

# CS 440/ECE 448 Lecture 10: Probability

Slides by Svetlana Lazebnik, 9/2016

Modified by Mark Hasegawa-Johnson, 2/2019



# Outline

- Motivation: Why use probability?
  - Laziness, Ignorance, and Randomness
  - Rational Bettor Theorem
- Review of Key Concepts
  - Outcomes, Events
  - Random Variables; probability mass function (pmf)
  - Jointly random variables: Joint, Marginal, and Conditional pmf
  - Independent vs. Conditionally Independent events

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# Motivation: Planning under uncertainty

- Recall: representation for planning
- **States** are specified as conjunctions of predicates
  - Start state:  $At(Me, UIUC) \wedge TravelTime(35min, UIUC, CMI) \wedge Now(12:45)$
  - Goal state:  $At(Me, CMI, 15:30)$
- **Actions** are described in terms of preconditions and effects:
  - $Go(t, src, dst)$ 
    - **Precond:**  $At(Me, src) \wedge TravelTime(dt, src, dst) \wedge Now(\leq t)$
    - **Effect:**  $At(Me, dst, t+dt)$

# Motivation: Planning under uncertainty

- Let action  $Go(t)$  = leave for airport at time  $t$ 
  - Will  $Go(t)$  succeed, i.e., get me to the airport in time for the flight?
- Problems:
  - Partial observability (road state, other drivers' plans, etc.)
  - Noisy sensors (traffic reports)
  - Uncertainty in action outcomes (flat tire, etc.)
  - Complexity of modeling and predicting traffic
- Hence a purely logical approach either
  - Risks falsehood: “ $Go(14:30)$  will get me there on time,” or
  - Leads to conclusions that are too weak for decision making:
    - $Go(14:30)$  will get me there on time if there's no accident, it doesn't rain, my tires remain intact, etc., etc.
    - $Go(04:30)$  will get me there on time

# Probability

Probabilistic assertions summarize effects of

- Laziness: reluctance to enumerate exceptions, qualifications, etc. --- possibly a deterministic and known environment, but with **computational complexity limitations**
- Ignorance: lack of explicit theories, relevant facts, initial conditions, etc. --- environment that is **unknown** (we don't know the transition function) or **partially observable** (we can't measure the current state)
- Intrinsically random phenomena – environment is **stochastic**, i.e., given a particular (action, current state), the (next state) is drawn at random with a particular probability distribution

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# Making decisions under uncertainty

- Suppose the agent believes the following:

$P(\text{Go}(\text{deadline-25}) \text{ gets me there on time}) = 0.04$

$P(\text{Go}(\text{deadline-90}) \text{ gets me there on time}) = 0.70$

$P(\text{Go}(\text{deadline-120}) \text{ gets me there on time}) = 0.95$

$P(\text{Go}(\text{deadline-180}) \text{ gets me there on time}) = 0.9999$

- Which action should the agent choose?
  - Depends on preferences for missing flight vs. time spent waiting
  - Encapsulated by a *utility function*
- The agent should choose the action that maximizes the *expected utility*:

$$\text{Prob}(A \text{ succeeds}) \times \text{Utility}(A \text{ succeeds}) + \text{Prob}(A \text{ fails}) \times \text{Utility}(A \text{ fails})$$



# Making decisions under uncertainty

- More generally: the expected utility of an action is defined as:

$$E[\text{Utility}|\text{Action}] = \sum_{\text{outcomes}} P(\text{outcome}|\text{action}) \text{Utility}(\text{outcome})$$

- **Utility theory** is used to represent and infer preferences
- **Decision theory** = probability theory + utility theory

# Where do probabilities come from?

- **Frequentism**

- Probabilities are relative frequencies
- For example, if we toss a coin many times,  $P(\text{heads})$  is the proportion of the time the coin will come up heads
- But what if we're dealing with an event that has never happened before?
  - What is the probability that the Earth will warm by 0.15 degrees this year?

- **Subjectivism**

- Probabilities are degrees of belief
  - But then, how do we assign belief values to statements?
  - In practice: models. Represent an *unknown event* as a series of *better-known events*
- A theoretical problem with Subjectivism:
    - Why do “beliefs” need to follow the laws of probability?

# The Rational Bettor Theorem

- Why should a rational agent hold beliefs that are consistent with axioms of probability?
  - For example,  $P(A) + P(\neg A) = 1$
- Suppose an agent believes that  $P(A)=0.7$ , and  $P(\neg A)=0.7$
- Offer the following bet: if A occurs, agent wins \$100. If A doesn't occur, agent loses \$105. Agent believes  $P(A) > 100/(100+105)$ , so agent accepts the bet.
- Offer another bet: if  $\neg A$  occurs, agent wins \$100. If  $\neg A$  doesn't occur, agent loses \$105. Agent believes  $P(\neg A) > 100/(100+105)$ , so agent accepts the bet. **Oops...**
- **Theorem**: An agent who holds beliefs inconsistent with axioms of probability can be convinced to accept a combination of bets that is guaranteed to lose them money

# Are humans “rational bettors”?

- Humans are pretty good at estimating some probabilities, and pretty bad at estimating others. What might cause humans to mis-estimate the probability of an event?
- What are some of the ways in which a “rational bettor” might take advantage of humans who mis-estimate probabilities?

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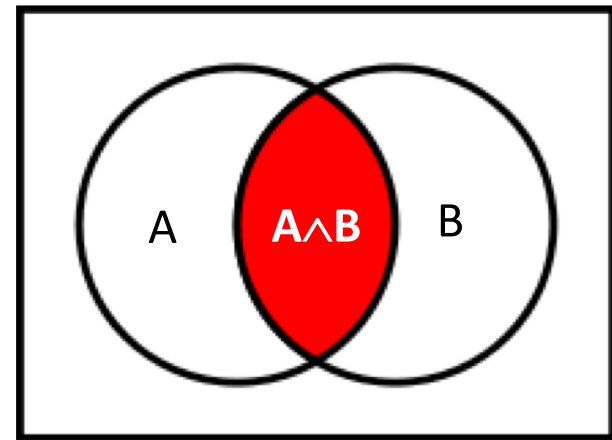
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# Events

- Probabilistic statements are defined over *events*, or sets of world states
  - $A = \text{“It is raining”}$
  - $B = \text{“The weather is either cloudy or snowy”}$
  - $C = \text{“I roll two dice, and the result is 11”}$
  - $D = \text{“My car is going between 30 and 50 miles per hour”}$
- An EVENT is a SET of OUTCOMES
  - $B = \{ \text{outcomes : cloudy OR snowy} \}$
  - $C = \{ \text{outcome tuples } (d1, d2) \text{ such that } d1+d2 = 11 \}$
- Notation:  $P(A)$  is the probability of the set of world states (outcomes) in which proposition A holds

# Kolmogorov's axioms of probability

- For any propositions (events) A, B
  - $0 \leq P(A) \leq 1$
  - $P(\text{True}) = 1$  and  $P(\text{False}) = 0$
  - $P(A \vee B) = P(A) + P(B) - P(A \wedge B)$ 
    - Subtraction accounts for double-counting
- Based on these axioms, what is  $P(\neg A)$ ?
- These axioms are sufficient to completely specify probability theory for *discrete* random variables
  - For continuous variables, need *density functions*



# Outcomes = Atomic events

- **OUTCOME or ATOMIC EVENT:** is a complete specification of the state of the world, or a complete assignment of domain values to all random variables
  - Atomic events are mutually exclusive and exhaustive
- E.g., if the world consists of only two Boolean variables *Cavity* and *Toothache*, then there are four outcomes:
  - Outcome #1:  $\neg Cavity \wedge \neg Toothache$
  - Outcome #2:  $\neg Cavity \wedge Toothache$
  - Outcome #3:  $Cavity \wedge \neg Toothache$
  - Outcome #4:  $Cavity \wedge Toothache$



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# Joint probability distributions

- A **joint distribution** is an assignment of probabilities to every possible atomic event

Atomic event	P
$\neg\text{Cavity} \wedge \neg\text{Toothache}$	0.8
$\neg\text{Cavity} \wedge \text{Toothache}$	0.1
$\text{Cavity} \wedge \neg\text{Toothache}$	0.05
$\text{Cavity} \wedge \text{Toothache}$	0.05

- Why does it follow from the axioms of probability that the probabilities of all possible atomic events must sum to 1?

# Joint probability distributions

- $P(X_1, X_2, \dots, X_N)$  refers to the probability of a particular outcome (the outcome in which the events  $X_1, X_2, \dots$ , and  $X_N$  all occur at the same time)
- $P(X_1, X_2, \dots, X_N)$  can also refer to the complete TABLE, with  $2^N$  entries, listing the probabilities of  $X_1$  either occurring or not occurring,  $X_2$  either occurring or not occurring, and so on.
- This ambiguity, between the probability VALUE and the probability TABLE, will be eliminated next lecture, when we introduce random variables.

# Joint probability distributions

- Suppose we have a joint distribution of  $N$  random variables, each of which takes values from a domain of size  $D$ :
  - What is the size of the probability table?
  - Impossible to write out completely for all but the smallest distributions

# Marginal distributions

- The marginal distribution of event  $X_k$  is just its probability,  $P(X_k)$ .
- To talk about marginal distributions only makes sense if you're not given  $P(X_k)$ . Instead, you're given the joint distribution,  $P(X_1, X_2, \dots, X_N)$ , and from it, you need to calculate  $P(X_k)$ .
- You calculate  $P(X_k)$  from  $P(X_1, X_2, \dots, X_N)$  by marginalizing.  $P(X_k)$  is called the marginal distribution of event  $X_k$ .

# Marginal probability distributions

- From the joint distribution  $p(X,Y)$  we can find the **marginal distributions**  $p(X)$  and  $p(Y)$

P(Cavity, Toothache)	
$\neg\text{Cavity} \wedge \neg\text{Toothache}$	0.8
$\neg\text{Cavity} \wedge \text{Toothache}$	0.1
$\text{Cavity} \wedge \neg\text{Toothache}$	0.05
$\text{Cavity} \wedge \text{Toothache}$	0.05

P(Cavity)	
$\neg\text{Cavity}$	?
$\text{Cavity}$	?

P(Toothache)	
$\neg\text{Toothache}$	?
$\text{Toothache}$	?

## Joint -> Marginal by adding the outcomes

- From the joint distribution  $p(X,Y)$  we can find the **marginal distributions**  $p(X)$  and  $p(Y)$
- To find  $p(X = x)$ , sum the probabilities of all atomic events where  $X = x$ :

$$P(X = 1) = P(X = 1, Y = 1) + P(X = 1, Y = 2) + P(X = 1, Y = 3) + \dots$$

- This is called **marginalization** (we are *marginalizing out* all the variables except X)

# Conditional distributions

- The conditional probability of event  $X_k$ , given event  $X_j$ , is the probability that  $X_k$  has occurred if you already know that  $X_j$  has occurred.
- The conditional distribution is written  $P(X_k | X_j)$ .
- The probability that both  $X_j$  and  $X_k$  occurred was, originally,  $P(X_j, X_k)$ .
- But now you know that  $X_j$  has occurred. So all of the other events are no longer possible.
  - Other events: probability used to be  $P(-X_j)$ , but now their probability is 0.
  - Events in which  $X_j$  occurred: probability used to be  $P(X_j)$ , but now their probability is 1.
- So we need to renormalize: the probability that both  $X_j$  and  $X_k$  occurred, GIVEN that  $X_j$  has occurred, is  $P(X_k | X_j) = P(X_j, X_k) / P(X_j)$ .

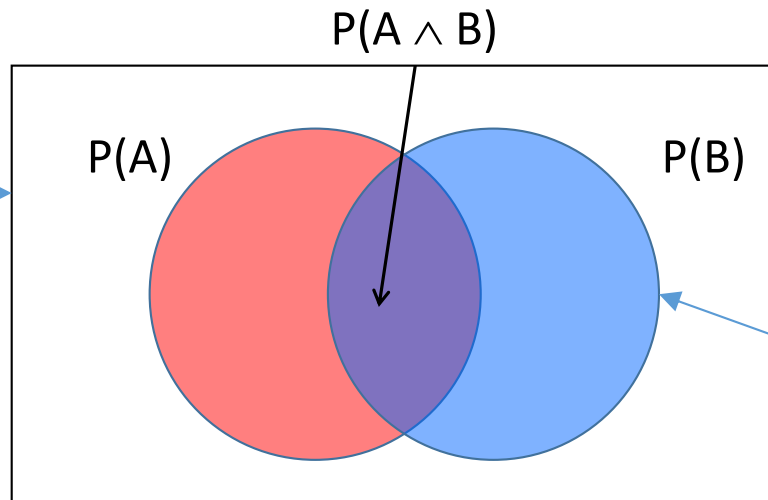


# Conditional Probability: renormalize (divide)

- Probability of cavity given toothache:  
 $P(\text{Cavity} = \text{true} \mid \text{Toothache} = \text{true})$

- For any two events A and B,  
$$P(A \mid B) = \frac{P(A \wedge B)}{P(B)} = \frac{P(A, B)}{P(B)}$$

The set of all possible events used to be this rectangle, so the whole rectangle used to have probability=1.



Now that we know B has occurred, the set of all possible events = the set of events in which B occurred. So we renormalize to make the area of this circle = 1.

# Conditional probability

P(Cavity, Toothache)	
$\neg\text{Cavity} \wedge \neg\text{Toothache}$	0.8
$\neg\text{Cavity} \wedge \text{Toothache}$	0.1
$\text{Cavity} \wedge \neg\text{Toothache}$	0.05
$\text{Cavity} \wedge \text{Toothache}$	0.05

P(Cavity)	
$\neg\text{Cavity}$	0.9
$\text{Cavity}$	0.1

P(Toothache)	
$\neg\text{Toothache}$	0.85
$\text{Toothache}$	0.15

- What is  $p(\text{Cavity} = \text{true} \mid \text{Toothache} = \text{false})$ ?  
 $p(\text{Cavity} \mid \neg\text{Toothache}) = 0.05/0.85 = 1/17$
- What is  $p(\text{Cavity} = \text{false} \mid \text{Toothache} = \text{true})$ ?  
 $p(\neg\text{Cavity} \mid \text{Toothache}) = 0.1/0.15 = 2/3$

# Conditional distributions

- A conditional distribution is a distribution over the values of one variable given fixed values of other variables

P(Cavity, Toothache)	
$\neg\text{Cavity} \wedge \neg\text{Toothache}$	0.8
$\neg\text{Cavity} \wedge \text{Toothache}$	0.1
$\text{Cavity} \wedge \neg\text{Toothache}$	0.05
$\text{Cavity} \wedge \text{Toothache}$	0.05

P(Cavity   Toothache = true)	
$\neg\text{Cavity}$	0.667
$\text{Cavity}$	0.333

P(Cavity   Toothache = false)	
$\neg\text{Cavity}$	0.941
$\text{Cavity}$	0.059

P(Toothache   Cavity = true)	
$\neg\text{Toothache}$	0.5
$\text{Toothache}$	0.5

P(Toothache   Cavity = false)	
$\neg\text{Toothache}$	0.889
$\text{Toothache}$	0.111

# Normalization trick

- To get the whole conditional distribution  $p(X | Y = y)$  at once, select all entries in the joint distribution table matching  $Y = y$  and renormalize them to sum to one

P(Cavity, Toothache)	
$\neg\text{Cavity} \wedge \neg\text{Toothache}$	0.8
$\neg\text{Cavity} \wedge \text{Toothache}$	0.1
$\text{Cavity} \wedge \neg\text{Toothache}$	0.05
$\text{Cavity} \wedge \text{Toothache}$	0.05

↓ Select

Toothache, Cavity = false	
$\neg\text{Toothache}$	0.8
$\text{Toothache}$	0.1

↓ Renormalize

P(Toothache   Cavity = false)	
$\neg\text{Toothache}$	0.889
$\text{Toothache}$	0.111

## Normalization trick

- To get the whole conditional distribution  $p(X | Y = y)$  at once, select all entries in the joint distribution table matching  $Y = y$  and renormalize them to sum to one
- Why does it work?

$$P(x|y) = \frac{P(x, y)}{\sum_{x'} P(x', y)} = \frac{P(x, y)}{P(y)} \quad \text{by marginalization}$$

# Product rule

- Definition of conditional probability:  $P(A | B) = \frac{P(A, B)}{P(B)}$
- Sometimes we have the conditional probability and want to obtain the joint:

$$P(A, B) = P(A | B)P(B) = P(B | A)P(A)$$

# Product rule

- Definition of conditional probability:  $P(A | B) = \frac{P(A, B)}{P(B)}$
- Sometimes we have the conditional probability and want to obtain the joint:

$$P(A, B) = P(A | B)P(B) = P(B | A)P(A)$$

- The chain rule:

$$\begin{aligned} P(A_1, \dots, A_n) &= P(A_1)P(A_2 | A_1)P(A_3 | A_1, A_2) \dots P(A_n | A_1, \dots, A_{n-1}) \\ &= \prod_{i=1}^n P(A_i | A_1, \dots, A_{i-1}) \end{aligned}$$

## Product Rule Example: The Birthday problem

- We have a set of  $n$  people. What is the probability that two of them share the same birthday?
- Easier to calculate the probability that  $n$  people *do not* share the same birthday

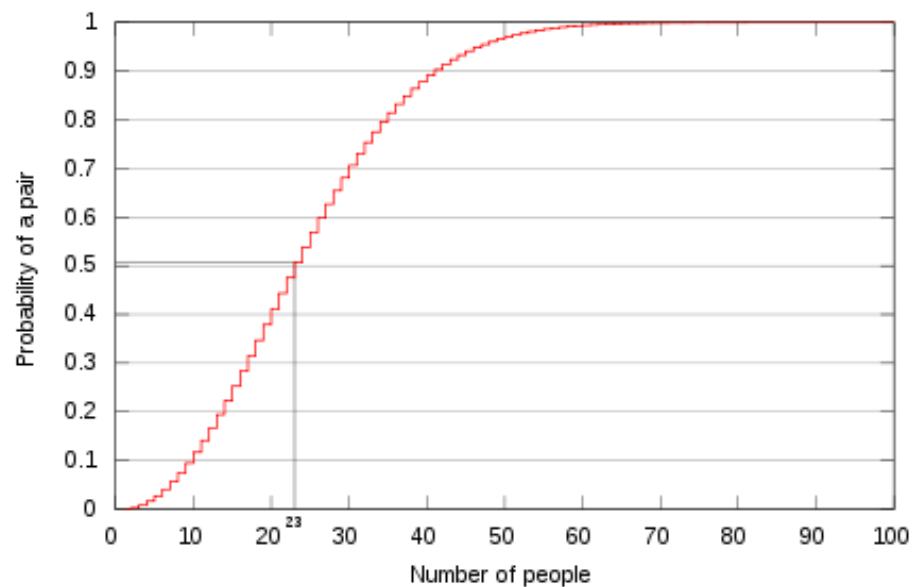
$$\begin{aligned} &P(B_1, \dots, B_n \text{ distinct}) \\ &= P(B_1, B_2 \text{ distinct})P(B_1, B_2, B_3 \text{ distinct} | B_1, B_2 \text{ distinct}) \dots \\ &\quad P(B_1, B_2, \dots, B_n \text{ distinct} | B_1, \dots, B_{n-1} \text{ distinct}) \end{aligned}$$

$$P(B_1, \dots, B_n \text{ distinct}) = \left(\frac{364}{365}\right) \left(\frac{363}{365}\right) \dots \left(\frac{365-n+1}{365}\right)$$



# The Birthday problem

- For 23 people, the probability of sharing a birthday is above 0.5!



[http://en.wikipedia.org/wiki/Birthday\\_problem](http://en.wikipedia.org/wiki/Birthday_problem)

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# Independence $\neq$ Mutually Exclusive

- Two events A and B are *independent* if and only if
$$p(A \wedge B) = p(A, B) = p(A) p(B)$$
  - In other words,  $p(A | B) = p(A)$  and  $p(B | A) = p(B)$
  - This is an important simplifying assumption for modeling, e.g., *Toothache* and *Weather* can be assumed to be independent?
- Are two *mutually exclusive* events independent?
  - No! Quite the opposite! If you know A happened, then you know that B *\_didn't\_* happen!!
$$p(A \vee B) = p(A) + p(B)$$

# Independence $\neq$ Conditional Independence

- Two events A and B are *independent* if and only if
$$p(A \wedge B) = p(A) p(B)$$
  - In other words,  $p(A | B) = p(A)$  and  $p(B | A) = p(B)$
  - This is an important simplifying assumption for modeling, e.g., *Toothache* and *Weather* can be assumed to be independent
- **Conditional independence:** A and B are *conditionally independent* given C iff
$$p(A \wedge B | C) = p(A | C) p(B | C)$$
  - Equivalent:
$$p(A | B, C) = p(A | C)$$
  - Equivalent:
$$p(B | A, C) = p(B | C)$$

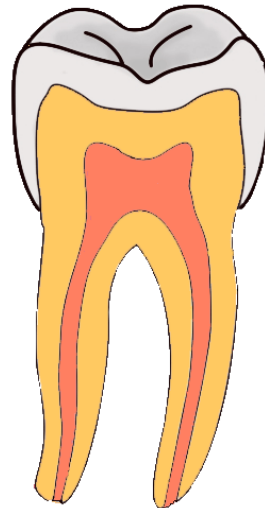
# Independence $\neq$ Conditional Independence

*Toothache*: Boolean variable indicating whether the patient has a toothache



By William Brassey Hole (Died: 1917)

*Cavity*: Boolean variable indicating whether the patient has a cavity



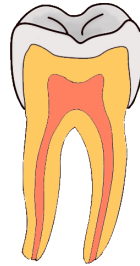
By Aduran, CC-SA 3.0

*Catch*: whether the dentist's probe catches in the cavity



By Dozenist, CC-SA 3.0

# These Events are not Independent



- If the patient has a toothache, then it's likely he has a cavity. Having a cavity makes it more likely that the probe will catch on something.

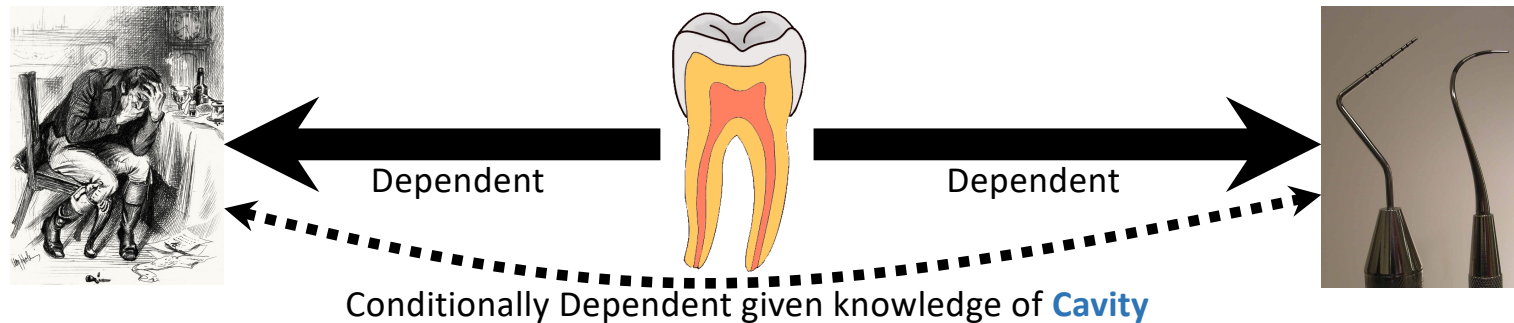
$$P(\text{Catch}|\text{Toothache}) > P(\text{Catch})$$

- If the probe catches on something, then it's likely that the patient has a cavity. If he has a cavity, then he might also have a toothache.

$$P(\text{Toothache}|\text{Catch}) > P(\text{Toothache})$$

- So Catch and Toothache are not independent

...but they are Conditionally Independent

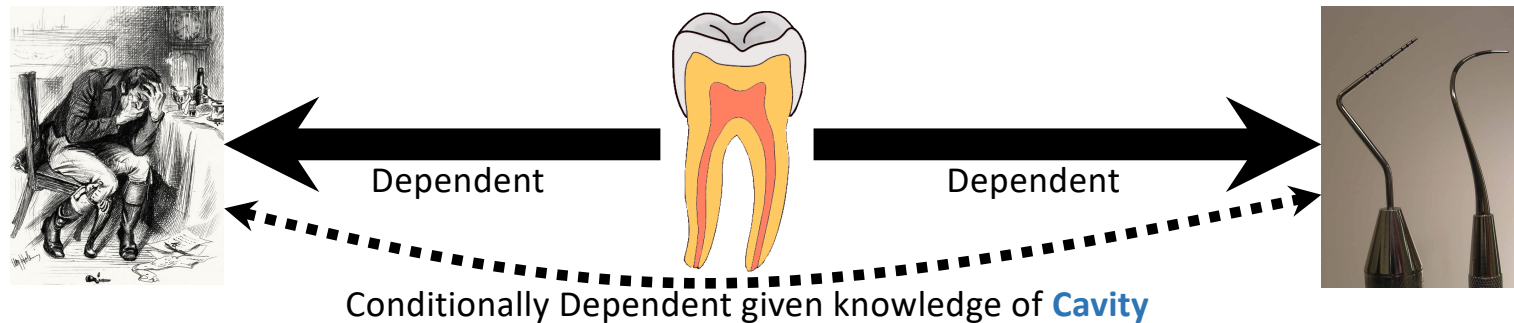


- Here are some reasons the probe might not catch, despite having a cavity:
  - The dentist might be really careless
  - The cavity might be really small
- Those reasons have nothing to do with the toothache!

$$P(\text{Catch}|\text{Cavity}, \text{Toothache}) = P(\text{Catch}|\text{Cavity})$$

- **Catch** and **Toothache** are conditionally independent given knowledge of **Cavity**

...but they are Conditionally Independent



These statements are all equivalent:

$$P(\text{Catch}|\text{Cavity}, \text{Toothache}) = P(\text{Catch}|\text{Cavity})$$

$$P(\text{Toothache}|\text{Cavity}, \text{Catch}) = P(\text{Toothache}|\text{Cavity})$$

$$P(\text{Toothache}, \text{Catch}|\text{Cavity}) = P(\text{Toothache}|\text{Cavity}) P(\text{Catch}|\text{Cavity})$$

...and they all mean that **Catch** and **Toothache** are conditionally independent given knowledge of **Cavity**



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