

CS 421 Lecture 23: Hoare logic

- Lecture outline
 - Proving properties of imperative programs
 - Hoare logic
 - Judgments, a.k.a. “Hoare formulas”
 - Axioms
 - Rules of inference

Review of last week

- Proof systems
 - Formal frameworks for writing proofs
 - Judgments, axioms, rules of inference
- Type systems
 - Used for type checking, type inference
 - Judgments of the form: $\Gamma \vdash e : \tau$
- Operational semantics
 - Used for proofs of correctness
 - Judgments of the form: $\sigma, \eta \vdash e \Downarrow v, \sigma'$

Review: operational semantics

- Operational semantics of functional languages
 - Based on expression evaluation
 - Proofs follow the structure of the expression
- Variants
 - OS_{subst}
 - OS_{clo}
 - OS_{state}

Example

let f = fun x -> 3 in (f 1, f true)

Today: proofs for imperative programs

- Hoare logic (or Hoare rules or Hoare formulas)
 - Prove correctness of imperative programs
- Specifies pre- and post-conditions for statement execution
 - Axiomatic semantics
 - Contract principle

Correctness of imperative programs

- Hoare formula says that if the variables in a program satisfy some properties, then after executing a given program, they satisfy some different properties.

- $P \{A\} Q$

- Examples:

$x > 0 \{ \text{while} (x > 0)$

$\{ y := y * x; x := x - 1; \} \} y = y * x!$

$x = x_0 \ \& \ y = y_0 \{ t := x; x := y; y := t \} x = y_0 \ \& \ y = x_0$

More examples

true { if (x < 0) x := -x; } x = |x|

true { n := length(a); b := [hd a];
a := tl a;
while (a != []) {
b = (hd a + hd b) :: b;
a = tl a; }

$$\} \quad b_i = \sum_{k=0}^{n-i-1} a_k \quad \text{(where } b_i = \text{hd (tl}^i \text{ b)} \\ \text{and similarly for } a_k \text{)}$$

Hoare logic

- Judgments: $P \{S\} Q$
- P, Q assertions about variables in the program
- S a statement in this language:
 - Stmt \rightarrow Var := Expr | Stmt; Stmt
 - | if (Expr) then Stmt else Stmt
 - | while (Expr) Stmt

Inference rules for Hoare logic

$$\overline{P[e/x] \{x := e\} P}$$

$$\frac{P \Rightarrow P' \quad P' \{S\} Q' \quad Q' \Rightarrow Q}{P \{S\} Q}$$

$$\frac{P \ \& \ b \ \{S\} \ P}{P \ \{\text{while } (b) \ S\} \ P \ \& \ \neg b}$$

$$\frac{P \ \{S_1\} \ Q \quad Q \ \{S_2\} \ R}{P \ \{S_1; S_2\} \ R}$$

$$\frac{P \ \& \ b \ \{S_1\} \ Q \quad P \ \& \ \neg b \ \{S_2\} \ Q}{P \ \{\text{if } (b) \ \text{then } S_1 \ \text{else } S_2\} \ Q}$$

Rule of assignment

$$\frac{}{P[e/x] \{x := e\} P}$$

$$x+1=2 \{x := x+1\} x=2$$

$$y=2 \{x := y\} x=2$$

Rule of assignment: examples

$y=2 \{ x:=y \} x=2$

$y=2 \{ x:=2 \} y=x$

$x+1=n+1 \{ x:=x+1 \} x=n+1$

$x+1=n \{ x:=x+1 \} x=n$

$x+1=n \{ x:=x+1 \} x=n$

$\text{true} \{ x:=2 \} x=2$

Rule of consequence

$$\frac{P \Rightarrow P' \quad P' \{S\} Q' \quad Q' \Rightarrow Q}{P \{S\} Q}$$

Rule of consequence: example

$$\frac{P \Rightarrow P' \quad P' \{S\} Q' \quad Q' \Rightarrow Q}{P \{S\} Q}$$

$$\frac{x = n \Rightarrow x + 1 = n + 1 \quad A \quad x = n + 1 \Rightarrow x = n + 1}{x = n \quad \{x := x + 1\} \quad x = n + 1}$$

$$A = \frac{}{x + 1 = n + 1 \quad \{x = x + 1\} \quad x = n + 1}$$

Which inferences are correct?

$$\frac{x > 0 \ \& \ x < 5 \quad \{x := x * x\} \quad x < 25}{x = 3 \quad \{x := x * x\} \quad x < 25}$$

$$\frac{x = 3 \quad \{x := x * x\} \quad x < 25}{x > 0 \ \& \ x < 5 \quad \{x := x * x\} \quad x < 25}$$

$$\frac{x * x < 25 \quad \{x := x * x\} \quad x < 25}{x > 0 \ \& \ x < 5 \quad \{x := x * x\} \quad x < 25}$$

Sequence rule

$$\frac{P\{S_1\}Q \quad Q\{S_2\}R}{P\{S_1;S_2\}R}$$

Sequence rule: example

$$\frac{P\{S_1\}Q \quad Q\{S_2\}R}{P\{S_1;S_2\}R}$$

		A	B
$x = x_0$	$\&$	$t = x_0$	$t = x_0$
$y = y_0$	$t := x$	$x = x_0$	$x = x_0$
		$\&$	$\&$
		$y = y_0$	$y = y_0$
		$\{x = y; y = t\}$	
$x = x_0$	$\&$	$\{t := x; x := y; y := t\}$	
$y = y_0$		$x = y_0$	
		$\&$	
		$y = x_0$	

Sequence rule: example

$$\mathbf{A} = \frac{\begin{array}{l} t = x_0 \\ x = x_0 \quad \& \\ y = y_0 \end{array} \quad \{ x := y \} \quad \begin{array}{l} t = x_0 \\ x = y_0 \quad \& \\ y = y_0 \end{array}}{\quad}$$

$$\mathbf{B} = \frac{\begin{array}{l} t = x_0 \\ x = y_0 \quad \& \\ y = y_0 \end{array} \quad \{ y := t \} \quad \begin{array}{l} t = x_0 \\ x = y_0 \quad \& \\ y = x_0 \end{array}}{\quad}$$

If rule

$$\frac{P \ \& \ b \ \{S_1\} \ Q \quad P \ \& \ \neg b \ \{S_2\} \ Q}{P \ \{\text{if } (b) \ \text{then } S_1 \ \text{else } S_2\} \ Q}$$

If rule: example

$$\frac{P \ \& \ b \ \{S_1\} \ Q \quad P \ \& \ \neg b \ \{S_2\} \ Q}{P \ \{\text{if } (b) \text{ then } S_1 \text{ else } S_2\} \ Q}$$

$$\begin{array}{c} \Rightarrow \frac{\dots \ \{x := -x\} \ \dots}{x = 0 \ \& \ \{x := -x\} \ \ x = |x_0|} \Rightarrow \qquad \Rightarrow \frac{\dots \ \{x := x\} \ \dots}{x = 0 \ \& \ \{x := x\} \ \ x = |x_0|} \Rightarrow \\ \hline \{ \text{if } x < 0 \\ \quad x = x_0 \quad \text{then } x := -x \quad x = |x_0| \\ \quad \text{else } x := x \} \end{array}$$

while rule

$$\frac{P \ \& \ b \ \{S\} \ P}{P \ \{\text{while } (b) \ S\} \ P \ \& \ \neg b}$$

while rule: example

$$\frac{P \ \& \ b \ \{ S \} \ P}{P \ \{ \text{while} \ (b) \ S \} \ P \ \& \ \neg b}$$

$s = 0; i = 0$

$\{ \text{while} \ (i < n) \{$
 $s := s+i;$
 $i := i+1;$

\Rightarrow

$$s = \sum_{j=0}^{i-1} j \ \& \ i = n$$

Comments on Hoare logic

- Proofs in Hoare logic are *almost* syntax-directed, *i.e.*, almost have the same shape as the program being proved.
 - The only exceptions are the uses of the rule of consequence.
- Applying Hoare rules is largely mechanical – given A and Q, most of the proof (including P) can be generated automatically.
 - Creativity is required mainly in determining the invariant in a while loop, because Q may not have the form “P & ¬b”.
 - A formula of that form needs to be found (after which the rule of consequence can be used, proving P & ¬b ⇒ Q).

Example: gcd algorithm

```
a > 0 & b > 0 & a=a0 & b=b0 {  
  while (a ≠ b)  
    if (a > b) then a := a - b;  
    else b := b - a;  
} a = gcd(a0, b0)
```