CS598JHM: Advanced NLP (Spring 2013) *http://courses.engr.illinois.edu/cs598jhm/* 

## Lecture 13: Dirichlet Processes

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### Finite mixture model

#### **Mixing proportions:**

The prior probability of each component (assuming uniform  $\alpha$ )  $\pi | \alpha \sim Dirichlet(\alpha/K, ..., \alpha/K)$ 

#### Mixture components:

The distribution over observations for each component  $\theta_k^* | H \sim H$  (*H* is typically a Dirichlet distribution)

#### Indicator variables:

Which component is observation i drawn from?  $z_i | \pi \sim Multinomial(\pi)$ 

#### The observations:

The probability of observation i under component  $z_i$  $x_i|z_i, \{\theta_k^*\} \sim F(\theta_{zi}^*)$  (*F* is typically a categorical distribution)

### Dirichlet Process $DP(\alpha, H)$

The **Dirichlet process**  $DP(\alpha, H)$  defines a distribution over distributions over a probability space  $\Theta$ . Draws  $G \sim DP(\alpha, H)$  from this DP are **random distributions** over  $\Theta$ 

 $DP(\alpha, H)$  has two parameters:

#### **Base distribution** *H*:

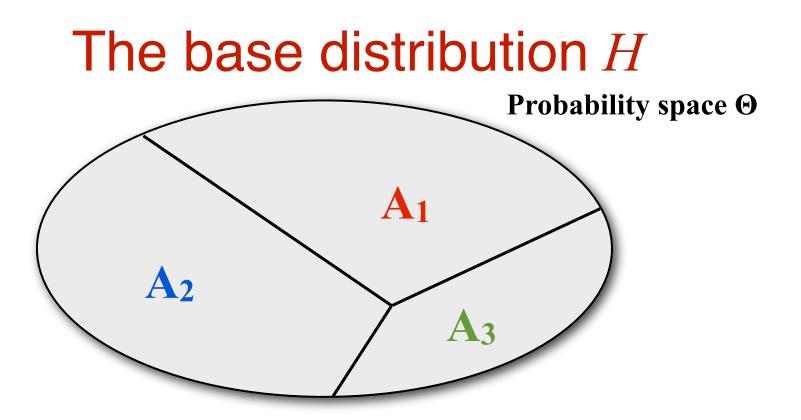
a distribution over the probability space  $\Theta$ 

#### **Concentration parameter** $\alpha$ :

a positive real number

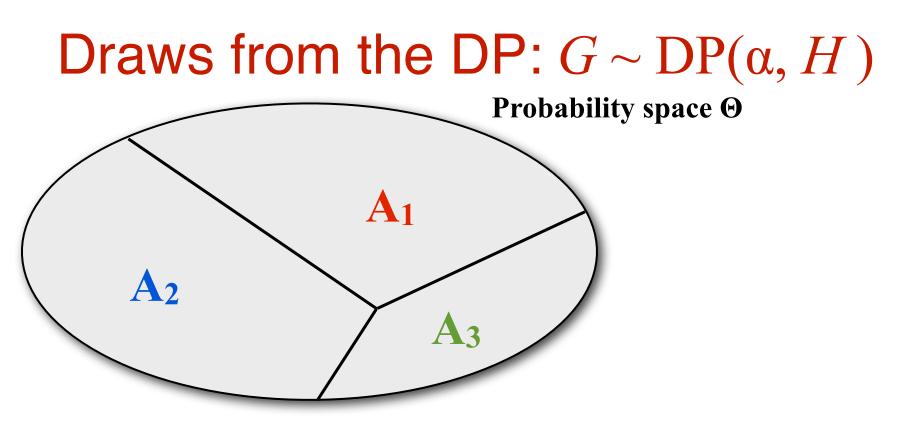
If  $G \sim DP(\alpha, H)$ , then for any finite measurable partition  $A_1...A_r$  of  $\Theta$ :

 $(G(A_1), ..., G(A_r)) \sim Dirichlet(\alpha H(A_1), ..., \alpha H(A_r))$ 



Since  $A_1, A_2, A_3$  partition  $\Theta$ , we can use the base distribution H to define a categorical distribution over  $A_1, A_2, A_3$ :  $H(A_1) + H(A_2) + H(A_3) = 1$ 

Note that we can use *H* to define a categorical distribution over *any* finite partition  $A_1...A_r$  of  $\Theta$ , even if *H* is smooth



Every individual draw *G* from  $DP(\alpha, H)$  is also a distribution over  $\Theta$ *G* also defines a categorical distribution over any partition of  $\Theta$ 

For *any* finite partition  $A_1...A_r$  of  $\Theta$ , this categorical distribution is drawn from a Dirichlet prior defined by  $\alpha$  and *H*:  $(G(A_1), G(A_2), G(A_3)) \sim Dir(\alpha H(A_1), \alpha H(A_2), \alpha H(A_3))$ 

### The role of H and $\alpha$

The base distribution *H* defines the **mean** (expectation) of *G*: For any measurable set  $A \subseteq \Theta$ , E[G(A)] = H(A)

The concentration parameter  $\alpha$  is **inversely** related to the **variance** of *G* :

 $V[G(A)] = H(A)(1 - H(A))/(\alpha + 1)$   $\alpha$  specifies how much mass is around the mean The larger  $\alpha$ , the smaller the variance

 $\alpha$  is also called the **strength parameter:** If we use DP( $\alpha$ , *H*) as a prior,  $\alpha$  tells us how much we can deviate from the prior:

As  $\alpha \to \infty$ ,  $G(A) \to H(A)$ 

### The posterior of $G: G|\theta_1, \dots \theta_n$

Assume the distribution *G* is drawn from a DP:  $G \sim DP(\alpha, H)$ 

The **prior** of *G*:

 $(G(A_1),..., G(A_K)) \sim Dirichlet(\alpha H(A_1), ..., \alpha H(A_K))$ 

Given a sequence of observations  $\theta_1... \theta_n$  from  $\Theta$ that are drawn from this  $G: \quad \theta_i | G \sim G$ What is the **posterior of** *G* given the observed  $\theta_1... \theta_n$  ?

For any finite partition  $A_1...A_K$  of  $\Theta$ , define the number of observations in  $A_k : n_k = \#\{i: \theta_i \in A_k\}$ 

The **posterior** of *G* given observations  $\theta_1... \theta_n$  $(G(A_1),..., G(A_K))|\theta_1, ... \theta_n \sim Dirichlet(\alpha H(A_1) + n_1, ..., \alpha H(A_K) + n_K)$ 

### The posterior of $G: G|\theta_1, ..., \theta_n$

The observations  $\theta_1 \dots \theta_n$  define an **empirical distribution** over  $\Theta$ :

← This is just a fancy way of saying  $P(A_k) = n_k/n$ 

The **posterior** of *G* given observations  $\theta_1 \dots \theta_n$ 

 $(G(A_1),...,G(A_K))|\theta_1,...\theta_n \sim Dirichlet(\alpha H(A_1) + n_1,...,\alpha H(A_K) + n_K)$ 

The posterior is a DP with:

 $\sum_{i=1}^{n} \delta_{\theta_i}$ 

- concentration parameter  $\alpha + n$
- a **base distribution** that is a weighted average of H and the empirical distribution.

$$G|\theta_1, \dots, \theta_n \sim DP(\alpha + n, \quad \frac{\alpha}{\alpha + n}H + \frac{n}{\alpha + n}\frac{\sum_{i=1}^n \delta_{\theta_i}}{n})$$

The weight of the empirical distribution is proportional to the amount of data. The weight of *H* is proportional to  $\alpha$ 

### The Blackwell MacQueen urn

Assume each value in  $\Theta$  has a unique color.

 $\theta_1...$   $\theta_n$  is a sequence of colored balls.

With probability  $\alpha / (\alpha + n)$ , the n+1th ball is drawn from *H* 

With probability  $n/(\alpha+n)$  the n+1th ball is drawn from an urn that contains all previously drawn balls.

Note that this implies that G is a discrete distribution, even if H is not.

### The clustering property of DPs

 $\theta_1...$   $\theta_n$  induces a partition of the set 1...n into k unique values.

This means that the DP defines a distribution over such partitions.

The expected number of clusters k increases with  $\alpha$  but grows only logarithmically in *n*:

 $E[k \mid n] \simeq \alpha \log(1 + n/\alpha)$ 

### NLP 101: language modeling

**Task:** Given a stream of words  $w_1...w_n$ , predict the next word  $w_{n+1}$  with a unigram model P(w)

#### **Answer:**

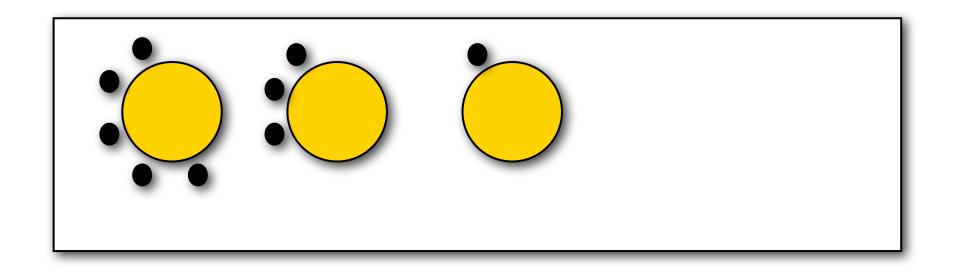
If  $w_{n+1}$  is a word w we've seen before:  $P(w_{n+1} = w) \propto Freq(w)$ 

But what if  $w_{n+1}$  has never been seen before? We need to reserve some mass for new events  $P(w_{n+1} \text{ is a new word}) \propto \alpha$ 

$$P(w_{n+1} = w) = Freq(w)/(n+\alpha) \text{ if } Freq(w) > 0$$
  
=  $\alpha/(n+\alpha)$  if  $Freq(w) = 0$ 

Bayesian Methods in NLP

#### The Chinese restaurant processs



The (i+1)th customer  $c_{i+1}$  sits:

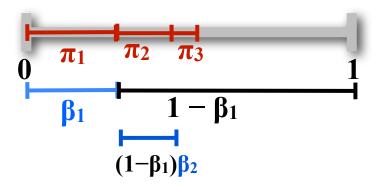
- at an *existing* table  $t_k$  that already has  $n_k$  customers with probability  $n_k/(i+\alpha)$
- at *new* table with probability  $\alpha/(i+\alpha)$

# The predictive distribution $\theta_{n+1}|\theta_1, ..., \theta_n$

The predictive distribution of  $\theta_{n+1}$  given a sequence of i.i.d. draws  $\theta_1, ..., \theta_n \sim G$ , with  $G \sim DP(\alpha, H)$  and G marginalized out is given by the posterior base distribution given  $\theta_1, ..., \theta_n$ 

$$P(\theta_{n+1} \in A) = E[G(A)|\theta_1, ..., \theta_n]$$
$$= \frac{\alpha}{\alpha + n} H(A) + \frac{\sum_{i=1}^n \delta_{\theta_i}(A)}{\alpha + n}$$

#### The stick-breaking representation



 $G \sim DP(\alpha, H)$  if:

- The component parameters are drawn from the base distribution:  $\theta_k^* \sim H$ 

- The weights of each cluster are defined by a stick-breaking process:

 $\beta_k \sim Beta(1, \alpha) \qquad \pi_k \sim \beta_k \prod_{l=1...k-1} (1-\beta_l)$ also written as  $\pi \sim GEM(\alpha)$  (Griffiths/Engen/McCloskey)  $G = \sum_{k=1...\infty} \pi_k \delta$ 

 $\theta_k^*$ 

### **Dirichlet Process Mixture Models**

Each observation  $x_i$  is associated with a latent parameter  $\theta_i$ Each  $\theta_i$  is drawn i.i.d. from *G*; each  $x_i$  is drawn from  $F(\theta_i)$ 

$$G|\alpha, \mathbf{H} \sim DP(\alpha, \mathbf{H})$$
  $\theta_i|G \sim G$   $\mathbf{x}_i|\theta_i \sim F(\theta_i)$ 

Since *G* is discrete,  $\theta_i$  can be equal to  $\theta_j$ All  $x_i$ ,  $x_j$  with  $\theta_i = \theta_j$  belong to the same mixture component There are a countably infinite number of mixture components.

#### **Stick-breaking representation:**

Mixing proportions:  $\pi | \alpha \sim GEM(\alpha)$ Indicator variables:  $z_i | \pi \sim Mult(\pi)$ Component parameters:  $\theta_k^* | H \sim H$ Observations:  $x_i | z_i, \{\theta_k^*\} \sim F(\theta_{z_i}^*)$ 

### **Hierarchical Dirichlet Processes**

Since both H and G are distributions over the same space  $\Theta$ , the base distribution of a DP can be a draw from another DP. This allows us to specify hierarchical Dirichlet Processes, where each group of data is generated by its own DP.

Assume a global measure  $G_0$  drawn from a DP:  $G_0 \sim DP(\gamma, H)$ 

For each group j, define another DP  $G_j$  with base measure  $G_0$ :  $G_j \sim DP(\alpha_0, G_0)$ (or  $G_j \sim DP(\alpha_j, G_0)$ , but it is common to assume all  $\alpha_j$  are the same)

 $\alpha_0$  specifies the amount of variability around the prior  $G_0$ 

Since all groups share the same base  $G_0$ , all  $G_j$  use the same atoms (balls of the same colors)