

Program Verification: Lecture 24

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Proving Properties of IMPL Programs

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We can **condense** knowledge from sources (1)-(2) into **General Proof Methods** that will be effective in proving IMPL programs.

Generic Properties of Reachability Formulas

Several **generic properties** about **reachability formulas** valid in any rewrite theory \mathcal{R} are always very useful:

1. **Constructor Instantiation of a Parameter.** Let $A \rightarrow_Y^* B$ be a **valid** reachability formula for a rewrite theory \mathcal{R} , where we use the arrow \rightarrow_Y^* to indicate that the formula is **parametric** on a set of variables Y .

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Theorem. If $u \mid \varphi \sqsubseteq v \mid \psi$, then $\llbracket u \mid \varphi \rrbracket \subseteq \llbracket v \mid \psi \rrbracket$. If $u \mid \varphi \sqsubseteq_Y v \mid \psi$, then for each ground constructor substitution $\rho \in [Y \rightarrow T_\Omega]$

Interlude on Pattern Subsumptions

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The **Split** auxiliary inference rule of Reachability logic ensures that the **validity** of a reachability formula

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But before, we need some **notation**.

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Recall from Lecture 23 that, to prove a **Hoare triple** as a reachability formula:

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Suppose we want to prove the following **while loop property**:

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Ideas (1) and (2) are combined in a **proof method of loop invariants** based on the following steps:

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Reasons (1) and (2) both move us in the **same direction**. We should **strengthen the invariant** I into a **stronger**:

$$I_{str}(\vec{Y}, \vec{X}) = I(\vec{Y}, \vec{X}) \wedge \phi.$$

Loop Invariants (IV)

Step 4: Abusing notation and calling I_{str} not just the **data constraint** but the entire **pattern predicate**, if we can show that:

$$A[\mathbf{while} \ b:(\vec{x}) \ \{stmt\} \rightsquigarrow K] \sqsubseteq_{K, \vec{Y}} I_{str}[\mathbf{while} \ b:(\vec{x}) \ \{stmt\} \rightsquigarrow K]$$

and

$$I_{str}\sigma[K] \sqsubseteq_{K, \vec{Y}} D[K]$$

then, by the **Expanding Preconditions and Restricting Midconditions** rule, if the IMPL Prover **can prove**:

$$\begin{aligned} & \langle \mathbf{while} \ b:(\vec{x}) \ \{stmt\} \rightsquigarrow K \mid TS \ \& \ \vec{x} \mapsto \vec{X} * VS \rangle \mid I_{str}(\vec{Y}, \vec{X}) \\ & \rightarrow^{\circledast} \langle K \mid TS \ \& \ \vec{x} \mapsto \vec{X} * VS \rangle \mid I_{str}(\vec{Y}, \vec{X}') \end{aligned}$$

we have also proved our **original goal**:

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This application is **correct** because the equational theory $(\Sigma_D, E_D \cup B_D)$ of the data type where expressions are **evaluated** in the IMPL semantics **protects the Booleans**. Therefore we have:

$$\mathcal{T}_{\Sigma_D/E_D \cup B_D} \models b(\vec{X}) = \text{true} \vee b(\vec{X}) = \text{false},$$

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Suppose we want to prove a reachability formula of the form:

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What can we do? We can apply the **Split** rule to reduce our original goal to the **two simpler goals** semantically equivalent to it:

$$\begin{aligned} & \langle \text{stmt} \rightsquigarrow K \mid TS \ \& \ \vec{x} \mapsto \vec{X} * VS \rangle \mid \varphi \wedge b(\vec{X}) = \text{true} \\ & \rightarrow^{*} \langle K \mid TS \ \& \ \vec{x} \mapsto \vec{X}' * VS \rangle \mid \psi \\ & \langle \text{stmt}' \rightsquigarrow K \mid TS \ \& \ \vec{x} \mapsto \vec{X} * VS \rangle \mid \varphi \wedge b(\vec{X}) = \text{false} \\ & \rightarrow^{*} \langle K \mid TS \ \& \ \vec{x} \mapsto \vec{X}' * VS \rangle \mid \psi. \end{aligned}$$

This application is **correct** because the equational theory $(\Sigma_D, E_D \cup B_D)$ of the data type where expressions are **evaluated** in the IMPL semantics **protects the Booleans**. Therefore we have:

$\mathcal{T}_{\Sigma_D/E_D \cup B_D} \models b(\vec{X}) = \text{true} \vee b(\vec{X}) = \text{false}$, as well as the isomorphism: $\mathcal{T}_{\Sigma_{\text{IMPL}}/E_{\text{IMPL}} \cup B} \upharpoonright_{\Sigma_D} \cong \mathcal{T}_{\Sigma_D/E_D \cup B_D}$.

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Suppose we want to prove a reachability formula

$A[stmt \ stmt' \rightsquigarrow K] \rightarrow^{\otimes} C[K]$ parametric on K and \vec{Y} about a **sequential composition**. What can we do?

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Acknowledgements

The program proving methodology presented in this lecture has been developed in joint work with Michael Abir. A more detailed document containing all the details of this proof methodology is in preparation.