Homework 4 (due Dec 4 Monday 10am)

Instructions: see previous homework. This homework is shorter and is worth half the weight.

- 1. [22 pts] We are given an undirected graph G = (V, E) with *n* vertices and *m* edges, where each edge *e* has a *time interval* [a(e), b(e)] indicating when *e* is "alive". Assume that $a(e), b(e) \in \{1, \ldots, 2m\}$ and the numbers are all distinct. We want to determine all time values $t \in \{1, \ldots, 2m\}$ for which the subgraph $G_t = (V, \{e \in E : t \in [a(e), b(e)]\})$ (consisting of all edges that are alive at time *t*) is connected.
 - (a) [5 pts] Using a data structure from class, show that the problem can be solved in $O(m \log^2 n)$ time.
 - (b) $[17 \ pts]$ Next, describe a direct algorithm that solves the problem in $O(m \log n)$ time. Hint: use divide-and-conquer on the time intervals, similar to segment trees. If an edge e = uv's time interval [a(e), b(e)] is "long", we can *contract* e, i.e., collapse its two vertices u and v into a single vertex...
- 2. $[28 \ pts]$ We want to maintain a dynamic set S of n intervals, subject to insertions and deletions, so that we can quickly compute the value c(S), defined as the minimum number of intervals of S that cover [0, 1].

(For example, for $S = \{[-0.3, 0.3], [-0.2, 0.05], [0.2, 0.4], [0.1, 0.6], [0.5, 0.9], [0.7, 1.1], [0.8, 0.95]\}$, we have c(S) = 4 since the 4 intervals [-0.3, 0.3], [0.1, 0.6], [0.5, 0.9], [0.7, 1.1] cover [0, 1]. You may assume that all endpoints are distinct.)

Define $\operatorname{succ}_S([a, b])$ to be the interval $[a', b'] \in S$ that satisfies $a' \leq b \leq b'$ while maximizing b'. It is known that the static problem can be solved by following greedy algorithm: let $[a_0, b_0] = [0, 0]$, and $[a_i, b_i] = \operatorname{succ}_S([a_{i-1}, b_{i-1}])$ for $i = 1, \ldots, \ell$, till $a_\ell \leq 1 \leq b_\ell$. Then $c(S) = \ell$. (You do not need to prove correctness of this greedy algorithm, though the proof is not difficult.)

- (a) [4 pts] First, show that for a static set P of n intervals, there is a data structure with O(n) preprocessing time and space, so that given any query interval [a, b] (not necessarily in P), we can compute succ_P([a, b]) in O(1) time. The O notation hides polylogarithmic (i.e., log^{O(1)} n) factors.
 - Hint: 1D range max.
- (b) [16 pts] For a static set P of n intervals, give a data structure with O(n) preprocessing time and space, so that for any additional query set Q of q intervals, we can compute c(P ∪ Q) in O(q) time.

Note: you may use the following fact: given any tree with n nodes (not necessarily balanced), we can build a static data structure with O(n) preprocessing time and space, so that given any node v and integer i, we can find the ancestor of v at level i (if exists) in O(1) time (this is known as a *level ancestor query*).

Hint: consider the tree/forest $T = \{(I, \operatorname{succ}_P(I)) : I \in P\}.$

(c) [8 pts] Now, consider a dynamic setting where the update sequence satisfies a first-in first-out (FIFO) assumption: namely, whenever I is inserted before I', we are promised that I must be deleted before I'.

Using (a) and (b), give a dynamic data structure that supports insertions and deletions in S in $\widetilde{O}(\sqrt{n})$ amortized time and can compute c(S) in $\widetilde{O}(\sqrt{n})$ time, assuming FIFO updates.

Hint: do periodic rebuilding after every q updates.

Bonus [up to 5 pts]: obtain the same result in the general dynamic setting without the FIFO assumption (this might require a different approach).