vmatrix} = \lambda^2 + \lambda + 4.33$$

$$\lambda = -\frac{1}{2} \pm \frac{1}{2} \sqrt{1 - 17.32}$$

$$= -0.5 \pm j 2.02$$