

CS 579 Computational Complexity: Lecture 27

admin: p56 delayed - ar tonight

today: query complexity - extended deadline

so far: comparison of different TM resources

- deterministic
- nondeterministic
- space
- non-uniformity
- alternation
- randomness
- counting
- interactive

results: trivial inclusions $\text{NP} \subseteq \text{PSPACE}$

- robustness of models, e.g. $\text{BPP}_{1/3} = \text{BPP}_{1/10}$
- completeness results, e.g. Cook-Levin
- non-trivial inclusions, e.g. $\text{BPP} \subseteq \text{PH}$

Q: can we prove complexity classes are different?

A: hierarchy thms $\text{TIME}(n^3) \neq \text{TIME}(n^5)$

Q: anything else?

A: "nothings" etc known ← relativization barrier

next two weeks: complexity theory of concrete models of computation

today: query complexity

↳ not full power of TM ⇒ can prove results!

ex: sorting

- capture "natural" computational phenomena

given n items x_1, \dots, x_n , sort them

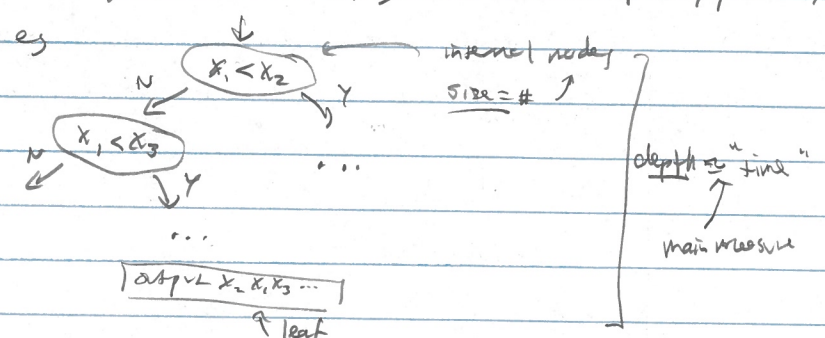
↑ abstract

↑ have comparison oracle " $x_i < x_j$ "

If many sorting algo. fit this model, not all!

recall: can be done w/ $O(n \lg n)$ comparisons, e.g. merge sort, heap sort, quick sort, etc

formalism: via decision tree, e.g. query complexity



prop: any sorting algo. in comparison model requires $\Omega(n \lg n)$ depth

PF: decision tree depth $d \Rightarrow \leq 2^d$ leaves (binary answers)

← all $n!$ orderings must appear

$$\Rightarrow d \geq \lg(n!) \geq \Omega(n \lg n)$$

def: a decision tree T on variables x_1, \dots, x_n is a labelled binary tree w/ single root

- leaves $\in \{0, 1\}$ (computer)

- internal nodes labelled w/ variables x_i , children " $x_i=0$ " " $x_i=1$ "

- depth = max distance from root to leaf

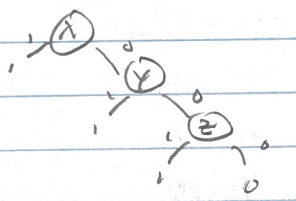
- computes $T: \{0, 1\}^n \rightarrow \{0, 1\}^k$ - starting at root node

- if at " x_i " labelled node, take " $x_i=b_i$ " child, for b_i the value of x_i
- if at leaf: return its value

depth of root \rightarrow temp pol

- cost $(T, x) = \#$ of variables queried when computing $T(x)$

eg. $OR_3(x_1, x_2, x_3) =$



cost $(T, 100) = 1$

001-3

\rightarrow cost \leq depth

\uparrow per input \uparrow worst case

def: $f: \{0,1\}^n \rightarrow \{0,1\}$ $D(f) = \min_{\text{computation } T} \max_x \text{cost}(T, x)$
= depth (T)

Con: $D(f) \leq n$ \uparrow only n vars to query \uparrow

pf: query x_1, x_2, \dots, x_n , output $f(x)$

Prop: $D(OR_n) \geq n$

if: use "adversary argument" on depth $\leq n$ tree T

adversary: find " $x_i = 0$ " to each variable in tree until leaf is reached, output b
as depth $\leq n$ tree \Rightarrow some variable not queried, say x_{i_0}

if $b = 0$: set $x_{i_0} = 1 \Rightarrow OR_n(x) = 1$ but $T(x) = 0$

$b = 1$: $x_i = 0$ all $i \Rightarrow OR_n(x) = 0$ $\therefore 1 \neq 0$

def: $P^{dec} = \{f: \{0,1\}^n \rightarrow \{0,1\} \mid D(f) \leq \text{poly}(\log(n))\}$ \uparrow families of functions
Con: $OR \notin P^{dec}$ \uparrow NP $\subseteq \mathbb{Z}$ "efficient"

def: a b -certificate for $f: \{0,1\}^n \rightarrow \{0,1\}$ at x is set $S \subseteq [n]$
and values $x|_S \in \{0,1\}^{|S|}$ s.t. $\forall y \in \{0,1\}^n: y|_S = x|_S \Rightarrow f(y) = b$ \uparrow prov. witness

def: $N_b(f) = \min_k \{ \# \text{ of } x \text{ s.t. } f(x) = b \text{ have } b\text{-certificate size } \leq k \}$
 \uparrow guess variables then check

ex: $N_1(OR_n) = 1$

$N_0(OR_n) = n$ \uparrow follows from adversary argument

def: $NP^{dec} = \{f: \{0,1\}^n \rightarrow \{0,1\} \mid N_1(f) \in \text{poly}(n)\}$
Con: $NP^{dec} \subseteq P^{dec}$ \uparrow N_0

lem: $D(f) \geq N_0(f), N_1(f)$

pf: T decision tree for f , any x $S_x = \{ \text{query of } T \text{ on } x \}$
 $\Rightarrow |S_x| = \text{cost}(T, x) \in D(f)$. variables $\notin S_x$ do not affect T on x
 $\Rightarrow S_x$ is $(f(x))$ -cert for x

Con: $P^{dec} \subseteq NP^{dec} \subseteq CONP^{dec}$

Con: $P^{dec} \not\subseteq N^{dec} \neq CONP^{dec}$ \uparrow expected
 \uparrow $N^{dec} \subseteq OR$ \uparrow $CONP^{dec} \subseteq \leftarrow N_0(OR_n) \geq n$

thm = any f , $D(f) \in N_0(f) \cdot N_1(f)$

Co: $P^{dec} = NP^{dec} \cap coNP^{dec}$ [unexpected!]

PF: $f \in NP^{dec} \Rightarrow N_1(f) \in poly(\lg n)$
 $" \in coNP \quad " \quad N_0 \quad " \quad " \Rightarrow D(f) \in poly(\lg n) \cdot poly(\lg n) \leq poly(\lg n)$
 $\Rightarrow f \in P^{dec}$

PF: $k = N_0(f)$, $l = N_1(f)$

idea: let $C_0 \subseteq \binom{[k]}{2}$ be minimal 0-cert
 $C_1 \subseteq \binom{[l]}{2}$ " 1-cert

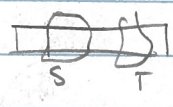
use queries to reduce C_0, C_1 until function is constant

key lem: $(S, x|_S)$ 0-cert, $(T, x|_T)$ 1-cert $\Rightarrow |S \cap T| > 0$
 (shaded w/ no query)

PF: by contradiction, assume $S \cap T = \emptyset$

pick $y \in \{0,1\}^k$ st $y|_S = x|_S \Rightarrow f(y) = 0$

$y|_T = x|_T \Rightarrow f(y) = 1$
 possible = S, T disjoint



algo: on input x :

- 1) define $Q \subseteq [n]$ w/ $Q = \emptyset$
- 2) while $f(x)$ undetermined subject to $x|_Q$ known
 - a) pick minimum size 0-cert S for f , consistent w/ $x|_Q$
 - b) query $x|_S \cap Q$ $\leftarrow |S| \leq k$
 - c) $Q \leftarrow Q \cup S$
- 3) output constant value of f subject to $x|_Q$

correctness = $f(x)$ undetermined st $x|_Q$ ift \leftarrow consistency

\exists 0-cert $(S, y|_S)$ st $x|_{Q \cap S} = y|_{Q \cap S}$
 \exists 1-cert $(T, y|_T)$ st $x|_{Q \cap T} = y|_{Q \cap T}$
 $\Rightarrow |S \cap Q| > 0, |T \cap Q| > 0, |(S \cap T) \cap Q| > 0$

hence:
 \Rightarrow some minimal 0-cert S exists in step 2a, as \leftarrow key lemma
 \Rightarrow additional $|S|$ coordinates of x queried in step 2b
 \Rightarrow will eventually query enough of x to determine $f(x)$
 \Rightarrow correct

complexity = uses $\leq k \cdot (\# \text{ rounds})$ queries $\leq k \cdot l$

$C_{ln} = \# \text{ rounds} \leq l = N_0(f) \Rightarrow$

PF: consistency of y ...

Michael Forbes

Mitigation & Illinois. etc

2019-04-09.4 ← 2019-04-09.3

→ 2019-04-11.1

CS579

consider any 1-bit (T, y_T) consistent w x/Q

$\Rightarrow \Rightarrow |S(T \setminus Q)| > 1 \quad |(S \cap T) \setminus Q| > 1$

$\Rightarrow |T \setminus (Q \cup S)| \leq |T \setminus Q| - 1$

↑ S queries ≥ 1 value in T

\Rightarrow each round all 1-bits consistent w Q either - become inconsistent w $x/Q \cup S$
- have 1 fewer unknown variable

as $l = N_0(f)$ each minimal 1-bit starts w l unknown variable

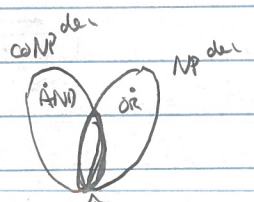
\Rightarrow in l rounds - \emptyset is 1-bit $\Rightarrow f|_{x/Q} = 1$

- no 1-bits consistent w $x/Q \Rightarrow f|_{x/Q} = 0$

f on x/Q is constant

\Rightarrow algo outputs value \square

hence:



$P = NP^A conv$

next time - communication complexity.