# Spectral Graph Drawing 

based on papers by Yehuda Koren

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- Draw edges using only straight segments.
- Goal: place the vertices in p-dimensional space to get a "beautiful" layout.


## The Graph Drawing Problem


(a)

(c)

(b)

(d)

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- vertices connected by an edge to be close to each other
- higher weighted edge: even closer
- but not too close in general


## Formulation

- A $p$-dimensional layout defined by $x^{1}, \ldots, x^{p} \in \mathbb{R}^{n}$.


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## Formulation

- A $p$-dimensional layout defined by $x^{1}, \ldots, x^{p} \in \mathbb{R}^{n}$.
- Vertex $i$ is at coordinates $\left(x^{1}(i), \ldots, x^{p}(i)\right)$.
- Euclidean distance between vertices $i$ and $j$

$$
d_{i j}=\sqrt{\sum_{k=1}^{p}\left(x^{k}(i)-x^{k}(j)\right)^{2}}
$$

## Spectral answers to optimization problems

## Theorem (1)

Given a symmetric matrix $A_{n \times n}$, denote by $v^{1}, \ldots, v^{n}$ its eigenvectors, with corresponding eigenvalues $\lambda_{1} \leq \cdots \leq \lambda_{n}$. Then, $v^{1}, \ldots, v^{p}$ are an optimal solution of the constrained minimization problem:

$$
\min _{x_{1}, \ldots, x_{P}} \sum_{k=1}^{p}\left(x^{k}\right)^{T} A x^{k}
$$

subject to

$$
\left(x^{k}\right)^{T} x^{l}=\delta_{k l}, \quad k, l=1, \ldots, p
$$

where $\delta_{k l}$ is 1 if $k=l, 0$ otherwise.

## Spectral answers to optimization problems

Generalized eigenvector of $(L, D)$ is $u$ s.t.

$$
L u=\mu D u
$$

## Spectral answers to optimization problems

## Theorem (2)

Given a symmetric matrix $A_{n \times n}$ and a positive definite matrix $B_{n \times n}$, denote by $v^{1}, \ldots, v^{n}$ the generalized eigenvectors of $(A, B)$, with corresponding eigenvalues $\lambda_{1} \leq \cdots \leq \lambda_{n}$. Then, $v^{1}, \ldots, v^{p}$ are an optimal solution of the constrained minimization problem:

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\min _{x_{1}, \ldots, x_{p}} \frac{\sum_{i=1}^{p}\left(x^{i}\right)^{T} A x^{i}}{\sum_{i=1}^{p}\left(x^{i}\right)^{T} B x^{i}}
$$

subject to

$$
\begin{aligned}
\left(x^{1}\right)^{T} B x^{1} & =\left(x^{2}\right)^{T} B x^{2}=\cdots=\left(x^{p}\right)^{T} B x^{p} \\
\left(x^{k}\right)^{T} B x^{l} & =0
\end{aligned}
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\left(x^{i}\right)^{T} B x^{j} & =0 \\
\left(x^{i}\right)^{T} B v^{j} & =0
\end{aligned}
$$

## "Force-Directed" Method

- Minimization problem:

$$
\min _{x_{1}, \ldots, x_{p}} \frac{\sum_{(i, j) \in E} w_{i j} d_{i j}^{2}}{\sum_{i<j} d_{i j}^{2}}
$$

subject to $\operatorname{Var}\left(x^{1}\right)=\ldots=\operatorname{Var}\left(x^{p}\right)$

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\text { and } \operatorname{Cov}\left(x^{k}, x^{l}\right)=0, \quad 1 \leq k \neq l \leq p
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- $\operatorname{Var}(x)=\frac{1}{n} \sum_{i=1}^{n}(x(i)-\bar{x})^{2}$
- $\operatorname{Cov}\left(x^{k}, x^{l}\right)=\frac{1}{n} \sum_{i=1}^{n}\left(x^{k}(i)-\bar{x}^{k}\right)\left(x^{l}(i)-\bar{x}^{l}\right)$


## "Force-Directed" Method

- We can make $\bar{x}^{k}=0$ for each $k$ i.e. $\sum_{i=1}^{n} x^{k}(i)=\left(x^{k}\right)^{T} \cdot 1_{n}=0$


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- Thus we can reformulate the problem as

$$
\min _{x_{1}, \ldots, x_{p}} \frac{\sum_{k=1}^{p}\left(x^{k}\right)^{T} L x^{k}}{\sum_{k=1}^{p}\left(x^{k}\right)^{T} x^{k}}
$$

$$
\begin{array}{rll}
\text { subject to }\left(x^{k}\right)^{T}\left(x^{l}\right)=\delta_{k l}, & & k, l=1, \ldots, p \\
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- Thus we can reformulate the problem as

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\end{array}
$$

- The answer is $v^{2}, \ldots, v^{p+1}$.


## Degree-Normalized "Force-Directed" Method

- Minimization problem:

$$
\min _{x_{1}, \ldots, x_{p}} \frac{\sum_{k=1}^{p}\left(x^{k}\right)^{T} L x^{k}}{\sum_{k=1}^{p}\left(x^{k}\right)^{T} D x^{k}}
$$

$$
\begin{array}{cl}
\text { subject to }\left(x^{k}\right)^{T} D\left(x^{l}\right)=\delta_{k l}, & k, l=1, \ldots, p \\
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\end{array}
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- The answer is $u^{2}, \ldots, u^{p+1}$, the generalized eigenvectors of $(L, D)$.


## Weighted Centroid Characterization

- Aesthetically, a vertex should be at the weighted centroid of its neighbors.


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- Differentiating $x^{T} L x$ with respect to $x(i)$ gives

$$
\frac{\partial x^{T} L x}{\partial x(i)}=2 \sum_{j \in N(i)} w_{i j}(x(i)-x(j))
$$

which is zero when

$$
x(i)=\frac{\sum_{j \in N(i)} w_{i j} x(j)}{\operatorname{deg}(i)}
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- This can be written, for all $i$ together, as

$$
\begin{aligned}
D^{-1} L x & =\mu x \\
L x & =\mu D x
\end{aligned}
$$

which endorses the use of generalized eigenvectors of ( $L, D$ )

## Weighted Centroid Characterization

- Using generalized eigenvectors of $(L, D)$ gives

$$
x(i)-\frac{\sum_{j \in N(i)} w_{i j} x(j)}{\operatorname{deg}(i)}=\mu \cdot x(i)
$$

- Using Laplacian eigenvectors gives

$$
x(i)-\frac{\sum_{j \in N(i)} w_{i j} x(j)}{\operatorname{deg}(i)}=\lambda \cdot \operatorname{deg}(i)^{-1} \cdot x(i)
$$

## Weighted Centroid Characterization



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- start with a random vector $x_{0}$ s.t. $x_{0}^{T} D 1_{n}=0$.


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- $x_{i+1}=D^{-1} A x_{i}$


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- or rather, $x_{i+1}=\frac{1}{2}\left(I+D^{-1} A\right) x_{i}$
- Random walk!


## References

- Koren, Yehuda. "Drawing graphs by eigenvectors: theory and practice." Computers \& Mathematics with Applications 49.11 (2005): 1867-1888.
- Koren, Yehuda. "On spectral graph drawing." Computing and Combinatorics. Springer Berlin Heidelberg, 2003. 496-508.

