

# Network Flow Algorithms

Lecture 17

April 1, 2014

# Part I

## Algorithm(s) for Maximum Flow

# Max-flow and min-cut?

Given a network  $G$  with capacities on the edges, and vertices  $s$  and  $t$ , consider the maximum flow  $f$  between  $s$  and  $t$ , and the minimum cut  $(S, T)$  between  $s$  and  $t$ . Then, we have that

(A)  $v(f) < c(S, T)$ .

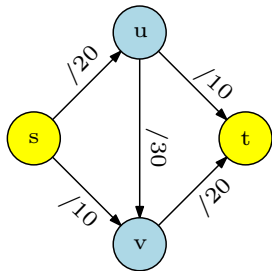
(B)  $v(f) \leq c(S, T)$ .

(C)  $v(f) > c(S, T)$ .

(D)  $v(f) \geq c(S, T)$ .

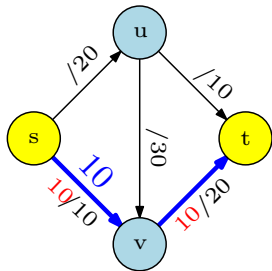
(E)  $v(f) = c(S, T)$ .

# Greedy Approach



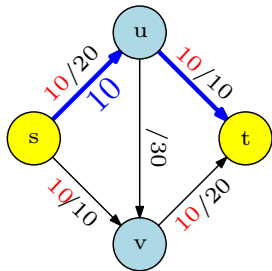
- 1 Begin with  $f(e) = 0$  for each edge.
- 2 Find a **s-t** path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$ .
- 3 **Augment** flow along this path.
- 4 Repeat augmentation for as long as possible.

# Greedy Approach



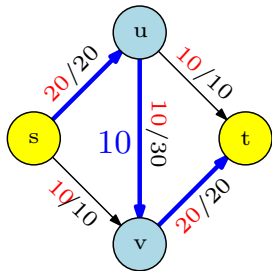
- 1 Begin with  $f(e) = 0$  for each edge.
- 2 Find a **s-t** path **P** with  $f(e) < c(e)$  for every edge  $e \in P$ .
- 3 **Augment** flow along this path.
- 4 Repeat augmentation for as long as possible.

# Greedy Approach



- 1 Begin with  $f(e) = 0$  for each edge.
- 2 Find a **s-t** path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$ .
- 3 **Augment** flow along this path.
- 4 Repeat augmentation for as long as possible.

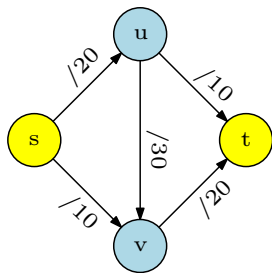
# Greedy Approach



- 1 Begin with  $f(e) = 0$  for each edge.
- 2 Find a **s-t** path **P** with  $f(e) < c(e)$  for every edge  $e \in P$ .
- 3 **Augment** flow along this path.
- 4 Repeat augmentation for as long as possible.

# Greedy Approach: Issues

Issues = What is this nonsense?



- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a **s-t** path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

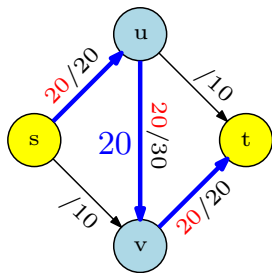
Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge  $(u, v)$ .



# Greedy Approach: Issues

Issues = What is this nonsense?



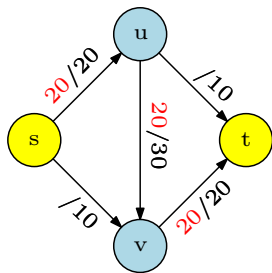
- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a **s-t** path **P** with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge **(u, v)**.

# Greedy Approach: Issues

Issues = What is this nonsense?



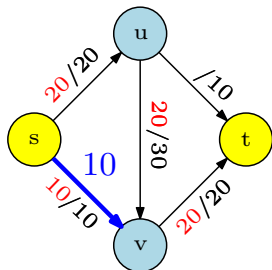
- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a **s-t** path **P** with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge **(u, v)**.

# Greedy Approach: Issues

Issues = What is this nonsense?



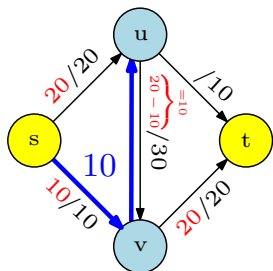
- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a  $s$ - $t$  path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge  $(u, v)$ .

# Greedy Approach: Issues

Issues = What is this nonsense?



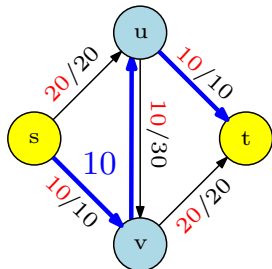
- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a **s-t** path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge  $(u, v)$ .

# Greedy Approach: Issues

Issues = What is this nonsense?



- 1 Begin with  $f(e) = 0$  for each edge
- 2 Find a  $s$ - $t$  path  $P$  with  $f(e) < c(e)$  for every edge  $e \in P$
- 3 Augment flow along this path
- 4 Repeat augmentation for as long as possible.

Greedy can get stuck in sub-optimal flow!

Need to “push-back” flow along edge  $(u, v)$ .

# Residual Graph

The “leftover” graph

## Definition

For a network  $G = (V, E)$  and flow  $f$ , the **residual graph**  $G_f = (V', E')$  of  $G$  with respect to  $f$  is

- 1  $V' = V$ ,
- 2 **Forward Edges**: For each edge  $e \in E$  with  $f(e) < c(e)$ , we add  $e \in E'$  with capacity  $c(e) - f(e)$ .
- 3 **Backward Edges**: For each edge  $e = (u, v) \in E$  with  $f(e) > 0$ , we add  $(v, u) \in E'$  with capacity  $f(e)$ .

# Residual Graph Example

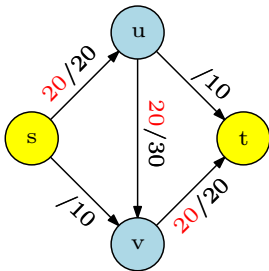


Figure : Flow on edges is indicated in red

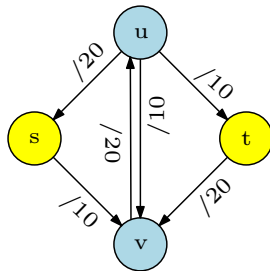


Figure : Residual Graph

# Residual graph has...

Given a network with  $n$  vertices and  $m$  edges, and a valid flow  $f$  in it, the residual network  $G_f$ , has

- (A)  $m$  edges.
- (B)  $\leq 2m$  edges.
- (C)  $\leq 2m + n$  edges.
- (D)  $4m + 2n$  edges.
- (E)  $nm$  edges.
- (F) just the right number of edges - not too many, not too few.



# Residual Graph Property

**Observation:** Residual graph captures the “residual” problem exactly.

## Lemma

Let  $f$  be a flow in  $G$  and  $G_f$  be the residual graph. If  $f'$  is a flow in  $G_f$  then  $f + f'$  is a flow in  $G$  of value  $v(f) + v(f')$ .

## Lemma

Let  $f$  and  $f'$  be two flows in  $G$  with  $v(f') \geq v(f)$ . Then there is a flow  $f''$  of value  $v(f') - v(f)$  in  $G_f$ .

Definition of  $+$  and  $-$  for flows is intuitive and the above lemmas are easy in some sense but a bit messy to formally prove.

# Residual Graph Property

**Observation:** Residual graph captures the “residual” problem exactly.

## Lemma

Let  $\mathbf{f}$  be a flow in  $\mathbf{G}$  and  $\mathbf{G}_f$  be the residual graph. If  $\mathbf{f}'$  is a flow in  $\mathbf{G}_f$  then  $\mathbf{f} + \mathbf{f}'$  is a flow in  $\mathbf{G}$  of value  $v(\mathbf{f}) + v(\mathbf{f}')$ .

## Lemma

Let  $\mathbf{f}$  and  $\mathbf{f}'$  be two flows in  $\mathbf{G}$  with  $v(\mathbf{f}') \geq v(\mathbf{f})$ . Then there is a flow  $\mathbf{f}''$  of value  $v(\mathbf{f}') - v(\mathbf{f})$  in  $\mathbf{G}_f$ .

Definition of  $+$  and  $-$  for flows is intuitive and the above lemmas are easy in some sense but a bit messy to formally prove.

# Residual Graph Property

**Observation:** Residual graph captures the “residual” problem exactly.

## Lemma

Let  $\mathbf{f}$  be a flow in  $\mathbf{G}$  and  $\mathbf{G}_f$  be the residual graph. If  $\mathbf{f}'$  is a flow in  $\mathbf{G}_f$  then  $\mathbf{f} + \mathbf{f}'$  is a flow in  $\mathbf{G}$  of value  $v(\mathbf{f}) + v(\mathbf{f}')$ .

## Lemma

Let  $\mathbf{f}$  and  $\mathbf{f}'$  be two flows in  $\mathbf{G}$  with  $v(\mathbf{f}') \geq v(\mathbf{f})$ . Then there is a flow  $\mathbf{f}''$  of value  $v(\mathbf{f}') - v(\mathbf{f})$  in  $\mathbf{G}_f$ .

Definition of  $+$  and  $-$  for flows is intuitive and the above lemmas are easy in some sense but a bit messy to formally prove.

# Residual Graph Property

**Observation:** Residual graph captures the “residual” problem exactly.

## Lemma

Let  $\mathbf{f}$  be a flow in  $\mathbf{G}$  and  $\mathbf{G}_f$  be the residual graph. If  $\mathbf{f}'$  is a flow in  $\mathbf{G}_f$  then  $\mathbf{f} + \mathbf{f}'$  is a flow in  $\mathbf{G}$  of value  $v(\mathbf{f}) + v(\mathbf{f}')$ .

## Lemma

Let  $\mathbf{f}$  and  $\mathbf{f}'$  be two flows in  $\mathbf{G}$  with  $v(\mathbf{f}') \geq v(\mathbf{f})$ . Then there is a flow  $\mathbf{f}''$  of value  $v(\mathbf{f}') - v(\mathbf{f})$  in  $\mathbf{G}_f$ .

Definition of  $+$  and  $-$  for flows is intuitive and the above lemmas are easy in some sense but a bit messy to formally prove.

# Residual Graph Property: Implication

*Recursive* algorithm for finding a maximum flow:

```
MaxFlow( $G, s, t$ ):  
  if the flow from  $s$  to  $t$  is  $0$  then  
    return  $0$   
  Find any flow  $f$  with  $v(f) > 0$  in  $G$   
  Recursively compute a maximum flow  $f'$  in  $G_f$   
  Output the flow  $f + f'$ 
```

*Iterative* algorithm for finding a maximum flow:

```
MaxFlow( $G, s, t$ ):  
  Start with flow  $f$  that is  $0$  on all edges  
  while there is a flow  $f'$  in  $G_f$  with  $v(f') > 0$  do  
     $f = f + f'$   
    Update  $G_f$   
  
  Output  $f$ 
```

# Residual Graph Property: Implication

*Recursive* algorithm for finding a maximum flow:

```
MaxFlow( $G, s, t$ ):  
  if the flow from  $s$  to  $t$  is  $0$  then  
    return  $0$   
  Find any flow  $f$  with  $v(f) > 0$  in  $G$   
  Recursively compute a maximum flow  $f'$  in  $G_f$   
  Output the flow  $f + f'$ 
```

*Iterative* algorithm for finding a maximum flow:

```
MaxFlow( $G, s, t$ ):  
  Start with flow  $f$  that is  $0$  on all edges  
  while there is a flow  $f'$  in  $G_f$  with  $v(f') > 0$  do  
     $f = f + f'$   
    Update  $G_f$   
  
  Output  $f$ 
```

# Ford-Fulkerson Algorithm

## algFordFulkerson

for every edge  $e$ ,  $f(e) = 0$

$G_f$  is residual graph of  $G$  with respect to  $f$

**while**  $G_f$  has a simple  $s$ - $t$  path **do**

let  $P$  be simple  $s$ - $t$  path in  $G_f$

$f = \text{augment}(f, P)$

Construct new residual graph  $G_f$ .

## augment( $f, P$ )

let  $b$  be bottleneck capacity,

i.e., min capacity of edges in  $P$  (in  $G_f$ )

**for** each edge  $(u, v)$  in  $P$  **do**

**if**  $e = (u, v)$  is a forward edge **then**

$f(e) = f(e) + b$

**else** (\*  $(u, v)$  is a backward edge \*)

let  $e = (v, u)$  (\*  $(v, u)$  is in  $G$  \*)

$f(e) = f(e) - b$

**return**  $f$

# Ford-Fulkerson Algorithm

## algFordFulkerson

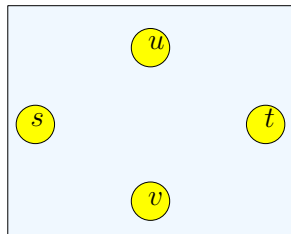
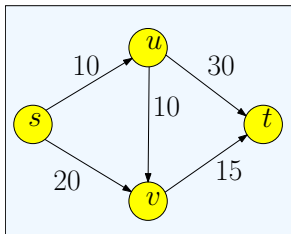
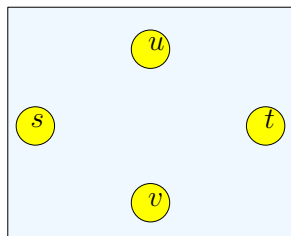
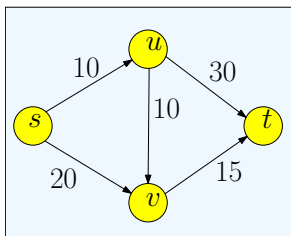
```
for every edge  $e$ ,  $f(e) = 0$   
 $G_f$  is residual graph of  $G$  with respect to  $f$   
while  $G_f$  has a simple  $s$ - $t$  path do  
    let  $P$  be simple  $s$ - $t$  path in  $G_f$   
     $f = \text{augment}(f, P)$   
    Construct new residual graph  $G_f$ .
```

## augment( $f, P$ )

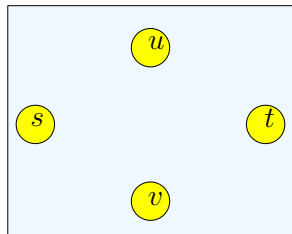
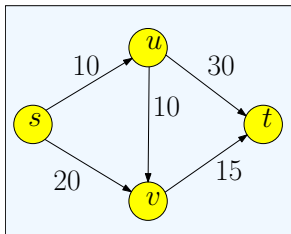
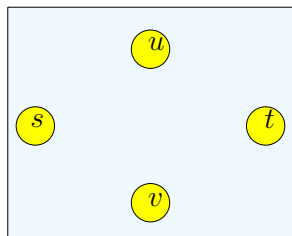
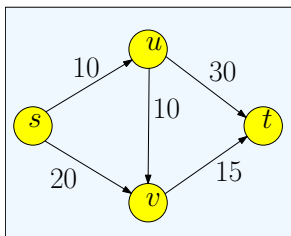
```
let  $b$  be bottleneck capacity,  
    i.e., min capacity of edges in  $P$  (in  $G_f$ )  
for each edge  $(u, v)$  in  $P$  do  
    if  $e = (u, v)$  is a forward edge then  
         $f(e) = f(e) + b$   
    else (*  $(u, v)$  is a backward edge *)  
        let  $e = (v, u)$  (*  $(v, u)$  is in  $G$  *)  
         $f(e) = f(e) - b$   
return  $f$ 
```



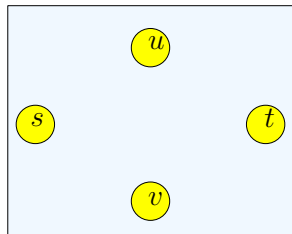
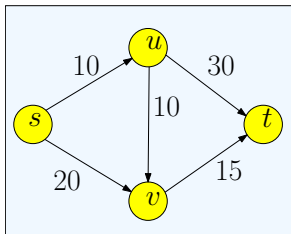
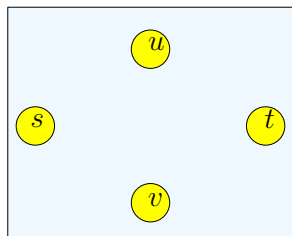
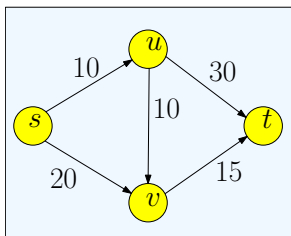
# Example



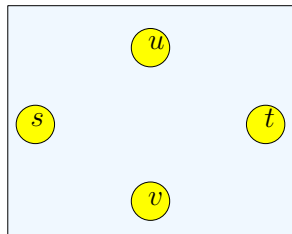
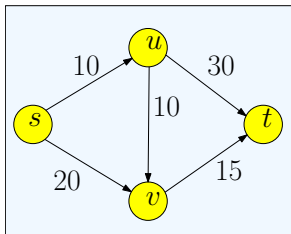
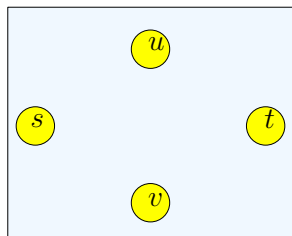
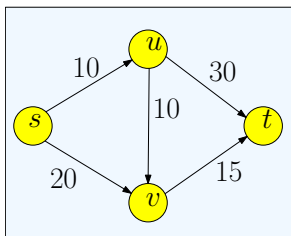
# Example continued



# Example continued



# Example continued



# Properties about Augmentation: Flow

## Lemma

If  $f$  is a flow and  $P$  is a simple  $s$ - $t$  path in  $G_f$ , then  $f' = \text{augment}(f, P)$  is also a flow.

## Proof.

Verify that  $f'$  is a flow. Let  $b$  be augmentation amount.

- 1 **Capacity constraint:** If  $(u, v) \in P$  is a forward edge then  $f'(e) = f(e) + b$  and  $b \leq c(e) - f(e)$ . If  $(u, v) \in P$  is a backward edge, then letting  $e = (v, u)$ ,  $f'(e) = f(e) - b$  and  $b \leq f(e)$ . Both cases  $0 \leq f'(e) \leq c(e)$ .
- 2 **Conservation constraint:** Let  $v$  be an internal node. Let  $e_1, e_2$  be edges of  $P$  incident to  $v$ . Four cases based on whether  $e_1, e_2$  are forward or backward edges. Check cases (see fig next slide).  $\square$

# Properties about Augmentation: Flow

## Lemma

If  $f$  is a flow and  $P$  is a simple  $s$ - $t$  path in  $G_f$ , then  $f' = \text{augment}(f, P)$  is also a flow.

## Proof.

Verify that  $f'$  is a flow. Let  $b$  be augmentation amount.

- 1 **Capacity constraint:** If  $(u, v) \in P$  is a forward edge then  $f'(e) = f(e) + b$  and  $b \leq c(e) - f(e)$ . If  $(u, v) \in P$  is a backward edge, then letting  $e = (v, u)$ ,  $f'(e) = f(e) - b$  and  $b \leq f(e)$ . Both cases  $0 \leq f'(e) \leq c(e)$ .
- 2 **Conservation constraint:** Let  $v$  be an internal node. Let  $e_1, e_2$  be edges of  $P$  incident to  $v$ . Four cases based on whether  $e_1, e_2$  are forward or backward edges. Check cases (see fig next slide).  $\square$

# Properties about Augmentation: Flow

## Lemma

If  $\mathbf{f}$  is a flow and  $\mathbf{P}$  is a simple  $\mathbf{s-t}$  path in  $\mathbf{G}_f$ , then  $\mathbf{f}' = \text{augment}(\mathbf{f}, \mathbf{P})$  is also a flow.

## Proof.

Verify that  $\mathbf{f}'$  is a flow. Let  $\mathbf{b}$  be augmentation amount.

- Capacity constraint:** If  $(\mathbf{u}, \mathbf{v}) \in \mathbf{P}$  is a forward edge then  $\mathbf{f}'(\mathbf{e}) = \mathbf{f}(\mathbf{e}) + \mathbf{b}$  and  $\mathbf{b} \leq \mathbf{c}(\mathbf{e}) - \mathbf{f}(\mathbf{e})$ . If  $(\mathbf{u}, \mathbf{v}) \in \mathbf{P}$  is a backward edge, then letting  $\mathbf{e} = (\mathbf{v}, \mathbf{u})$ ,  $\mathbf{f}'(\mathbf{e}) = \mathbf{f}(\mathbf{e}) - \mathbf{b}$  and  $\mathbf{b} \leq \mathbf{f}(\mathbf{e})$ . Both cases  $\mathbf{0} \leq \mathbf{f}'(\mathbf{e}) \leq \mathbf{c}(\mathbf{e})$ .
- Conservation constraint:** Let  $\mathbf{v}$  be an internal node. Let  $\mathbf{e}_1, \mathbf{e}_2$  be edges of  $\mathbf{P}$  incident to  $\mathbf{v}$ . Four cases based on whether  $\mathbf{e}_1, \mathbf{e}_2$  are forward or backward edges. Check cases (see fig next slide).  $\square$

# Properties about Augmentation: Flow

## Lemma

If  $f$  is a flow and  $P$  is a simple  $s$ - $t$  path in  $G_f$ , then  $f' = \text{augment}(f, P)$  is also a flow.

## Proof.

Verify that  $f'$  is a flow. Let  $b$  be augmentation amount.

- Capacity constraint:** If  $(u, v) \in P$  is a forward edge then  $f'(e) = f(e) + b$  and  $b \leq c(e) - f(e)$ . If  $(u, v) \in P$  is a backward edge, then letting  $e = (v, u)$ ,  $f'(e) = f(e) - b$  and  $b \leq f(e)$ . Both cases  $0 \leq f'(e) \leq c(e)$ .
- Conservation constraint:** Let  $v$  be an internal node. Let  $e_1, e_2$  be edges of  $P$  incident to  $v$ . Four cases based on whether  $e_1, e_2$  are forward or backward edges. Check cases (see fig next slide).  $\square$



# Properties about Augmentation: Flow

## Lemma

If  $f$  is a flow and  $P$  is a simple  $s$ - $t$  path in  $G_f$ , then  $f' = \text{augment}(f, P)$  is also a flow.

## Proof.

Verify that  $f'$  is a flow. Let  $b$  be augmentation amount.

- 1 **Capacity constraint:** If  $(u, v) \in P$  is a forward edge then  $f'(e) = f(e) + b$  and  $b \leq c(e) - f(e)$ . If  $(u, v) \in P$  is a backward edge, then letting  $e = (v, u)$ ,  $f'(e) = f(e) - b$  and  $b \leq f(e)$ . Both cases  $0 \leq f'(e) \leq c(e)$ .
- 2 **Conservation constraint:** Let  $v$  be an internal node. Let  $e_1, e_2$  be edges of  $P$  incident to  $v$ . Four cases based on whether  $e_1, e_2$  are forward or backward edges. Check cases (see fig next slide).  $\square$

# Properties of Augmentation

## Conservation Constraint

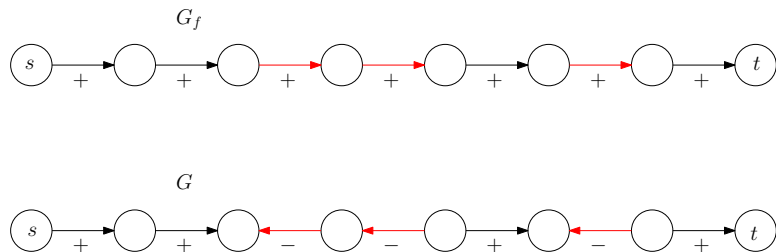


Figure : Augmenting path  $P$  in  $G_f$  and corresponding change of flow in  $G$ . Red edges are backward edges.

# Rational, integer or real?

Consider a network flow instance where all the numbers are integers. **algFordFulkerson** on this network outputs a flow such that its value is

- (A) Since the algorithm runs on a RAM machine, and it can perform any arithmetic operation, the output is a real number.
- (B) The algorithm does only subtract, add, divide and multiply operations. Thus the output is a rational number.
- (C) The algorithm does only subtract and add operations on numbers. Thus the output is an integer number.
- (D) **algFordFulkerson** does not necessarily terminates, so the question is ill defined.
- (E) If the capacities are negative, the algorithm might output  $+\infty$  (which is not an integer, rational or real number).

# Properties of Augmentation

## Integer Flow

### Lemma

*At every stage of the Ford-Fulkerson algorithm, the flow values on the edges (i.e.,  $f(e)$ , for all edges  $e$ ) and the residual capacities in  $G_f$  are integers.*

### Proof.

Initial flow and residual capacities are integers. Suppose lemma holds for  $j$  iterations. Then in  $(j + 1)$ st iteration, minimum capacity edge  $b$  is an integer, and so flow after augmentation is an integer.  $\square$

# Progress in Ford-Fulkerson

## Proposition

Let  $\mathbf{f}$  be a flow and  $\mathbf{f}'$  be flow after one augmentation. Then  $v(\mathbf{f}) < v(\mathbf{f}')$ .

## Proof.

Let  $\mathbf{P}$  be an augmenting path, i.e.,  $\mathbf{P}$  is a simple  $\mathbf{s-t}$  path in residual graph. We have the following.

- 1 First edge  $\mathbf{e}$  in  $\mathbf{P}$  must leave  $\mathbf{s}$ .
- 2 Original network  $\mathbf{G}$  has no incoming edges to  $\mathbf{s}$ ; hence  $\mathbf{e}$  is a forward edge.
- 3  $\mathbf{P}$  is simple and so never returns to  $\mathbf{s}$ .
- 4 Thus, value of flow increases by the flow on edge  $\mathbf{e}$ . □

# Termination proof for integral flow

## Theorem

Let  $C$  be the minimum cut value; in particular

$C \leq \sum_{e \text{ out of } s} c(e)$ . Ford-Fulkerson algorithm terminates after finding at most  $C$  augmenting paths.

## Proof.

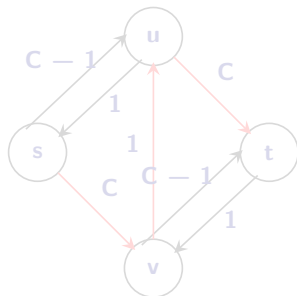
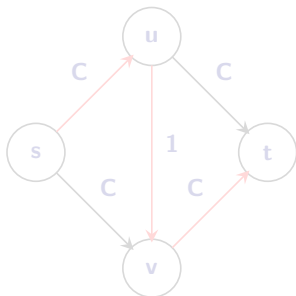
The value of the flow increases by at least  $1$  after each augmentation. Maximum value of flow is at most  $C$ . □

## Running time

- 1 Number of iterations  $\leq C$ .
- 2 Number of edges in  $G_f \leq 2m$ .
- 3 Time to find augmenting path is  $O(n + m)$ .
- 4 Running time is  $O(C(n + m))$  (or  $O(mC)$ ).

# Efficiency of Ford-Fulkerson

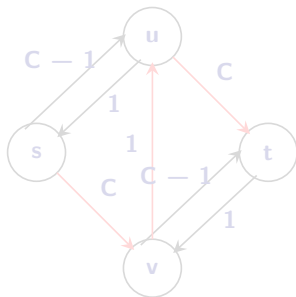
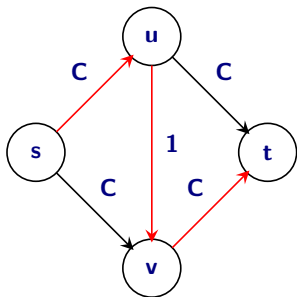
Running time =  $O(mC)$  is not polynomial. Can the running time be as  $\Omega(mC)$  or is our analysis weak?



Ford-Fulkerson can take  $\Omega(C)$  iterations.

# Efficiency of Ford-Fulkerson

Running time =  $O(mC)$  is not polynomial. Can the running time be as  $\Omega(mC)$  or is our analysis weak?

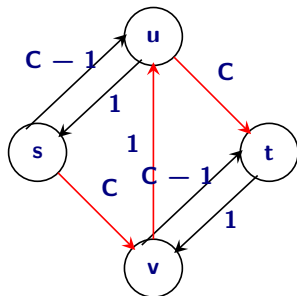
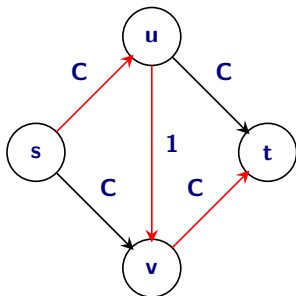


Ford-Fulkerson can take  $\Omega(C)$  iterations.



# Efficiency of Ford-Fulkerson

Running time =  $O(mC)$  is not polynomial. Can the running time be as  $\Omega(mC)$  or is our analysis weak?



Ford-Fulkerson can take  $\Omega(C)$  iterations.

# Correctness of Ford-Fulkerson

## Why the augmenting path approach works

**Question:** When the algorithm terminates, is the flow computed the maximum **s-t** flow?

Proof idea: show a cut of value equal to the flow. Also shows that maximum flow is equal to minimum cut!

# Correctness of Ford-Fulkerson

## Why the augmenting path approach works

**Question:** When the algorithm terminates, is the flow computed the maximum **s-t** flow?

Proof idea: show a cut of value equal to the flow. Also shows that maximum flow is equal to minimum cut!

# Recalling Cuts

## Definition

Given a flow network an **s-t cut** is a set of edges  $E' \subset E$  such that removing  $E'$  *disconnects*  $s$  from  $t$ : in other words there is no directed  $s \rightarrow t$  path in  $E - E'$ . **Capacity** of cut  $E'$  is  $\sum_{e \in E'} c(e)$ .

Let  $A \subset V$  such that

- 1  $s \in A$ ,  $t \notin A$ , and
- 2  $B = V \setminus A$  and hence  $t \in B$ .

Define  $(A, B) = \{(u, v) \in E \mid u \in A, v \in B\}$

## Claim

$(A, B)$  is an s-t cut.

Recall: Every *minimal* s-t cut  $E'$  is a cut of the form  $(A, B)$ .

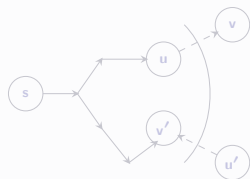
# Ford-Fulkerson Correctness

## Lemma

If there is no  $s$ - $t$  path in  $G_f$  then there is some cut  $(A, B)$  such that  $v(f) = c(A, B)$

## Proof.

Let  $A$  be all vertices reachable from  $s$  in  $G_f$ ;  $B = V \setminus A$ .



①  $s \in A$  and  $t \in B$ . So  $(A, B)$  is an  $s$ - $t$  cut in  $G$ .

② If  $e = (u, v) \in G$  with  $u \in A$  and  $v \in B$ , then  $f(e) = c(e)$  (saturated edge) because otherwise  $v$  is reachable from  $s$  in  $G_f$ .

□

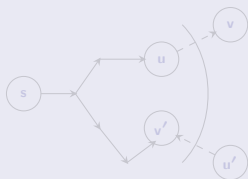
# Ford-Fulkerson Correctness

## Lemma

If there is no  $s$ - $t$  path in  $G_f$  then there is some cut  $(A, B)$  such that  $v(f) = c(A, B)$

## Proof.

Let  $A$  be all vertices reachable from  $s$  in  $G_f$ ;  $B = V \setminus A$ .



①  $s \in A$  and  $t \in B$ . So  $(A, B)$  is an  $s$ - $t$  cut in  $G$ .

② If  $e = (u, v) \in G$  with  $u \in A$  and  $v \in B$ , then  $f(e) = c(e)$  (saturated edge) because otherwise  $v$  is reachable from  $s$  in  $G_f$ .

□

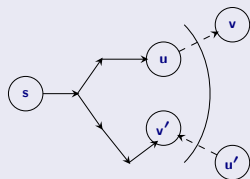
# Ford-Fulkerson Correctness

## Lemma

If there is no  $s$ - $t$  path in  $G_f$  then there is some cut  $(A, B)$  such that  $v(f) = c(A, B)$

## Proof.

Let  $A$  be all vertices reachable from  $s$  in  $G_f$ ;  $B = V \setminus A$ .



①  $s \in A$  and  $t \in B$ . So  $(A, B)$  is an  $s$ - $t$  cut in  $G$ .

② If  $e = (u, v) \in G$  with  $u \in A$  and  $v \in B$ , then  $f(e) = c(e)$  (saturated edge) because otherwise  $v$  is reachable from  $s$  in  $G_f$ .

□

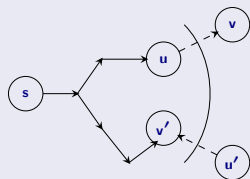
# Ford-Fulkerson Correctness

## Lemma

If there is no  $s$ - $t$  path in  $G_f$  then there is some cut  $(A, B)$  such that  $v(f) = c(A, B)$

## Proof.

Let  $A$  be all vertices reachable from  $s$  in  $G_f$ ;  $B = V \setminus A$ .



①  $s \in A$  and  $t \in B$ . So  $(A, B)$  is an  $s$ - $t$  cut in  $G$ .

② If  $e = (u, v) \in E$  with  $u \in A$  and  $v \in B$ , then  $f(e) = c(e)$  (saturated edge) because otherwise  $v$  is reachable from  $s$  in  $G_f$ .

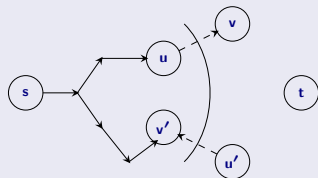
□



# Lemma Proof Continued

## Proof.

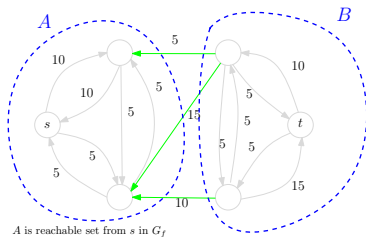
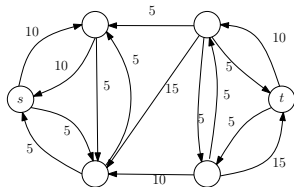
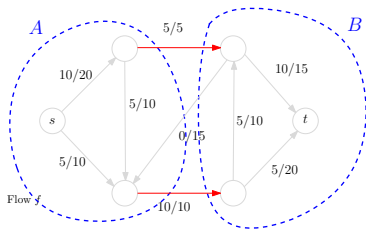
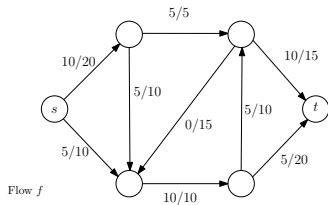
- 1 If  $e = (u', v') \in G$  with  $u' \in B$  and  $v' \in A$ , then  $f(e) = 0$  because otherwise  $u'$  is reachable from  $s$  in  $G_f$
- 2 Thus,



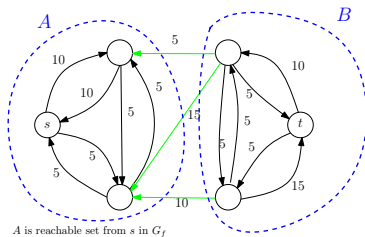
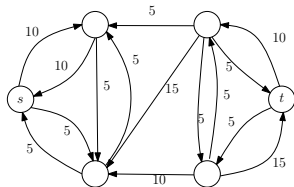
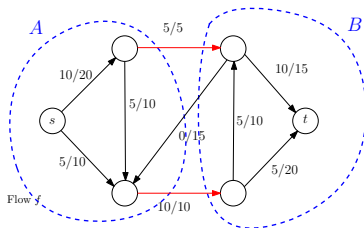
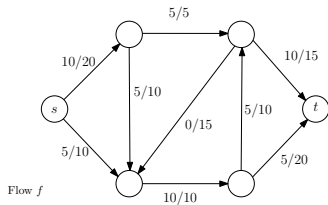
$$\begin{aligned} v(f) &= f^{\text{out}}(A) - f^{\text{in}}(A) \\ &= f^{\text{out}}(A) - 0 \\ &= c(A, B) - 0 \\ &= c(A, B). \end{aligned}$$



# Example



# Example



# Ford-Fulkerson Correctness

## Theorem

*The flow returned by the algorithm is the maximum flow.*

## Proof.

- 1 For any flow  $\mathbf{f}$  and  $s$ - $t$  cut  $(\mathbf{A}, \mathbf{B})$ ,  $v(\mathbf{f}) \leq c(\mathbf{A}, \mathbf{B})$ .
- 2 For flow  $\mathbf{f}^*$  returned by algorithm,  $v(\mathbf{f}^*) = c(\mathbf{A}^*, \mathbf{B}^*)$  for some  $s$ - $t$  cut  $(\mathbf{A}^*, \mathbf{B}^*)$ .
- 3 Hence,  $\mathbf{f}^*$  is maximum.



# Max-Flow Min-Cut Theorem and Integrality of Flows

## Theorem

*For any network  $G$ , the value of a maximum  $s$ - $t$  flow is equal to the capacity of the minimum  $s$ - $t$  cut.*

## Proof.

Ford-Fulkerson algorithm terminates with a maximum flow of value equal to the capacity of a (minimum) cut. □

# Max-Flow Min-Cut Theorem and Integrality of Flows

## Theorem

*For any network  $G$  with integer capacities, there is a maximum  $s$ - $t$  flow that is integer valued.*

## Proof.

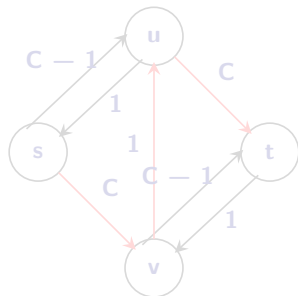
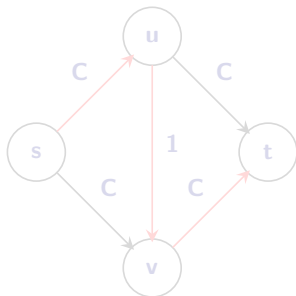
Ford-Fulkerson algorithm produces an integer valued flow when capacities are integers. □

# Does it terminate?

- (A) **algFordFulkerson** always terminates.
- (B) **algFordFulkerson** might not terminate if the input has real numbers.
- (C) **algFordFulkerson** might not terminate if the input has rational numbers.
- (D) **algFordFulkerson** might not terminate if the input is only integer numbers that are sufficiently large.

# Efficiency of Ford-Fulkerson

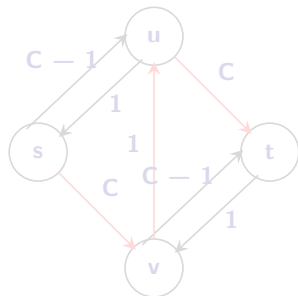
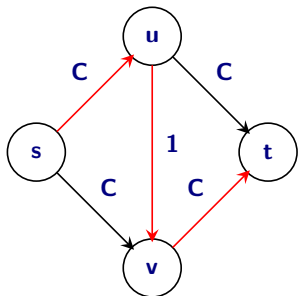
Running time =  $O(mC)$  is not polynomial. Can the upper bound be achieved?





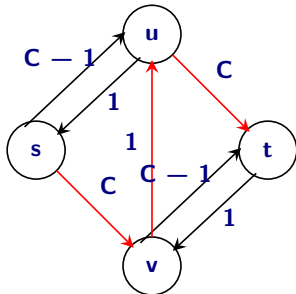
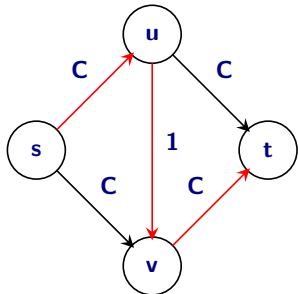
# Efficiency of Ford-Fulkerson

Running time =  $O(mC)$  is not polynomial. Can the upper bound be achieved?



# Efficiency of Ford-Fulkerson

Running time =  $O(mC)$  is not polynomial. Can the upper bound be achieved?



# Polynomial Time Algorithms

**Question:** Is there a polynomial time algorithm for maxflow?

**Question:** Is there a variant of Ford-Fulkerson that leads to a polynomial time algorithm? Can we choose an augmenting path in some clever way? Yes! Two variants.

- 1 Choose the augmenting path with largest bottleneck capacity.
- 2 Choose the shortest augmenting path.

# Polynomial Time Algorithms

**Question:** Is there a polynomial time algorithm for maxflow?

**Question:** Is there a variant of Ford-Fulkerson that leads to a polynomial time algorithm? Can we choose an augmenting path in some clever way? Yes! Two variants.

- 1 Choose the augmenting path with largest bottleneck capacity.
- 2 Choose the shortest augmenting path.

# Polynomial Time Algorithms

**Question:** Is there a polynomial time algorithm for maxflow?

**Question:** Is there a variant of Ford-Fulkerson that leads to a polynomial time algorithm? Can we choose an augmenting path in some clever way? Yes! Two variants.

- 1 Choose the augmenting path with largest bottleneck capacity.
- 2 Choose the shortest augmenting path.

# Finding path with largest bottleneck capacity

$G_f$  - residual network with (residual) capacities.

$n$  vertices and  $m$  edges.

Finding the  $s$ - $t$  path with largest bottleneck capacity can be done (faster is better) in:

- (A)  $O(n + m)$
- (B)  $O(n \log + m)$
- (C)  $O(nm)$
- (D)  $O(m^2)$
- (E)  $O(m^3)$

time (expected or deterministic is fine here).

# Augmenting Paths with Large Bottleneck Capacity

- 1 Pick augmenting paths with largest bottleneck capacity in each iteration of Ford-Fulkerson.
- 2 How do we find path with largest bottleneck capacity?
  - 1 Assume we know  $\Delta$  the bottleneck capacity
  - 2 Remove all edges with residual capacity  $\leq \Delta$
  - 3 Check if there is a path from  $s$  to  $t$
  - 4 Do binary search to find largest  $\Delta$
  - 5 Running time:  $O(m \log C)$
- 3 Can we bound the number of augmentations? Can show that in  $O(m \log C)$  augmentations the algorithm reaches a max flow. This leads to an  $O(m^2 \log^2 C)$  time algorithm.

# Augmenting Paths with Large Bottleneck Capacity

- 1 Pick augmenting paths with largest bottleneck capacity in each iteration of Ford-Fulkerson.
- 2 How do we find path with largest bottleneck capacity?
  - 1 Assume we know  $\Delta$  the bottleneck capacity
  - 2 Remove all edges with residual capacity  $\leq \Delta$
  - 3 Check if there is a path from  $s$  to  $t$
  - 4 Do binary search to find largest  $\Delta$
  - 5 Running time:  $O(m \log C)$
- 3 Can we bound the number of augmentations? Can show that in  $O(m \log C)$  augmentations the algorithm reaches a max flow. This leads to an  $O(m^2 \log^2 C)$  time algorithm.



# Augmenting Paths with Large Bottleneck Capacity

- 1 Pick augmenting paths with largest bottleneck capacity in each iteration of Ford-Fulkerson.
- 2 How do we find path with largest bottleneck capacity?
  - 1 Assume we know  $\Delta$  the bottleneck capacity
  - 2 Remove all edges with residual capacity  $\leq \Delta$
  - 3 Check if there is a path from  $s$  to  $t$
  - 4 Do binary search to find largest  $\Delta$
  - 5 Running time:  $O(m \log C)$
- 3 Can we bound the number of augmentations? Can show that in  $O(m \log C)$  augmentations the algorithm reaches a max flow. This leads to an  $O(m^2 \log^2 C)$  time algorithm.

# Augmenting Paths with Large Bottleneck Capacity

How do we find path with largest bottleneck capacity?

- 1 Max bottleneck capacity is one of the edge capacities. Why?
- 2 Can do binary search on the edge capacities. First, sort the edges by their capacities and then do binary search on that array as before.
- 3 Algorithm's running time is  $O(m \log m)$ .
- 4 Different algorithm that also leads to  $O(m \log m)$  time algorithm by adapting Prim's algorithm.
- 5  $O(m)$  time using linear-time median selection algorithm.

# Removing Dependence on $C$

## ① Dinic [1970], Edmonds and Karp [1972]

Picking augmenting paths with fewest number of edges yields a  $O(m^2n)$  algorithm, i.e., independent of  $C$ . Such an algorithm is called a **strongly polynomial** time algorithm since the running time does not depend on the numbers (assuming RAM model). (Many implementation of Ford-Fulkerson would actually use shortest augmenting path if they use **BFS** to find an **s-t** path).

- ② Further improvements can yield algorithms running in  $O(mn \log n)$ , or  $O(n^3)$ .

# Ford-Fulkerson Algorithm

## algEdmondsKarp

for every edge  $e$ ,  $f(e) = 0$

$G_f$  is residual graph of  $G$  with respect to  $f$

**while**  $G_f$  has a simple  $s$ - $t$  path **do**

    Perform **BFS** in  $G_f$

**P**: shortest  $s$ - $t$  path in  $G_f$

**f** = **augment**( $f$ , **P**)

    Construct new residual graph  $G_f$ .

Running time  $O(m^2n)$ .

# Finding a Minimum Cut

**Question:** How do we find an actual minimum **s-t** cut?

Proof gives the algorithm!

- 1 Compute an **s-t** maximum flow **f** in **G**
- 2 Obtain the residual graph **G<sub>f</sub>**
- 3 Find the nodes **A** reachable from **s** in **G<sub>f</sub>**
- 4 Output the cut  $(\mathbf{A}, \mathbf{B}) = \{(u, v) \mid u \in \mathbf{A}, v \in \mathbf{B}\}$ . **Note:** The cut is found in **G** while **A** is found in **G<sub>f</sub>**

Running time is essentially the same as finding a maximum flow.

**Note:** Given **G** and a flow **f** there is a linear time algorithm to check if **f** is a maximum flow and if it is, outputs a minimum cut. How?

# Finding a Minimum Cut

**Question:** How do we find an actual minimum **s-t** cut?

Proof gives the algorithm!

- 1 Compute an **s-t** maximum flow **f** in **G**
- 2 Obtain the residual graph **G<sub>f</sub>**
- 3 Find the nodes **A** reachable from **s** in **G<sub>f</sub>**
- 4 Output the cut  $(\mathbf{A}, \mathbf{B}) = \{(u, v) \mid u \in \mathbf{A}, v \in \mathbf{B}\}$ . **Note:** The cut is found in **G** while **A** is found in **G<sub>f</sub>**

Running time is essentially the same as finding a maximum flow.

**Note:** Given **G** and a flow **f** there is a linear time algorithm to check if **f** is a maximum flow and if it is, outputs a minimum cut. How?

# Notes







# Notes

Dinic, E. A. (1970). Algorithm for solution of a problem of maximum flow in a network with power estimation. *Soviet Math. Doklady*, 11:1277–1280.

Edmonds, J. and Karp, R. M. (1972). Theoretical improvements in algorithmic efficiency for network flow problems. *J. Assoc. Comput. Mach.*, 19(2):248–264.