

Approximation Algorithms

Lecture 7

September 16, 2014

Today's Lecture

Don't give up on **NP-Hard** problems:

- (A) Faster exponential time algorithms: $n^{O(n)}$, 3^n , 2^n , etc.
- (B) Fixed parameter tractable.
- (C) Find an approximate solution.

Part I

Greedy algorithms and approximation algorithms

Greedy algorithms

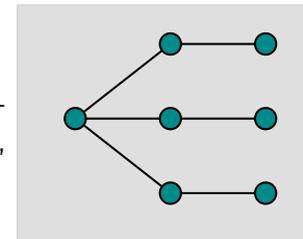
1. **greedy algorithms**: do locally the right thing...
2. ...and they suck.

VertexCoverMin

Instance: A graph G .

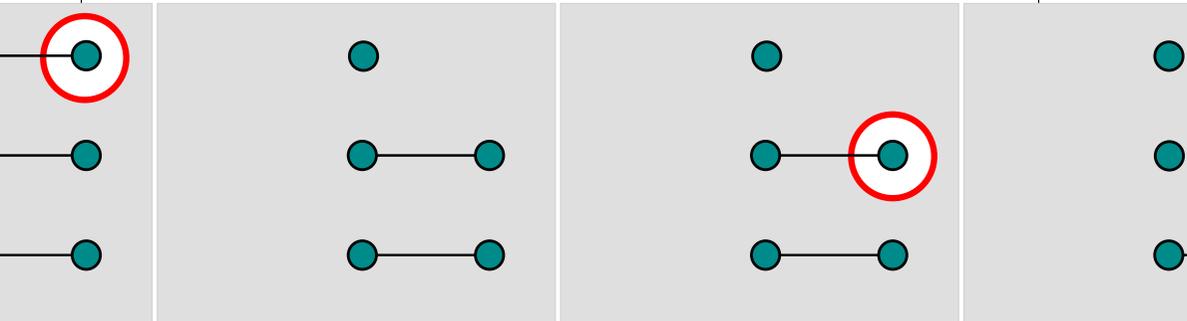
Question: Return the **smallest** subset $S \subseteq V(G)$, s.t. S touches all the edges of G .

3. **GreedyVertexCover**: pick vertex with highest degree, remove, repeat.



Greedy algorithms

GreedyVertexCover in action...



Observation

GreedyVertexCover returns 4 vertices, but opt is 3 vertices.

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Good enough...

Definition

In a **minimization** optimization problem, one looks for a valid solution that minimizes a certain target function.

1. **VertexCoverMin**: $\text{Opt}(\mathbf{G}) = \min_{S \subseteq V(\mathbf{G}), S \text{ cover of } \mathbf{G}} |S|$.
2. **VertexCover(G)**: set realizing sol.
3. **Opt(G)**: value of the target function for the optimal solution.

Definition

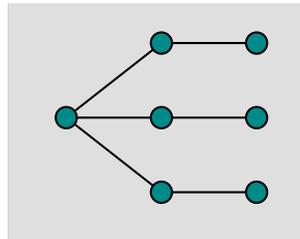
Alg is α -**approximation algorithm** for problem **Min**, achieving an approximation $\alpha \geq 1$, if for all inputs **G**, we have:

$$\frac{\text{Alg}(\mathbf{G})}{\text{Opt}(\mathbf{G})} \leq \alpha.$$

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Back to GreedyVertexCover

1. **GreedyVertexCover**: pick vertex with highest degree, remove, repeat.
2. Returns 4, but opt is 3!
3. Can **not** be better than a $4/3$ -approximation algorithm.
4. Actually it is much worse!



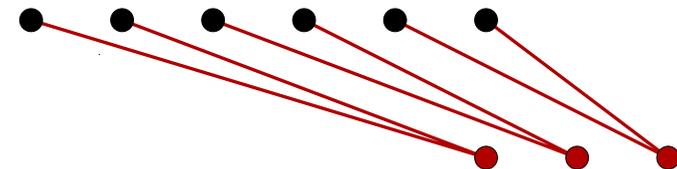
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How bad is GreedyVertexCover?

Build a bipartite graph.

Let the top partite set be of size n .

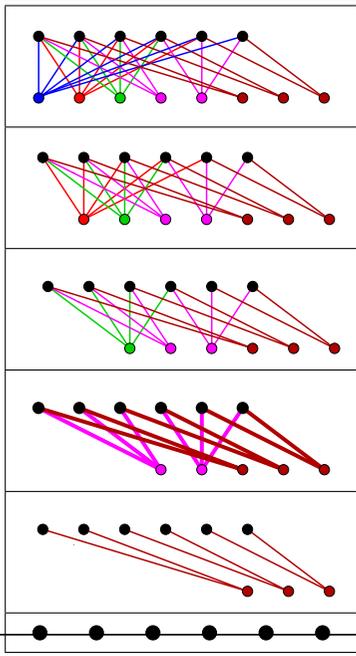
In the bottom set add $\lfloor n/2 \rfloor$ vertices of degree 2, such that each edge goes to a different vertex above.



Repeatedly add $\lfloor n/i \rfloor$ bottom vertices of degree i , for $i = 2, \dots, n$.

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How bad is GreedyVertexCover?



1. Bottom row taken by Greedy.
2. Top row was a smaller solution.

Lemma

The algorithm **GreedyVertexCover** is $\Omega(\log n)$ approximation to the optimal solution to **VertexCoverMin**.

See notes for details!

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Greedy Vertex Cover

Theorem

The greedy algorithm for **VertexCover** achieves $\Theta(\log n)$ approximation, where n (resp. m) is the number of vertices (resp., edges) in the graph. Running time is $O(mn^2)$.

Proof

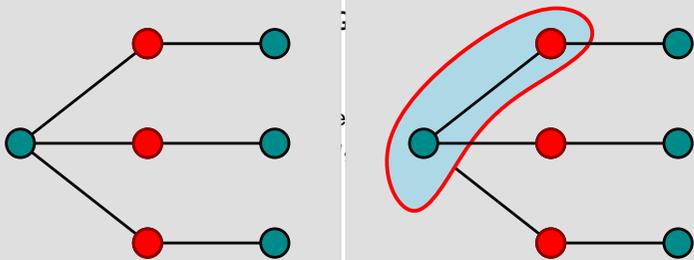
Lower bound follows from lemma.

Upper bound follows from analysis of greedy algorithm for **Set Cover**, which will be done shortly.

As for the running time, each iteration of the algorithm takes $O(mn)$ time, and there are at most n iterations.

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Two for the price of one



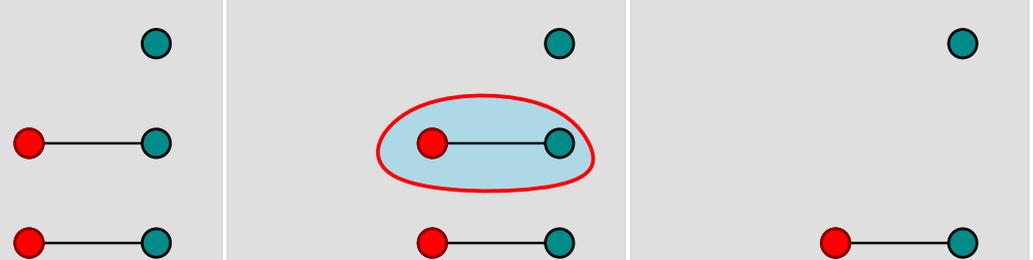
Theorem

ApproxVertexCover is a 2-approximation algorithm for **VertexCoverMin** that runs in $O(n^2)$ time.

Proof...

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Two for the price of one - example



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Part II

Fixed parameter tractability,
approximation, and fast
exponential time algorithms (to
say nothing of the dog)

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What if the vertex cover is small?

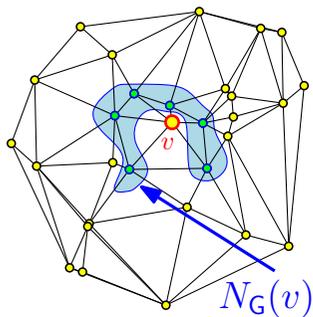
1. $G = (V, E)$ with n vertices
2. $K \leftarrow$ Approximate **VertexCoverMin** up to a factor of two.
3. Any vertex cover of G is of size $\geq K/2$.
4. Naively compute optimal in $O(n^{K+2})$ time.

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Induced subgraph

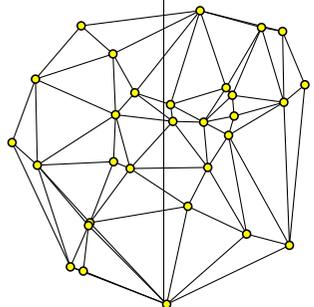
Definition

$N_G(v)$: **Neighborhood** of v – set of vertices of G adjacent to v .



Definition

Let $G = (V, E)$ be a graph. For a subset $S \subseteq V$, let G_S be the **induced subgraph** over S .



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Exact fixed parameter tractable algorithm

Fixed parameter tractable algorithm for **VertexCoverMin**.

Computes minimum vertex cover for the induced graph G_X :

```
fpVCI( $X, \beta$ )  
    //  $\beta$ : size of VC computed so far.  
    if  $X = \emptyset$  or  $G_X$  has no edges then return  $\beta$   
     $e \leftarrow$  any edge  $uv$  of  $G_X$ .  
     $\beta_1 = \mathbf{fpVCI}(X \setminus \{u, v\}, \beta + 2)$   
     $\beta_2 = \mathbf{fpVCI}(X \setminus (\{u\} \cup N_{G_X}(v)), \beta + |N_{G_X}(v)|)$   
     $\beta_3 = \mathbf{fpVCI}(X \setminus (\{v\} \cup N_{G_X}(u)), \beta + |N_{G_X}(u)|)$   
    return  $\min(\beta_1, \beta_2, \beta_3)$ .
```

```
algFPVertexCover( $G = (V, E)$ )  
    return fpVCI( $V, 0$ )
```

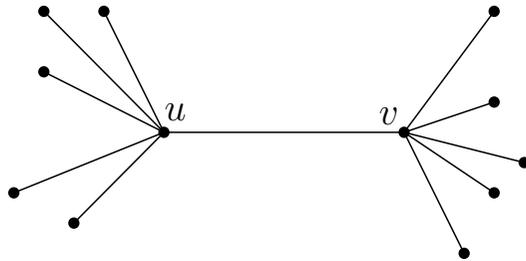
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Depth of recursion

Lemma

The algorithm **algFPVertexCover** returns the optimal solution to the given instance of **VertexCoverMin**.

Proof...



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Depth of recursion II

Lemma

The depth of the recursion of **algFPVertexCover**(**G**) is at most α , where α is the minimum size vertex cover in **G**.

Proof.

1. When the algorithm takes both **u** and **v** - one of them in opt. Can happen at most α times.
2. Algorithm picks $N_{G_x}(v)$ (i.e., β_2). Conceptually add **v** to the vertex cover being computed.
3. Do the same thing for the case of β_3 .
4. Every such call add one element of the opt to conceptual set cover. Depth of recursion is $\leq \alpha$.

□

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Vertex Cover

Exact fixed parameter tractable algorithm

Theorem

G: graph with **n** vertices. Min vertex cover of size α . Then, **algFPVertexCover** returns opt. vertex cover.

Running time is $O(3^\alpha n^2)$.

Proof:

1. By lemma, recursion tree has depth α .
2. Rec-tree contains $\leq 2 \cdot 3^\alpha$ nodes.
3. Each node requires $O(n^2)$ work. ■

Algorithms with running time $O(n^c f(\alpha))$, where α is some parameter that depends on the problem are **fixed parameter tractable**.

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Part III

Traveling Salesperson Problem

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TSP

TSP-Min

Instance: $G = (V, E)$ a complete graph, and $\omega(e)$ a cost function on edges of G .

Question: The cheapest tour that visits all the vertices of G exactly once.

Solved exactly naively in $\approx n!$ time.
Using DP, solvable in $O(n^2 2^n)$ time.

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TSP Hardness

Theorem

TSP-Min can not be approximated within **any** factor unless **NP = P**.

Proof.

1. Reduction from **Hamiltonian Cycle** into **TSP**.
2. $G = (V, E)$: instance of Hamiltonian cycle.
3. H : Complete graph over V .
$$\forall u, v \in V \quad w_H(uv) = \begin{cases} 1 & uv \in E \\ 2 & \text{otherwise.} \end{cases}$$
4. \exists tour of price n in $H \iff \exists$ Hamiltonian cycle in G .
5. No Hamiltonian cycle \implies **TSP** price at least $n + 1$.
6. But... replace **2** by cn , for c an arbitrary number

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TSP Hardness - proof continued

Proof.

1. Price of all tours are either:
 - (i) n (only if \exists Hamiltonian cycle in G),
 - (ii) larger than $cn + 1$ (actually, $\geq cn + (n - 1)$).
2. Suppose you had a poly time c -approximation to **TSP-Min**.
3. Run it on H :
 - (i) If returned value $\geq cn + 1 \implies$ no Ham Cycle since $(cn + 1)/c > n$
 - (ii) If returned value $\leq cn \implies$ Ham Cycle since $OPT \leq cn < cn + 1$
4. c -approximation algorithm to **TSP** \implies poly-time algorithm for **NP-Complete** problem. Possible only if **P = NP**.

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TSP with the triangle inequality

Because it is not that bad after all.

TSP $_{\Delta \neq}$ -Min

Instance: $G = (V, E)$ is a complete graph. There is also a cost function $\omega(\cdot)$ defined over the edges of G , that complies with the triangle inequality.

Question: The cheapest tour that visits all the vertices of G exactly once.

triangle inequality: $\omega(\cdot)$ if

$$\forall u, v, w \in V(G), \quad \omega(u, v) \leq \omega(u, w) + \omega(w, v).$$

Shortcutting

σ : a path from s to t in $G \implies \omega(st) \leq \omega(\sigma)$.

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TSP with the triangle inequality

Continued...

Definition

Cycle in \mathbf{G} is **Eulerian** if it visits every **edge** of \mathbf{G} exactly once.

Assume you already seen the following:

Lemma

A graph \mathbf{G} has a cycle that visits every edge of \mathbf{G} exactly once (i.e., an Eulerian cycle) if and only if \mathbf{G} is connected, and all the vertices have even degree. Such a cycle can be computed in $O(n + m)$ time, where n and m are the number of vertices and edges of \mathbf{G} , respectively.

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TSP with the triangle inequality

Continued...

1. C_{opt} optimal **TSP** tour in \mathbf{G} .
2. **Observation:**
 $\omega(C_{\text{opt}}) \geq \text{weight}(\text{cheapest spanning graph of } \mathbf{G})$.
3. **MST:** cheapest spanning graph of \mathbf{G} .
 $\omega(C_{\text{opt}}) \geq \omega(\text{MST}(\mathbf{G}))$
4. $O(n \log n + m) = O(n^2)$: time to compute **MST**.
 $n = |\mathbf{V}(\mathbf{G})|$, $m = \binom{n}{2}$.

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TSP with the triangle inequality

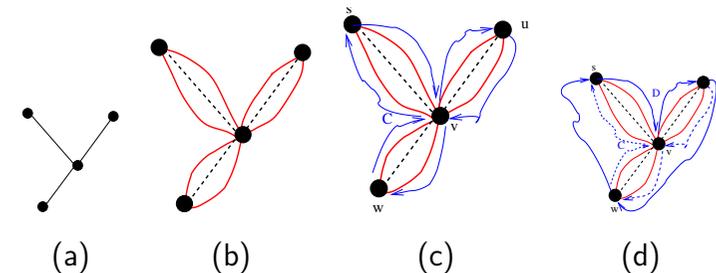
2-approximation

1. $T \leftarrow \text{MST}(\mathbf{G})$
2. $H \leftarrow$ duplicate every edge of T .
3. H has an Eulerian tour.
4. C : Eulerian cycle in H .
5. $\omega(C) = \omega(H) = 2\omega(T) = 2\omega(\text{MST}(\mathbf{G})) \leq 2\omega(C_{\text{opt}})$.
6. π : Shortcut C so visit every vertex once.
7. $\omega(\pi) \leq \omega(C)$

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TSP with the triangle inequality

2-approximation algorithm in figures



Euler Tour: VUVWVSU
First occurrences: **VUUVWVSU**
Shortcut String: **VUWSU**

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TSP with the triangle inequality

2-approximation - result

Theorem

\mathbf{G} : Instance of $TSP_{\Delta \neq}$ -Min.

\mathbf{C}_{opt} : min cost TSP tour of \mathbf{G} .

\implies Compute a tour of \mathbf{G} of length $\leq 2\omega(\mathbf{C}_{\text{opt}})$.

Running time of the algorithm is $O(n^2)$.

\mathbf{G} : n vertices, cost function $\omega(\cdot)$ on the edges that comply with the triangle inequality.

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TSP with the triangle inequality

3/2-approximation

Definition

$\mathbf{G} = (\mathbf{V}, \mathbf{E})$, a subset $\mathbf{M} \subseteq \mathbf{E}$ is a **matching** if no pair of edges of \mathbf{M} share endpoints.

A **perfect matching** is a matching that covers all the vertices of \mathbf{G} .

w : weight function on the edges. **Min-weight perfect matching**, is the minimum weight matching among all perfect matching, where

$$\omega(\mathbf{M}) = \sum_{e \in \mathbf{M}} \omega(e).$$

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TSP with the triangle inequality

3/2-approximation

The following is known:

Theorem

Given a graph \mathbf{G} and weights on the edges, one can compute the min-weight perfect matching of \mathbf{G} in polynomial time.

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Min weight perfect matching vs. TSP

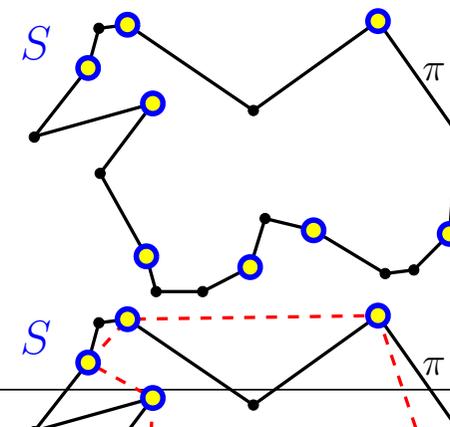
Lemma

$\mathbf{G} = (\mathbf{V}, \mathbf{E})$: complete graph.

$\mathbf{S} \subseteq \mathbf{V}$: even size.

$\omega(\cdot)$: a weight function over \mathbf{E} .

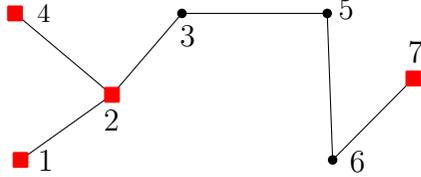
\implies min-weight perfect matching in $\mathbf{G}_{\mathbf{S}}$ is $\leq \omega(\text{TSP}(\mathbf{G}))/2$.



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A more perfect tree?

1. How to make the tree Eulerian?



2. Pesky odd degree vertices must die!
3. Number of odd degree vertices in a graph is even!
4. Compute min-weight matching on odd vertices, and add to **MST**.
5. $\mathbf{H} = \mathbf{MST} + \mathbf{min-weight-matching}$ is Eulerian.
6. Weight of resulting cycle in $\mathbf{H} \leq (3/2)\omega(\mathbf{TSP})$.

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Even number of odd degree vertices

Lemma

The number of odd degree vertices in any graph G' is even.

Proof:

$\mu = \sum_{v \in V(G')} d(v) = 2|E(G')|$ and thus even.

$U = \sum_{v \in V(G'), d(v) \text{ is even}} d(v)$ even too.

Thus,

$$\alpha = \sum_{v \in V, d(v) \text{ is odd}} d(v) = \mu - U = \text{even number,}$$

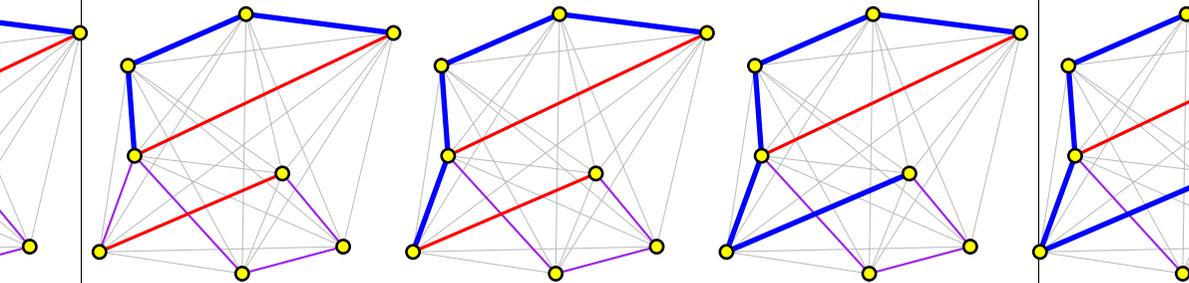
since μ and U are both even.

Number of elements in sum of all odd numbers must be even, since the total sum is even.

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3/2-approximation algorithm for TSP

Animated!



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3/2-approximation algorithm for TSP

The result

Theorem

Given an instance of TSP with the triangle inequality, one can compute in polynomial time, a $(3/2)$ -approximation to the optimal TSP.

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Biographical Notes

The $3/2$ -approximation for TSP with the triangle inequality is due to ?.