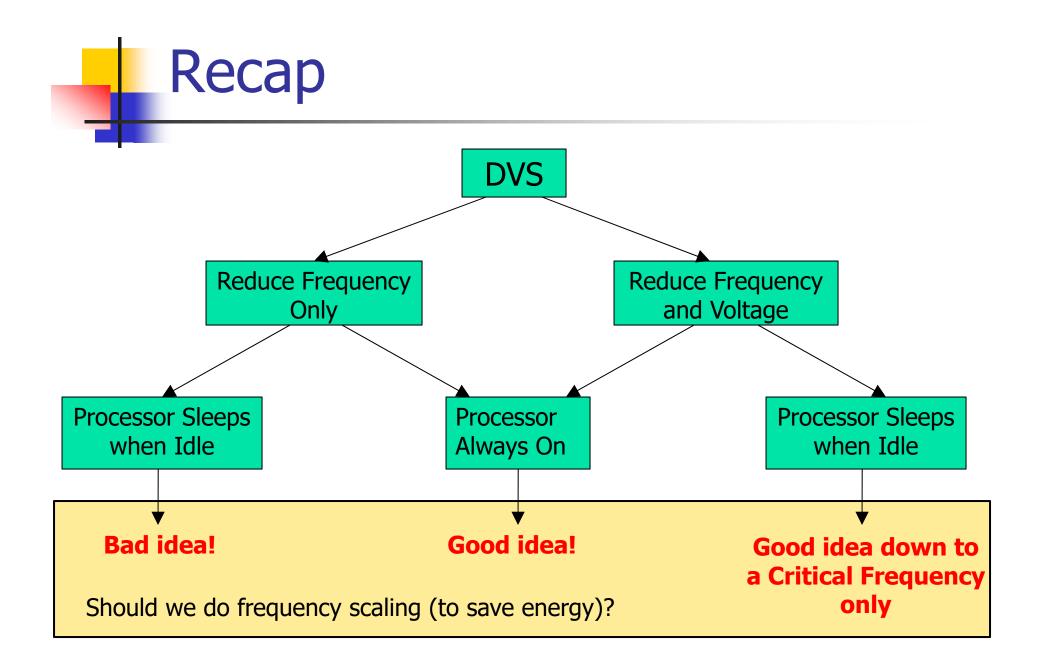
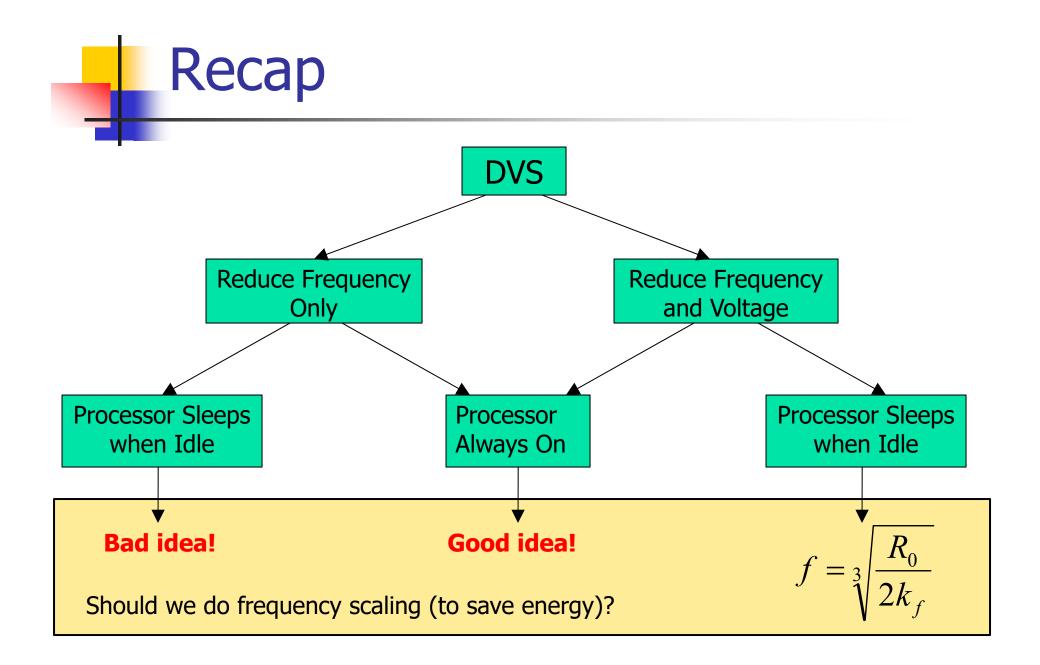


Continued





Advanced Configuration and Power Interface (ACPI)

- Defines different power saving states in a platform-independent manner
- The standard was originally developed by Intel, Microsoft, and Toshiba (in 1996), then later joined by HP, and Phoenix.
- The latest version is "Revision 6.3," published by UEFI (Jan 2019).

Global States

GO: working

- G1: Sleeping and hibernation (several degrees available)
- G2:, Soft Off: almost the same as G3 Mechanical Off, except that the power supply still supplies power, at a minimum, to the power button to allow wakeup. A full reboot is required.
- G3, Mechanical Off: The computer's power has been totally removed via a mechanical switch.

Processor Performance States (P-States)

- **PO** max power and frequency
- P1 less than P0, voltage/frequency scaled
- P2 less than P1, voltage/frequency scaled
- • •
- Pn less than P(n-1), voltage/frequency scaled

Processor "Sleep" States (C-states)

- **CO**: is the operating state.
- C1 (often known as *Halt*): is a state where the processor is not executing instructions, but can return to an executing state instantaneously. All ACPI-conformant processors must support this power state.
- C2 (often known as *Stop-Clock*): is a state where the processor maintains all software-visible state, but may take longer to wake up. This processor state is optional.
- C3 (often known as *Sleep*) is a state where the processor does not need to keep its cache, but maintains other state. This processor state is optional.

- Energy expended on wakeup, E_{wake}
- To sleep or not to sleep?

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 - Not to sleep (for time *t*):

$$E_{no-sleep} = (k_v V^2 f + R_0) t$$

• To sleep (for time *t*) then wake up:

$$E_{sleep} = P_{sleep} t + E_{wake}$$

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$$t > \frac{E_{wake}}{k_v V^2 f + R_0 - P_{sleep}}$$

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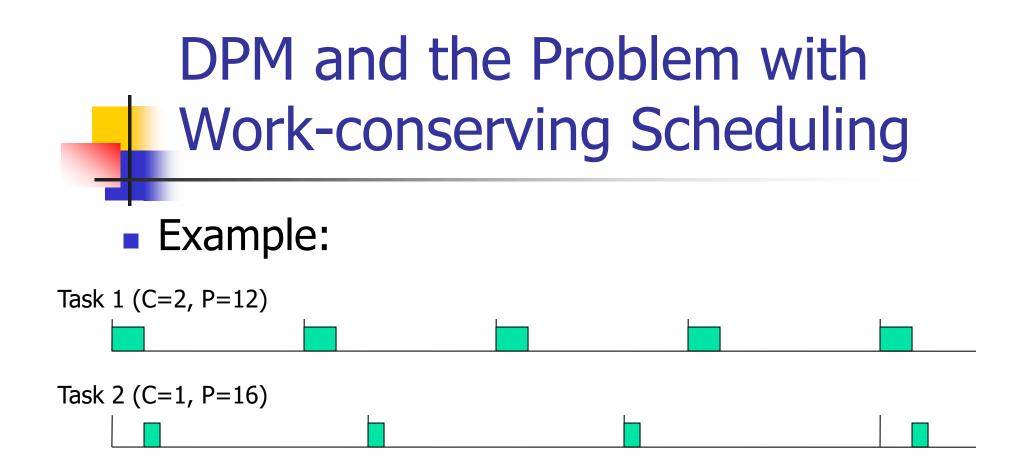
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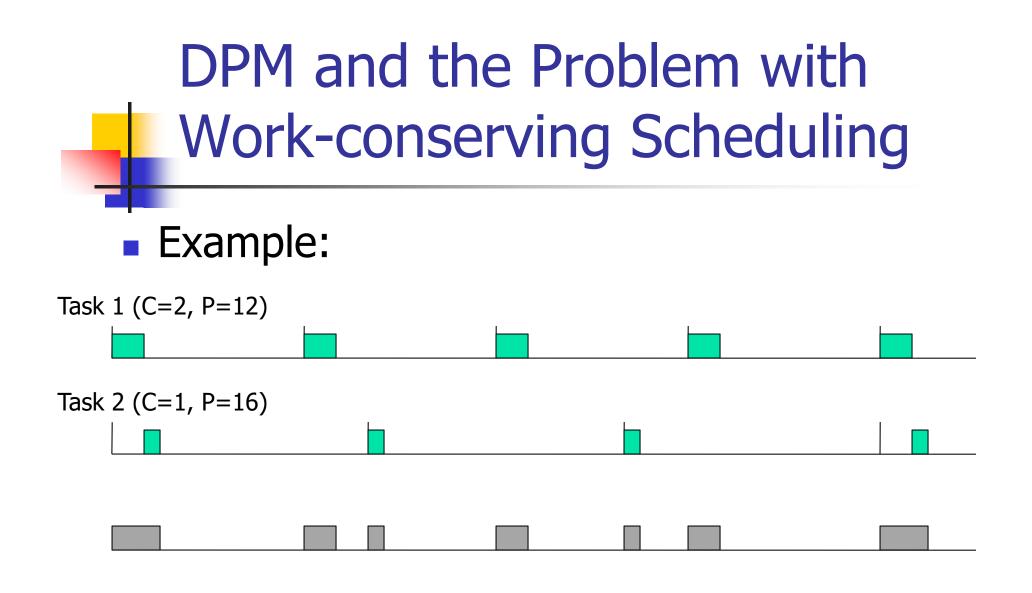
• To save energy by sleeping: $E_{sleep} < E_{no-sleep}$

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 Minimum sleep interval

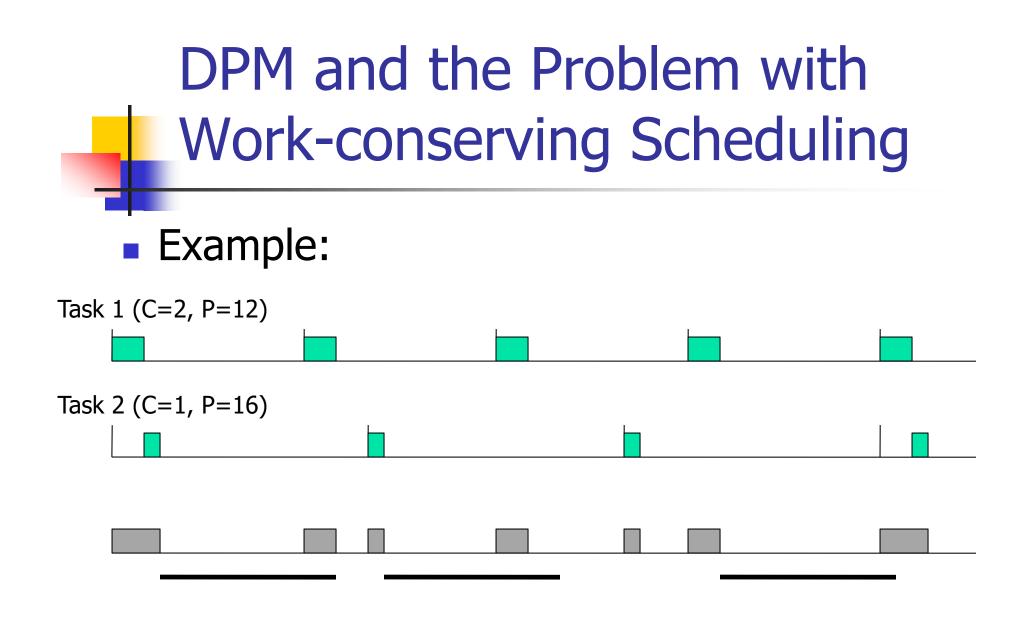
Dynamic Power Management

- DPM refers to turning devices off (or putting them in deep sleep modes)
- Device wakeup has a cost that imposes a minimum sleep interval (a breakeven time)
- DPM must maximize power savings due to sleep while maintaining schedulability

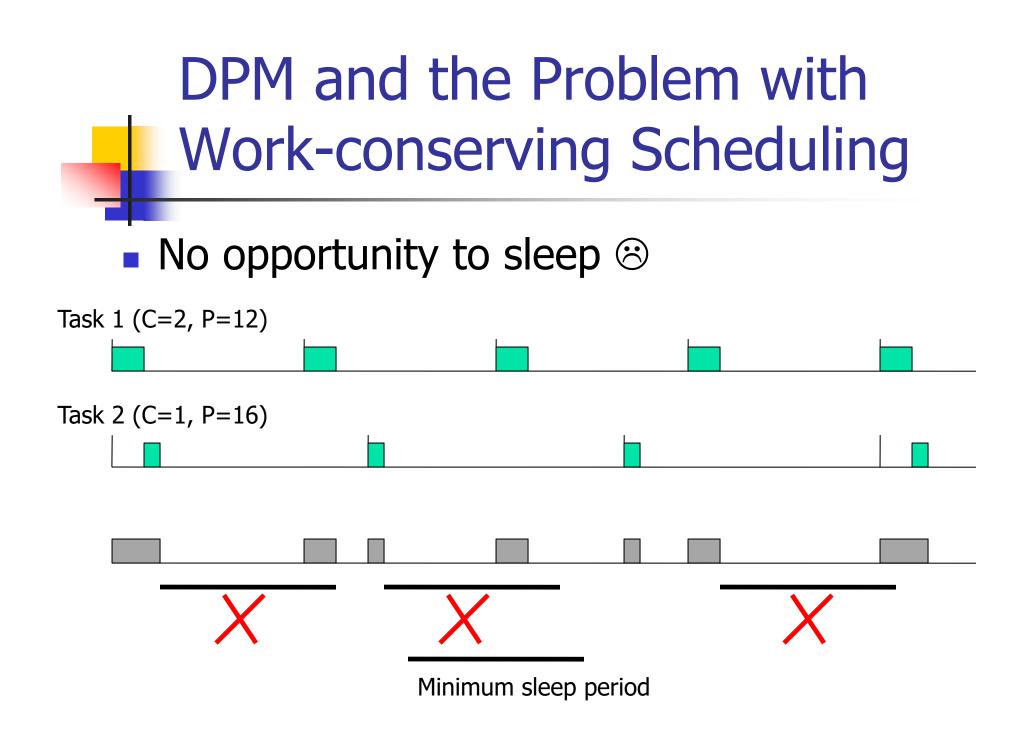


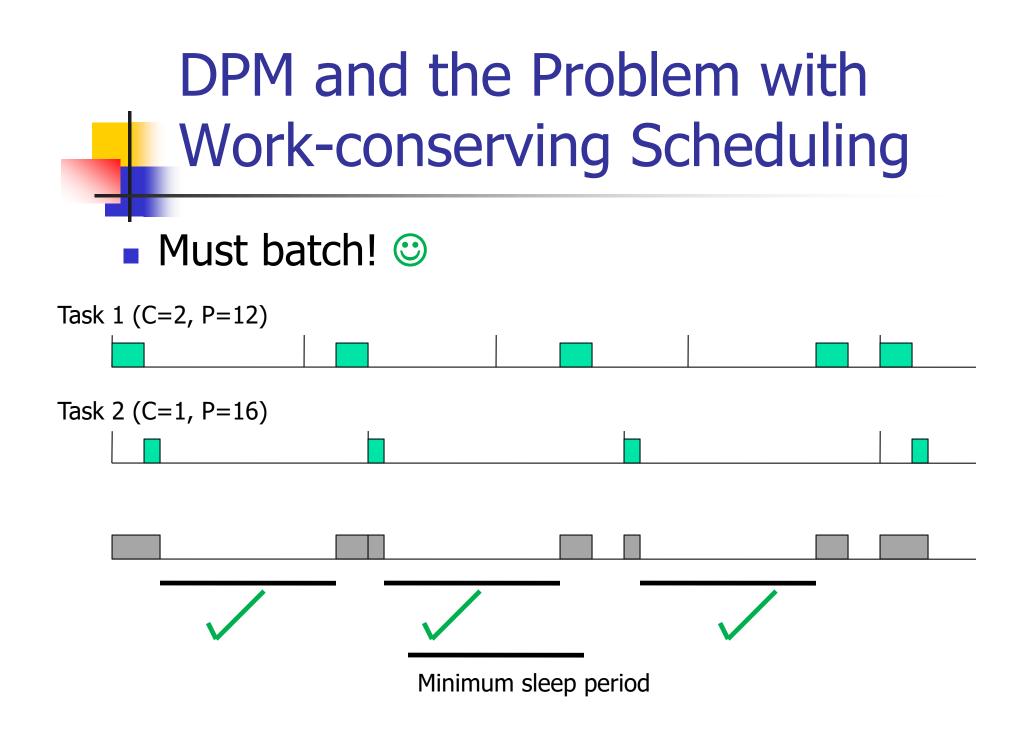


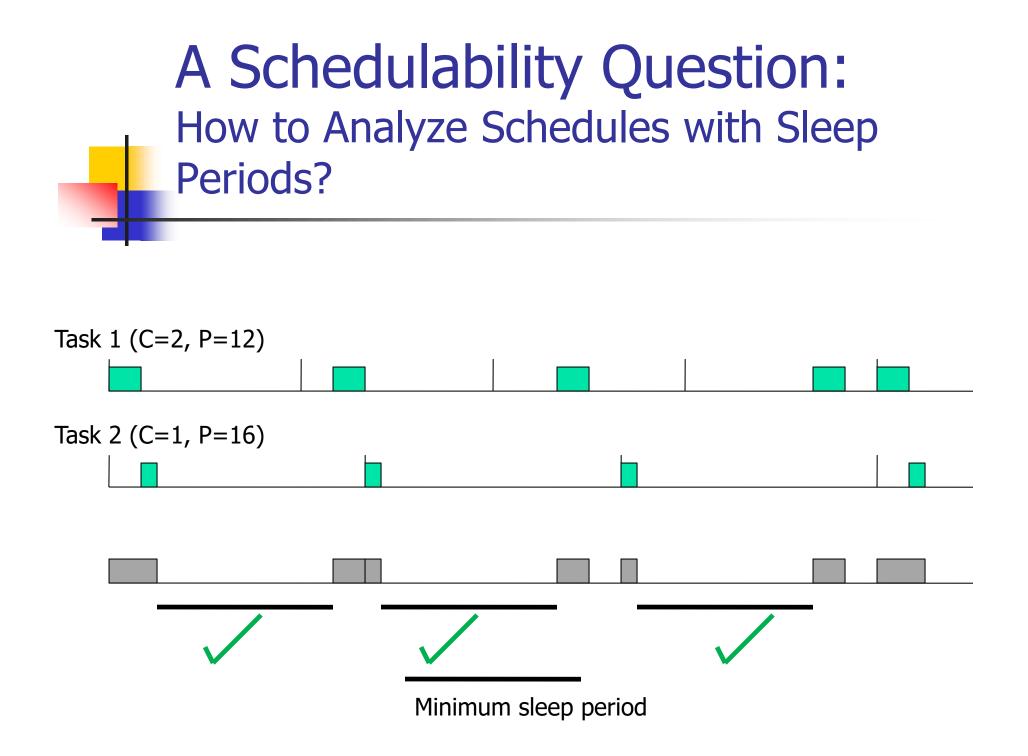
Minimum sleep period



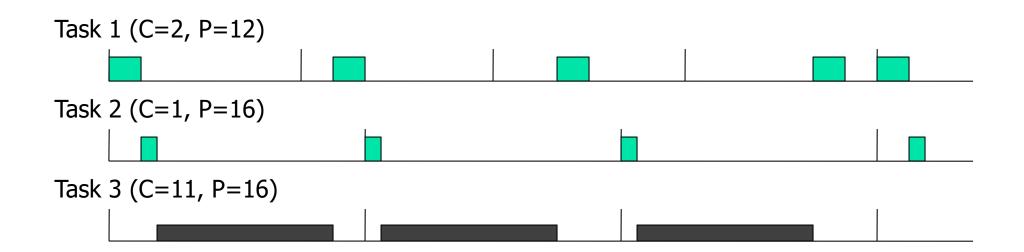
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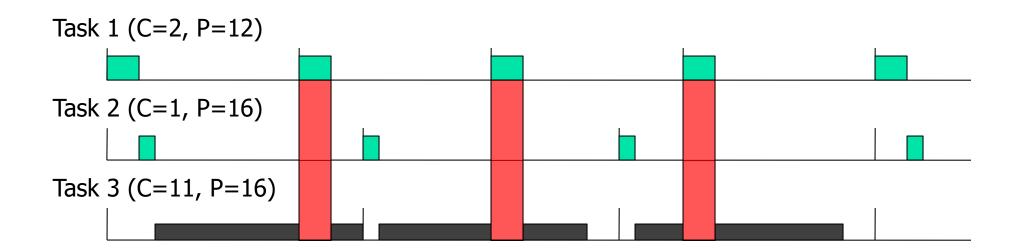




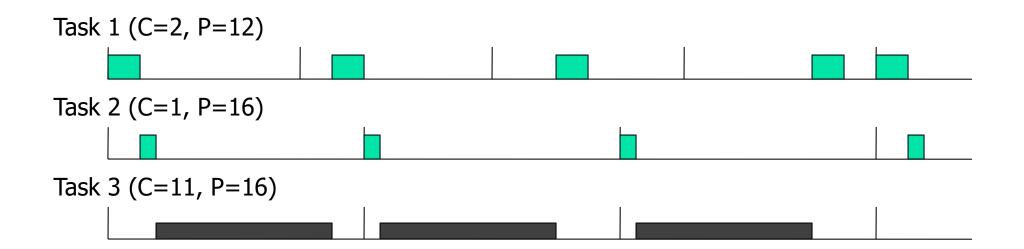
Option 1: Treat sleep periods like a periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?



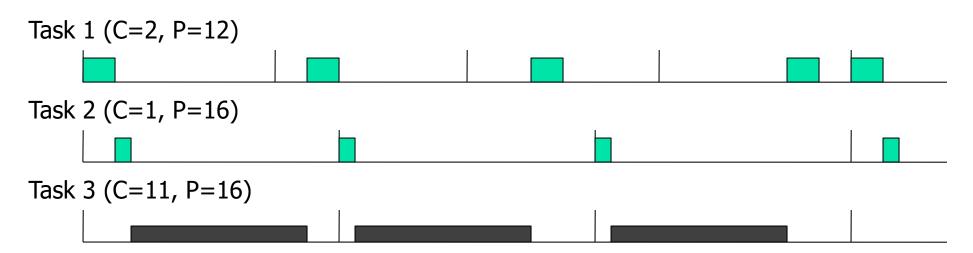
- Option 1: Treat sleep periods like a periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?
 - Does not work because the "sleep task" cannot be preempted, whereas the rest of the tasks are preemptible. The utilization bound works only for fully preemptive scheduling.



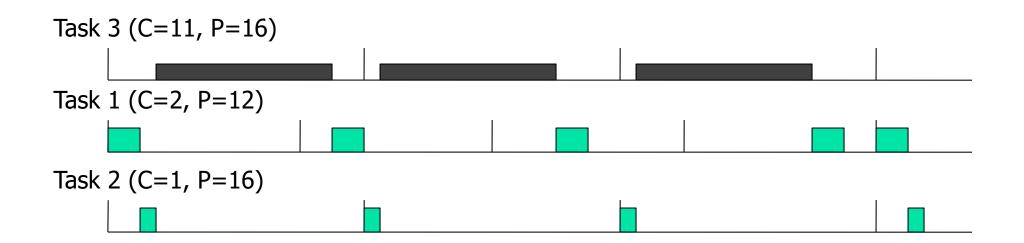
 Option 2: Treat sleep periods like the *highest-priority* periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?



- Option 2: Treat sleep periods like the *highest-priority* periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?
 - Does not work because the "sleep task" may need to have a larger period than the actual top-priority task, which contradicts ratemonotonic scheduling. The bound does not work.



 Option 3: Treat sleep periods like the *highest-priority* periodic task. Use *exact response time analysis* for schedulability.
Problems?



Device Forbidden Regions

- Option 3: Treat sleep periods like the *highest-priority* periodic task. Use *exact response time analysis* for schedulability.
 Problems?
 - A Valid solution, but pessimistic.

(Called: Device Forbidden Regions. Published in RTAS 2008.)

