Computational Complexity

Lecture 1
in which we talk about
Time Complexity, P, NP and coNP

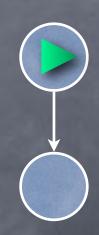


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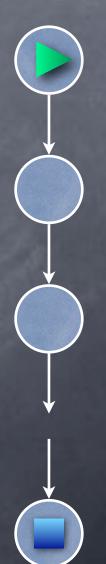
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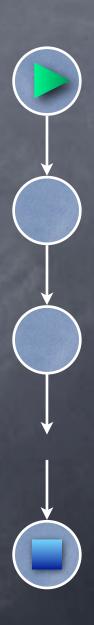


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 - output explicitly encoded in the final configuration (say, in the control-state)





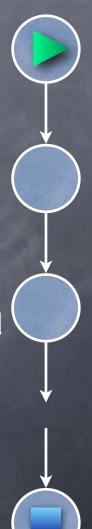
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 - (Note: complexity T is a <u>function</u> of n)

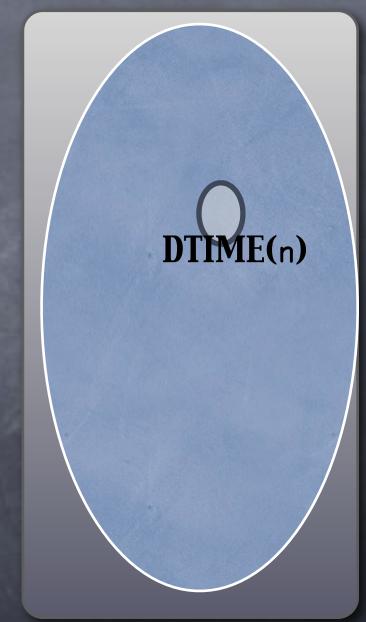
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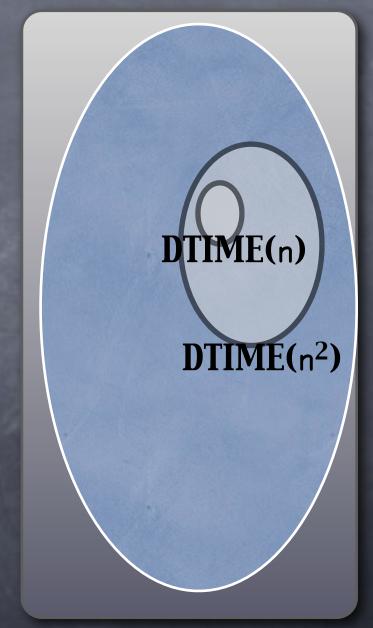
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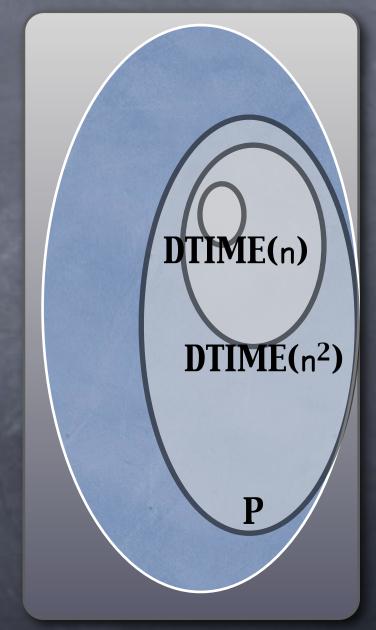


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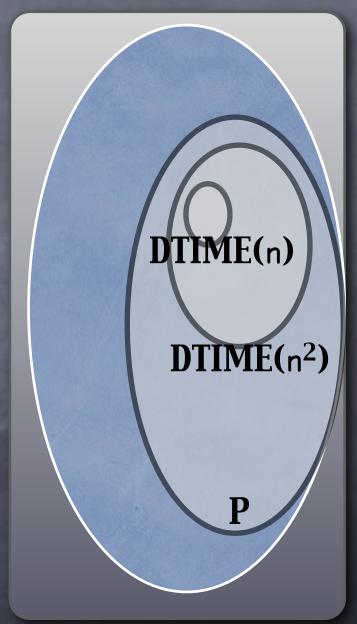
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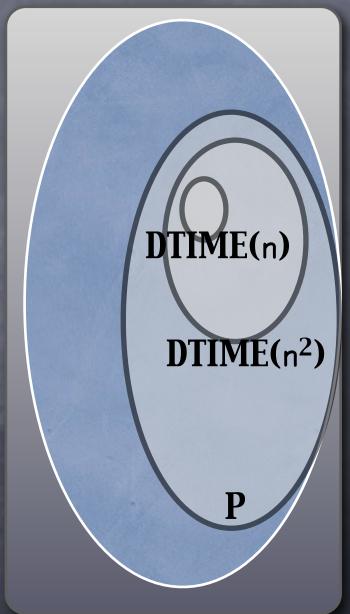
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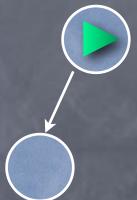


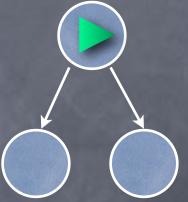
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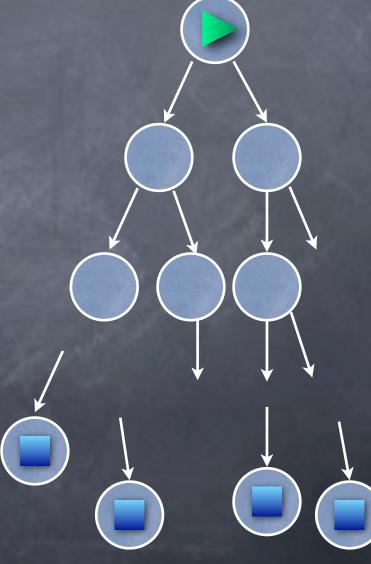
- $P = \bigcup_{a,b,c > 0} DTIME(a.n^c+b)$
- DTIME(T) depends on the specifics of the TM model (no. of tapes, alphabet size)
- But P is robust: Models can simulate each other with only "polynomial slow down"







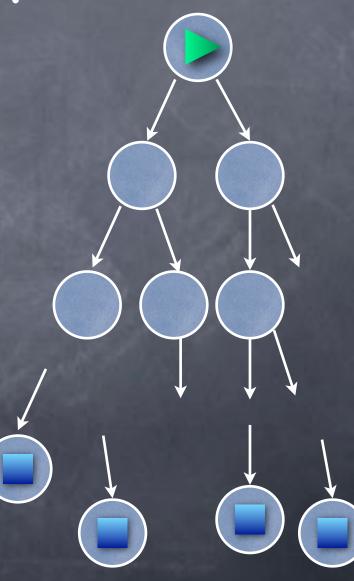




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- □ L ∈ NTIME(T): an NTM decides L in time at most T



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 - Finding a certificate (or even finding if there exists a certificate) may take longer

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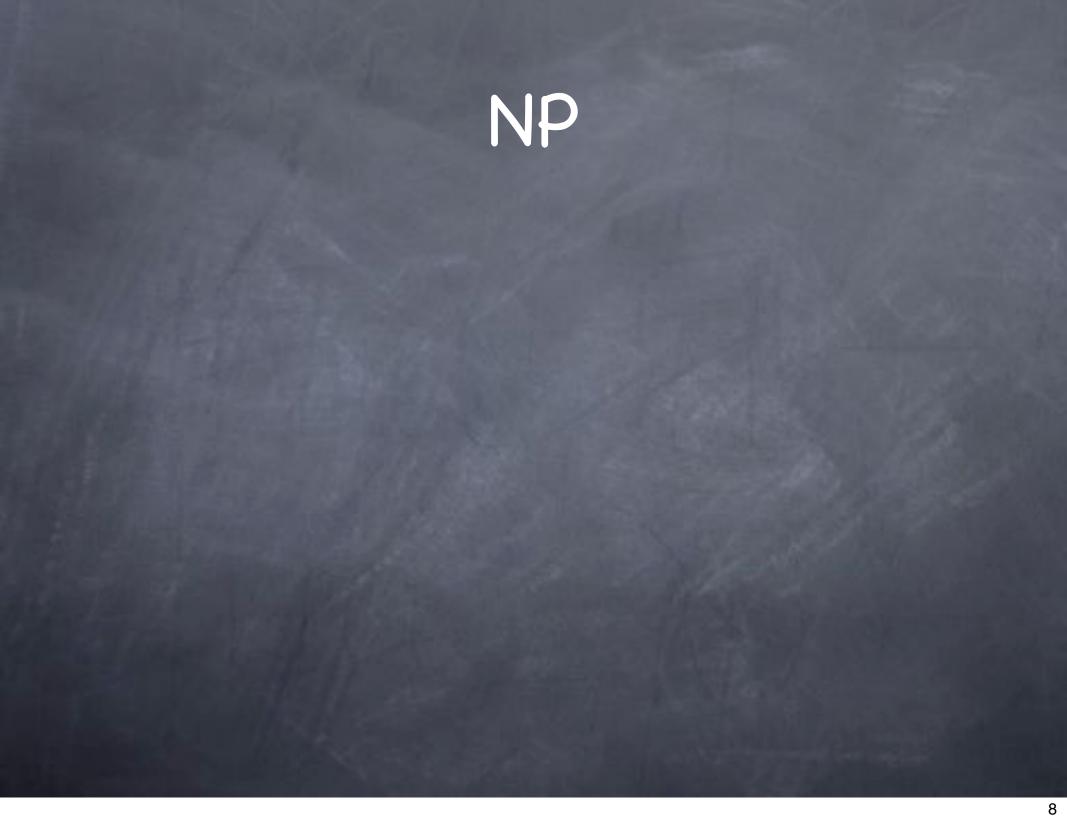
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- Note: Completeness and soundness

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- All problems in P (empty certificate)

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- Solve all sorts of optimization problems efficiently!

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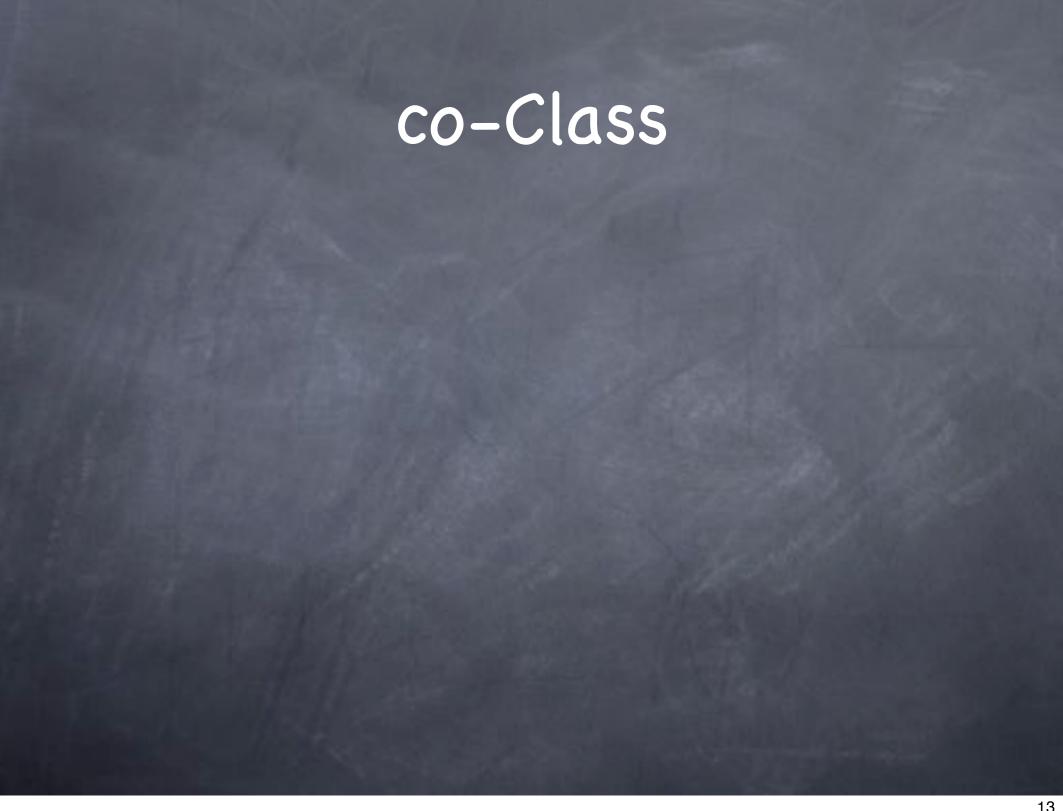
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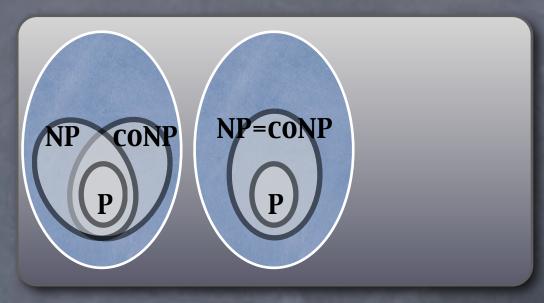
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 - flip accept/reject states and flip "there exists" and "for all" in the acceptance criterion (NTM ↔ "co-NTM")

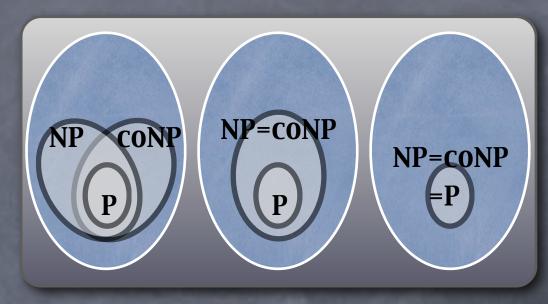
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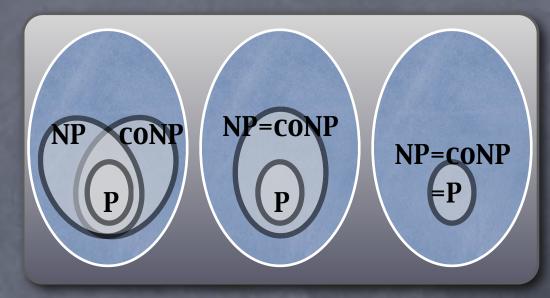
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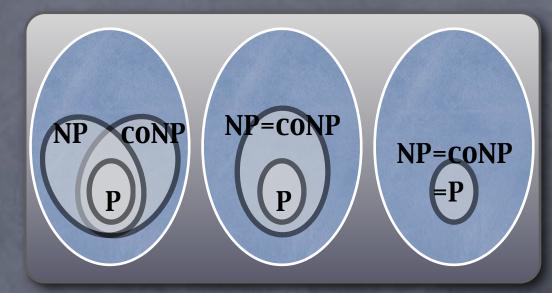




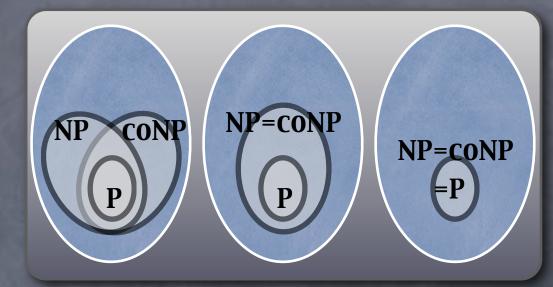
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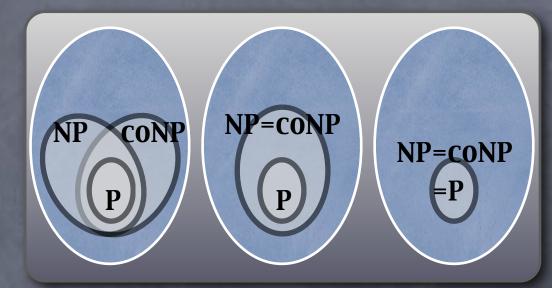


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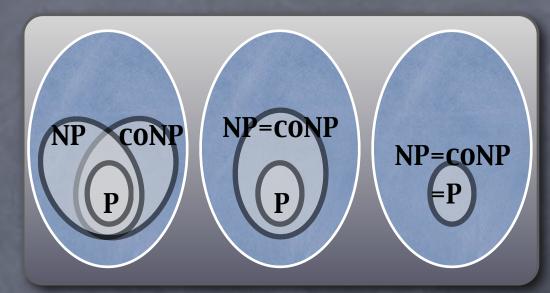
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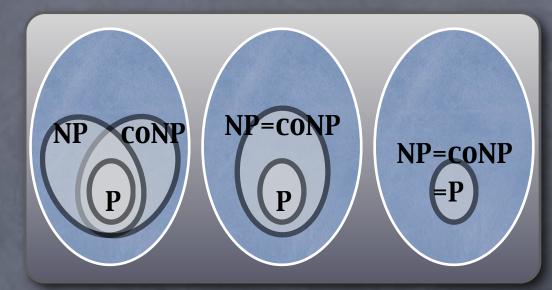
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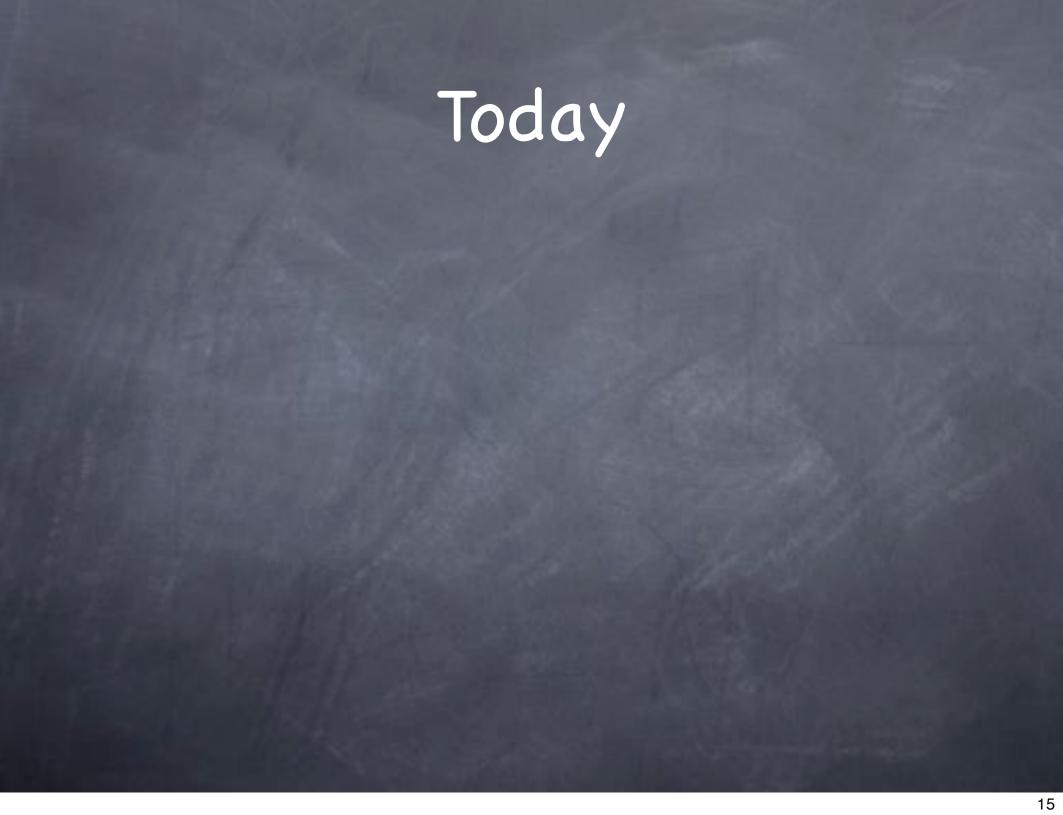


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 - \otimes x \rightarrow (x,pad), so that Exp(|x|) = Poly(|x,pad|)

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- Also, EXP = NEXP [Exercise]
 - padding to scale up both classes
- If P=NP, then the complexity landscape would get greatly simplified than believed (more later)



DTIME

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 - P, EXP

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 - Two views: co-NTM and "no counter-example"

NP completeness

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 - a la reductions (of course)