

# Reductions and NP

Lecture 21

November 15, 2011

Part I

Reductions Continued

# Polynomial Time Reduction

## Karp reduction

A **polynomial time reduction** from a decision problem  $X$  to a decision problem  $Y$  is an algorithm  $\mathcal{A}$  that has the following properties:

- given an instance  $I_X$  of  $X$ ,  $\mathcal{A}$  produces an instance  $I_Y$  of  $Y$
- $\mathcal{A}$  runs in time polynomial in  $|I_X|$ . This implies that  $|I_Y|$  (size of  $I_Y$ ) is polynomial in  $|I_X|$
- Answer to  $I_X$  YES iff answer to  $I_Y$  is YES.

Notation:  $X \leq_P Y$  if  $X$  reduces to  $Y$

## Proposition

If  $X \leq_P Y$  then a polynomial time algorithm for  $Y$  implies a polynomial time algorithm for  $X$ .

Such a reduction is called a **Karp reduction**. Most reductions we will need are Karp reductions.

# A More General Reduction

## Turing Reduction

## Definition (Turing reduction.)

Problem  $X$  polynomial time reduces to  $Y$  if there is an algorithm  $\mathcal{A}$  for  $X$  that has the following properties:

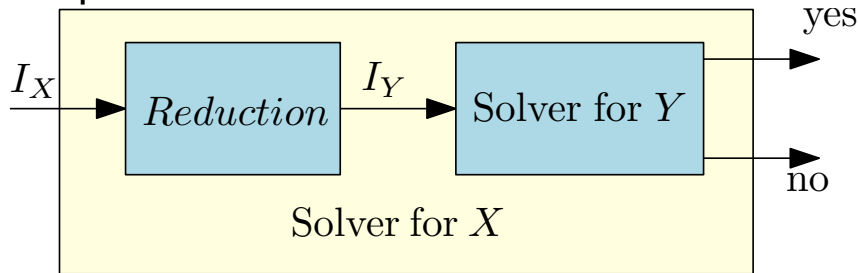
- on any given instance  $I_X$  of  $X$ ,  $\mathcal{A}$  uses polynomial in  $|I_X|$  “steps”
- a step is either a standard computation step, or
- a sub-routine call to an algorithm that solves  $Y$ .

This is a **Turing reduction**.

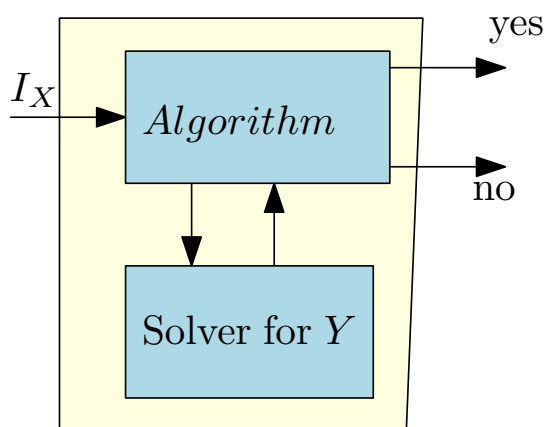
**Note:** In making sub-routine call to algorithm to solve  $Y$ ,  $\mathcal{A}$  can only ask questions of size polynomial in  $|I_X|$ . Why?

# Comparing reductions

- Karp reduction:



- Turing reduction:



## Turing reduction

- Algorithm to solve  $X$  can call solver for  $Y$  many times.
- Conceptually, every call to the solver of  $Y$  takes constant time.

## Example of Turing Reduction

**Input** Collection of arcs on a circle.

**Goal** Compute the maximum number of non-overlapping arcs.

Reduced to the following problem:?

**Input** Collection of intervals on the line.

**Goal** Compute the maximum number of non-overlapping intervals.

How? Used algorithm for interval problem multiple times.

# Turing vs Karp Reductions

- Turing reductions more general than Karp reductions.
- Turing reduction useful in obtaining algorithms via reductions.
- Karp reduction is simpler and easier to use to prove hardness of problems.
- Perhaps surprisingly, Karp reductions, although limited, suffice for most known **NP-COMPLETENESS** proofs.

## Propositional Formulas

### Definition

Consider a set of boolean variables  $x_1, x_2, \dots, x_n$ .

- A **literal** is either a boolean variable  $x_i$  or its negation  $\neg x_i$ .
- A **clause** is a disjunction of literals.  
For example,  $x_1 \vee x_2 \vee \neg x_4$  is a clause.
- A **formula in conjunctive normal form (CNF)** is propositional formula which is a conjunction of clauses
  - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is a **CNF** formula.
- A formula  $\varphi$  is a **3CNF**:  
A **CNF** formula such that every clause has **exactly** 3 literals.
  - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3 \vee x_1)$  is a **3CNF** formula, but  $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is not.

## Problem: SAT

**Instance:** A CNF formula  $\varphi$ .

**Question:** Is there a truth assignment to the variables of  $\varphi$  such that  $\varphi$  evaluates to true?

## Problem: 3SAT

**Instance:** A 3CNF formula  $\varphi$ .

**Question:** Is there a truth assignment to the variables of  $\varphi$  such that  $\varphi$  evaluates to true?

# Satisfiability

## SAT

Given a CNF formula  $\varphi$ , is there a truth assignment to variables such that  $\varphi$  evaluates to true?

## Example

$(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is satisfiable; take  $x_1, x_2, \dots, x_5$  to be all true

$(x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_1 \vee x_2)$  is not satisfiable

## 3SAT

Given a 3CNF formula  $\varphi$ , is there a truth assignment to variables such that  $\varphi$  evaluates to true?

(More on 2SAT in a bit...)

# Importance of SAT and 3SAT

- SAT and 3SAT are basic constraint satisfaction problems.
- Many different problems can be reduced to them because of the simple yet powerful expressiveness of logical constraints.
- Arise naturally in many applications involving hardware and software verification and correctness.
- As we will see, it is a fundamental problem in theory of NP-COMPLETENESS.

## SAT $\leq_P$ 3SAT

### How SAT is different from 3SAT?

In SAT clauses might have arbitrary length: 1, 2, 3, ... variables:

$$(x \vee y \vee z \vee w \vee u) \wedge (\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge (\neg x)$$

In 3SAT every clause must have *exactly* 3 different literals.

To reduce from an instance of SAT to an instance of 3SAT, we must make all clauses to have exactly 3 variables...

### Basic idea

- Pad short clauses so they have 3 literals.
- Break long clauses into shorter clauses.
- Repeat the above till we have a 3CNF.

# 3SAT $\leq_P$ SAT

- 3SAT  $\leq_P$  SAT.
- Because...  
A 3SAT instance is also an instance of SAT.

# SAT $\leq_P$ 3SAT

## Claim

**SAT  $\leq_P$  3SAT.**

Given  $\varphi$  a SAT formula we create a 3SAT formula  $\varphi'$  such that

- $\varphi$  is satisfiable iff  $\varphi'$  is satisfiable
- $\varphi'$  can be constructed from  $\varphi$  in time polynomial in  $|\varphi|$ .

**Idea:** if a clause of  $\varphi$  is not of length 3, replace it with several clauses of length exactly 3

# SAT $\leq_P$ 3SAT

A clause with a single literal

## Reduction Ideas

**Challenge:** Some of the clauses in  $\varphi$  may have less or more than 3 literals. For each clause with  $< 3$  or  $> 3$  literals, we will construct a set of logically equivalent clauses.

- **Case clause with one literal:** Let  $c$  be a clause with a single literal (i.e.,  $c = \ell$ ). Let  $u, v$  be new variables. Consider

$$c' = (\ell \vee u \vee v) \wedge (\ell \vee u \vee \neg v) \\ \wedge (\ell \vee \neg u \vee v) \wedge (\ell \vee \neg u \vee \neg v).$$

Observe that  $c'$  is satisfiable iff  $c$  is satisfiable

# SAT $\leq_P$ 3SAT

A clause with two literals

## Reduction Ideas: 2 and more literals

- **Case clause with 2 literals:** Let  $c = \ell_1 \vee \ell_2$ . Let  $u$  be a new variable. Consider

$$c' = (\ell_1 \vee \ell_2 \vee u) \wedge (\ell_1 \vee \ell_2 \vee \neg u).$$

Again  $c$  is satisfiable iff  $c'$  is satisfiable



# Breaking a clause

## Lemma

For any boolean formulas  $X$  and  $Y$  and  $z$  a new boolean variable.  
Then

$X \vee Y$  is satisfiable

if and only if,  $z$  can be assigned a value such that

$(X \vee z) \wedge (Y \vee \neg z)$  is satisfiable

(with the same assignment to the variables appearing in  $X$  and  $Y$ ).

## SAT $\leq_P$ 3SAT (contd)

Clauses with more than 3 literals

Let  $c = l_1 \vee \dots \vee l_k$ . Let  $u_1, \dots, u_{k-3}$  be new variables. Consider

$$\begin{aligned} c' = & (l_1 \vee l_2 \vee u_1) \wedge (l_3 \vee \neg u_1 \vee u_2) \\ & \wedge (l_4 \vee \neg u_2 \vee u_3) \wedge \\ & \dots \wedge (l_{k-2} \vee \neg u_{k-4} \vee u_{k-3}) \wedge (l_{k-1} \vee l_k \vee \neg u_{k-3}). \end{aligned}$$

## Claim

$c$  is satisfiable iff  $c'$  is satisfiable.

Another way to see it — reduce size of clause by one:

$$c' = (l_1 \vee l_2 \dots \vee l_{k-2} \vee u_{k-3}) \wedge (l_{k-1} \vee l_k \vee \neg u_{k-3}).$$

## Example

$$\begin{aligned}\varphi = & \left( \neg x_1 \vee \neg x_4 \right) \wedge \left( x_1 \vee \neg x_2 \vee \neg x_3 \right) \\ & \wedge \left( \neg x_2 \vee \neg x_3 \vee x_4 \vee x_1 \right) \wedge \left( x_1 \right).\end{aligned}$$

Equivalent form:

$$\begin{aligned}\psi = & \left( \neg x_1 \vee \neg x_4 \vee z \right) \wedge \left( \neg x_1 \vee \neg x_4 \vee \neg z \right) \\ & \wedge \left( x_1 \vee \neg x_2 \vee \neg x_3 \right) \\ & \wedge \left( \neg x_2 \vee \neg x_3 \vee y_1 \right) \wedge \left( x_4 \vee x_1 \vee \neg y_1 \right) \\ & \wedge \left( x_1 \vee u \vee v \right) \wedge \left( x_1 \vee u \vee \neg v \right) \\ & \wedge \left( x_1 \vee \neg u \vee v \right) \wedge \left( x_1 \vee \neg u \vee \neg v \right).\end{aligned}$$

## Overall Reduction Algorithm

Reduction from **SAT** to **3SAT**

**ReduceSATTo3SAT**( $\varphi$ ):

//  $\varphi$ : CNF formula.

**for** each clause  $c$  of  $\varphi$  **do**

**if**  $c$  does not have exactly 3 literals **then**

        construct  $c'$  as before

**else**

$c' = c$

$\psi$  is conjunction of all  $c'$  constructed in loop

**return** **Solver3SAT**( $\psi$ )

## Correctness (informal)

$\varphi$  is satisfiable iff  $\psi$  is satisfiable because for each clause  $c$ , the new **3CNF** formula  $c'$  is logically equivalent to  $c$ .

# What about **2SAT**?

**2SAT** can be solved in polynomial time! (In fact, linear time!)

No known polynomial time reduction from **SAT** (or **3SAT**) to **2SAT**. If there was, then **SAT** and **3SAT** would be solvable in polynomial time.

## Why the reduction from **3SAT** to **2SAT** fails?

Consider a clause  $(x \vee y \vee z)$ . We need to reduce it to a collection of **2CNF** clauses. Introduce a fresh variable  $\alpha$ , and rewrite this as

$$\begin{array}{ll} (x \vee y \vee \alpha) \wedge (\neg \alpha \vee z) & \text{(bad! clause with 3 vars)} \\ \text{or } (x \vee \alpha) \wedge (\neg \alpha \vee y \vee z) & \text{(bad! clause with 3 vars).} \end{array}$$

(In animal farm language: **2SAT** good, **3SAT** bad.)

# What about **2SAT**?

A challenging exercise: Given a **2SAT** formula show to compute its satisfying assignment...

(Hint: Create a graph with two vertices for each variable (for a variable  $x$  there would be two vertices with labels  $x = 0$  and  $x = 1$ ). For every **2CNF** clause add two directed edges in the graph. The edges are implication edges: They state that if you decide to assign a certain value to a variable, then you must assign a certain value to some other variable.

Now compute the strong connected components in this graph, and continue from there...)

## Problem: Independent Set

**Instance:** A graph  $G$ , integer  $k$

**Question:** Is there an independent set in  $G$  of size  $k$ ?

## $3SAT \leq_P$ Independent Set

### The reduction $3SAT \leq_P$ Independent Set

**Input:** Given a  $3CNF$  formula  $\varphi$

**Goal:** Construct a graph  $G_\varphi$  and number  $k$  such that  $G_\varphi$  has an independent set of size  $k$  if and only if  $\varphi$  is satisfiable.

$G_\varphi$  should be constructable in time polynomial in size of  $\varphi$

**Importance of reduction:** Although  $3SAT$  is much more expressive, it can be reduced to a seemingly specialized Independent Set problem.

**Notice:** We handle only  $3CNF$  formulas – reduction would not work for other kinds of boolean formulas.

# Interpreting 3SAT

There are two ways to think about **3SAT**

- Find a way to assign 0/1 (false/true) to the variables such that the formula evaluates to true, that is each clause evaluates to true.
- Pick a literal from each clause and find a truth assignment to make all of them true. You will fail if two of the literals you pick are in **conflict**, i.e., you pick  $x_i$  and  $\neg x_i$

We will take the second view of **3SAT** to construct the reduction.

## The Reduction

- $G_\varphi$  will have one vertex for each literal in a clause
- Connect the 3 literals in a clause to form a triangle; the independent set will pick at most one vertex from each clause, which will correspond to the literal to be set to true
- Connect 2 vertices if they label complementary literals; this ensures that the literals corresponding to the independent set do not have a conflict
- Take  $k$  to be the number of clauses

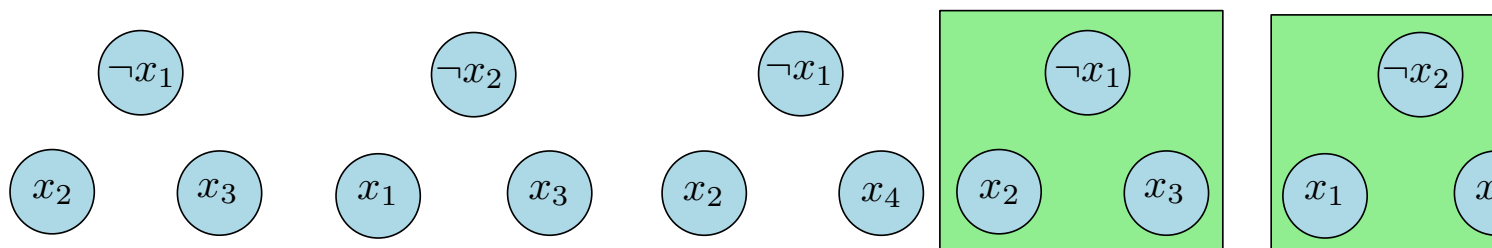


Figure: Graph for

# Correctness

## Proposition

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  (= number of clauses in  $\varphi$ ).

## Proof.

$\Rightarrow$  Let  $a$  be the truth assignment satisfying  $\varphi$

- Pick one of the vertices, corresponding to true literals under  $a$ , from each triangle. This is an independent set of the appropriate size □

# Correctness (contd)

## Proposition

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  (= number of clauses in  $\varphi$ ).

## Proof.

$\Leftarrow$  Let  $S$  be an independent set of size  $k$

- $S$  must contain exactly one vertex from each clause
- $S$  cannot contain vertices labeled by conflicting clauses
- Thus, it is possible to obtain a truth assignment that makes in the literals in  $S$  true; such an assignment satisfies one literal in every clause □

# Transitivity of Reductions

## Lemma

$X \leq_P Y$  and  $Y \leq_P Z$  implies that  $X \leq_P Z$ .

**Note:**  $X \leq_P Y$  does not imply that  $Y \leq_P X$  and hence it is very important to know the FROM and TO in a reduction.

To prove  $X \leq_P Y$  you need to show a reduction FROM  $X$  TO  $Y$   
In other words show that an algorithm for  $Y$  implies an algorithm for  $X$ .

## Part II

### Definition of NP

## Problems

- Independent Set
- Vertex Cover
- Set Cover
- SAT
- 3SAT

## Relationship

$3SAT \leq_P \text{Independent Set} \stackrel{\leq_P}{\geq_P} \text{Vertex Cover} \leq_P \text{Set Cover}$   
 $3SAT \leq_P \text{SAT} \leq_P 3SAT$

# Problems and Algorithms: Formal Approach

## Decision Problems

- **Problem Instance:** Binary string  $s$ , with size  $|s|$
- **Problem:** A set  $X$  of strings on which the answer should be "yes"; we call these YES instances of  $X$ . Strings not in  $X$  are NO instances of  $X$ .

## Definition

- $A$  is an **algorithm for problem  $X$**  if  $A(s) = \text{"yes"}$  iff  $s \in X$
- $A$  is said to have a **polynomial running time** if there is a polynomial  $p(\cdot)$  such that for every string  $s$ ,  $A(s)$  terminates in at most  $O(p(|s|))$  steps



# Polynomial Time

## Definition

**Polynomial time** (denoted  $P$ ) is the class of all (decision) problems that have an algorithm that solves it in polynomial time

## Example

Problems in  $P$  include

- Is there a shortest path from  $s$  to  $t$  of length  $\leq k$  in  $G$ ?
- Is there a flow of value  $\geq k$  in network  $G$ ?
- Is there an assignment to variables to satisfy given linear constraints?

# Efficiency Hypothesis

*A problem  $X$  has an efficient algorithm iff  $X \in P$ , that is  $X$  has a polynomial time algorithm.*

Justifications:

- Robustness of definition to variations in machines.
- A sound theoretical definition.
- Most known polynomial time algorithms for “natural” problems have small polynomial running times.

# Problems with no known polynomial time algorithms

## Problems

- **Independent Set**
- **Vertex Cover**
- **Set Cover**
- **SAT**
- **3SAT**

There are of course undecidable problems (no algorithm at all!) but many problems that we want to solve are like above.

**Question:** What is common to above problems?

## Efficient Checkability

Above problems share the following feature:

*For any YES instance  $I_X$  of  $X$  there is a proof/certificate/solution that is of length  $\text{poly}(|I_X|)$  such that given a proof one can efficiently check that  $I_X$  is indeed a YES instance*

Examples:

- **SAT** formula  $\varphi$ : proof is a satisfying assignment
- **Independent Set** in graph  $G$  and  $k$ : a subset  $S$  of vertices

## Definition

An algorithm  $C(\cdot, \cdot)$  is a **certifier** for problem  $X$  if for every  $s \in X$  there is some string  $t$  such that  $C(s, t) = \text{"yes"}$ , and conversely, if for some  $s$  and  $t$ ,  $C(s, t) = \text{"yes"}$  then  $s \in X$ .

The string  $t$  is called a **certificate** or **proof** for  $s$

## Efficient Certifier

$C$  is an **efficient certifier** for problem  $X$  if there is a polynomial  $p(\cdot)$  such that for every string  $s$ ,  $s \in X$  iff there is a string  $t$  with  $|t| \leq p(|s|)$ ,  $C(s, t) = \text{"yes"}$  and  $C$  runs in polynomial time

## Example: Independent Set

- **Problem:** Does  $G = (V, E)$  have an independent set of size  $\geq k$ ?
  - **Certificate:** Set  $S \subseteq V$
  - **Certifier:** Check  $|S| \geq k$  and no pair of vertices in  $S$  is connected by an edge

# Example: Vertex Cover

- **Problem:** Does  $G$  have a vertex cover of size  $\leq k$ ?
  - **Certificate:**  $S \subseteq V$
  - **Certifier:** Check  $|S| \leq k$  and that for every edge at least one endpoint is in  $S$

# Example: SAT

- **Problem:** Does formula  $\varphi$  have a satisfying truth assignment?
  - **Certificate:** Assignment  $a$  of 0/1 values to each variable
  - **Certifier:** Check each clause under  $a$  and say “yes” if all clauses are true

# Example: Composites

- **Problem:** Is number  $s$  a composite?
  - **Certificate:** A factor  $t \leq s$  such that  $t \neq 1$  and  $t \neq s$
  - **Certifier:** Check that  $t$  divides  $s$  (Euclid's algorithm)

## Nondeterministic Polynomial Time

### Definition

**Nondeterministic Polynomial Time** (denoted by **NP**) is the class of all problems that have efficient certifiers

### Example

**Independent Set, Vertex Cover, Set Cover, SAT, 3SAT,**  
Composites are all examples of problems in **NP**

# Asymmetry in Definition of NP

Note that only YES instances have a short proof/certificate. NO instances need not have a short certificate.

Example: **SAT** formula  $\varphi$ . No easy way to prove that  $\varphi$  is NOT satisfiable!

More on this and co-NP later on.

## P versus NP

### Proposition

$$P \subseteq NP$$

For a problem in  $P$  no need for a certificate!

### Proof.

Consider problem  $X \in P$  with algorithm  $A$ . Need to demonstrate that  $X$  has an efficient certifier

- Certifier  $C$  on input  $s, t$ , runs  $A(s)$  and returns the answer
- $C$  runs in polynomial time
- If  $s \in X$  then for every  $t$ ,  $C(s, t) = \text{"yes"}$
- If  $s \notin X$  then for every  $t$ ,  $C(s, t) = \text{"no"}$

□

# Exponential Time

## Definition

**Exponential Time** (denoted **EXP**) is the collection of all problems that have an algorithm which on input  $s$  runs in exponential time, i.e.,  $O(2^{\text{poly}(|s|)})$

Example:  $O(2^n)$ ,  $O(2^{n \log n})$ ,  $O(2^{n^3})$ , ...

## NP versus EXP

## Proposition

$NP \subseteq EXP$

## Proof.

Let  $X \in NP$  with certifier  $C$ . Need to design an exponential time algorithm for  $X$

- For every  $t$ , with  $|t| \leq p(|s|)$  run  $C(s, t)$ ; answer “yes” if any one of these calls returns “yes”
- The above algorithm correctly solves  $X$  (exercise)
- Algorithm runs in  $O(q(|s| + |p(s)|)2^{p(|s|)})$ , where  $q$  is the running time of  $C$



# Examples

- **SAT**: try all possible truth assignment to variables.
- **Independent Set**: try all possible subsets of vertices.
- **Vertex Cover**: try all possible subsets of vertices.

## Is **NP** efficiently solvable?

We know  $P \subseteq NP \subseteq EXP$

### Big Question

Is there are problem in **NP** that **does not** belong to **P**? Is  $P = NP$ ?



# If $P = NP$ . . .

Or: If pigs could fly then life would be sweet.

- Many important optimization problems can be solved efficiently.
- The **RSA** cryptosystem can be broken.
- No security on the web.
- No e-commerce . . .
- Creativity can be automated! Proofs for mathematical statement can be found by computers automatically (if short ones exist).

## $P$ versus $NP$

### Status

Relationship between  $P$  and  $NP$  remains one of the most important open problems in mathematics/computer science.

**Consensus:** Most people feel/believe  $P \neq NP$ .

Resolving  $P$  versus  $NP$  is a Clay Millennium Prize Problem. You can win a million dollars in addition to a Turing award and major fame!