

Approximate Nearest Neighbor Search (ANN)

store n pts $P \subseteq \mathbb{R}^d$ (d const)

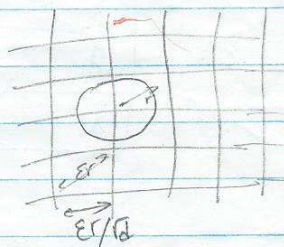
st. given query pt $q \in \mathbb{R}^d$, find $p \in P$ with
 $d(p, q) \leq (1+\epsilon) \min_{p' \in P} d(p', q)$

Exact problem ($\epsilon=0$): by halfspace range searching in dH drums
 $O(n)$ space, $O^*(n^{1-1/\lceil d/2 \rceil})$ time
 or $O^*(n^{\lceil d/2 \rceil})$ space, $O(\log n)$ time

Approx decision problem: given r ,
 return some pt of distance $\leq (1+\epsilon)r$
 or declare all pts have distance $> r$.

Method 0: for decision with fixed r

form grid of side length $\epsilon r / \sqrt{d}$
 store $S =$ all nonempty grid cells



query(q):

check if any grid cell intersecting ball(q, r)
 is in $S \leftarrow$ by hashing

space $O(n)$

time $O(\# \text{ grid cells intersecting ball}(q, r))$

$$= O\left(\frac{\text{volume}(\text{ball}(q, (1+\epsilon)r))}{(\epsilon r / \sqrt{d})^d}\right)$$

$$= O\left(\frac{2\pi^{d/2}}{d\Gamma(d/2)} \frac{((1+\epsilon)r)^d}{(\epsilon r / \sqrt{d})^d}\right)$$

$$= O\left(\left(\frac{c}{\epsilon}\right)^d\right)$$

naively: $O\left(\frac{r^d}{(\epsilon r / \sqrt{d})^d}\right)$

$= O\left(\left(\frac{\sqrt{d}}{\epsilon}\right)^d\right)$

Rmk - alternatively, $O\left(\left(\frac{c}{\epsilon}\right)^d n\right)$ space, $O(1)$ time

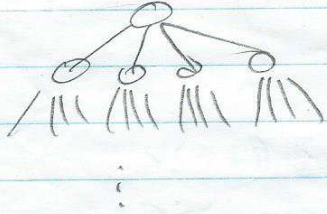
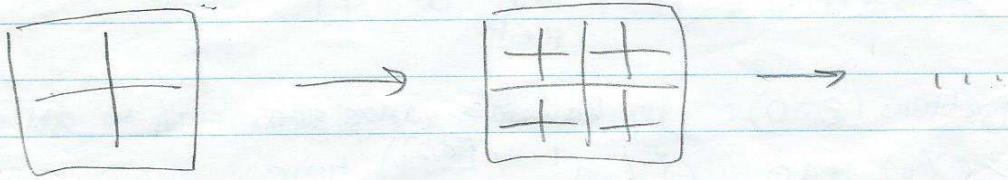
what if r is not fixed?

(store $S =$ all grid cells intersecting ball(p, r) for some $p \in P$)

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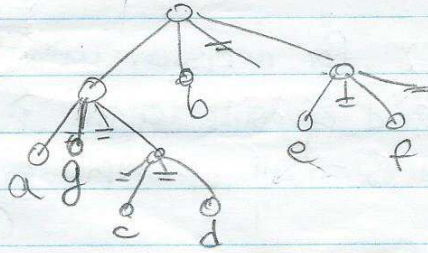
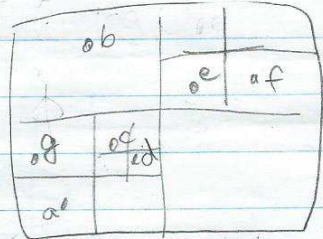
Method 1: Quadtree

idea - hierarchy of grids



Def A quadtree cell B is a grid cell of side length 2^l for some $l \in \{0, 1, \dots, \log U\}$

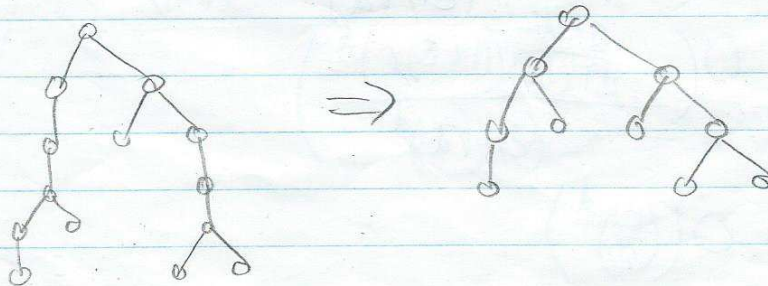
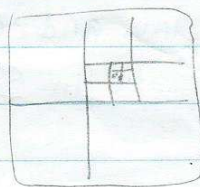
eg.



height $O(\log U)$

space $O(n \log U)$

reducible to $O(n)$ by compressed quadtree (shortcutting 'deg-1 nodes')



decis-query (B, q, r):

if $\text{ball}(q, r)$ does not intersect B return

if B has side length $< \epsilon r / \sqrt{d}$ return any pt in B

for each child B_i of B

decis-query (B_i, q, r)

$$\Rightarrow \text{time} = O(\# \text{quadtree cells of side length } > \frac{\epsilon r}{\sqrt{d}} \text{ intersecting } B)$$

$$= O\left(\sum_{\ell: 2^\ell > \frac{\epsilon r}{\sqrt{d}}} \left\lceil \frac{rd}{(2^\ell)^d} \right\rceil\right)$$

(ignore const factors dependency on d)

$$= O\left(\left\lceil \frac{1}{(\epsilon/\sqrt{d})^d} \right\rceil + \left\lceil \frac{1}{(2\epsilon/\sqrt{d})^d} \right\rceil + \dots\right)$$

$$= O\left(\log U + \frac{1}{\epsilon^d}\right)$$

how to adapt to ANN?

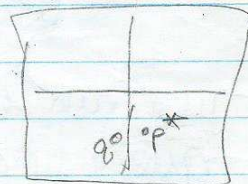
[maintain curr. min r , expand cells in increas order of dist]

Method 2 ... with Shifting (Bern '93) ← first aim for const factor first approx.

naive-ANN-query (B, q):

find child B_i containing q

return naive-ANN-query (B_i, q)



Let p^* = nearest neighbor of q

$$r^* = d(p^*, q)$$

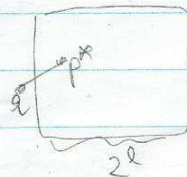
Def q is good if p^* and q lie in a quadtree cell of side length $< 2(d+1)r^*$

Shifting Lemma Shift all pts by random vector in $[0]^d$

Then q is good with const prob.

Pf: Say $(d+1)r^* < 2^\ell \leq 2(d+1)r^*$

$\Pr[q \text{ bad}] \equiv \Pr[p^*q \text{ crosses boundary of quadtree cell of side length } 2^\ell]$



$\leq \Pr[\text{shift lies in a bad interval of length } r^* \text{ along some dim}]$

$$\leq d \cdot \frac{r^*}{2^l} \leq \frac{d}{d+1} \quad \square$$

Shifting Lemma (Deterministic version)

Say d even, $U = 2^w$.

Shift all pts by vector $v_i = \left(\frac{i2^w}{d+1}, \dots, \frac{i2^w}{d+1} \right)$, $i=0, \dots, d$.

Then q is good for some i .

Pf: q bad for $i \Rightarrow \frac{i2^w}{d+1} \bmod 2^l$ lies in a bad interval of length r^* along one dim.

\Rightarrow multiply by $\frac{d+1}{2^l}$ $i2^{w-l} \bmod (d+1)$ lies in a bad interval of length $\frac{(d+1)r^*}{2^l} < 1$

$\Rightarrow i2^{w-l} \bmod (d+1)$ is equal to a specific bad integer.

\Rightarrow since 2^{w-l} and $d+1$ are rel. prime, at most one bad i per dim. So by pigeonhole, \exists good i . \square

Fact: $ax \equiv b \pmod{n}$ has unique soln if a, n are relatively prime

Just run naive-ANN-query for each of these $d+1$ shifts.

query time: $O(\log U)$

Analysis:

let p be returned pt at leaf.

Suppose q is good,

p^* and q are in quadtree

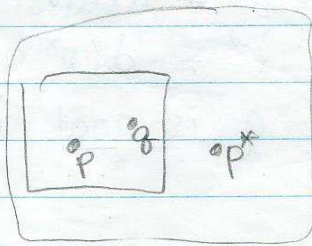
cell of side length $< 2(d+1)r^*$

\Rightarrow so are p and q

$\Rightarrow d(p, q) < 2(d+1)\sqrt{d} r^*$

\Rightarrow approx factor $O(1)$.

reduce query time to $O(\log n)$? [Arya, Mount et al. '94]



Method 3: Balanced Quadtree

Lemma \exists quadtree cell B

s.t. $|P \cap B|, |P - B| \leq \frac{2^d}{2^{d+1}} n$

tree centroid



Pf: let B be smallest quadtree cell with $|P \cap B| \geq \frac{1}{2^{d+1}} n$

Then $|P - B| \leq \frac{2^d}{2^{d+1}} n$

and for each child B_i of B,

$|P \cap B_i| \leq \frac{1}{2^{d+1}} n \Rightarrow |P \cap B| \leq \frac{2^d}{2^{d+1}} n$

recurse in $P \cap B$ & $P - B$

\Rightarrow binary tree of height $\log \frac{2^{d+1}}{2^d} n = O(\log n)$

\Rightarrow query time $O(\log n)$

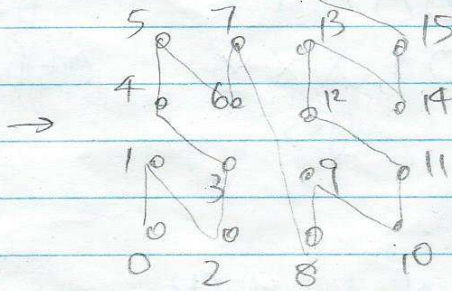
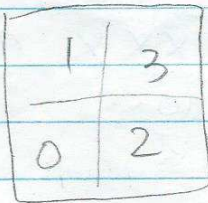
approx factor $O(1)$ by shifting

{other variants:
Arya, Mount et al's
BBD trees,
Goalrich et al's
BAR trees, ...}

Method 4: Z-Ordering (C.'02)

idea - don't use any trees!

directly reduce to 1D, by sorting?



space-filling
Curve

(other exs:

Hilbert curve
etc.)

Def Given point $p = (x, y) \in [U]^2$,

write $x = a_{w-1}a_{w-2} \dots a_0$ in binary

$y = b_{w-1}b_{w-2} \dots b_0$

define $\text{shuffle}(p) = a_{w-1}b_{w-1}a_{w-2}b_{w-2} \dots a_0b_0$

eg $x=2, y=1 \rightarrow \begin{matrix} 010 \\ 001 \end{matrix} \xrightarrow{\text{shuffle}} 001001 \rightarrow 9$

Notes

- $\text{shuffle}(p)$ corresponds to position in Z-order

✓ shuffle maps a quadtree cell to an interval of contiguous integers in 1D.

Lemma can compare $\text{shuffle}(p)$ with $\text{shuffle}(q)$ in $O(1)$ time.

Pf: $p = (x, y), q = (x', y')$

eg $x = 1101 \quad y = 1011$

$x' = 1011 \quad y' = 1001$

$x \oplus x' = 0110 \quad y \oplus y' = 0010$

\oplus bitwise or
msb most significant
1 bit

if $\text{msb}(x \oplus x') > \text{msb}(y \oplus y')$

compare x with x'

else compare y with y'

to check $\text{msb}(a) > \text{msb}(b)$:

check $a > b$ and $a \oplus b > b$.

eg $a = 01xxx$

$b = 0001x$

$a \oplus b = 01xxx$

yes

$a = 0001x$

$b = 01xxx$

$a \oplus b = 01xxx$

no

$a = 01xxx$

$b = 01xxx$

$a \oplus b = 00xxx$

no

□

Preproc alg'm:

for each of $d+1$ shifts

store pts sorted along Z-order

$\Rightarrow O(n \log n)$ time

$O(n)$ space

query(q):

for each of $d+1$ shifts

find pred & succ of q

return closest pt found

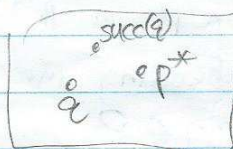
\Rightarrow $O(\log n)$ time

Analysis:

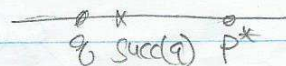
Suppose q is good.

p^* , q are in quadtree

cell of side length $< 4(d+1)r^*$



z-order



\Rightarrow so is succ or pred of q .

\Rightarrow approx factor $O(1)$.

Rmk: immediately improvable to $O(\log \log U)$ or $O(\sqrt{\log n})$
by ID data structures!

can be made dynamic!

Refining approx factor:

Option 1: let $r = \text{factor-c approx}$.

divide ball(q, cr) into $O(\frac{1}{\epsilon^d})$ quadtree cells
of side length $\leq \frac{\epsilon r}{\sqrt{d}}$

test if each subcell is empty

\hookrightarrow maps to ID search.

\Rightarrow query time $O(\frac{1}{\epsilon^d} \log n)$ or $O(\frac{1}{\epsilon^d} \log \log U)$...

Best ϵ -dependency? still open.

Arya, Mount et al. '94 $O(n)$ space, $O(\frac{1}{\epsilon^d} \log n)$ time

Clarkson '94 / C. '97 $\tilde{O}(\frac{1}{\epsilon^d} n)$ space, $O(\frac{1}{\epsilon^d} \log n)$ time

Arya, da Fonseca, Mount '12-'16 $\tilde{O}(\frac{1}{\epsilon^d} n)$ space, $O(\frac{1}{\epsilon^d} \log n)$ time

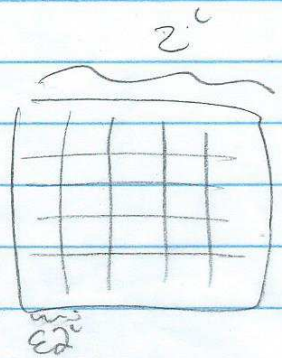
" " " '17 / C. '17 $\tilde{O}(\frac{1}{\epsilon^d} n)$ " $O(\frac{1}{\epsilon^d} \log n)$ "

A7

Option 2: (C. Har-Peled - Jones '18)

idea - keep query alg'm same
but use multiple orderings

Increase fan-out to $(\frac{1}{\epsilon})^d$ (i.e. compress $\log \frac{1}{\epsilon}$ levels into one)
reorder children



0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15

0	2	1	3
4	6	5	7
8	10	9	11
12	14	13	15

0	2	4	6
5	7	1	3
8	10	12	14
13	15	9	11

...

\forall children u_i, u_j ,
 \exists ordering s.t. u_i, u_j adjacent.

orderings $O\left(\left(\frac{1}{\epsilon}\right)^d \underbrace{\log \frac{1}{\epsilon}}_{\text{\# levels compressed}}\right)$

[many appl'ns ...]