

Chapter 14

Network Flow II - The Vengeance

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Version: 0.11

14.1. Accountability

The comic in [Figure 14.1](#) is by Jonathan Shewchuk and is referring to the Calvin and Hobbes comics.

People that do not know maximum flows: essentially everybody.

Average salary on earth < \$5,000

People that know maximum flow - most of them work in programming related jobs and make at least \$10,000 a year.

Salary of people that learned maximum flows: > \$10,000

Salary of people that did not learn maximum flows: < \$5,000

Salary of people that know Latin: 0 (unemployed).

Thus, by just learning maximum flows (and not knowing Latin) you can double your future salary!

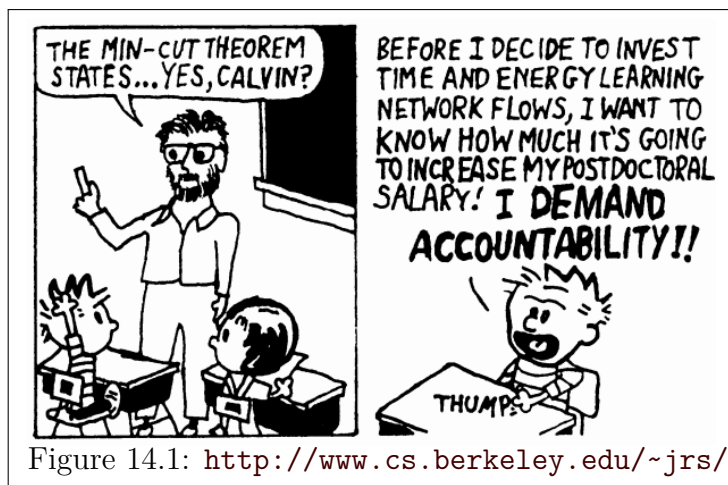


Figure 14.1: <http://www.cs.berkeley.edu/~jrs/>

14.2. The Ford-Fulkerson Method

The `mtdFordFulkerson` method is depicted on the right.

Lemma 14.2.1. *If the capacities on the edges of G are integers, then `mtdFordFulkerson` runs in $O(m|f^*|)$ time, where $|f^*|$ is the amount of flow in the maximum flow and $m = |E(G)|$.*

Proof: Observe that the `mtdFordFulkerson` method performs only subtraction, addition and min operations. Thus, if it finds an augmenting path π , then $c_f(\pi)$ must be a *positive* integer number. Namely, $c_f(\pi) \geq 1$. Thus, $|f^*|$ must be an integer number (by induction), and each iteration of the algorithm improves the flow by at least 1. It follows that after $|f^*|$ iterations the algorithm stops. Each iteration takes $O(m + n) = O(m)$ time, as can be easily verified. ■

```
mtdFordFulkerson( $G, s, t$ )
  Initialize flow  $f$  to zero
  while  $\exists$  path  $\pi$  from  $s$  to  $t$  in  $G_f$  do
     $c_f(\pi) \leftarrow \min \{c_f(u, v) \mid (u, v) \in \pi\}$ 
    for  $\forall (u, v) \in \pi$  do
       $f(u, v) \leftarrow f(u, v) + c_f(\pi)$ 
       $f(v, u) \leftarrow f(v, u) - c_f(\pi)$ 
```

The following observation is an easy consequence of our discussion.

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Observation 14.2.2 (Integrality theorem). *If the capacity function c takes on only integral values, then the maximum flow f produced by the `mtdFordFulkerson` method has the property that $|f|$ is integer-valued. Moreover, for all vertices u and v , the value of $f(u,v)$ is also an integer.*

14.3. The Edmonds-Karp algorithm

The `Edmonds-Karp` algorithm works by modifying the `mtdFordFulkerson` method so that it always returns the shortest augmenting path in G_f (i.e., path with smallest number of edges). This is implemented by finding π using `BFS` in G_f .

Definition 14.3.1. For a flow f , let $\delta_f(v)$ be the length of the shortest path from the source s to v in the residual graph G_f . Each edge is considered to be of length 1.

We will shortly prove that, for any vertex $v \in V \setminus \{s,t\}$, the function $\delta_f(v)$, in the residual network G_f , increases monotonically with each flow augmentation. We delay proving this (key) technical fact (see `Lemma 14.3.5` below), and first show its implications.

Lemma 14.3.2. *During the execution of the `Edmonds-Karp` algorithm, an edge (u,v) might disappear (and thus reappear) from G_f at most $n/2$ times throughout the execution of the algorithm, where $n = |V(G)|$.*

Proof: Consider an iteration when the edge (u,v) disappears. Clearly, in this iteration the edge (u,v) appeared in the augmenting path π . Furthermore, this edge was fully utilized; namely, $c_f(\pi) = c_f(uv)$, where f is the flow in the beginning of the iteration when it disappeared. We continue running `Edmonds-Karp` till (u,v) “magically” reappears. This means that in the iteration before (u,v) reappeared in the residual graph, the algorithm handled an augmenting path σ that contained the *reverse* edge (v,u) . Let g be the flow used to compute σ . We have, by the monotonicity of $\delta(\cdot)$ [i.e., `Lemma 14.3.5` below], that

$$\delta_g(u) = \delta_g(v) + 1 \geq \delta_f(v) + 1 = \delta_f(u) + 2$$

as `Edmonds-Karp` is always augmenting along the shortest path. Namely, the distance of s to u had increased by 2 between its disappearance and its reappearance. Since $\delta_0(u) \geq 0$ and the maximum value of $\delta_f(u)$ is n , it follows that (u,v) can disappear and reappear at most $n/2$ times during the execution of the `Edmonds-Karp` algorithm. ■

Observe that $\delta_f(u)$ might become infinity at some point during the algorithm execution (i.e., u is no longer reachable from s). If so, by monotonicity, the edge (u,v) would never appear again, in the residual graph, in any future iteration of the algorithm.

Observation 14.3.3. *Every time we add an augmenting path during the execution of the `Edmonds-Karp` algorithm, at least one edge disappears from the residual graph G_f . Indeed, every edge that realizes the residual capacity (of the augmenting path) will disappear once we push the maximum possible flow along this path.*

Lemma 14.3.4. *The `Edmonds-Karp` algorithm handles at most $O(nm)$ augmenting paths before it stops. Its running time is $O(nm^2)$, where $n = |V(G)|$ and $m = |E(G)|$.*

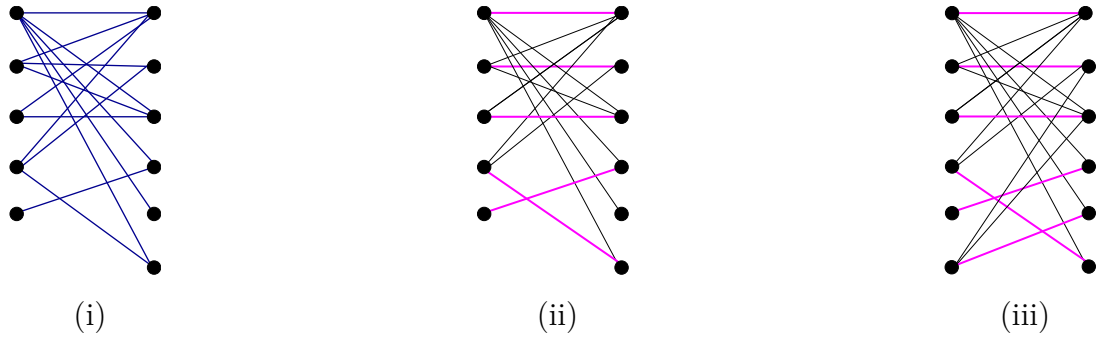


Figure 14.2: (i) A bipartite graph. (ii) A maximum matching in this graph. (iii) A perfect matching (in a different graph).

Proof: Every edge might disappear at most $n/2$ times during **Edmonds-Karp** execution, by **Lemma 14.3.2**. Thus, there are at most $nm/2$ edge disappearances during the execution of the **Edmonds-Karp** algorithm. At each iteration, we perform path augmentation, and at least one edge disappears along it from the residual graph. Thus, the **Edmonds-Karp** algorithm perform at most $O(mn)$ iterations.

Performing a single iteration of the algorithm boils down to computing an augmenting path. Computing such a path takes $O(m)$ time as we have to perform BFS to find the augmenting path. It follows, that the overall running time of the algorithm is $O(nm^2)$. ■

We still need to prove the aforementioned monotonicity property. (This is the only part in our discussion of network flow where the argument gets a bit tedious. So bear with us, after all, you are going to double your salary here.)

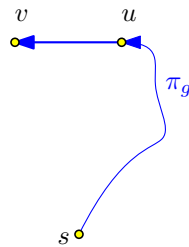
Lemma 14.3.5. *If the **Edmonds-Karp** algorithm is run on a flow network $G = (V, E)$ with source s and sink t , then for all vertices $v \in V \setminus \{s, t\}$, the shortest path distance $\delta_f(v)$ in the residual network G_f increases monotonically with each flow augmentation.*

Proof: Assume, for the sake of contradiction, that this is false. Consider the flow just after the first iteration when this claim failed. Let f denote the flow before this (fatal) iteration was performed, and let g be the flow after.

Let v be the vertex such that $\delta_g(v)$ is minimal, among all vertices for which the monotonicity fails. Formally, this is the vertex v where $\delta_g(v)$ is minimal and

$$\delta_g(v) < \delta_f(v). \quad (*)$$

Let $\pi_g = s \rightarrow \dots \rightarrow u \rightarrow v$ be the shortest path in G_g from s to v . Clearly, $(u, v) \in E(G_g)$, and thus $\delta_g(u) = \delta_g(v) - 1$.



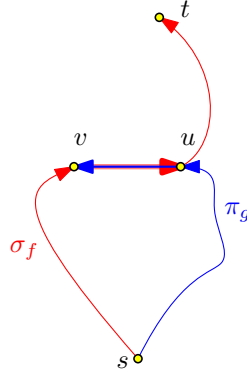
By the choice of v it must be that $\delta_g(u) \geq \delta_f(u)$, since otherwise the monotonicity property fails for u , and u is closer to s than v in G_g , and this, in turn, contradicts our choice of v as being the closest vertex to s that fails the monotonicity property. There are now two possibilities:

(i) If $(u, v) \in E(G_f)$ then

$$\delta_f(v) \leq \delta_f(u) + 1 \leq \delta_g(u) + 1 = \delta_g(v) - 1 + 1 = \delta_g(v).$$

This contradicts our assumptions that $\delta_f(v) > \delta_g(v)$.

(ii) If (u, v) is not in $E(G_f)$ then the augmenting path σ_f used in computing g from f contains the edge (v, u) . Indeed, the edge (u, v) reappeared in the residual graph G_g (while not being present in G_f). The only way this can happen is if the augmenting path σ_f pushed a flow in the other direction on the edge (u, v) . Namely, $(v, u) \in \sigma_f$.



However, the algorithm always augment along the shortest path. We have that

$$\delta_f(u) = \delta_f(v) + 1 \underbrace{>}_{(*)} \delta_g(v) + 1 > \delta_g(v) = \delta_g(u) + 1,$$

by the definition of u . Thus, $\delta_f(u) > \delta_g(u)$ (i.e., the monotonicity property fails for u) and $\delta_g(u) < \delta_g(v)$. A contradiction to the choice of v . ■

14.4. Applications and extensions for Network Flow

14.4.1. Maximum Bipartite Matching

Definition 14.4.1. For an undirected graph $G = (V, E)$ a **matching** is a subset of edges $M \subseteq E$ such that for all vertices $v \in V$, at most one edge of M is incident on v .

A **maximum matching** is a matching M such that for any matching M' we have $|M| \geq |M'|$.

A matching is **perfect** if it involves all vertices. See Figure 14.2 for examples of these definitions.

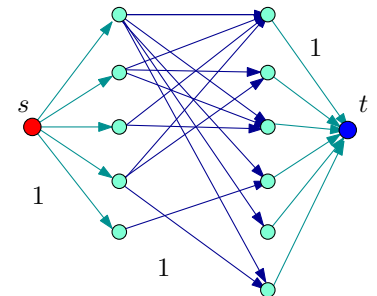


Figure 14.3

Theorem 14.4.2. One can compute maximum bipartite matching using network flow in $O(nm)$ time, for a bipartite graph with n vertices and m edges.

Proof: Given a bipartite graph G , we create a new graph with a new source on the left side and sink on the right, see [Figure 14.3](#).

Direct all edges from left to right and set the capacity of all edges to 1. Let H be the resulting flow network. It is now easy to verify that by the Integrality theorem, a flow in H is either 0 or one on every edge, and thus a flow of value k in H is just a collection of k vertex disjoint paths between s and t in H , which corresponds to a matching in G of size k .

Similarly, given a matching of size k in G , it can be easily interpreted as realizing a flow in H of size k . Thus, computing a maximum flow in H results in computing a maximum matching in G . The running time of the algorithm is $O(nm^2)$. ■

14.4.2. Extension: Multiple Sources and Sinks

Given a flow network with several sources and sinks, how can we compute maximum flow on such a network?

The idea is to create a super source, that send all its flow to the old sources and similarly create a super sink that receives all the flow. See [Figure 14.4](#). Clearly, computing flow in both networks is equivalent.

Bibliography

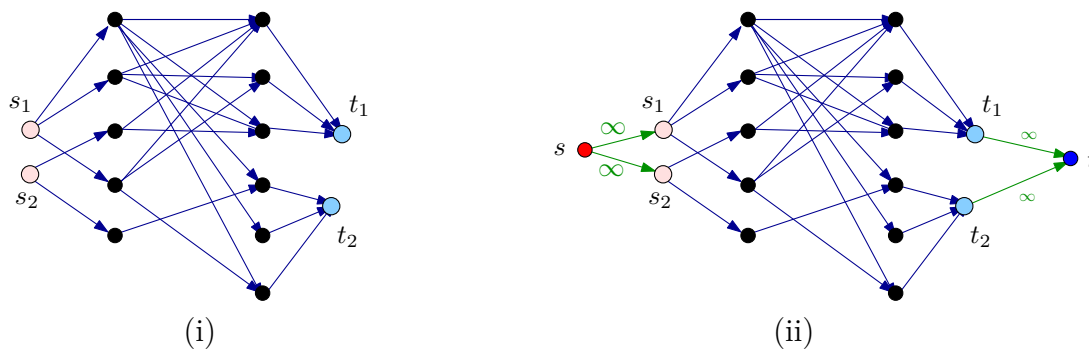


Figure 14.4: (i) A flow network with several sources and sinks, and (ii) an equivalent flow network with a single source and sink.