

# NP Completeness and Cook-Levin Theorem

Lecture 22

April 19, 2011

# P and NP and Turing Machines

- **P**: set of decision problems that have polynomial time algorithms.
- **NP**: set of decision problems that have polynomial time non-deterministic algorithms.

**Question:** What is an algorithm? Depends on the model of computation!

What is our model of computation?

Formally speaking our model of computation is Turing Machines.

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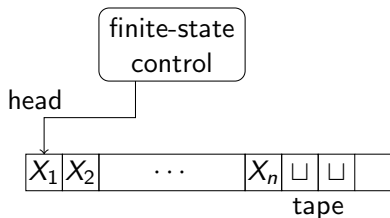
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# Turing Machines: Recap



- Infinite tape.
- Finite state control.
- Input at beginning of tape.
- Special tape letter "blank"  $\square$ .
- Head can move only one cell to left or right.

# Turing Machines: Formally

A **TM**  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$ :

- $Q$  is set of states in finite control
- $q_0$  start state,  $q_{accept}$  is accept state,  $q_{reject}$  is reject state
- $\Sigma$  is input alphabet,  $\Gamma$  is tape alphabet (includes  $\sqcup$ )
- $\delta : Q \times \Gamma \rightarrow \{L, R\} \times \Gamma \times Q$  is transition function
  - $\delta(q, a) = (q', b, L)$  means that  $M$  in state  $q$  and head seeing  $a$  on tape will move to state  $q'$  while replacing  $a$  on tape with  $b$  and head moves left.

$L(M)$ : language accepted by  $M$  is set of all input strings  $s$  on which  $M$  accepts; that is:

- **TM** is started in state  $q_0$ .
- Initially, the tape head is located at the first cell.
- The tape contain  $s$  on the tape followed by blanks.
- The **TM** halts in the state  $q_{accept}$ .



## Definition

$M$  is a polynomial time TM if there is some polynomial  $p(\cdot)$  such that on all inputs  $w$ ,  $M$  halts in  $p(|w|)$  steps.

## Definition

$L$  is a language in P iff there is a polynomial time TM  $M$  such that  $L = L(M)$ .

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$L$  is an NP language iff there is a *non-deterministic* polynomial time TM  $M$  such that  $L = L(M)$ .

Non-deterministic TM: each step has a choice of moves

- $\delta : Q \times \Gamma \rightarrow \mathcal{P}(Q \times \Gamma \times \{L, R\})$ .
  - Example:  $\delta(q, a) = \{(q_1, b, L), (q_2, c, R), (q_3, a, R)\}$  means that  $M$  can non-deterministically choose one of the three possible moves from  $(q, a)$ .
- $L(M)$ : set of all strings  $s$  on which there *exists* some sequence of valid choices at each step that lead from  $q_0$  to  $q_{accept}$

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# Non-deterministic TMs vs certifiers

## NP

Two definition of NP:

- $L$  is in NP iff  $L$  has a polynomial time certifier  $C(\cdot, \cdot)$ .
- $L$  is in NP iff  $L$  is decided by a non-deterministic polynomial time TM  $M$ .

## Claim

*Two definitions are equivalent.*

Why?

Informal proof idea: the certificate  $t$  for  $C$  corresponds to non-deterministic choices of  $M$  and vice-versa.

In other words  $L$  is in NP iff  $L$  is accepted by a NTM which first guesses a proof  $t$  of length poly in input  $|s|$  and then acts as a deterministic TM.

# Non-determinism, guessing and verification

- A non-deterministic machine has choices at each step and accepts a string if there *exists* a set of choices which lead to a final state.
- Equivalently the choices can be thought of as *guessing* a solution and then *verifying* that solution. In this view all the choices are made a priori and hence the verification can be deterministic. The “guess” is the “proof” and the “verifier” is the “certifier”.
- We reemphasize the asymmetry inherent in the definition of non-determinism. Strings in the language can be easily verified. No easy way to verify that a string is not in the language.

# Algorithms: TMs vs RAM Model

Why do we use TMs some times and RAM Model other times?

- TMs are very simple: no complicated instruction set, no jumps/pointers, no explicit loops etc.
  - Simplicity is useful in proofs.
  - The “right” formal bare-bones model when dealing with subtleties.
- RAM model is a closer approximation to the running time/space usage of realistic computers for reasonable problem sizes
  - Not appropriate for certain kinds of formal proofs when algorithms can take super-polynomial time and space

# “Hardest” Problems

## Question

What is the hardest problem in  $NP$ ? How do we define it?

## Towards a definition

- Hardest problem must be in  $NP$ .
- Hardest problem must be at least as “difficult” as every other problem in  $NP$ .

# NP-Complete Problems

## Definition

A problem  $X$  is said to be **NP-Complete** if

- $X \in \text{NP}$ , and
- (**Hardness**) For any  $Y \in \text{NP}$ ,  $Y \leq_P X$ .



# Solving NP-Complete Problems

## Proposition

Suppose  $X$  is NP-COMPLETE. Then  $X$  can be solved in polynomial time if and only if  $P = NP$ .

## Proof.

$\Rightarrow$  Suppose  $X$  can be solved in polynomial time

- Let  $Y \in NP$ . We know  $Y \leq_P X$ .
- We showed that if  $Y \leq_P X$  and  $X$  can be solved in polynomial time, then  $Y$  can be solved in polynomial time.
- Thus, every problem  $Y \in NP$  is such that  $Y \in P$ ;  $NP \subseteq P$ .
- Since  $P \subseteq NP$ , we have  $P = NP$ .

$\Leftarrow$  Since  $P = NP$ , and  $X \in NP$ , we have a polynomial time algorithm for  $X$ . □

# NP-Hard Problems

## Definition

A problem  $X$  is said to be **NP-HARD** if

- (**Hardness**) For any  $Y \in \text{NP}$ ,  $Y \leq_P X$

An **NP-HARD** problem need not be in **NP**!

**Example:** Halting problem is **NP-HARD** (why?) but not **NP-COMPLETE**.

# Consequences of proving **NP-Completeness**

If **X** is **NP-COMplete**

- Since we believe  $P \neq NP$ ,
- and solving **X** implies  $P = NP$ .

**X** is **unlikely** to be efficiently solvable.

At the very least, many smart people before you have failed to find an efficient algorithm for **X**.

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# NP-Complete Problems

## Question

Are there any problems that are NP-COMPLETE?

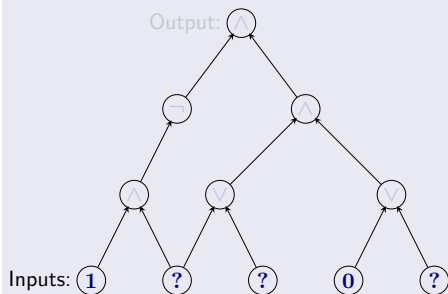
## Answer

Yes! Many, many problems are NP-COMPLETE.

# Circuits

## Definition

A circuit is a directed *acyclic* graph with

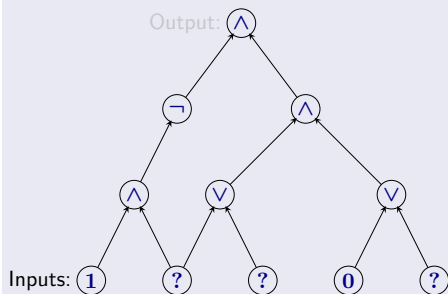


- **Input** vertices (without incoming edges) labelled with **0**, **1** or a distinct variable
- Every other vertex is labelled  $\vee$ ,  $\wedge$  or  $\neg$
- Single node **output** vertex with no outgoing edges



## Definition

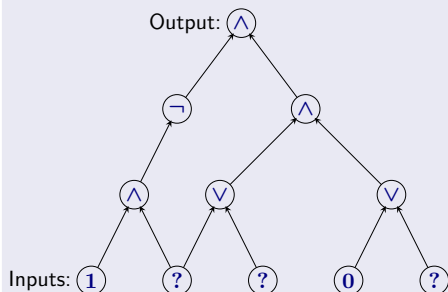
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# Cook-Levin Theorem

## Definition (Circuit Satisfaction (**CSAT**)).

Given a circuit as input, is there an assignment to the input variables that causes the output to get value **1**?

## Theorem (Cook-Levin)

**CSAT** is **NP-COMPLETE**.

Need to show

- **CSAT** is in **NP**
- every **NP** problem **X** reduces to **CSAT**.

# CSAT: Circuit Satisfaction

## Claim

*CSAT* is in NP.

- **Certificate:** Assignment to input variables.
- **Certifier:** Evaluate the value of each gate in a topological sort of DAG and check the output gate value.

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# CSAT is NP-hard: Idea

Need to show that every NP problem  $X$  reduces to CSAT.

What does it mean that  $X \in \text{NP}$ ?

$X \in \text{NP}$  implies that there are polynomials  $p()$  and  $q()$  and certifier/verifier program  $C$  such that for every string  $s$  the following is true:

- If  $s$  is a YES instance ( $s \in X$ ) then there is a *proof*  $t$  of length  $p(|s|)$  such that  $C(s, t)$  says YES.
- If  $s$  is a NO instance ( $s \notin X$ ) then for every string  $t$  of length at  $p(|s|)$ ,  $C(s, t)$  says NO.
- $C(s, t)$  runs in time  $q(|s| + |t|)$  time (hence polynomial time).

# Reducing **X** to **CSAT**

**X** is in **NP** means we have access to  $p()$ ,  $q()$ ,  $C(\cdot, \cdot)$ .

What is  $C(\cdot, \cdot)$ ? It is a program or equivalently a Turing Machine!

How are  $p()$  and  $q()$  given? As numbers.

Example: if **3** is given then  $p(n) = n^3$ .

Thus an **NP** problem is essentially a three tuple  $\langle p, q, C \rangle$  where  $C$  is either a program or a **TM**.

# Reducing $X$ to CSAT

Thus an NP problem is essentially a three tuple  $\langle p, q, C \rangle$  where  $C$  is either a program or TM.

**Problem X:** Given string  $s$ , is  $s \in X$ ?

Same as the following: is there a proof  $t$  of length  $p(|s|)$  such that  $C(s, t)$  says YES.

How do we reduce  $X$  to CSAT? Need an algorithm  $A$  that

- takes  $s$  (and  $\langle p, q, C \rangle$ ) and creates a circuit  $G$  in polynomial time in  $|s|$  (note that  $\langle p, q, C \rangle$  are fixed).
- $G$  is satisfiable if and only if there is a proof  $t$  such that  $C(s, t)$  says YES.



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**Simple but Big Idea:** Programs are essentially the same as Circuits!

- Convert  $C(s, t)$  into a circuit  $G$  with  $t$  as unknown inputs (rest is known including  $s$ )
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- Asking if there is a proof  $t$  that makes  $C(s, t)$  say YES is same as whether there is an assignment of values to “unknown” variables  $t_1, t_2, \dots, t_k$  that will make  $G$  evaluate to true/YES.

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# Example: Independent Set

- **Problem:** Does  $G = (V, E)$  have an **Independent Set** of size  $\geq k$ ?
  - **Certificate:** Set  $S \subseteq V$
  - **Certifier:** Check  $|S| \geq k$  and no pair of vertices in  $S$  is connected by an edge

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# Example: Independent Set

Formally why is **Independent Set** in NP?

- Input:

$\langle n, y_{1,1}, y_{1,2}, \dots, y_{1,n}, y_{2,1}, \dots, y_{2,n}, \dots, y_{n,1}, \dots, y_{n,n}, k \rangle$   
encodes  $\langle \mathbf{G}, k \rangle$ .

- $n$  is number of vertices in  $\mathbf{G}$
  - $y_{i,j}$  is a bit which is **1** if edge  $(i,j)$  is in  $\mathbf{G}$  and **0** otherwise (adjacency matrix representation)
  - $k$  is size of independent set.
- Certificate:  $\mathbf{t} = t_1 t_2 \dots t_n$ . Interpretation is that  $t_i$  is **1** if vertex  $i$  is in the independent set, **0** otherwise.

# Certifier for Independent Set

Certifier  $C(s, t)$  for **Independent Set**:

```
if ( $t_1 + t_2 + \dots + t_n < k$ ) then
  return NO
else
  for each  $(i, j)$  do
    if ( $t_i \wedge t_j \wedge y_{i,j}$ ) then
      return NO

return YES
```

# Example: Independent Set

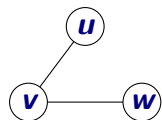
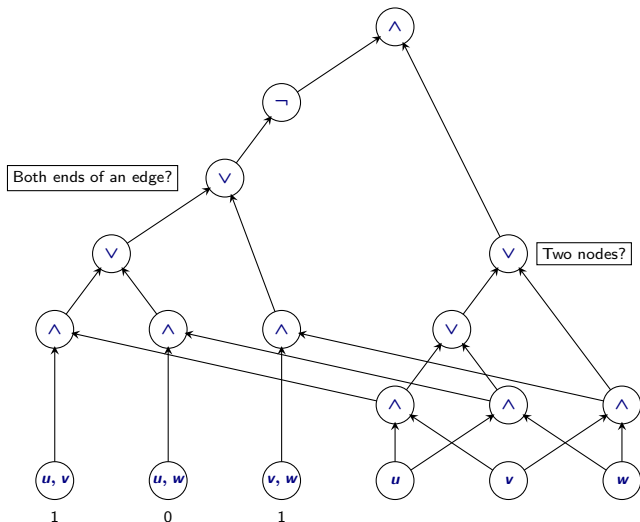


Figure: Graph  $G$  with  $k = 2$



# Circuit from Certifier

# Programs, Turing Machines and Circuits

Consider “program”  $A$  that takes  $f(|s|)$  steps on input string  $s$ .

**Question:** What computer is the program running on and what does *step* mean?

Real computers difficult to reason with mathematically because

- instruction set is too rich
- pointers and control flow jumps in one step
- assumption that pointer to code fits in one word

Turing Machines

- simpler model of computation to reason with
- can simulate real computers with *polynomial* slow down
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# Certifiers that at TMs

Assume  $C(\cdot, \cdot)$  is a (deterministic) Turing Machine  $M$

**Problem:** Given  $M$ , input  $s$ ,  $p$ ,  $q$  decide if there is a proof  $t$  of length  $p(|s|)$  such that  $M$  on  $s, t$  will halt in  $q(|s|)$  time and say YES.

There is an algorithm  $\mathcal{A}$  that can reduce above problem to **CSAT** mechanically as follows.

- $\mathcal{A}$  first computes  $p(|s|)$  and  $q(|s|)$ .
- Knows that  $M$  can use at most  $q(|s|)$  memory/tape cells
- Knows that  $M$  can run for at most  $q(|s|)$  time
- Simulates the evolution of the state of  $M$  and memory over time using a big circuit.

# Simulation of Computation via Circuit

- Think of  $M$ 's state at time  $\ell$  as a string  $\mathbf{x}^\ell = \mathbf{x}_1 \mathbf{x}_2 \dots \mathbf{x}_k$  where each  $\mathbf{x}_i \in \{0, 1, B\} \times Q \cup \{q_{-1}\}$ .
- At time  $0$  the state of  $M$  consists of input string  $\mathbf{s}$  a guess  $\mathbf{t}$  (unknown variables) of length  $p(|\mathbf{s}|)$  and rest  $q(|\mathbf{s}|)$  blank symbols.
- At time  $q(|\mathbf{s}|)$  we wish to know if  $M$  stops in  $q_{\text{accept}}$  with say all blanks on the tape.
- We write a circuit  $\mathcal{C}_\ell$  which captures the transition of  $M$  from time  $\ell$  to time  $\ell + 1$ .
- Composition of the circuits for all times  $0$  to  $q(|\mathbf{s}|)$  gives a big (still poly) sized circuit  $\mathcal{C}$
- The final output of  $\mathcal{C}$  should be true if and only if the entire state of  $M$  at the end leads to an accept state.

# NP-Hardness of Circuit Satisfaction

Key Ideas in reduction:

- Use **TM**s as the code for certifier for simplicity
- Since  $p()$  and  $q()$  are known to  $\mathcal{A}$ , it can set up all required memory and time steps in advance
- Simulate computation of the **TM** from one time to the next as a circuit that only looks at three adjacent cells at a time

**Note:** Above reduction can be done to **SAT** as well. Reduction to **SAT** was the original proof of Steve Cook.

# NP-Hardness of Circuit Satisfaction

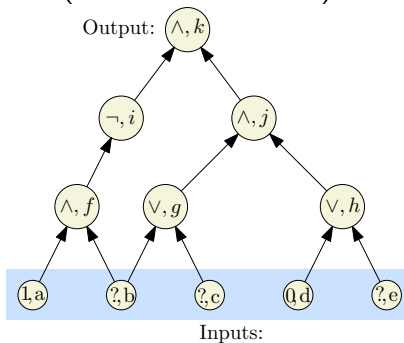
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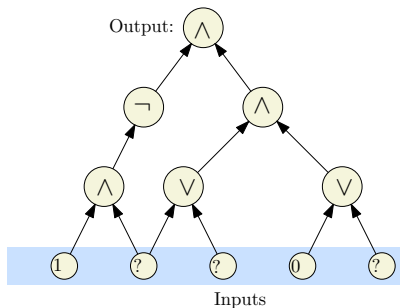
# SAT is NP-Complete

- We have seen that **SAT**  $\in$  NP
  - To show **NP-HARDNESS**, we will reduce Circuit Satisfiability (**CSAT**) to **SAT**
- Instance of **CSAT** (we label each node):

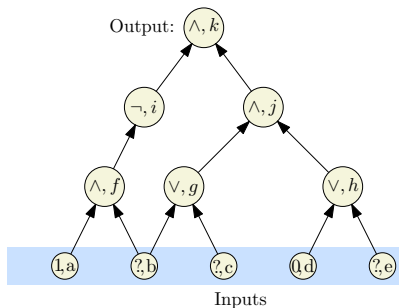


# Converting a circuit into a CNF formula

Label the nodes



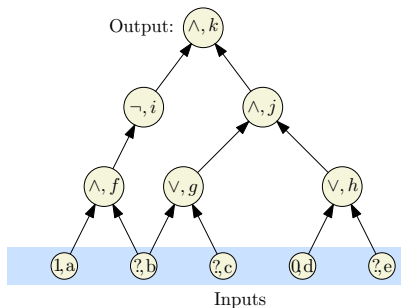
(A) Input circuit



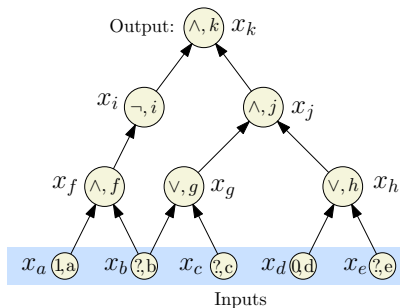
(B) Label the nodes.

# Converting a circuit into a CNF formula

Introduce a variable for each node



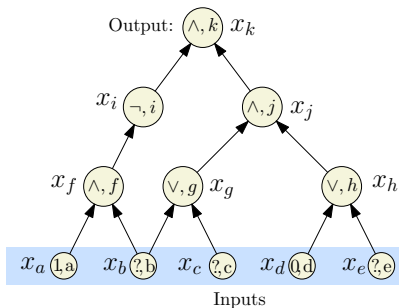
(B) Label the nodes.



(C) Introduce var for each node.

# Converting a circuit into a CNF formula

Write a sub-formula for each variable that is true if the var is computed correctly.



(C) Introduce var for each node.

$x_k$  (Demand a sat' assignment!)

$$x_k = x_i \wedge x_j$$

$$x_j = x_g \wedge x_h$$

$$x_i = \neg x_f$$

$$x_h = x_d \vee x_e$$

$$x_g = x_b \vee x_c$$

$$x_f = x_a \wedge x_b$$

$$x_d = 0$$

$$x_a = 1$$

(D) Write a sub-formula for each variable that is true if the var is computed correctly.



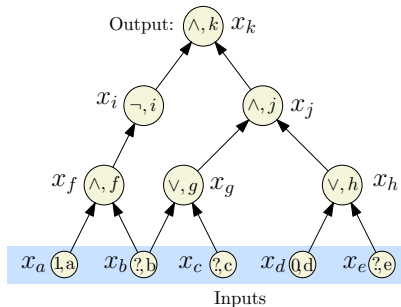
# Converting a circuit into a CNF formula

Convert each sub-formula to an equivalent CNF formula

$x_k$	$x_k$
$x_k = x_i \wedge x_j$	$(\neg x_k \vee x_i) \wedge (\neg x_k \vee x_j) \wedge (x_k \vee \neg x_i \vee \neg x_j)$
$x_j = x_g \wedge x_h$	$(\neg x_j \vee x_g) \wedge (\neg x_j \vee x_h) \wedge (x_j \vee \neg x_g \vee \neg x_h) \wedge$
$x_i = \neg x_f$	$(x_i \vee x_f) \wedge (\neg x_i \vee x_f) \wedge$
$x_h = x_d \vee x_e$	$(x_h \vee \neg x_d) \wedge (x_h \vee \neg x_e) \wedge (\neg x_h \vee x_d \vee x_e)$
$x_g = x_b \vee x_c$	$(x_g \vee \neg x_b) \wedge (x_g \vee \neg x_c) \wedge (\neg x_g \vee x_b \vee x_c)$
$x_f = x_a \wedge x_b$	$(\neg x_f \vee x_a) \wedge (\neg x_f \vee x_b) \wedge (x_f \vee \neg x_a \vee \neg x_b)$
$x_d = 0$	$\neg x_d$
$x_a = 1$	$x_a$

# Converting a circuit into a CNF formula

Take the conjunction of all the CNF sub-formulas



$$\begin{aligned} & x_k \wedge (\neg x_k \vee x_i) \wedge (\neg x_k \vee x_j) \\ & \wedge (x_k \vee \neg x_i \vee \neg x_j) \wedge (\neg x_j \vee x_g) \\ & \wedge (\neg x_j \vee x_h) \wedge (x_j \vee \neg x_g \vee \neg x_h) \\ & \wedge (x_i \vee x_f) \wedge (\neg x_i \vee x_f) \\ & \wedge (x_h \vee \neg x_d) \wedge (x_h \vee \neg x_e) \\ & \wedge (\neg x_h \vee x_d \vee x_e) \wedge (x_g \vee \neg x_b) \\ & \wedge (x_g \vee \neg x_c) \wedge (\neg x_g \vee x_b \vee x_c) \\ & \wedge (\neg x_f \vee x_a) \wedge (\neg x_f \vee x_b) \\ & \wedge (x_f \vee \neg x_a \vee \neg x_b) \wedge (\neg x_d) \wedge x_a \end{aligned}$$

We got a CNF formula that is satisfiable if and only if the original circuit is satisfiable.

# Reduction: $\text{CSAT} \leq_P \text{SAT}$

- For each gate (vertex)  $v$  in the circuit, create a variable  $x_v$
- **Case**  $\neg$ :  $v$  is labeled  $\neg$  and has one incoming edge from  $u$  (so  $x_v = \neg x_u$ ). In **SAT** formula generate, add clauses  $(x_u \vee x_v)$ ,  $(\neg x_u \vee \neg x_v)$ . Observe that

$$x_v = \neg x_u \text{ is true} \iff \begin{array}{l} (x_u \vee x_v) \\ (\neg x_u \vee \neg x_v) \end{array} \text{ both true.}$$

# Reduction: $\text{CSAT} \leq_P \text{SAT}$

Continued...

- **Case  $\vee$ :** So  $x_v = x_u \vee x_w$ . In **SAT** formula generated, add clauses  $(x_v \vee \neg x_u)$ ,  $(x_v \vee \neg x_w)$ , and  $(\neg x_v \vee x_u \vee x_w)$ . Again, observe that

$$x_v = x_u \vee x_w \text{ is true} \iff \begin{array}{l} (x_v \vee \neg x_u), \\ (x_v \vee \neg x_w), \\ (\neg x_v \vee x_u \vee x_w) \end{array} \text{ all true.}$$

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- **Case  $\wedge$ :** So  $x_v = x_u \wedge x_w$ . In **SAT** formula generated, add clauses  $(\neg x_v \vee x_u)$ ,  $(\neg x_v \vee x_w)$ , and  $(x_v \vee \neg x_u \vee \neg x_w)$ . Again observe that

$$x_v = x_u \wedge x_w \text{ is true} \iff \begin{array}{l} (\neg x_v \vee x_u), \\ (\neg x_v \vee x_w), \\ (x_v \vee \neg x_u \vee \neg x_w) \end{array} \text{ all true.}$$

# Reduction: $\text{CSAT} \leq_P \text{SAT}$

Continued...

- If  $v$  is an input gate with a fixed value then we do the following.  
If  $x_v = 1$  add clause  $x_v$ . If  $x_v = 0$  add clause  $\neg x_v$
- Add the clause  $x_v$  where  $v$  is the variable for the output gate

# Correctness of Reduction

Need to show circuit  $C$  is satisfiable iff  $\varphi_C$  is satisfiable

$\Rightarrow$  Consider a satisfying assignment  $a$  for  $C$

- Find values of all gates in  $C$  under  $a$
- Give value of gate  $v$  to variable  $x_v$ ; call this assignment  $a'$
- $a'$  satisfies  $\varphi_C$  (exercise)

$\Leftarrow$  Consider a satisfying assignment  $a$  for  $\varphi_C$

- Let  $a'$  be the restriction of  $a$  to only the input variables
- Value of gate  $v$  under  $a'$  is the same as value of  $x_v$  in  $a$
- Thus,  $a'$  satisfies  $C$

## Theorem

**SAT** is NP-COMplete.

# Proving that a problem $X$ is **NP-Complete**

To prove  $X$  is **NP-COMPLETE**, show

- Show  $X$  is in **NP**.
  - certificate/proof of polynomial size in input
  - polynomial time certifier  $C(s, t)$
- Reduction from a known **NP-COMPLETE** problem such as **CSAT** or **SAT** to  $X$

$SAT \leq_P X$  implies that every **NP** problem  $Y \leq_P X$ . Why?

Transitivity of reductions:

$Y \leq_P SAT$  and  $SAT \leq_P X$  and hence  $Y \leq_P X$ .



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- **3-SAT**  $\leq_P$  Independent Set (which is in **NP**) and hence **Independent Set** is **NP-COMplete**.
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# Notes