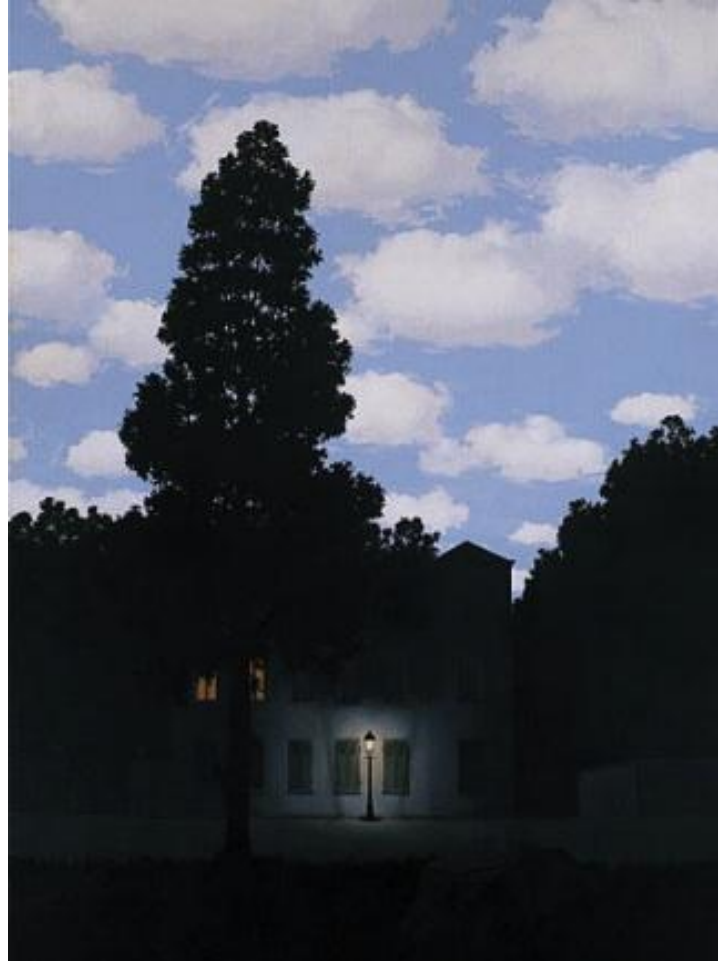


# Light and Shading



"Empire of Light", Magritte

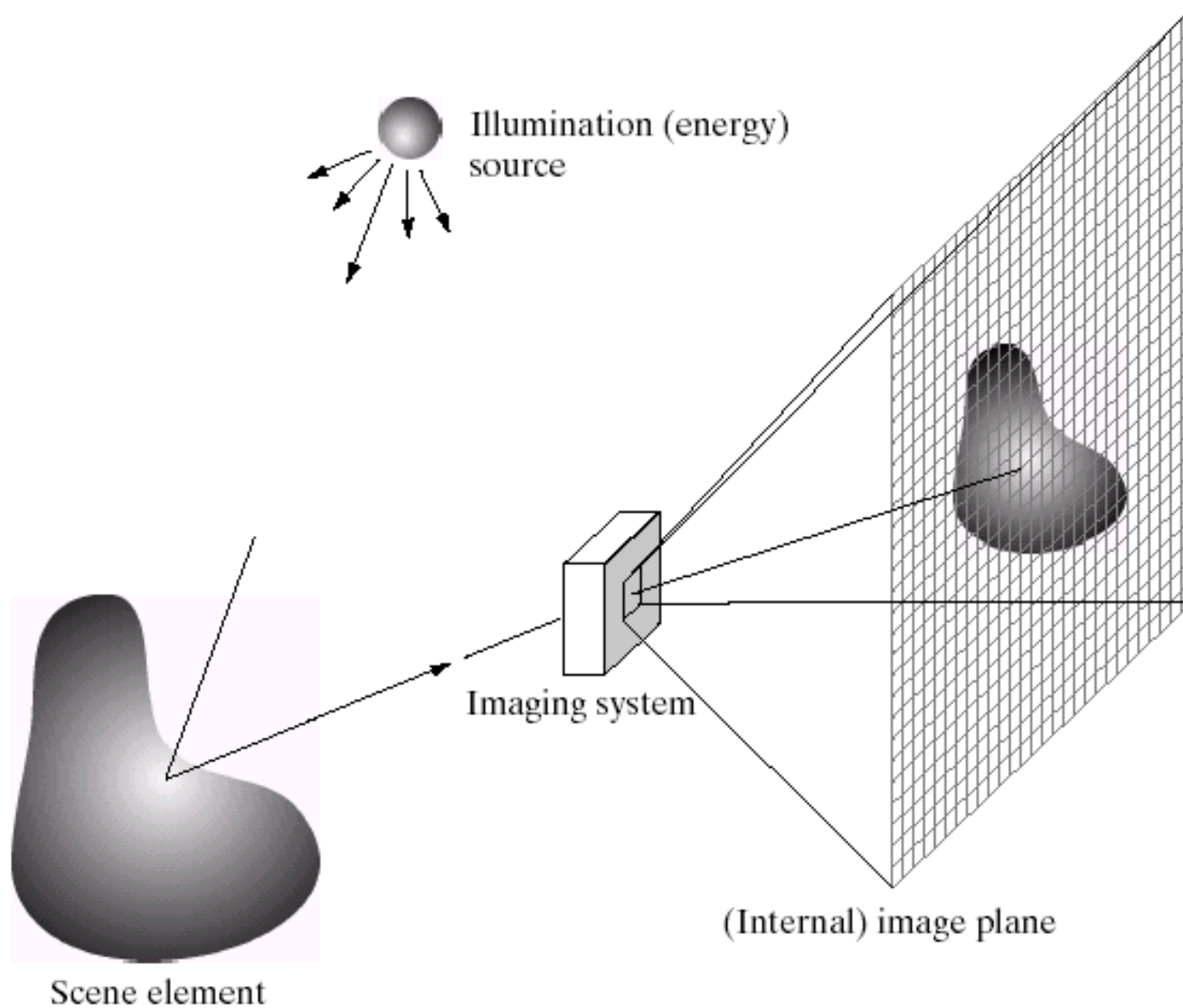
Computer Vision

Derek Hoiem, University of Illinois

# Administrative stuff

- Some people waiting to get in
- Tentative office hours
  - Derek: Wed 4pm, 8pm (skype only)
  - Ruiqi: Mon 7pm, Thurs 4pm
- Homework 1 released soon
- Any questions?

# How light is recorded



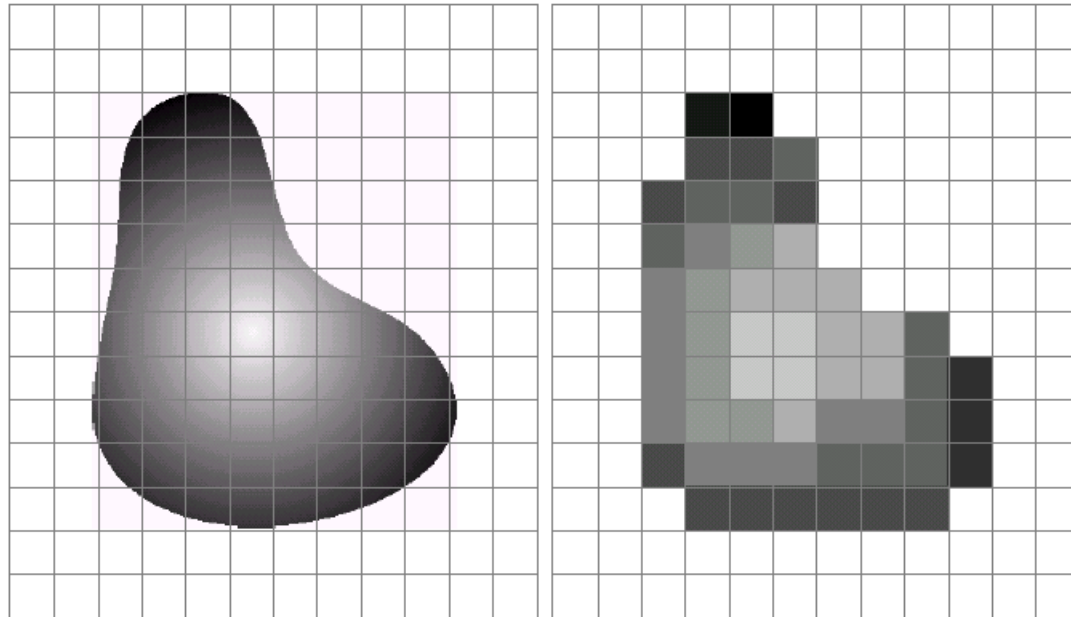
# Digital camera



## A digital camera replaces film with a sensor array

- Each cell in the array is light-sensitive diode that converts photons to electrons
- Two common types: Charge Coupled Device (CCD) and CMOS
- <http://electronics.howstuffworks.com/digital-camera.htm>

# Sensor Array



a b

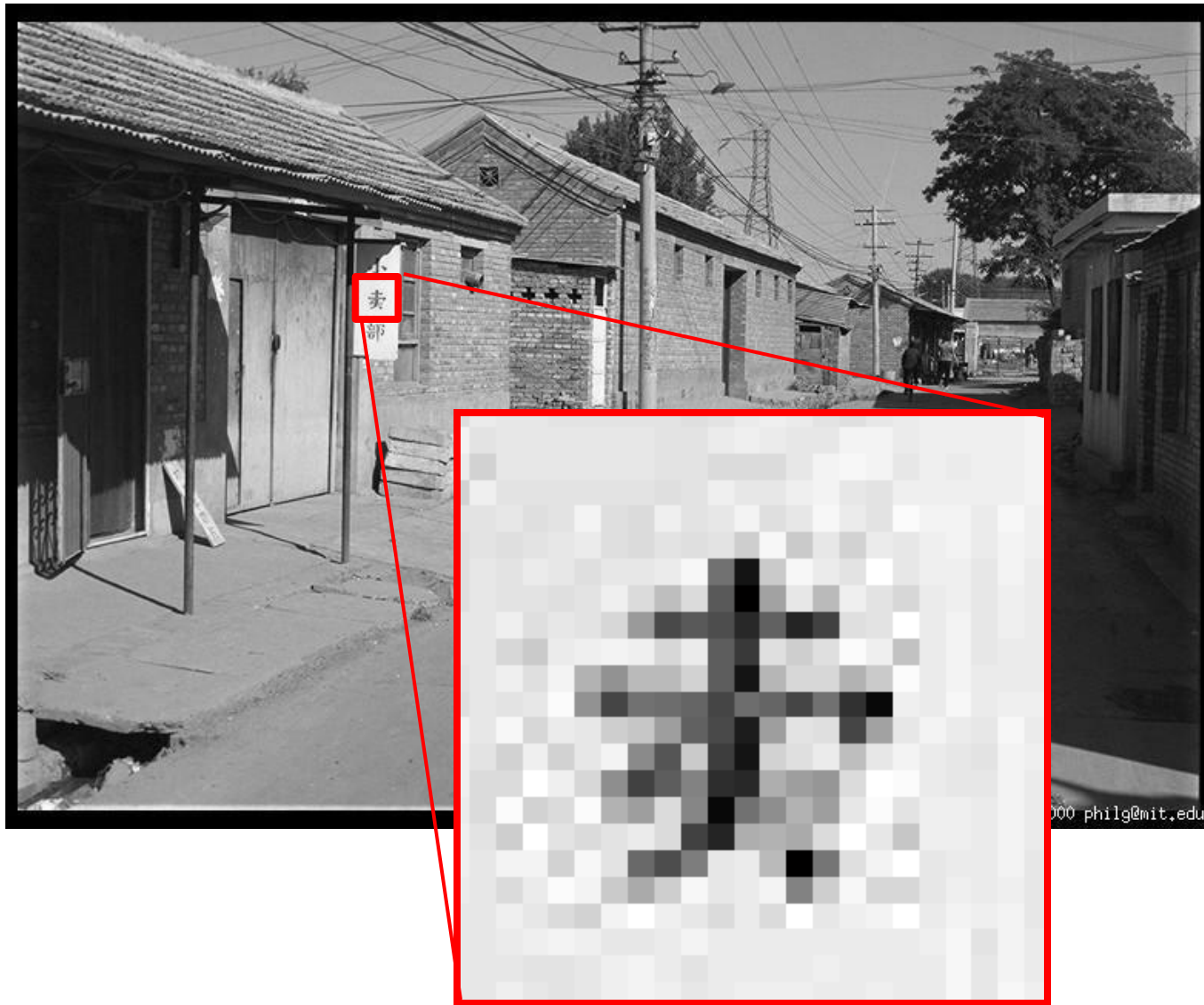
**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.



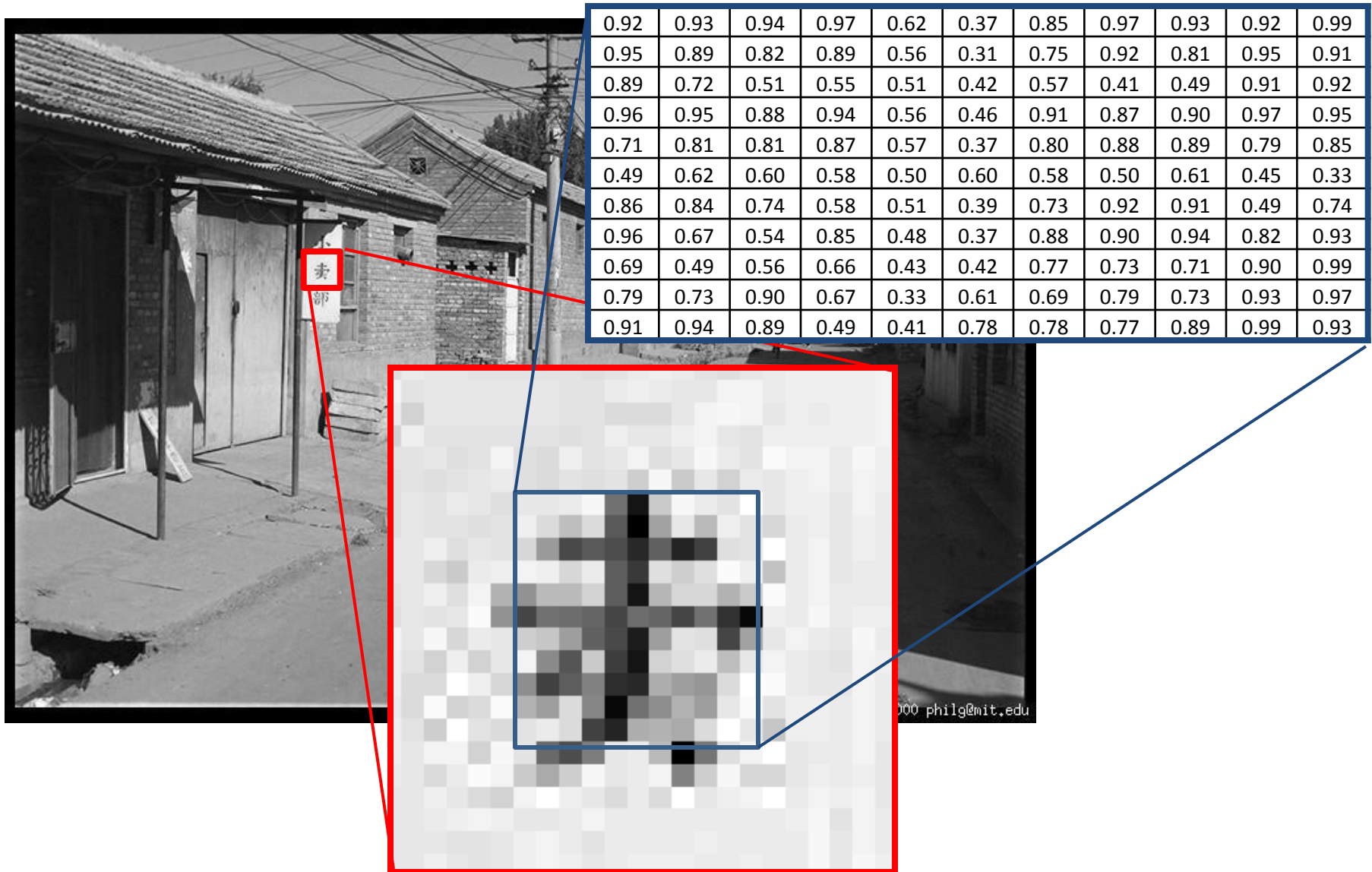
CMOS sensor

Each sensor cell records amount of light coming in at a small range of orientations

# The raster image (pixel matrix)



# The raster image (pixel matrix)



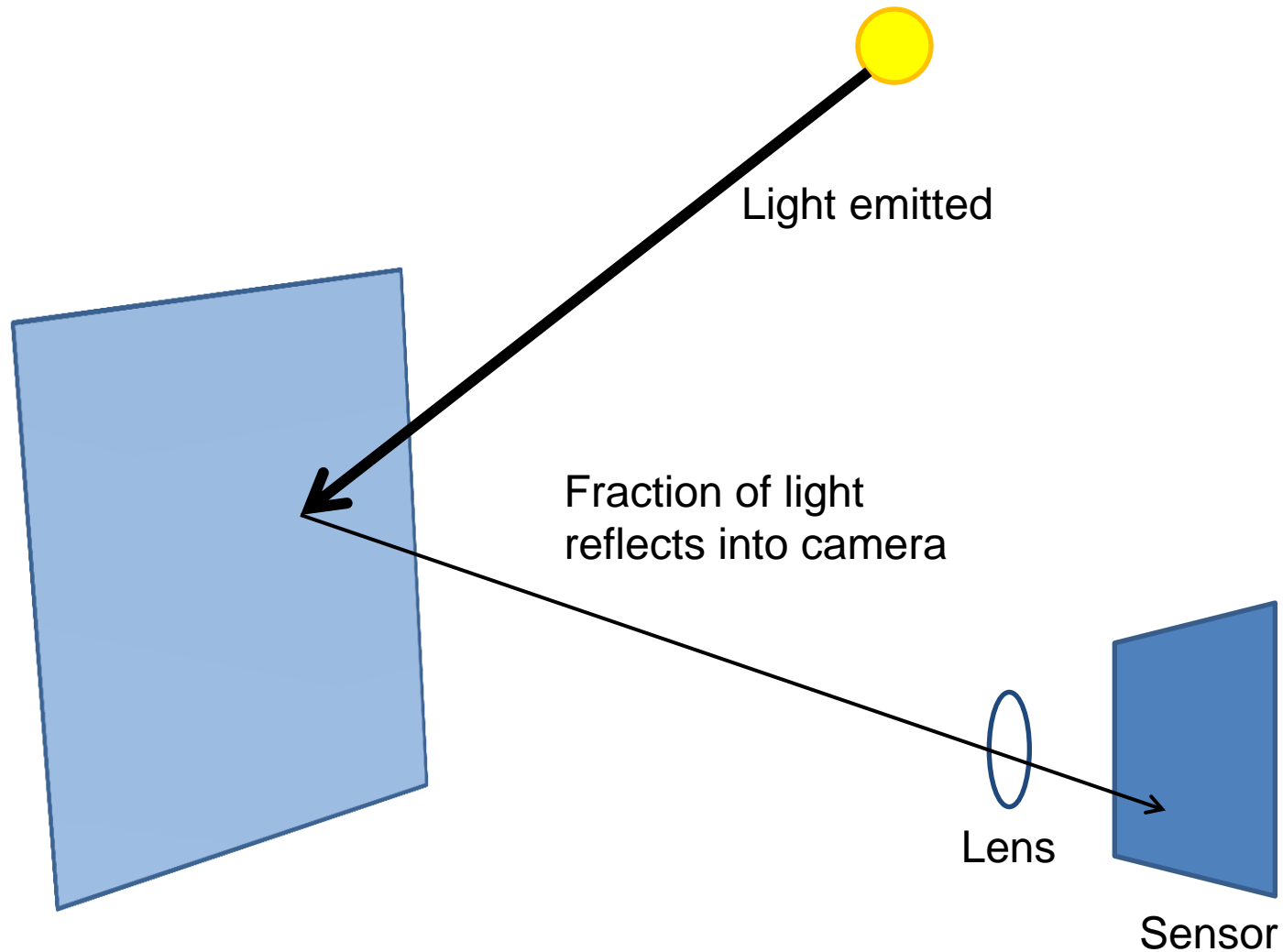
# Today's class: Light and Shading



- What determines a pixel's intensity?
- What can we infer about the scene from pixel intensities?

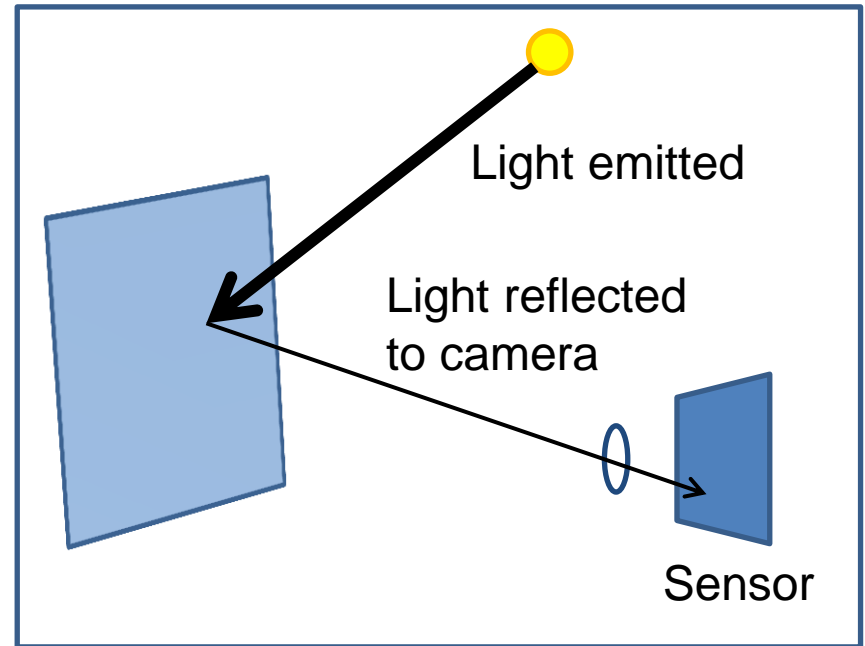


# How does a pixel get its value?



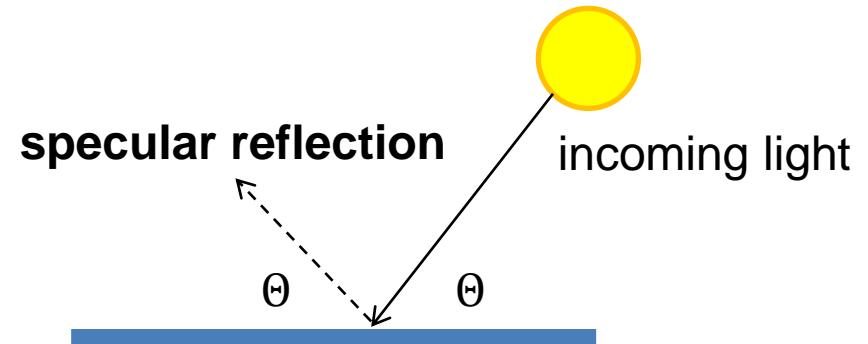
# How does a pixel get its value?

- Major factors
  - Illumination strength and direction
  - Surface geometry
  - Surface material
  - Nearby surfaces
  - Camera gain/exposure

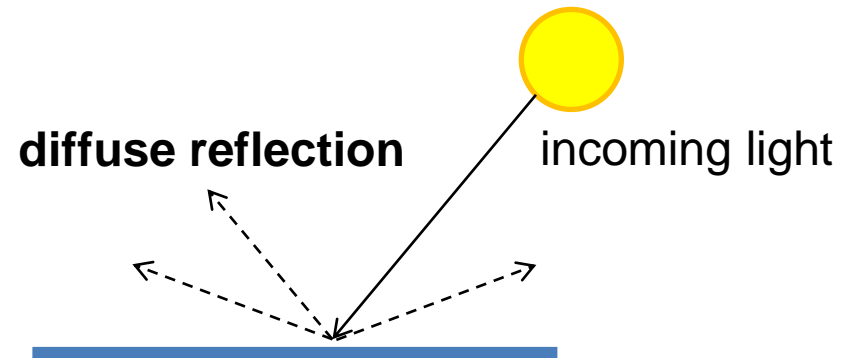


# Basic models of reflection

- Specular: light bounces off at the incident angle
  - E.g., mirror

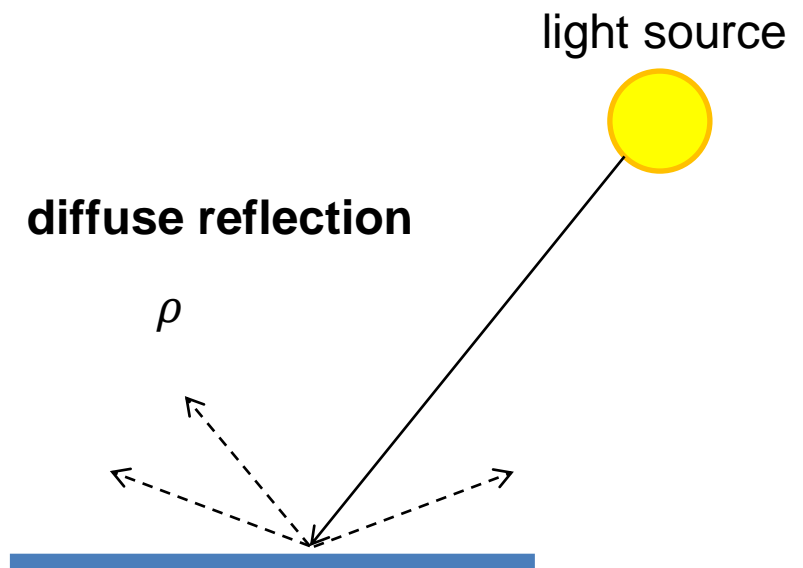
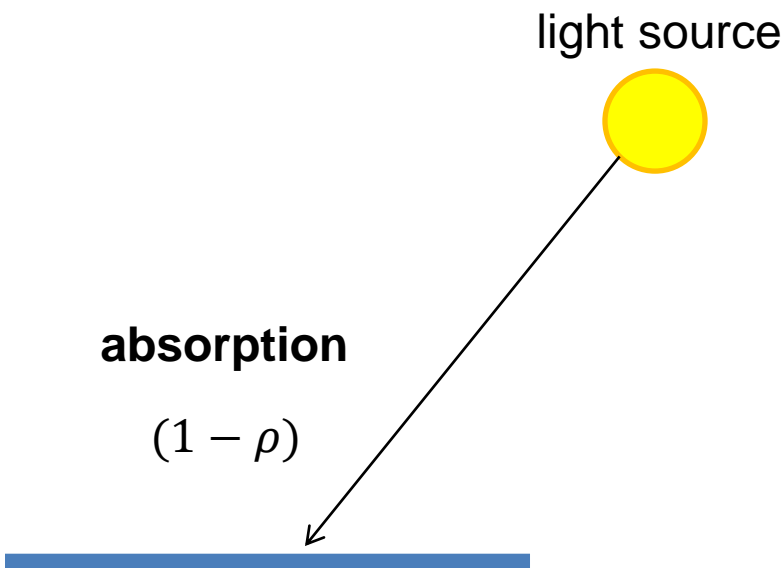


- Diffuse: light scatters in all directions
  - E.g., brick, cloth, rough wood



# Lambertian reflectance model

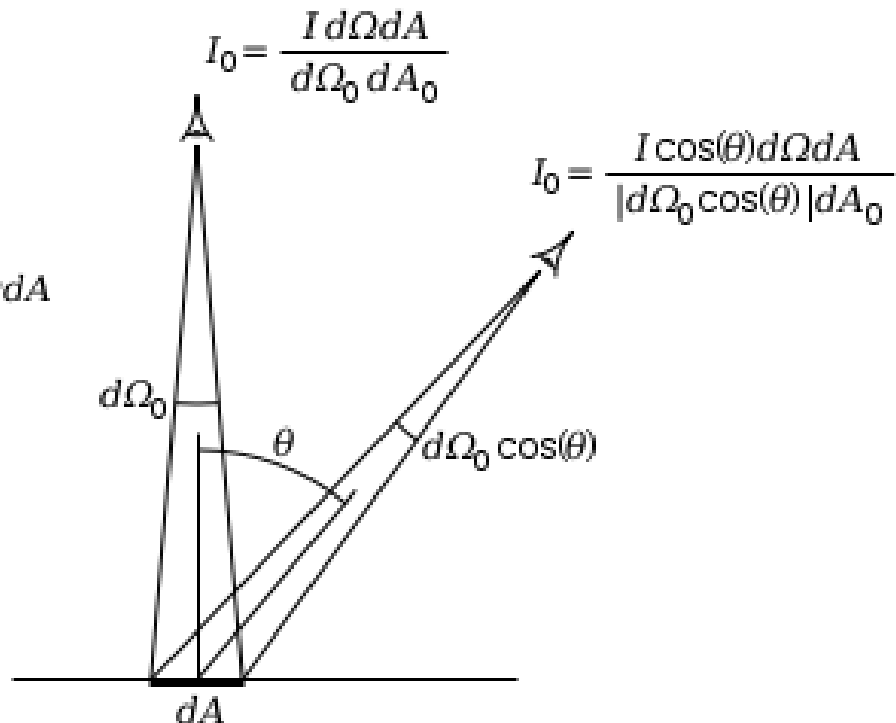
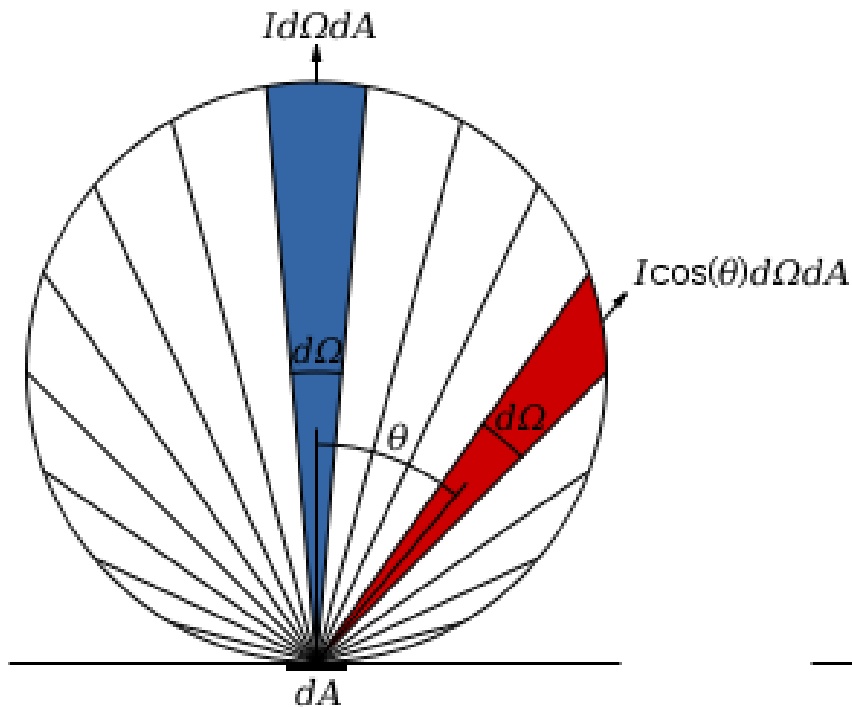
- Some light is absorbed (function of albedo  $\rho$ )
- Remaining light is scattered (diffuse reflection)
- Examples: soft cloth, concrete, matte paints



# Diffuse reflection: Lambert's cosine law

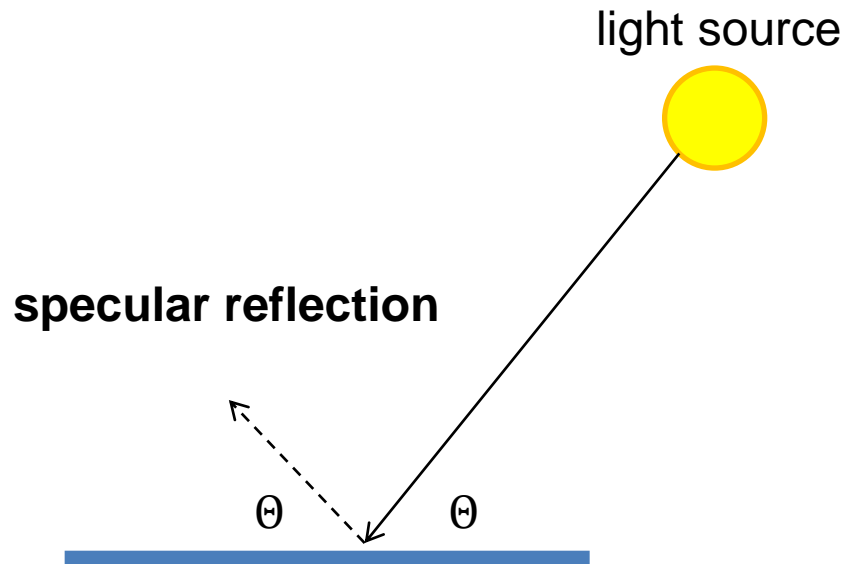
Intensity does *not* depend on viewer angle.

- Amount of reflected light proportional to  $\cos(\theta)$
- Visible solid angle also proportional to  $\cos(\theta)$



# Specular Reflection

- Reflected direction depends on light orientation and surface normal
  - E.g., mirrors are fully specular
  - Most surfaces can be modeled with a mixture of diffuse and specular components



Flickr, by suzysputnik



Flickr, by piratejohnny

# Most surfaces have both specular and diffuse components

- Specularity = spot where specular reflection dominates (typically reflects light source)



Photo: northcountryhardwoodfloors.com



Typically, specular component is small

# Intensity and Surface Orientation

Intensity depends on illumination angle because less light comes in at oblique angles.

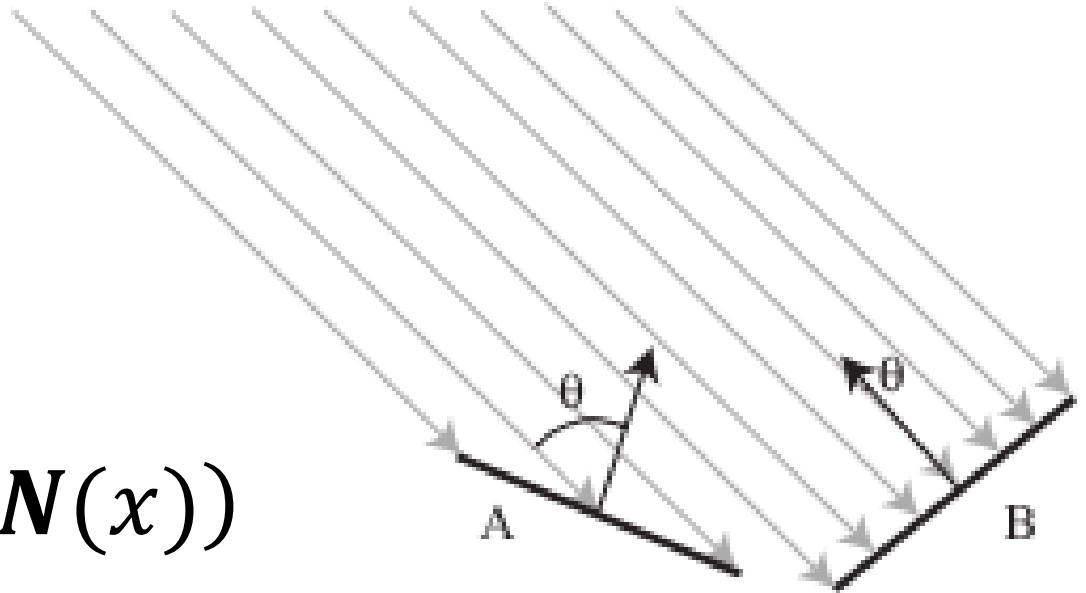
$\rho$  = albedo

$\mathbf{S}$  = directional source

$\mathbf{N}$  = surface normal

$I$  = reflected intensity

$$I(x) = \rho(x)(\mathbf{S} \cdot \mathbf{N}(x))$$

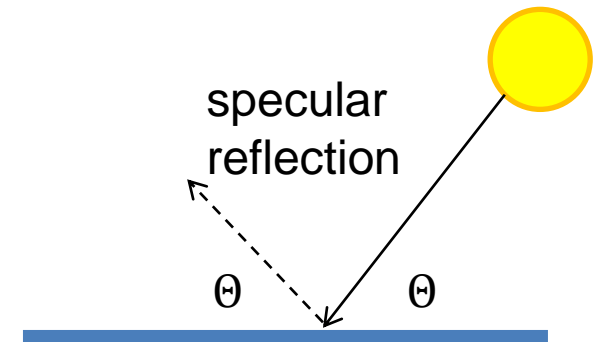
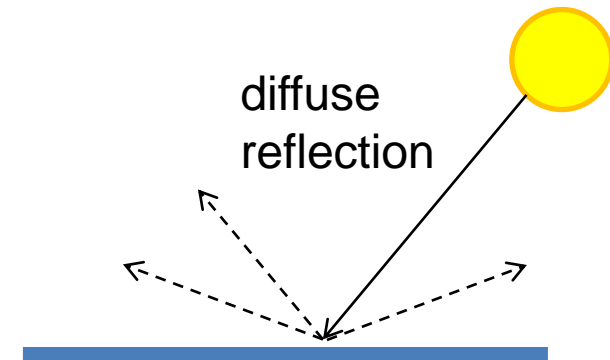
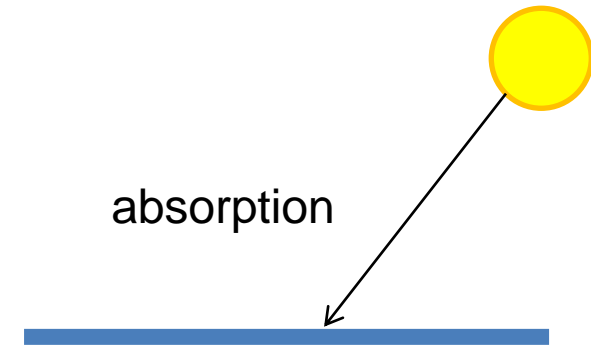






# Recap

- When light hits a typical surface
  - Some light is absorbed ( $1-\rho$ )
    - More absorbed for low albedos
  - Some light is reflected diffusely
    - Independent of viewing direction
  - Some light is reflected specularly
    - Light bounces off (like a mirror), depends on viewing direction

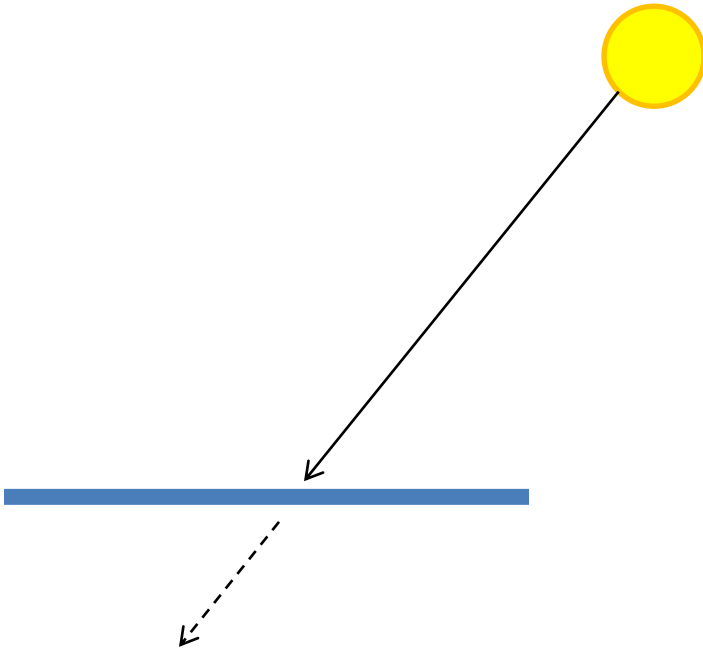


# Other possible effects



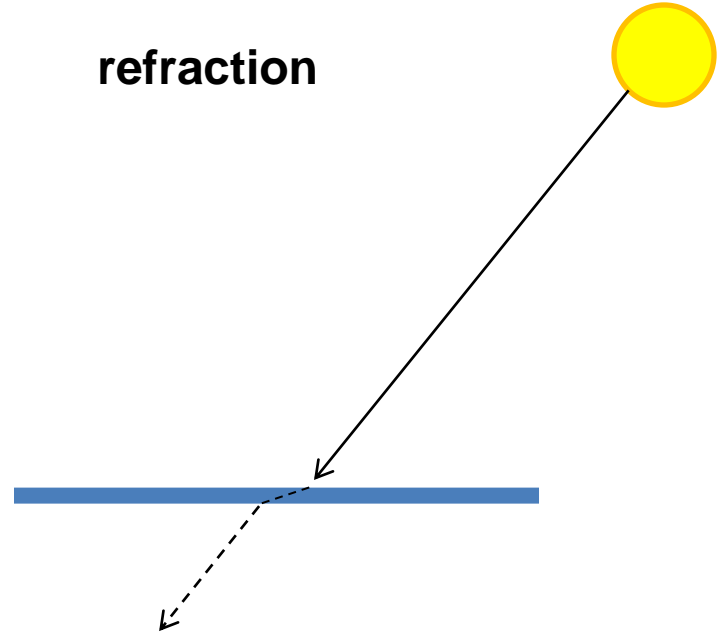
**transparency**

light source



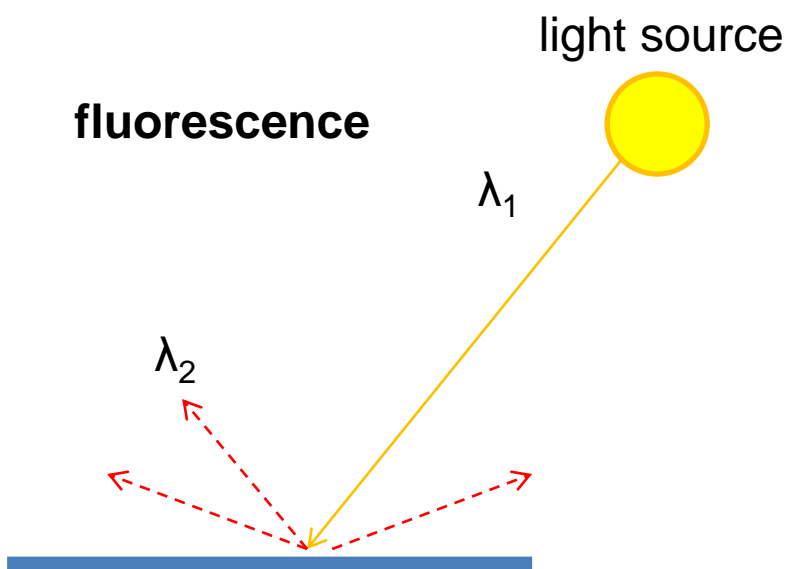
**refraction**

light source

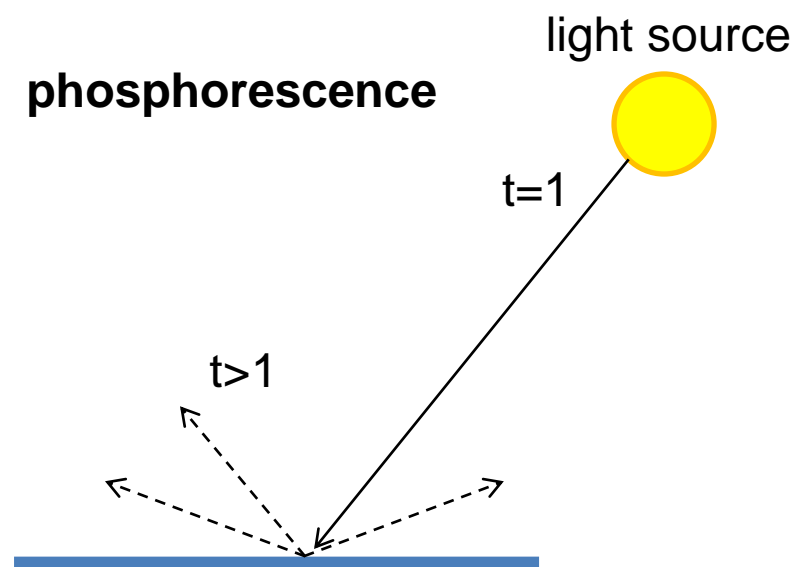


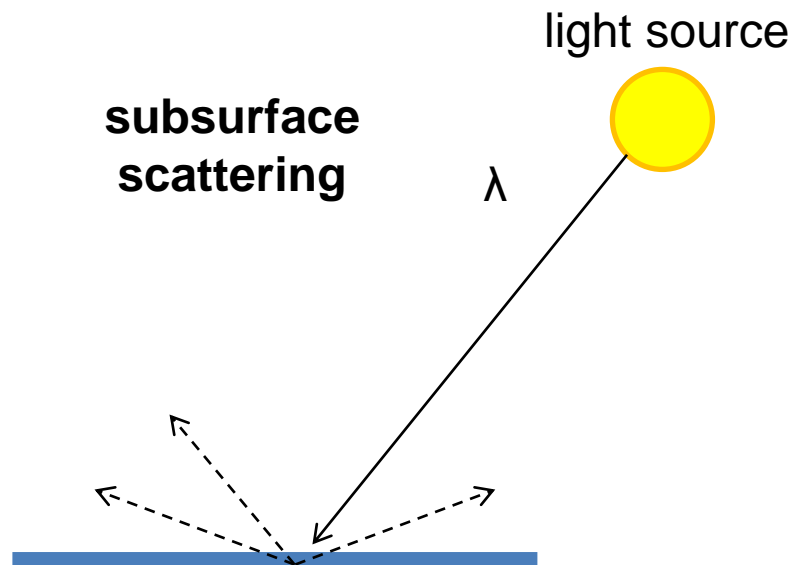


**fluorescence**



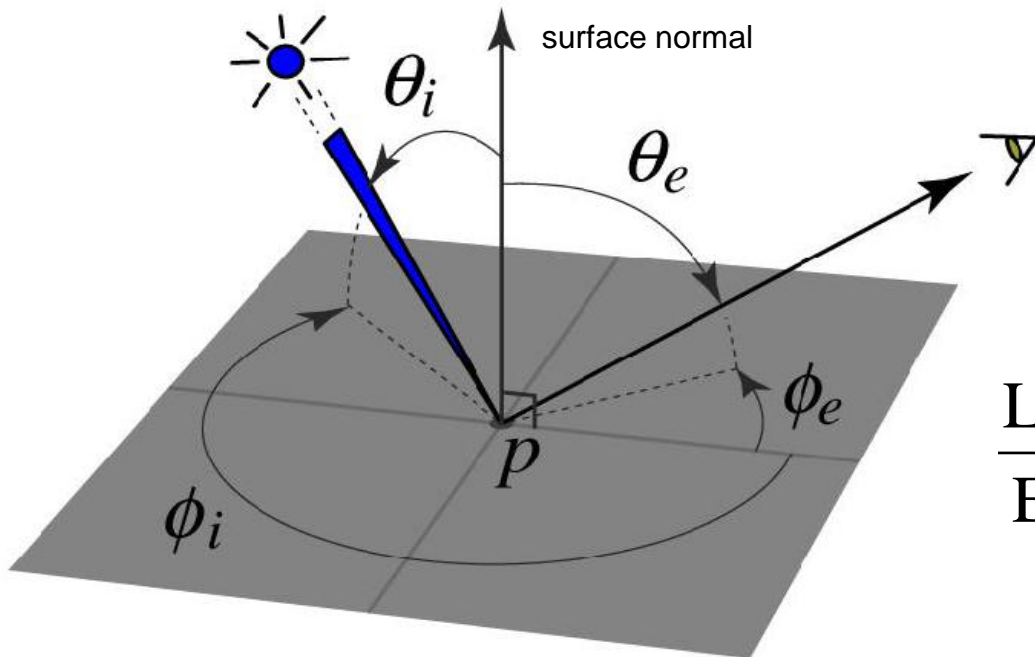
**phosphorescence**





# BRDF: Bidirectional Reflectance Distribution Function

- Model of local reflection that tells how bright a surface appears when viewed from one direction when light falls on it from another

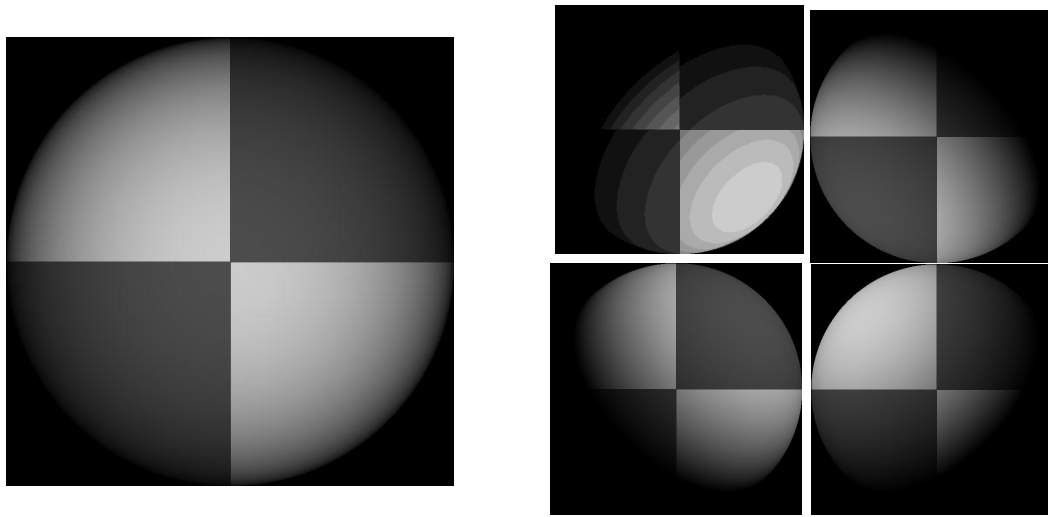


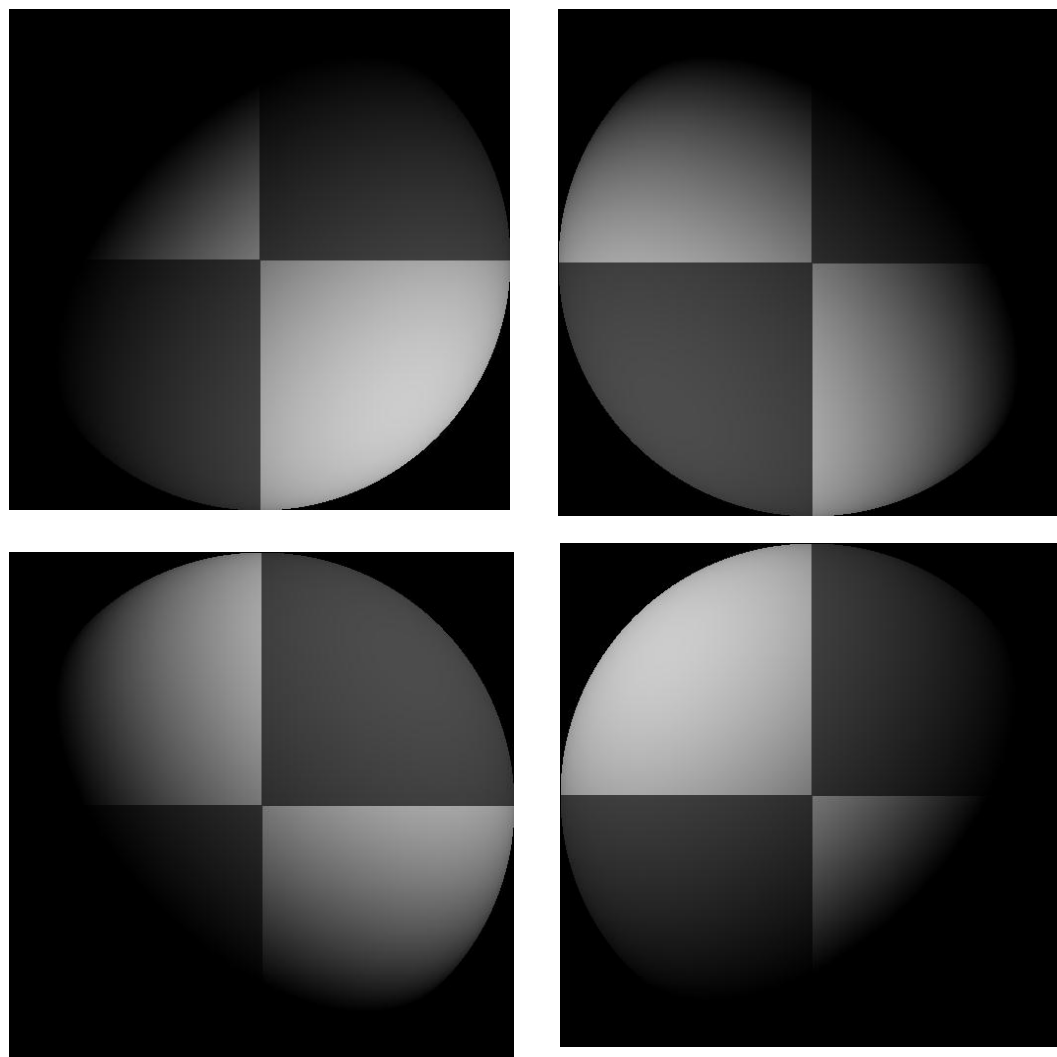
$$\rho(\theta_i, \phi_i, \theta_e, \phi_e; \lambda) =$$

$$\frac{L_e(\theta_e, \phi_e)}{E_i(\theta_i, \phi_i)} = \frac{L_e(\theta_e, \phi_e)}{L_i(\theta_i, \phi_i) \cos \theta_i d\omega}$$

# Application: photometric stereo

- Assume:
  - a set of point sources that are infinitely distant
  - a set of pictures of an object, obtained in exactly the same camera/object configuration but using different sources
  - A Lambertian object (or the specular component has been identified and removed)

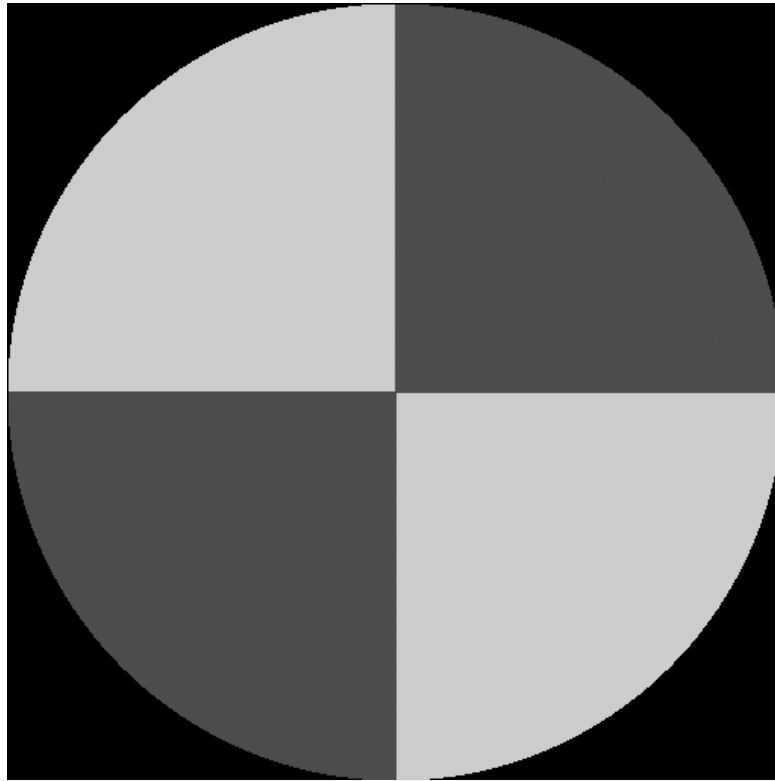




Each image is:  $I_i(x) = \mathbf{S}_i \cdot (p(x)\mathbf{N}(x))$

So if we have enough images with known sources, we can solve for  $\mathbf{B}(x) = p(x)\mathbf{N}(x)$  
 $\swarrow$   
 albedo times  
 3D normal



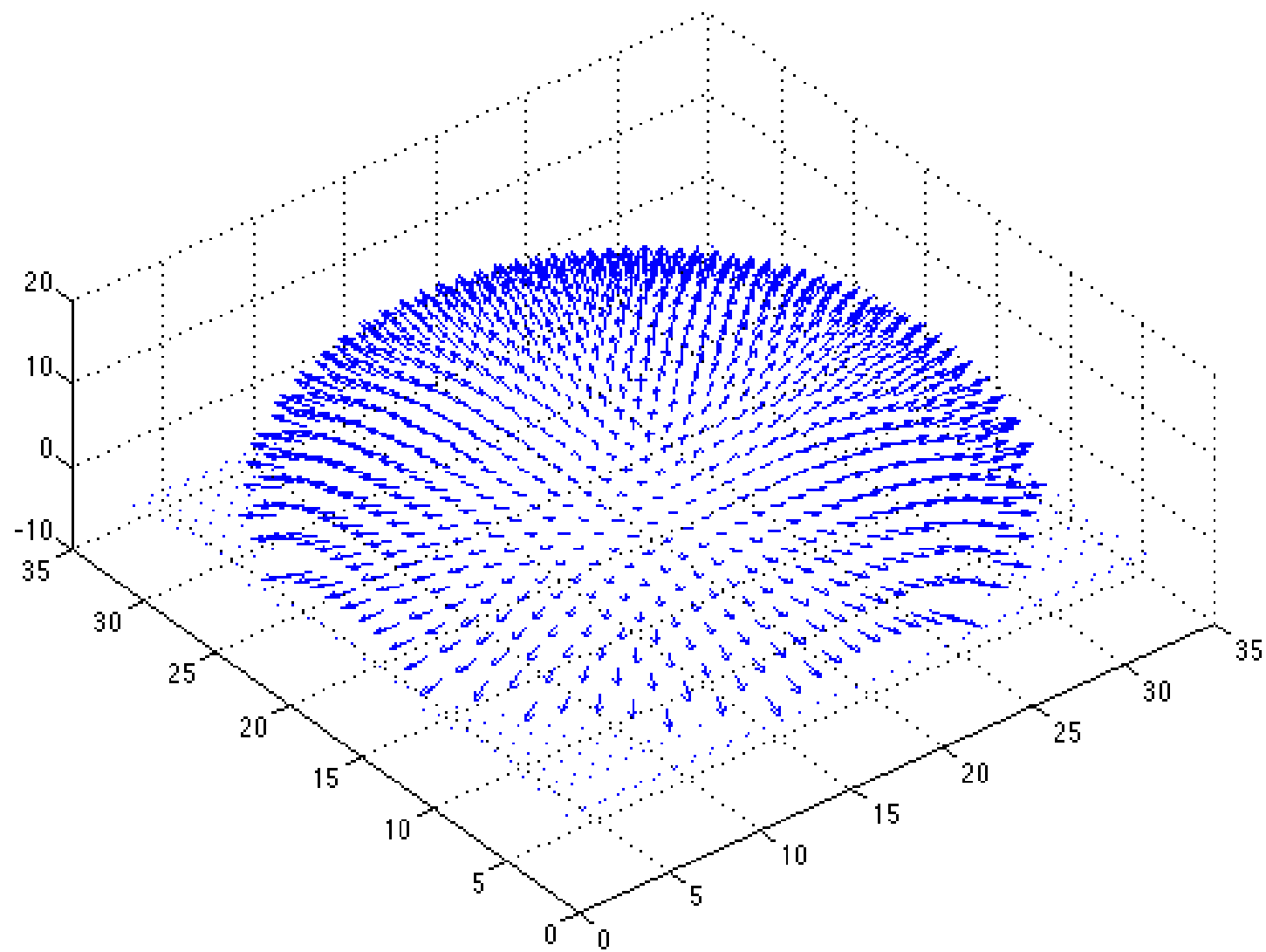


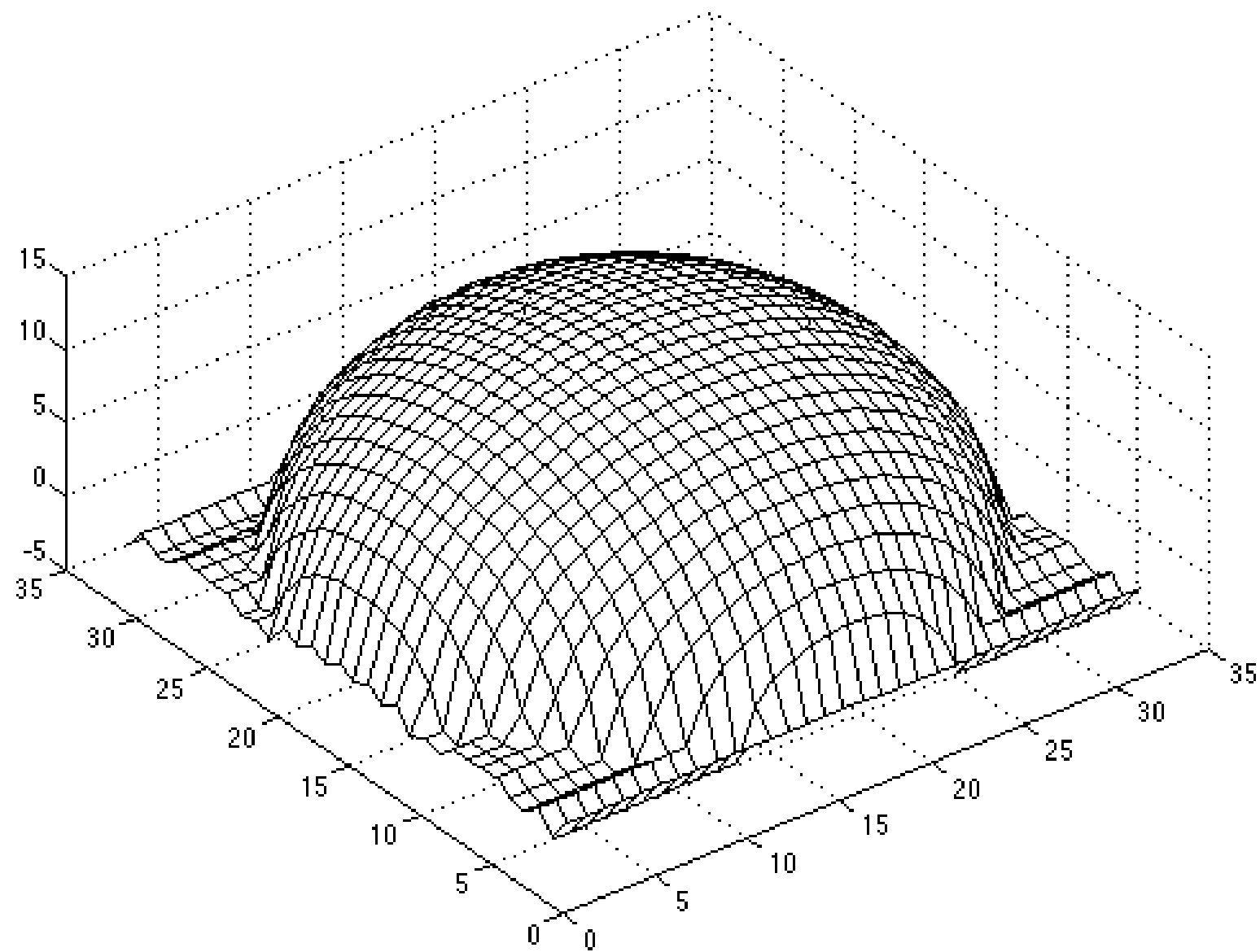
$$\mathbf{B}(x) = p(x)\mathbf{N}(x)$$

And the albedo (shown here) is given by:

$$p(x) = \sqrt{\mathbf{B}(x) \cdot \mathbf{B}(x)}$$

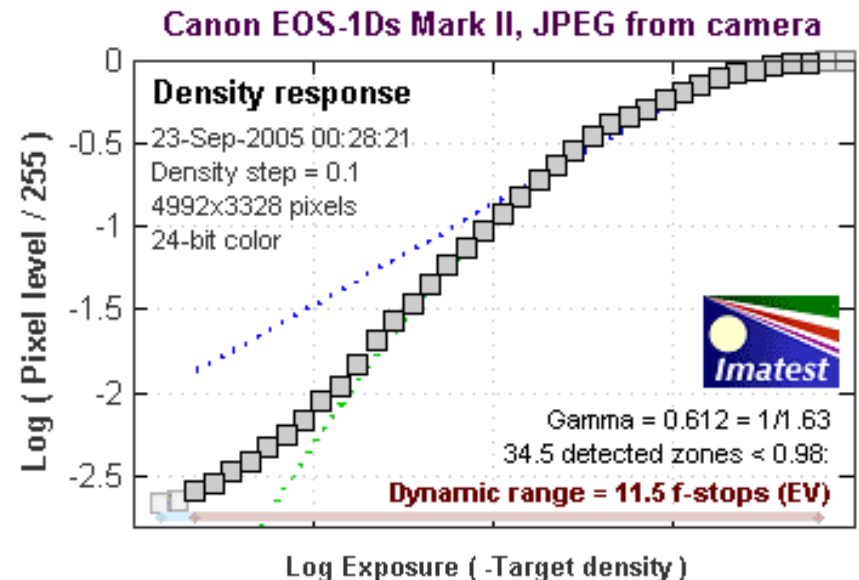
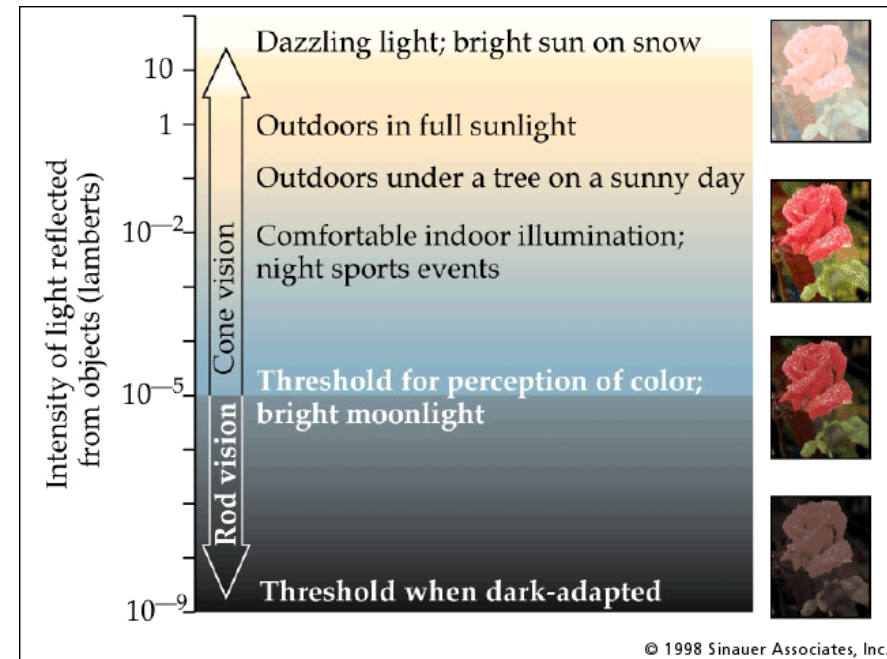
(the normal is a unit vector)





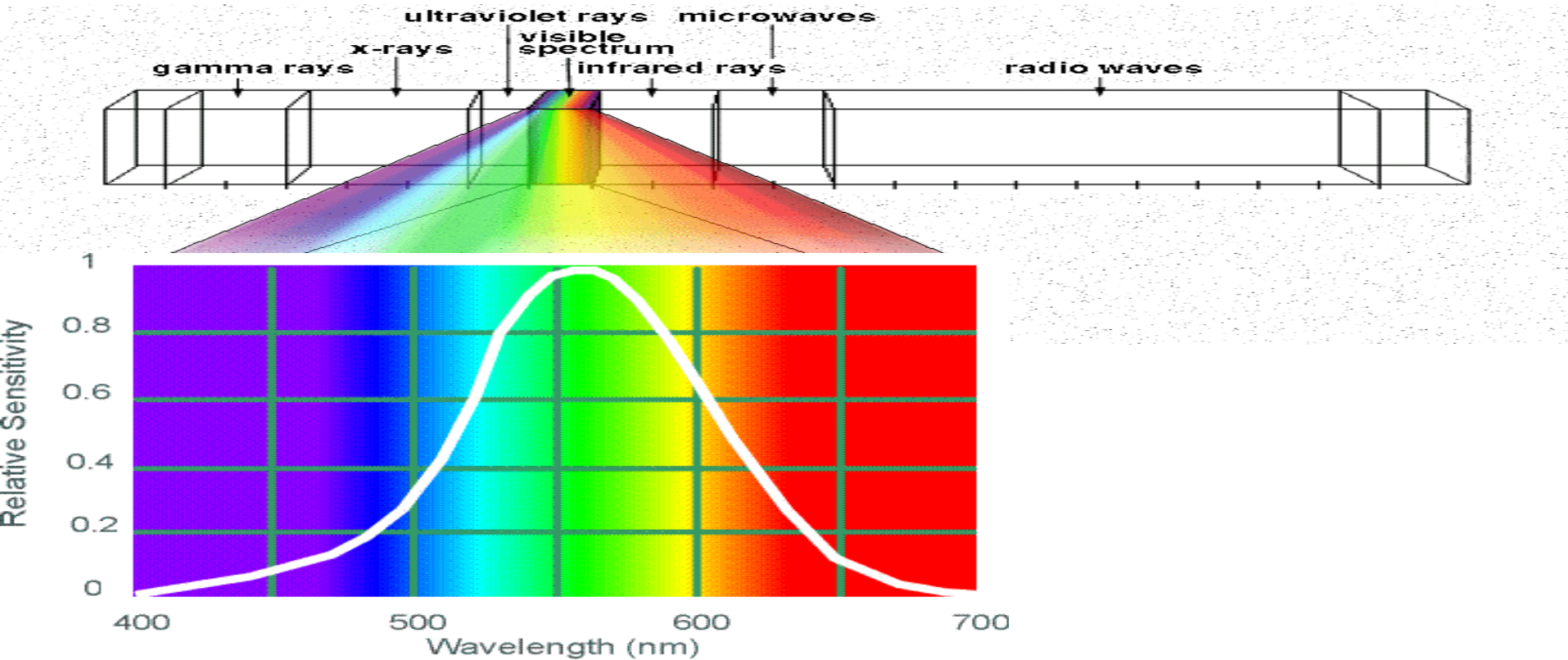
# Dynamic range and camera response

- Typical scenes have a huge dynamic range
- Camera response is roughly linear in the mid range (15 to 240) but non-linear at the extremes
  - called saturation or undersaturation



# Color

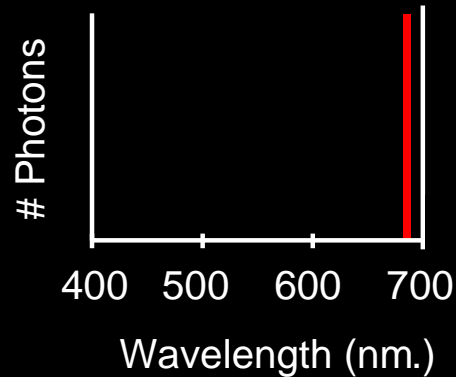
Light is composed of a spectrum of wavelengths



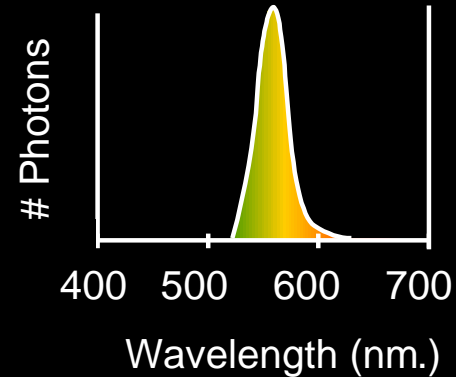
Human Luminance Sensitivity Function

# Some examples of the spectra of light sources

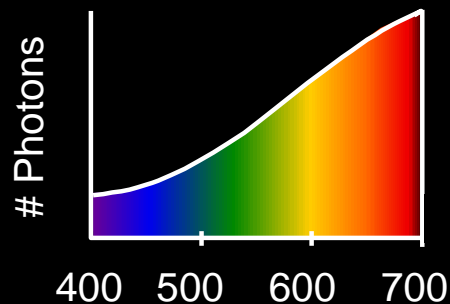
A. Ruby Laser



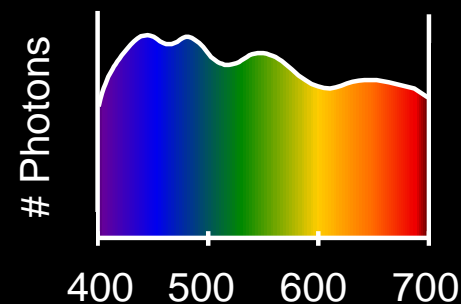
B. Gallium Phosphide Crystal



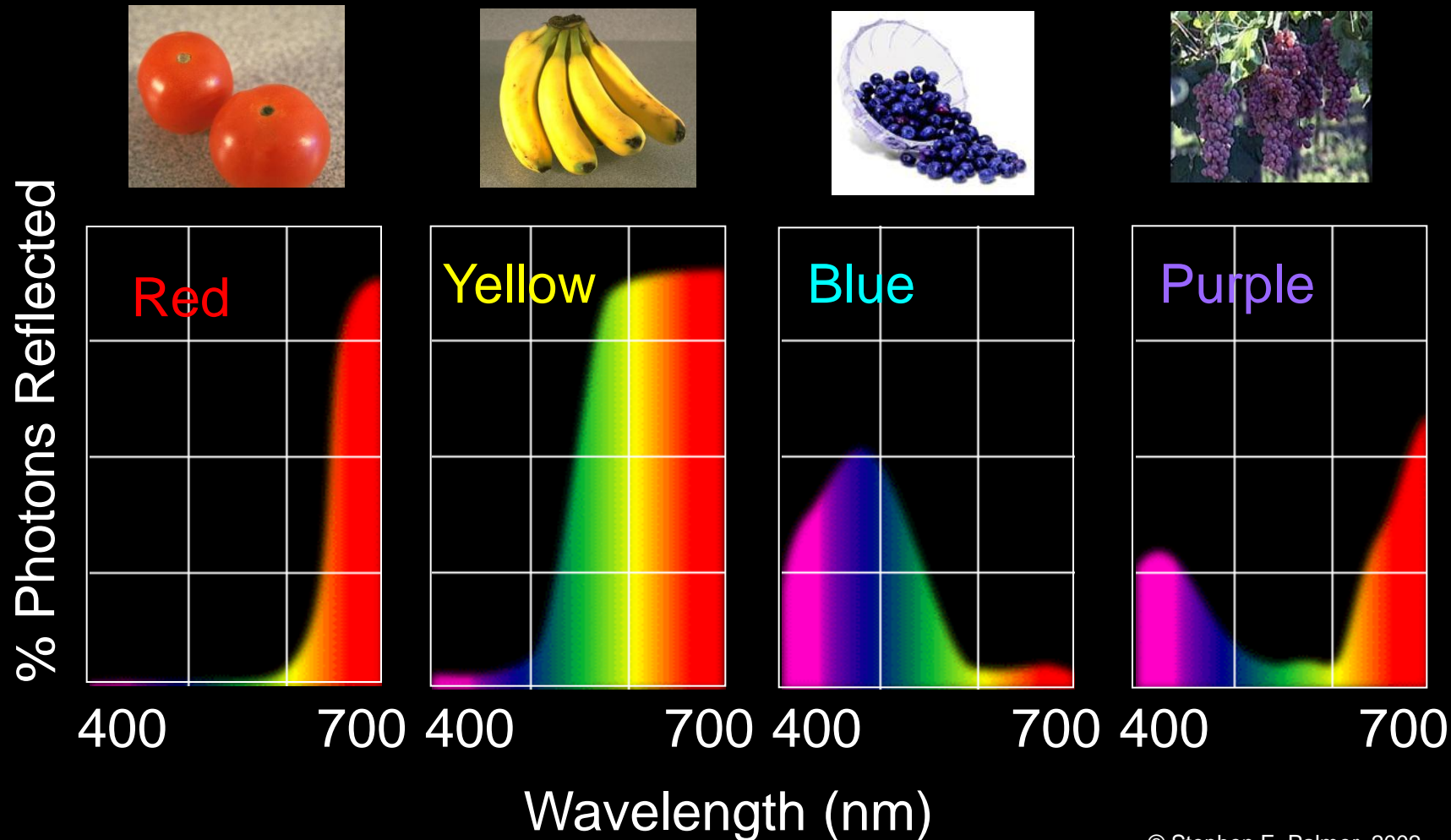
C. Tungsten Lightbulb



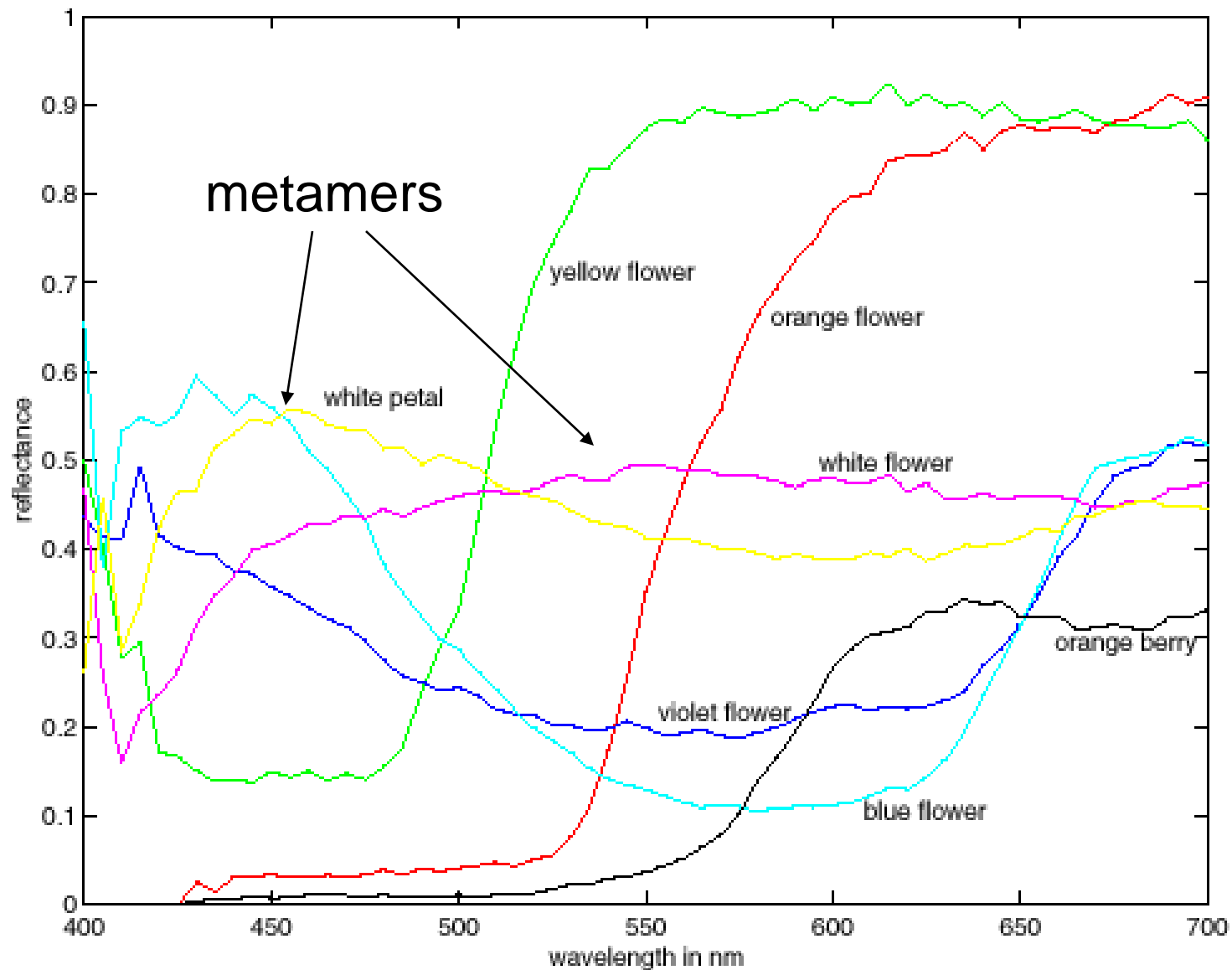
D. Normal Daylight



# Some examples of the reflectance spectra of surfaces



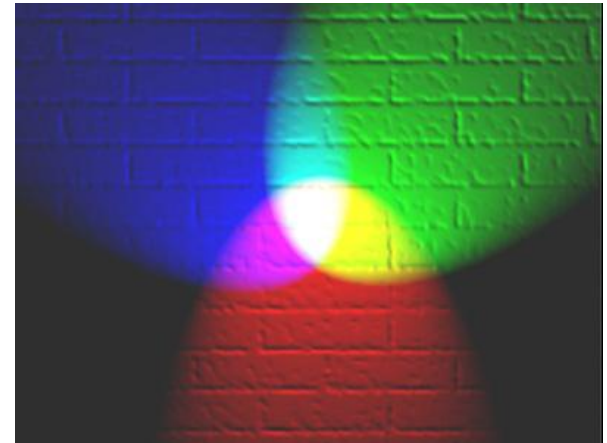
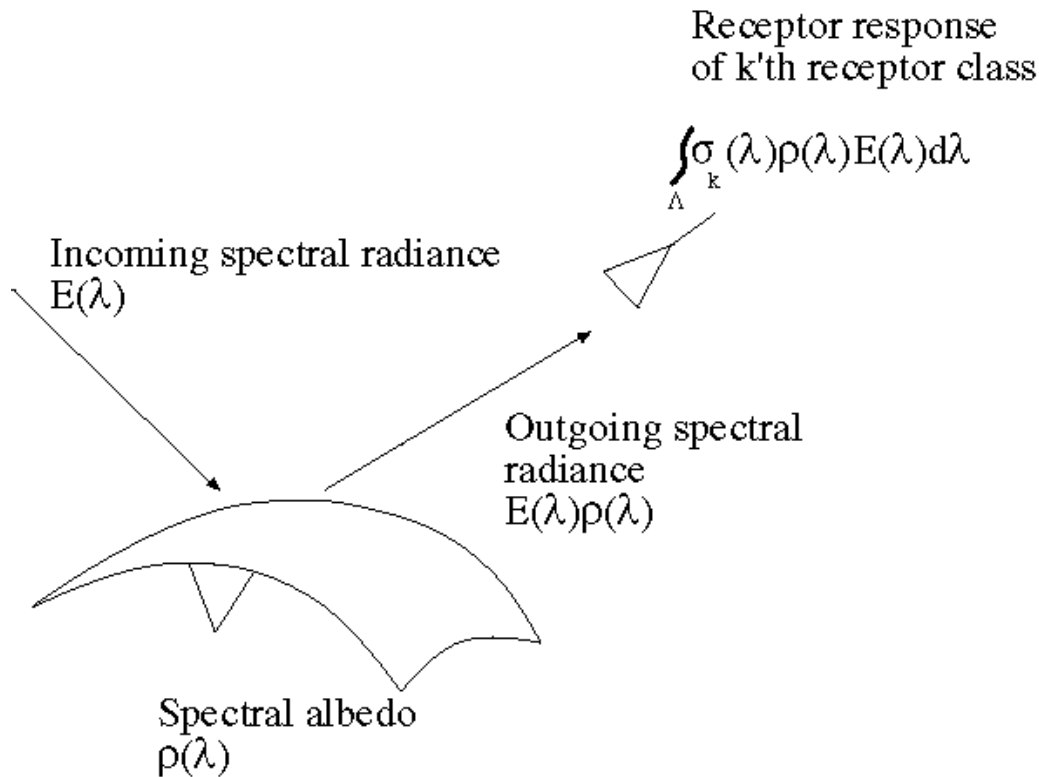
# More spectra





# The color of objects

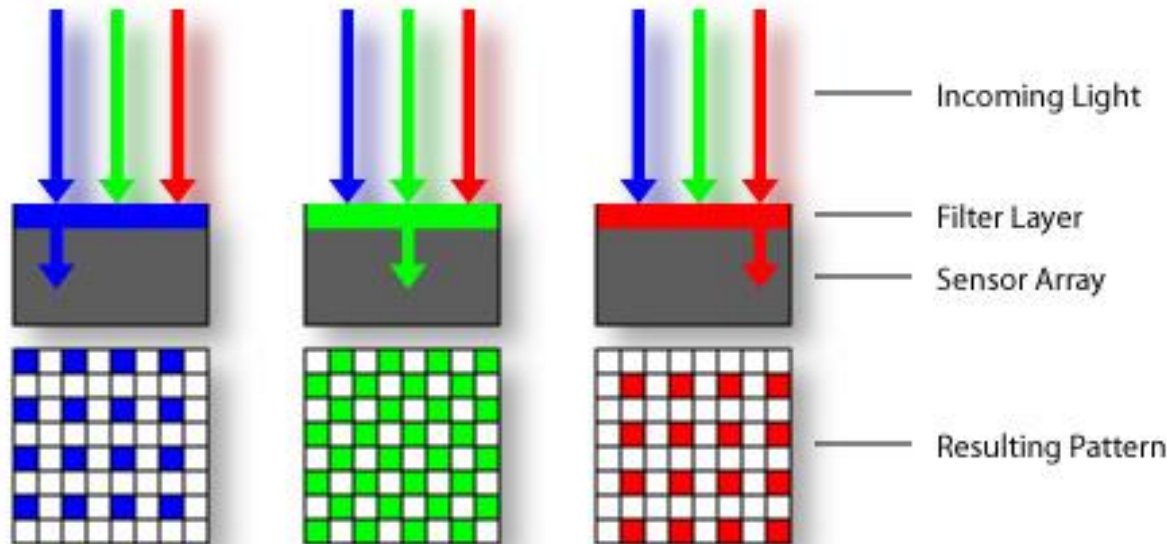
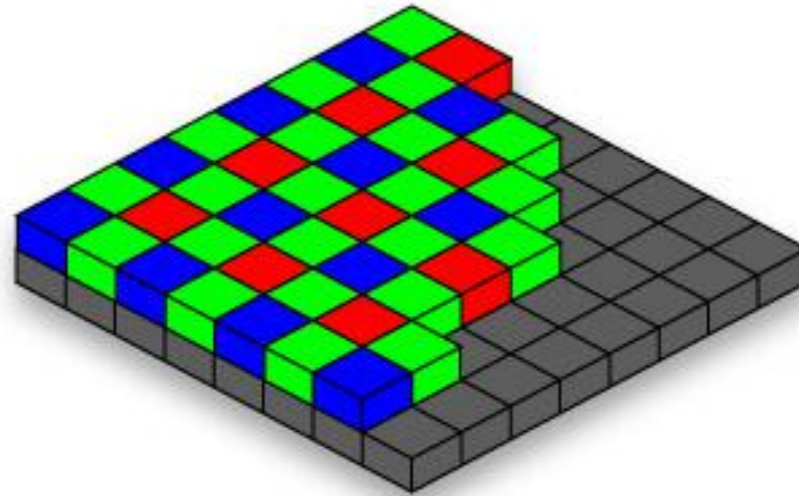
- Colored light arriving at the camera involves two effects
  - The color of the light source (illumination + inter-reflections)
  - The color of the surface



# Color Sensing: Bayer Grid



Estimate RGB at each cell from neighboring values



# Color Image

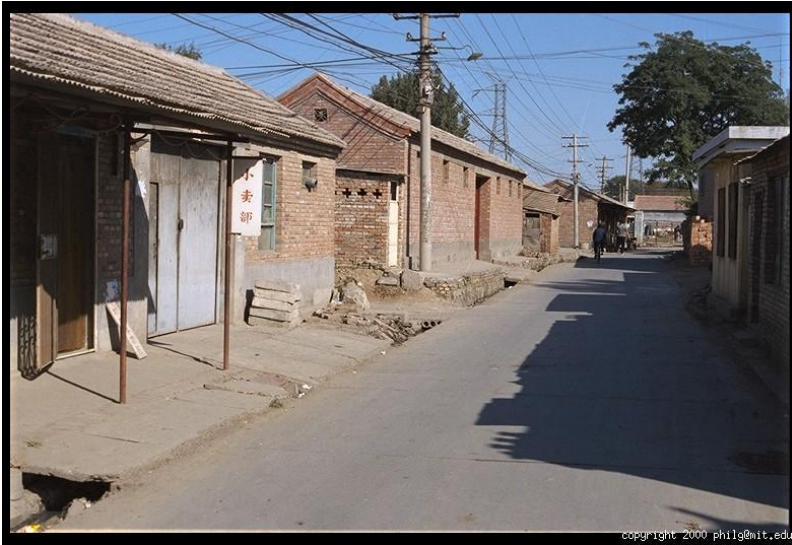
R



G



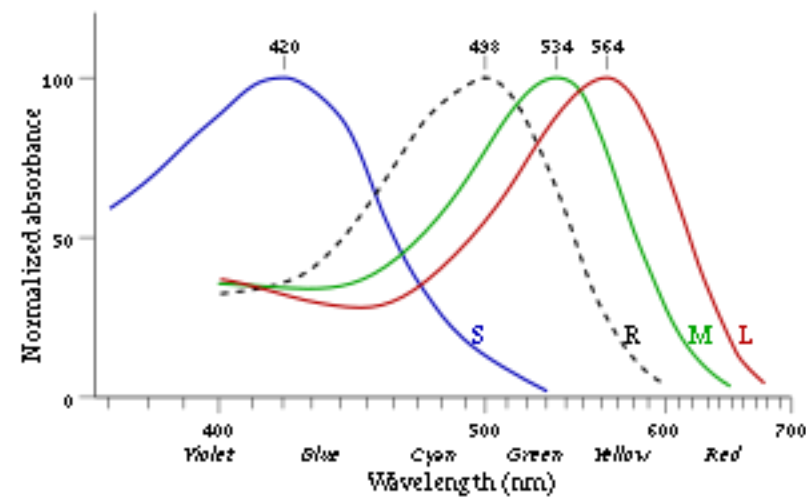
B



# Why RGB?

If light is a spectrum, why are images RGB?

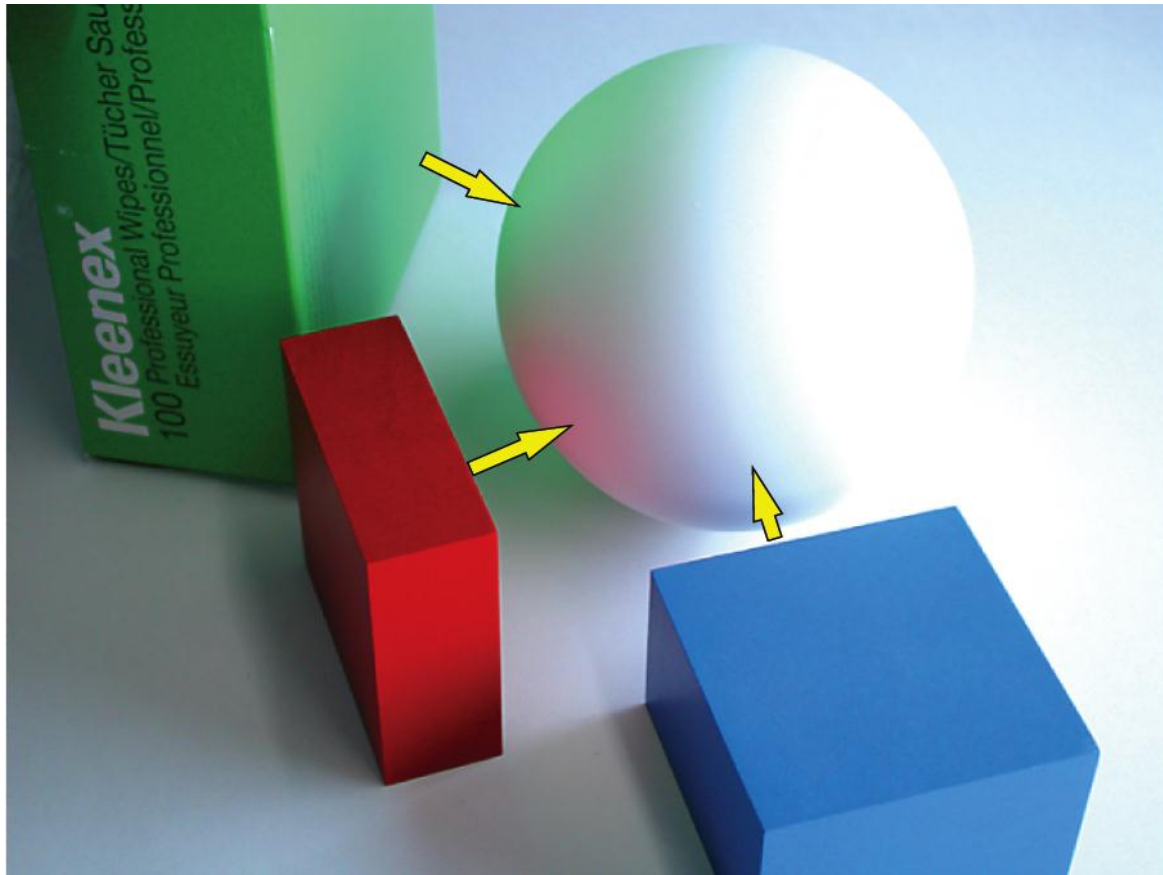
# Human color receptors



- Long (red), Medium (green), and Short (blue) cones, plus intensity rods
- Fun facts
  - “M” and “L” on the X-chromosome
    - That’s why men are more likely to be color blind (see what it’s like: <http://www.vischeck.com/vischeck/vischeckURL.php>)
  - “L” has high variation, so some women are tetrachromatic
  - Some animals have 1 (night animals), 2 (e.g., dogs), 4 (fish, birds), 5 (pigeons, some reptiles/amphibians), or even 12 (mantis shrimp) types of cones

# So far: light $\rightarrow$ surface $\rightarrow$ camera

- Called a local illumination model
- But much light comes from surrounding surfaces



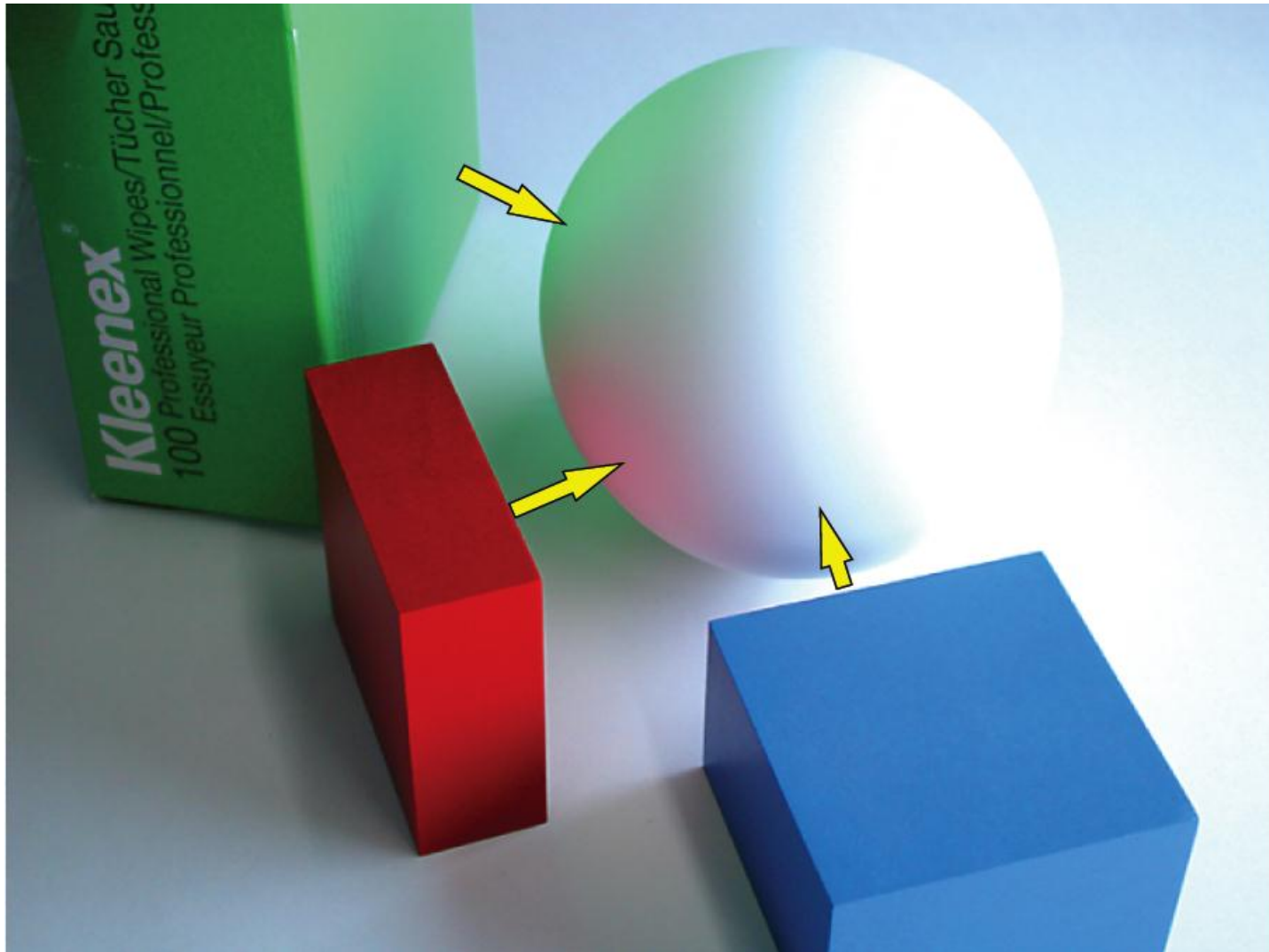
From Koenderink slides on image texture and the flow of light



Inter-reflection is a major source of light



# Inter-reflection affects the apparent color of objects

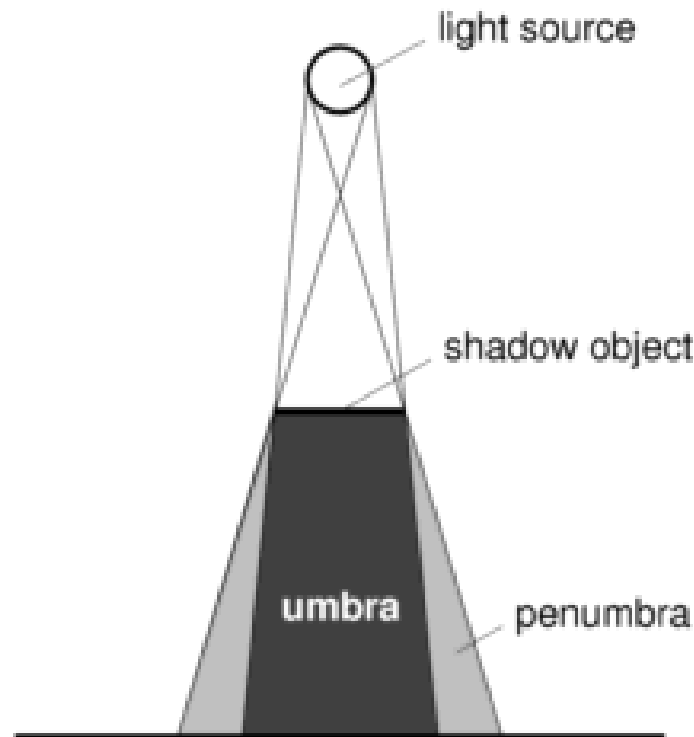


From Koenderink slides on image texture and the flow of light

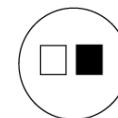
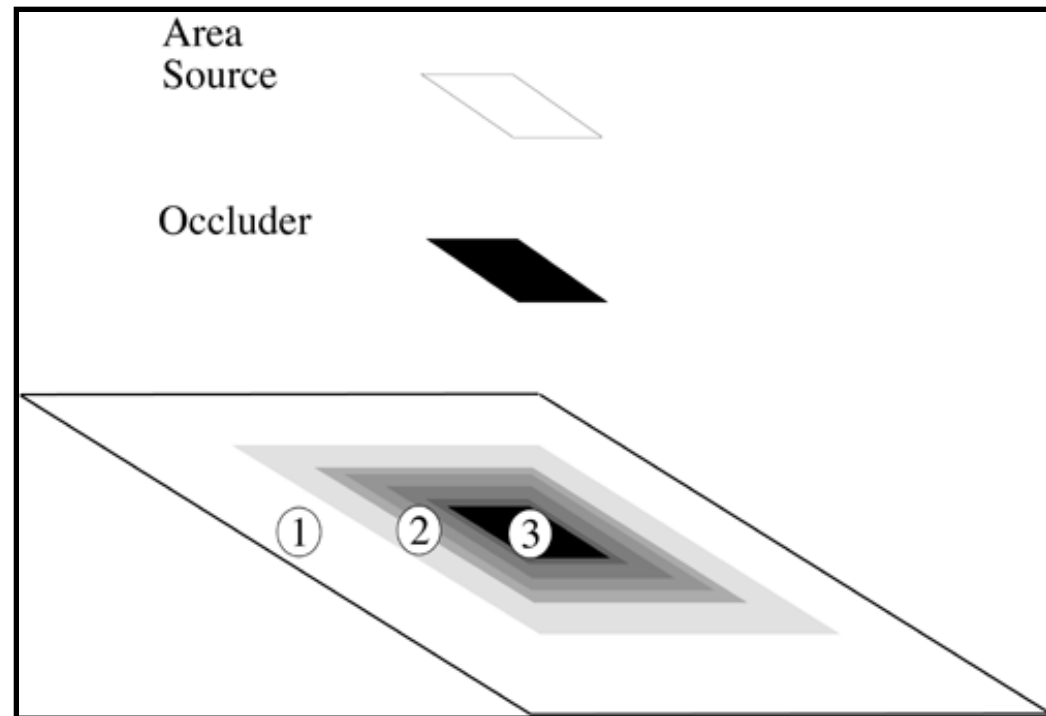
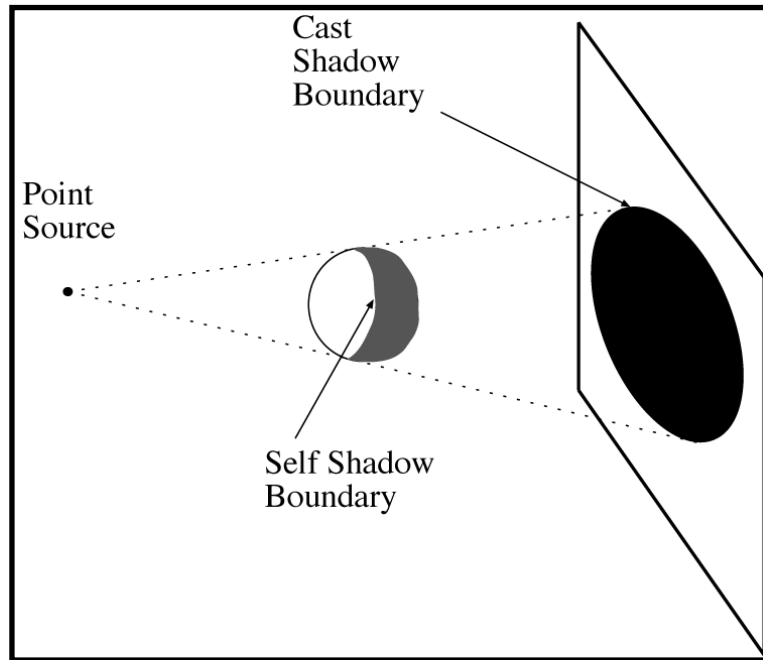


# Scene surfaces also cause shadows

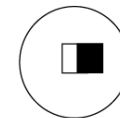
- Shadow: reduction in intensity due to a blocked source



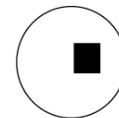
# Shadows



1



2

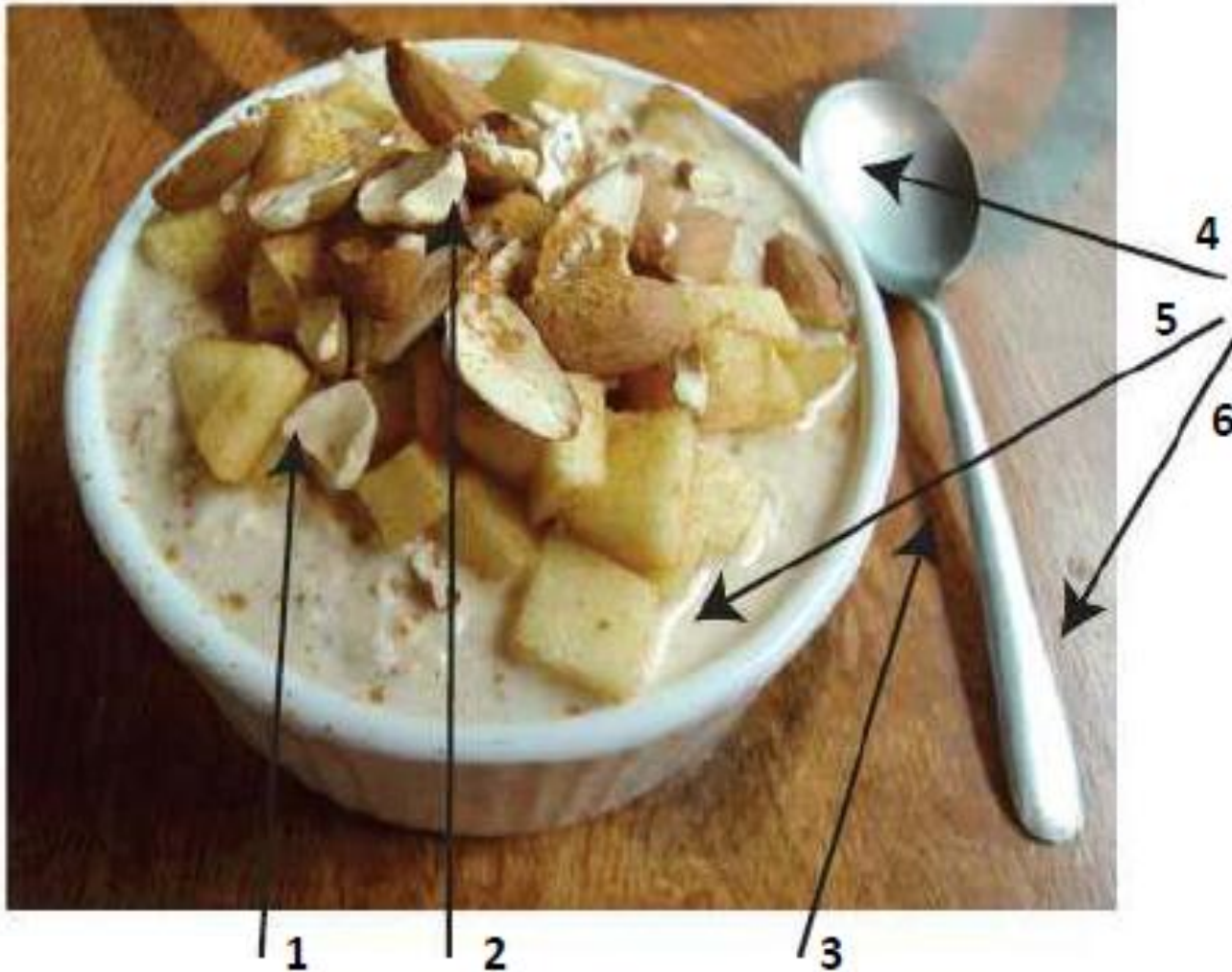


3

# Models of light sources

- Distant point source
  - One illumination direction
  - E.g., sun
- Area source
  - E.g., white walls, diffuser lamps, sky
- Ambient light
  - Substitute for dealing with interreflections
- Global illumination model
  - Account for interreflections in modeled scene

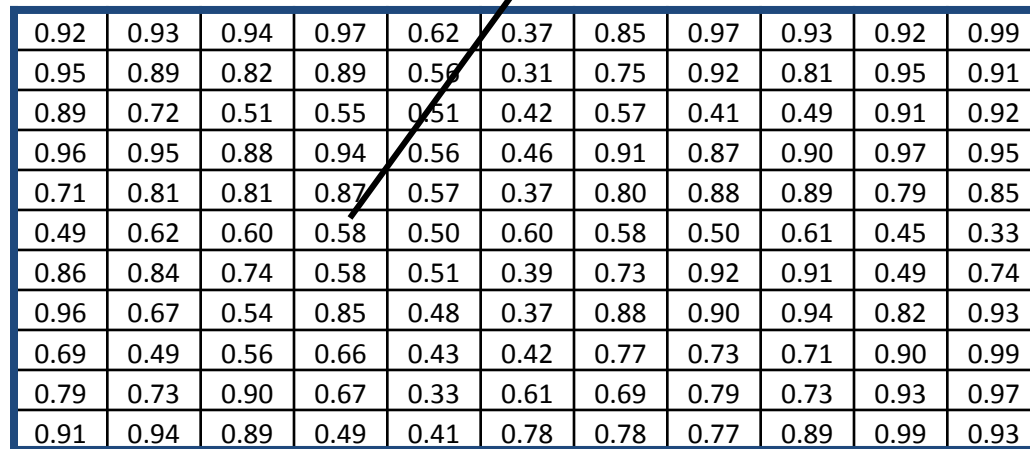
# Recap



Possible factors: albedo, shadows, texture, specularities, curvature, lighting direction

# What does the intensity of a pixel tell us?

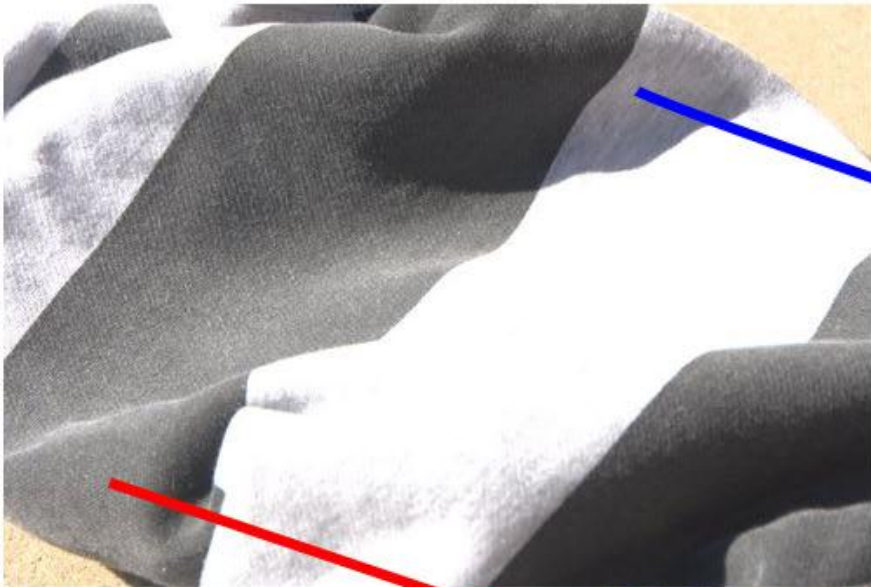
$\text{im}(234, 452) = 0.58$



0.92	0.93	0.94	0.97	0.62	0.37	0.85	0.97	0.93	0.92	0.99
0.95	0.89	0.82	0.89	0.55	0.31	0.75	0.92	0.81	0.95	0.91
0.89	0.72	0.51	0.55	0.51	0.42	0.57	0.41	0.49	0.91	0.92
0.96	0.95	0.88	0.94	0.56	0.46	0.91	0.87	0.90	0.97	0.95
0.71	0.81	0.81	0.87	0.57	0.37	0.80	0.88	0.89	0.79	0.85
0.49	0.62	0.60	0.58	0.50	0.60	0.58	0.50	0.61	0.45	0.33
0.86	0.84	0.74	0.58	0.51	0.39	0.73	0.92	0.91	0.49	0.74
0.96	0.67	0.54	0.85	0.48	0.37	0.88	0.90	0.94	0.82	0.93
0.69	0.49	0.56	0.66	0.43	0.42	0.77	0.73	0.71	0.90	0.99
0.79	0.73	0.90	0.67	0.33	0.61	0.69	0.79	0.73	0.93	0.97
0.91	0.94	0.89	0.49	0.41	0.78	0.78	0.77	0.89	0.99	0.93

# The plight of the poor pixel

- A pixel's brightness is determined by
  - Light source (strength, direction, color)
  - Surface orientation
  - Surface material and albedo
  - Reflected light and shadows from surrounding surfaces
  - Gain on the sensor
- A pixel's brightness tells us nothing by itself



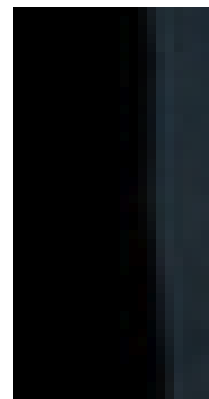
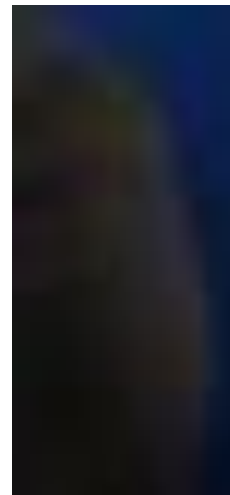


Photo by [nickwheeleroz](#), Flickr

Slide: Forsyth



# And yet we can interpret images...



- Key idea: for nearby scene points, most factors do not change much
- The information is mainly contained in *local differences* of brightness

Darkness = Large Difference in Neighboring Pixels



# What is this?







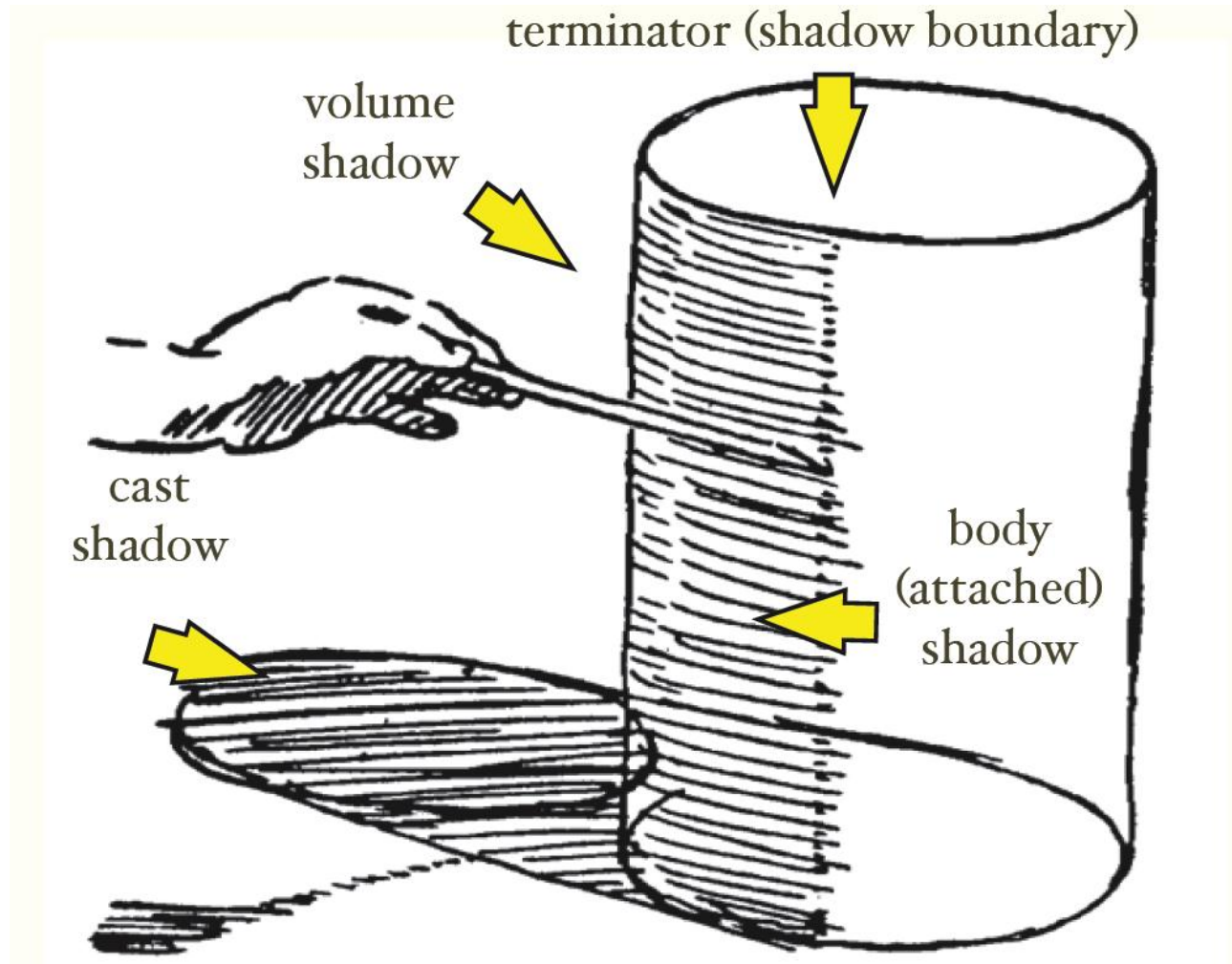
# What differences in intensity tell us about shape

- Changes in surface normal
- Texture
- Proximity
- Indents and bumps
- Grooves and creases



Photos Koenderink slides on image texture and the flow of light

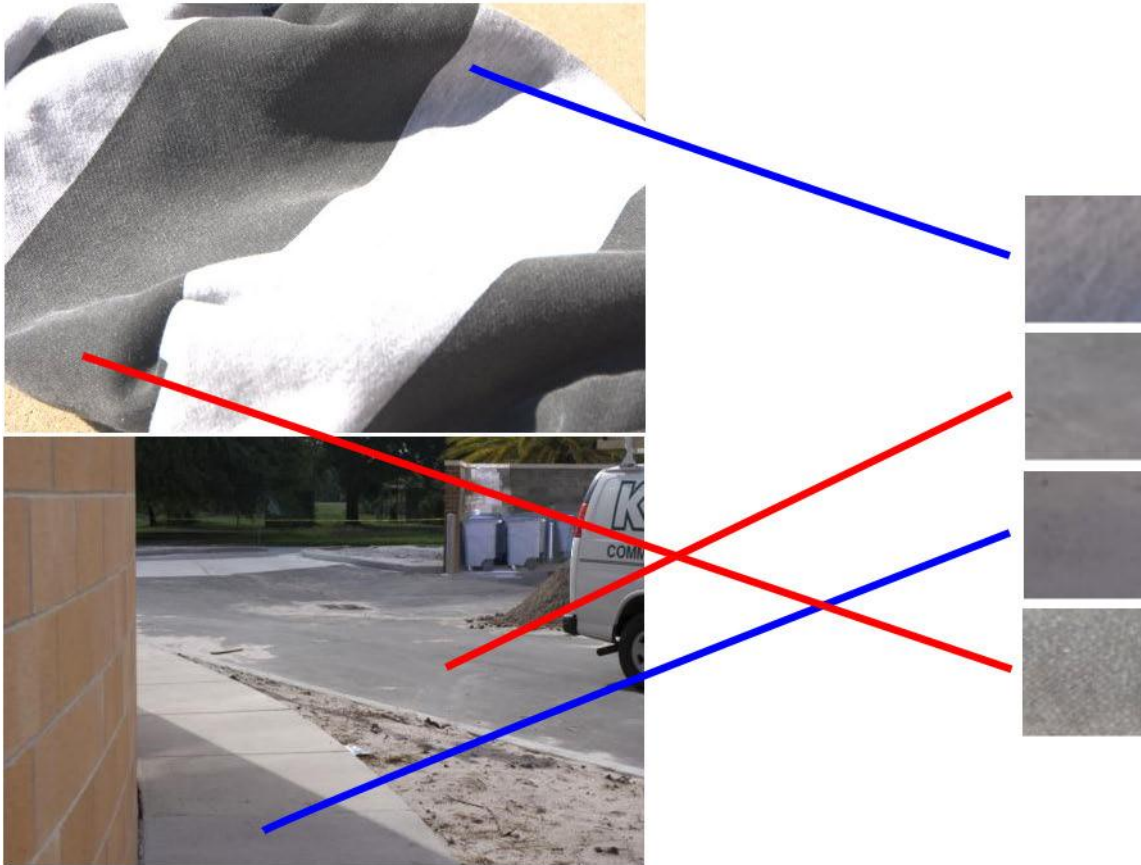
# Shadows as cues



From Koenderink slides on image texture and the flow of light

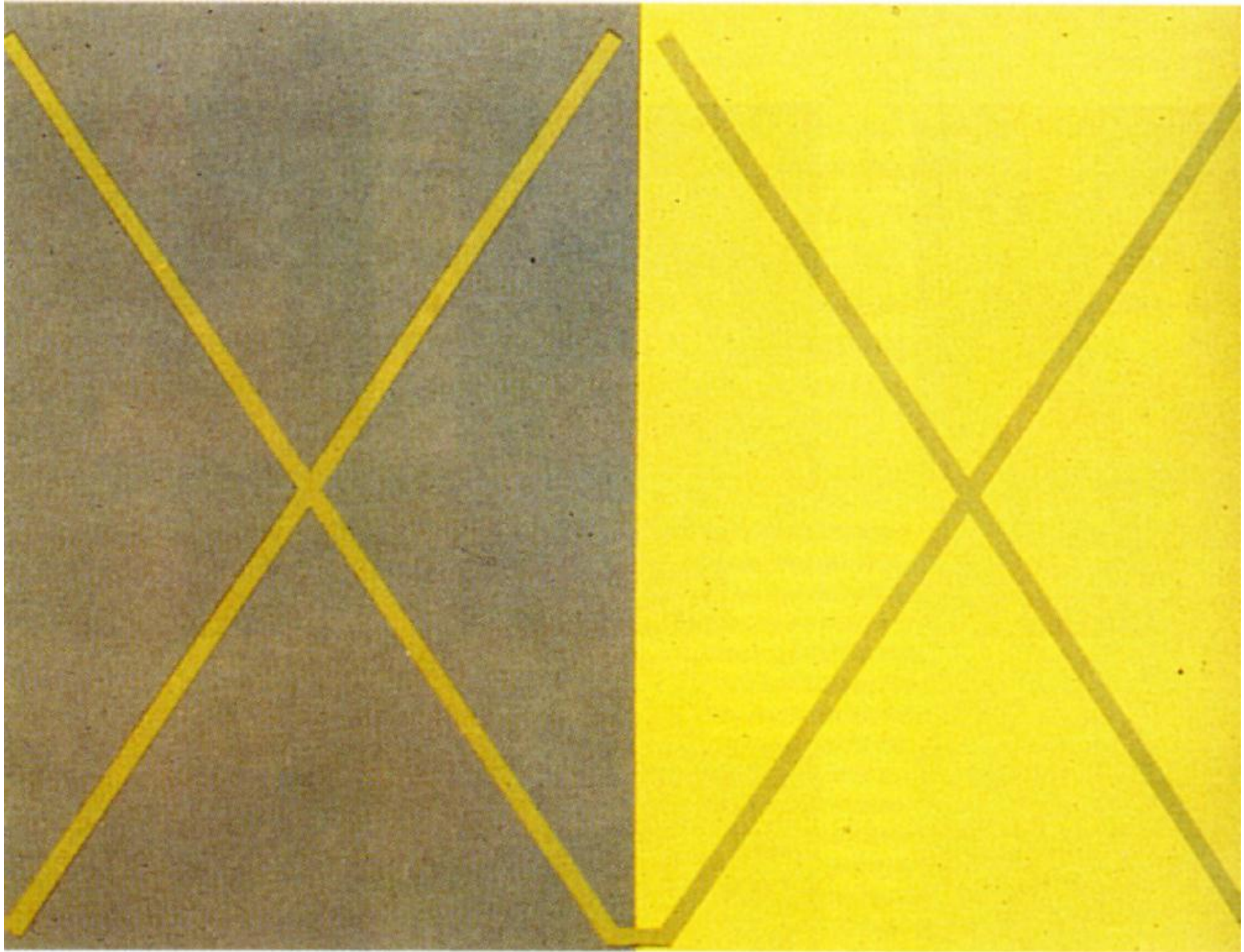
# Color constancy

- Interpret surface in terms of albedo or “true color”, rather than observed intensity
  - Humans are good at it
  - Computers are not nearly as good





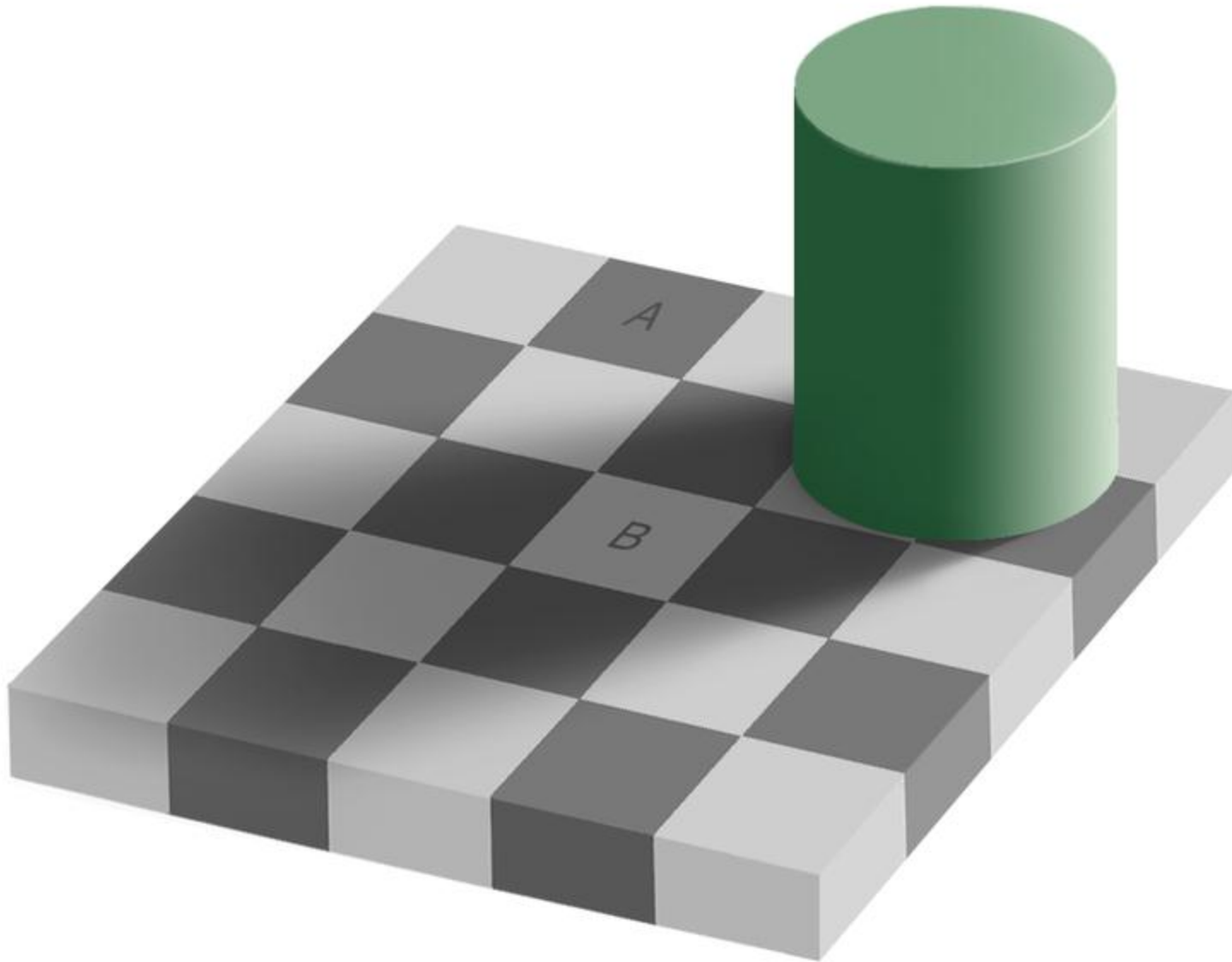
One source of constancy: local comparisons





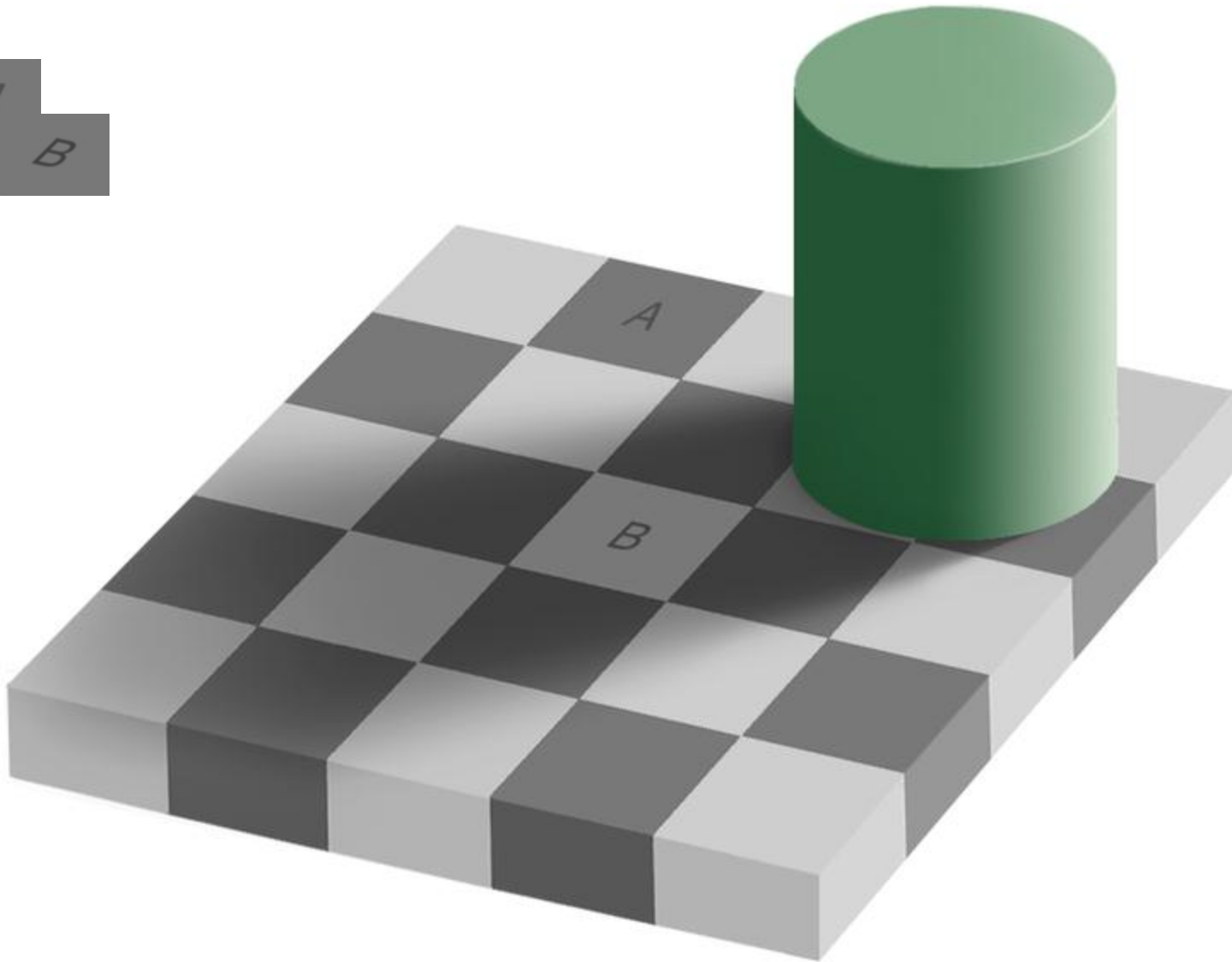


# Perception of Intensity



from Ted Adelson

# Perception of Intensity



# Color Correction

- Simple idea: multiply R, G, and B values by separate constants

$$\begin{bmatrix} \tilde{r} \\ \tilde{g} \\ \tilde{b} \end{bmatrix} = \begin{bmatrix} \alpha_r & 0 & 0 \\ 0 & \alpha_g & 0 \\ 0 & 0 & \alpha_b \end{bmatrix} \begin{bmatrix} r \\ g \\ b \end{bmatrix}$$

- How to choose the constants?
  - “White world” assumption: brightest pixel is white
    - Divide by largest value
  - “Gray world” assumption: average value should be gray
    - E.g., multiply r channel by  $\text{avg}(r) / \text{avg}((r+g+b)/3)$
  - White balancing: choose a reference as the white or gray color

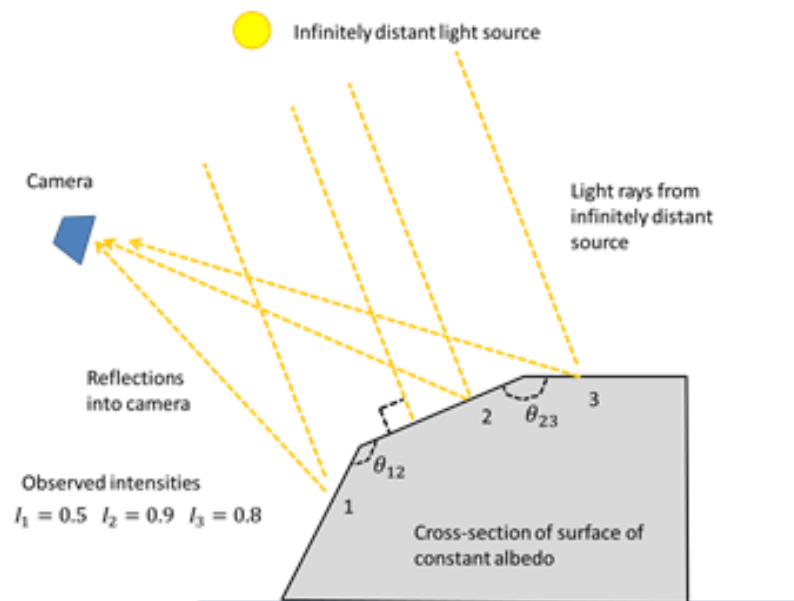
# HW 1, Problem 1a



## 1. Lighting (20%)

- A. Answer the following regarding the above image (photo credit: dolmansaxli from Flickr). Consider shadows, specularities, albedo, surface orientation, light sources, etc. Short answers (several words) are sufficient (8%):
1. Why is (2) brighter than (1)? Each points to the asphalt.
  2. Why is (4) darker than (3)? 4 points to the marking.
  3. Why is (5) brighter than (3)? Each points to the side of the wooden block.
  4. Why isn't (6) black, given that there is no direct path from it to the sun?

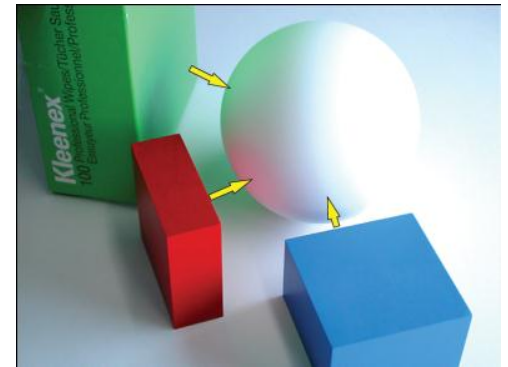
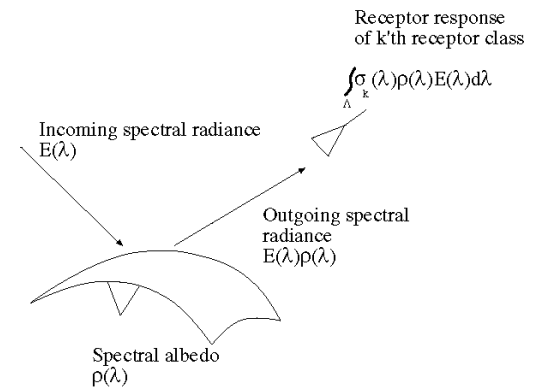
# HW 1, Problem 1b



- B. Answer the following using the above illustration. Suppose you have observed the intensities of three points on an object ( $I_1, I_2, I_3$ ), which are lit by an infinitely distant point source (the sun). The surface normal at point 2 is exactly perpendicular to the sun. The surface normals of points 1 and 3 differ in only one angle ( $\theta$ ), as shown in the cross-section.
- Suppose the surface has a specular component. Will the observed intensities change as the camera moves (if so why/how)? (4%)
  - Suppose the surface material is Lambertian and has uniform (constant) albedo and that the camera response function is linear (and ignore effects due to interreflections in the scene). Show (with equations for arbitrary observed intensities) how to compute the angles  $\theta_{12}, \theta_{23}$  between surfaces containing points 1 and 2 and points 2 and 3. Then, compute the values of  $\theta_{12}, \theta_{23}$  for the observed intensities (0.5, 0.9, 0.8). (8%)

# Things to remember

- Important terms: diffuse/specular reflectance, albedo, umbra/penumbra
- Observed intensity depends on light sources, geometry/material of reflecting surface, surrounding objects, camera settings
- Objects cast light and shadows on each other
- Differences in intensity are primary cues for shape



# Thank you

- Next class: Image Filters