

# Appendix to Lecture 20: Automata and LTL Model Checking

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## LTL Satisfaction as Language Containment

Recall that, given a Kripke structure  $\mathcal{K} = (A, \rightarrow_{\mathcal{K}}, L)$  on atomic propositions  $AP$ , and choosing an initial state  $a \in A$  and an LTL formula  $\varphi \in LTL(AP)$ , the satisfaction relation is defined by the chain of equivalences:

$$\mathcal{K}, a \models \varphi \Leftrightarrow \forall \pi \in Paths(\mathcal{K})_a \ \pi \models \varphi \Leftrightarrow \forall \pi \in Paths(\mathcal{K})_a \ \pi; L \models \varphi.$$

If we define the set  $Traces(\mathcal{K})_a$  of the traces of  $\mathcal{K}$  from initial state  $a$  as:  $Traces(\mathcal{K})_a = \{\pi; L \mid \pi \in Paths(\mathcal{K})_a\}$ , we can rephrase the above definition of satisfaction as the simpler equivalence:

$$\mathcal{K}, a \models \varphi \Leftrightarrow \forall \tau \in Traces(\mathcal{K})_a \ \tau \models \varphi.$$

But we can view  $Traces(\mathcal{K})_a$  as a *language of infinite words* on the alphabet  $\mathcal{P}(AP)$ . Specifically, an *infinite word on an alphabet*  $\Lambda$  is just a function  $\tau \in [\mathbb{N} \rightarrow \Lambda]$ , where we suggestively denote  $[\mathbb{N} \rightarrow \Lambda]$  as  $\Lambda^\omega$  ( $\omega$  denotes the set of natural numbers viewed as an “ordinal set” with its  $<$  order), to emphasize that this is the language of infinite words on  $\Lambda$ , just as  $\Lambda^*$  is the language of finite words on  $\Lambda$ . Therefore, we have the language containment:  $Traces(\mathcal{K})_a \subseteq \mathcal{P}(AP)^\omega$ .

Now observe that the relation  $\tau \models \varphi$  between an infinite word  $\tau \in \mathcal{P}(AP)^\omega$  and an LTL formula  $\varphi \in LTL(AP)$  is defined *independently of any Kripke structure*, since the inductive semantic definition of  $\tau \models \varphi$  is given in terms of the syntactic structure of  $\varphi$  and can be *expressed in terms of traces*, regardless of where such traces come from. Therefore, an LTL formula  $\varphi \in LTL(AP)$  also defines a language of infinite words, namely, the set of all traces  $\tau$  that satisfy  $\varphi$ . Call this language  $\mathcal{L}(\varphi)$  the *language of*  $\varphi$ , i.e.,  $\mathcal{L}(\varphi) = \{\tau \in \mathcal{P}(AP)^\omega \mid \tau \models \varphi\}$ . Using this notation, we can express the satisfaction relation  $\mathcal{K}, a \models \varphi$  in an even simpler, language-theoretic way by the equivalence:

$$\mathcal{K}, a \models \varphi \Leftrightarrow Traces(\mathcal{K})_a \subseteq \mathcal{L}(\varphi).$$

The intuitive meaning is that, semantically, the property  $\varphi$  specifies a *set of allowable traces*, so  $\mathcal{K}$  starting at  $a$  satisfies property  $\varphi$  iff all its traces are among those allowed by  $\varphi$ .

## Büchi Automata and Decidability of $\omega$ -Regular Languages

Recall that *regular languages* are languages recognized by finite automata; and that Boolean operations on such languages, such as union, intersection and complement, as well as properties such as language containment or language emptiness, can be *effectively computed*, resp. *decided*, by means of automata. Thanks to the work of the Swiss mathematician Richard Büchi, finite automata on an input alphabet  $\Lambda$  can also recognize  *$\omega$ -regular languages* as subsets of the set  $\Lambda^\omega$  of infinite words on  $\Lambda$ . The definition of a finite automaton  $\mathcal{A}$  on an input alphabet  $\Lambda$  remains the same: we specify its input alphabet, finite set of states, initial state (or set of initial

states),  $\Lambda$ -labeled transition relation, and a subset of final/accepting states. *The only thing that changes is the notion of acceptance.* A finite word  $w \in \Lambda^*$  is accepted by an automaton  $\mathcal{A}$  iff the input  $w$  can reach a state in the set  $F$  of accepting states of  $\mathcal{A}$ . Instead,  $\mathcal{A}$  will accept an infinite word  $\tau \in \Lambda^\omega$  iff  $F \cap \text{inf}(\tau) \neq \emptyset$ , where  $\text{inf}(\tau)$  denotes the set of states of  $\mathcal{A}$  that are visited infinitely often by the infinite input  $\tau$ . Although automata remain the same, when this new interpretation of input acceptance is given to them, they are called *Büchi automata*, in honor of Richard Büchi.

For our current purposes, we just need to use two facts about Büchi automata and  $\omega$ -regular languages: (1) (**Language Intersection**) If two  $\omega$ -regular languages,  $L_1$  and  $L_2$  on  $\Lambda$  are respectively recognized by Büchi automata  $\mathcal{A}_1$  and  $\mathcal{A}_2$ , then their intersection  $L_1 \cap L_2$  is also an  $\omega$ -regular language recognized by a Büchi automaton  $\mathcal{A}_1 \otimes \mathcal{A}_2$  called the *synchronous product* of  $\mathcal{A}_1$  and  $\mathcal{A}_2$  (see [1], Section 9.2 for a detailed construction of  $\mathcal{A}_1 \otimes \mathcal{A}_2$ ). (2) (**Language Emptiness**) Given a Büchi automaton  $\mathcal{A}$ , there is an algorithm to effectively decide whether the language  $\mathcal{L}(\mathcal{A})$  recognized by  $\mathcal{A}$  is empty or not. Specifically, the procedure deciding the  $\omega$ -regular language emptiness problem answers “empty” when  $\mathcal{L}(\mathcal{A})$  is empty, but in case  $\mathcal{L}(\mathcal{A})$  is non-empty, it effectively computes a *witness*  $\tau \in \mathcal{L}(\mathcal{A})$  proving its non-emptiness.

## Model Checking LTL Properties with Büchi Automata

We now have almost all the ingredients needed to obtain a model checking *decision procedure* for deciding the LTL satisfaction problem  $\mathcal{K}, a \models \varphi$  in case the set of states  $\text{Reach}_{\mathcal{K}}(a)$  reachable from  $a$  is *finite*, except for two remaining technical details.

First, we need to associate to  $(\mathcal{K}, a)$  a Büchi automaton  $\mathbb{B}(\mathcal{K}, a)$  such that  $\mathcal{L}(\mathbb{B}(\mathcal{K}, a)) = \text{Traces}(\mathcal{K})_a$ . This is easy: we can build  $\mathbb{B}(\mathcal{K}, a)$  with input alphabet  $\mathcal{P}(AP)$  so that it exactly mimics the behavior of  $\mathcal{K}$  from the initial state  $a$  as follows: (1) its set of states *and* its set of accepting states are both  $\{\iota\} \uplus \text{Reach}_{\mathcal{K}}(a)$ , (2) its initial state is the new added state  $\iota$ , and (3) its labeled transition relation is the union:

$$\{\iota \xrightarrow{L(a)} a\} \cup \{b \xrightarrow{L(c)} c \mid b, c \in \text{Reach}_{\mathcal{K}}(a) \wedge b \rightarrow_{\mathcal{K}} c\}.$$

The equality  $\mathcal{L}(\mathbb{B}(\mathcal{K}, a)) = \text{Traces}(\mathcal{K})_a$  follows trivially from this construction, since there is a one-to-one correspondence between the infinite executions of  $\mathcal{K}$  from  $a$  and the infinite computations of  $\mathbb{B}(\mathcal{K}, a)$  having the exact same traces by construction.

Second, we need to observe the fact that the language  $\mathcal{L}(\varphi)$  is  $\omega$ -regular. This is because  $\mathcal{L}(\varphi)$  is the language recognized by a Büchi automaton  $\mathbb{B}_\varphi$  that can be effectively constructed from the LTL formula  $\varphi$ . Since the details of the construction  $\varphi \mapsto \mathbb{B}_\varphi$  are rather involved, I refer to Section 9.4 of [1] (or, alternatively, to Section 6.8 of [4]), where this construction is described in full detail.

We are now ready to prove the main theorem of this Appendix:

**Theorem** (Decidability of LTL Model Checking). When the set of states  $\text{Reach}_{\mathcal{K}}(a)$  reachable from state  $a$  is finite, the LTL satisfaction problem  $\mathcal{K}, a \models \varphi$  is decidable. Furthermore, when  $\mathcal{K}, a \not\models \varphi$ , the decision procedure returns a (finite representation of) a trace  $\tau \in \text{Traces}(\mathcal{K})_a$  such that  $\tau \not\models \varphi$ .

**Proof:** Since we have the equivalence  $\mathcal{K}, a \models \varphi \Leftrightarrow \text{Traces}(\mathcal{K})_a \subseteq \mathcal{L}(\varphi)$ , we just need to have a decision procedure for effectively checking the set containment  $\text{Traces}(\mathcal{K})_a \subseteq \mathcal{L}(\varphi)$ .

But this is equivalent to checking the emptiness problem  $Traces(\mathcal{K})_a \cap \mathcal{L}(\varphi)^c = \emptyset$ , where  $\mathcal{L}(\varphi)^c$  denotes the complement of  $\mathcal{L}(\varphi)$  in  $\mathcal{P}(AP)^\omega$ . But by the semantic definition  $\tau \models \neg\varphi \Leftrightarrow_{def} \tau \not\models \varphi$ , we have the language identity  $\mathcal{L}(\varphi)^c = \mathcal{L}(\neg\varphi)$ . So we just need a decision procedure for the emptiness problem  $Traces(\mathcal{K})_a \cap \mathcal{L}(\neg\varphi) = \emptyset$ . But this is just the emptiness problem  $\mathcal{L}(\mathbb{B}(\mathcal{K}, a)) \cap \mathcal{L}(\mathbb{B}_{\neg\varphi}) = \emptyset$ ; that is, the Büchi automata language emptiness problem  $\mathcal{L}(\mathbb{B}(\mathcal{K}, a) \otimes \mathbb{B}_{\neg\varphi}) = \emptyset$ , which is decidable and returns a trace  $\tau \in Traces(\mathcal{K})_a$  if the intersection is non-empty, as desired.  $\square$

## Further Reading

The already cited Chapter 9 of [1] contains a detailed description of all the concepts presented here. In particular, Section 9.5 describes an *on the fly LTL model checking algorithm* to efficiently decide the emptiness problem  $\mathcal{L}(\mathbb{B}(\mathcal{K}, a) \otimes \mathbb{B}_{\neg\varphi}) = \emptyset$  using double depth first search. This is the explicit-state model checking algorithm used by both the Spin model checker [3] and the Maude LTL model checker [2]. Another useful reference for the automata-theoretic approach to model checking is provided in Chapters 5 and 6 of [4].

## References

- [1] E. M. Clarke, O. Grumberg, and D. A. Peled. *Model Checking*. MIT Press, 2001.
- [2] S. Eker, J. Meseguer, and A. Sridharanarayanan. The Maude LTL model checker. *Electron. Notes Theor. Comput. Sci.*, 71:162–187, 2002.
- [3] G. Holzmann. *The Spin Model Checker - Primer and Reference Manual*. Addison-Wesley, 2003.
- [4] D. A. Peled. *Software Reliability Methods*. Texts in Computer Science. Springer, 2001.