ECE 330 HW 9

In class quiz - Fri, Nov 30.

Copies of the textbook are kept at the Grainger Engineering Library Reserve

Textbook problem 5.1

Textbook problem 5.4 (a and b only)

Textbook problem 5.5

Special Problem #1 (see solution Spring 2004 Final)

A dynamic system is modeled as:

$$\dot{x_1} = -3x_1 + 2x_2$$

$$\dot{x_2} = x_1^2 - 2x_2 + 2$$

- 1. Find all equilibrium points.
- 2. Linearize the system at each equilibrium point.
- 3. Determine the eigenvalues at each equilibrium point. Determine which points are stable and which are unstable.

Special Problem #1 (see solution Spring 2003 Final)

A nonlinear dynamic model of a system is: $\frac{dx}{dt} + x^2 - 16 = 0$

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- 1. Find the two equilibrium points x_{e_1} and x_{e_2} .
- 2. Find the linearized model $(\frac{d\triangle x}{dt})$ valid for either equilibrium point.
- 3. Is x_{e_1} stable or unstable equilibrium point?
- 4. Is x_{e_2} stable or unstable equilibrium point?