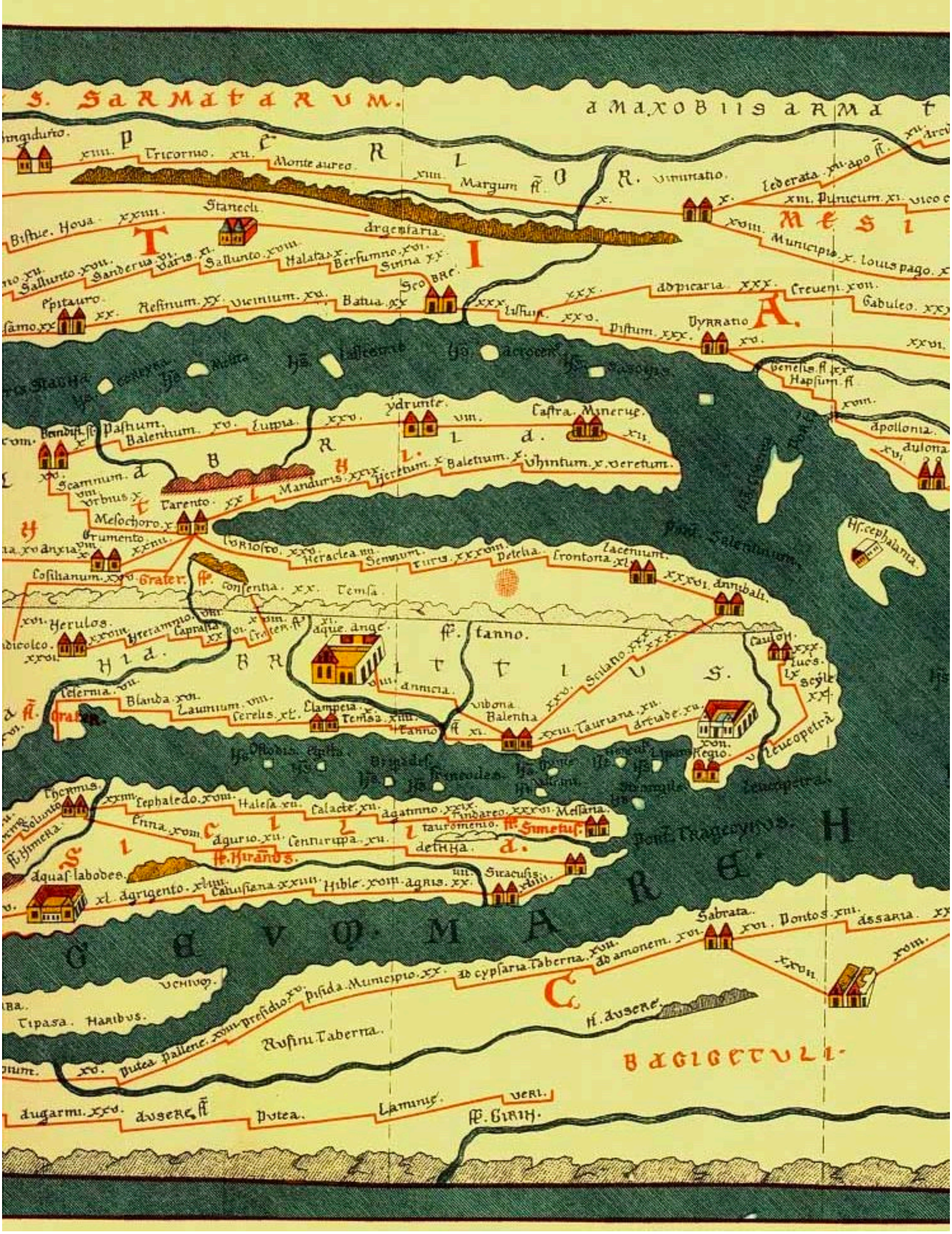
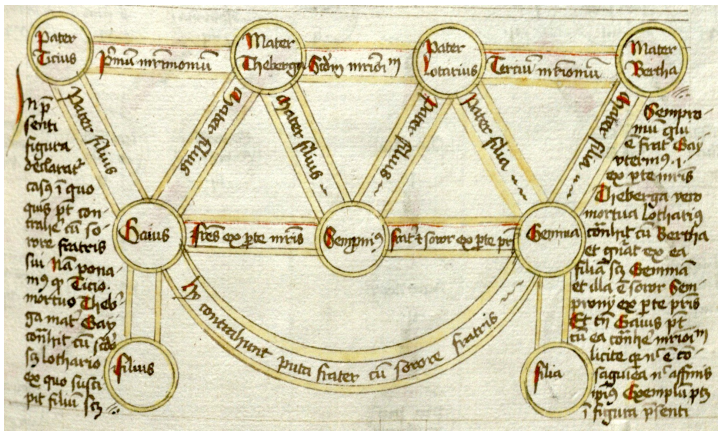
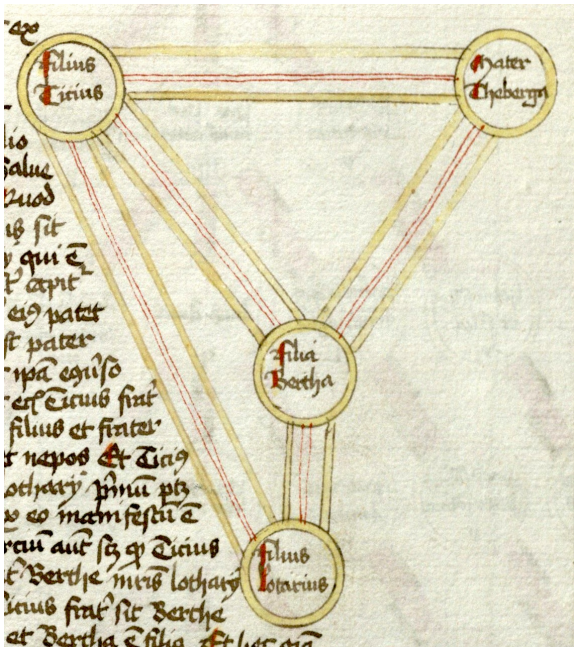
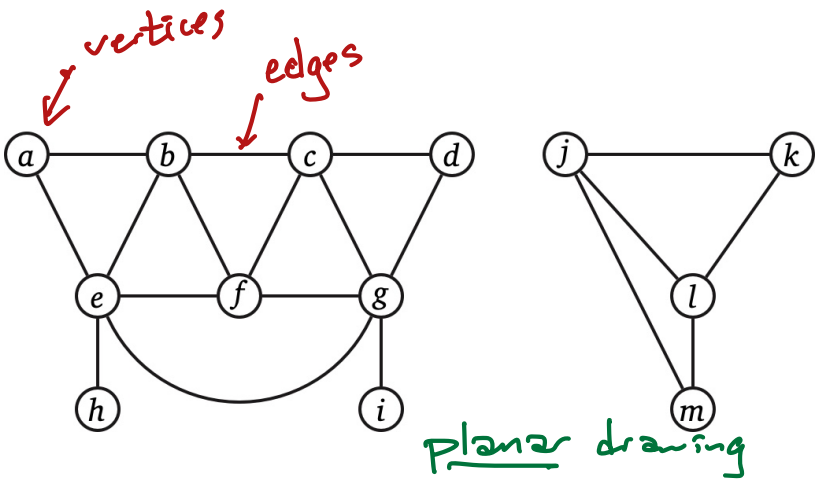

SARMATARUM.
AMAXOBII SARMAT
Tricornio
Monte aureo
Margum
Viminatio
Lederata
Punicum
Municipio
Stanecli
argentaria
Saldunto
Sanderua
Sallunto
Halata
Berfumno
Sinna
Pitauro
Aesinum
Vicinium
Batua
Scodra
Lissum
Pistum
Dyrratio
Apollonia
Castra Minerue
Ydrunte
Pasthum
Balentium
Lupia
Balentium
Uhintum
Veretum
Manduris
Scammum
Urbius
Tarento
Mesochoro
Grumento
Anxia
Cosilianum
Crater
Consentia
Temsa
Heraclea
Semnum
Turis
Petelia
Lacenium
Crontona
Annibali
Aque Ange
Tanno
Caulon
Scylle
Vibona Balentia
Blanda
Laumium
Cerelis
Clampeia
Taurlana
Regio
Leucopetra
Cephalledo
Thermis
Halesa
Calacte
Agatinno
Tindareo
Messana
Tauromenio
Simetus
Enna
Agurio
Centuripa
Dethna
Hirano
Aquas Labodes
Agrigento
Caluisiana
Hible
Agris
Siracusis
Sabrata
Pontos
Assaria
Ad amonem
Ad cypsaria Taberna
Pisida Municipio
Putea Pallene
Rusini Taberna
Tipasa
Haribus
Augarmi
Ausere
Putea
Lamnie
Veri
Girin
BAGIGETULI







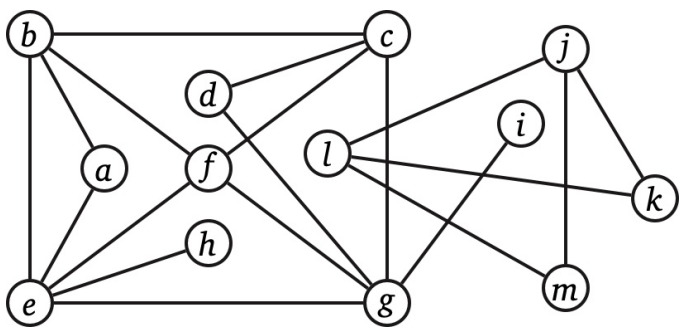
planar drawing

V — vertices
any finite nonempty set

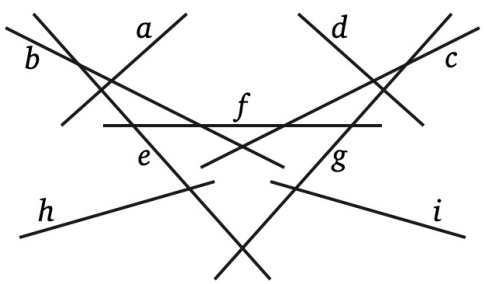
E — edges
= pairs of vertices

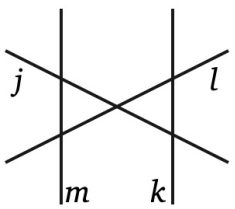
undirected: $\{u,v\} = uv = vu$

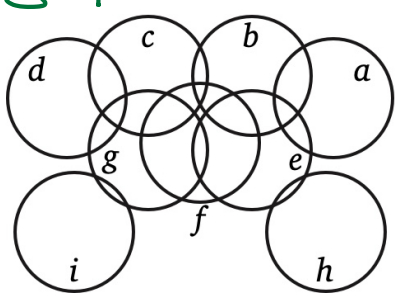
directed: $(u,v) = u \to v$

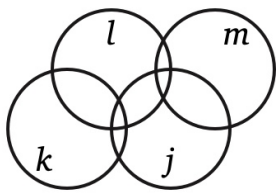


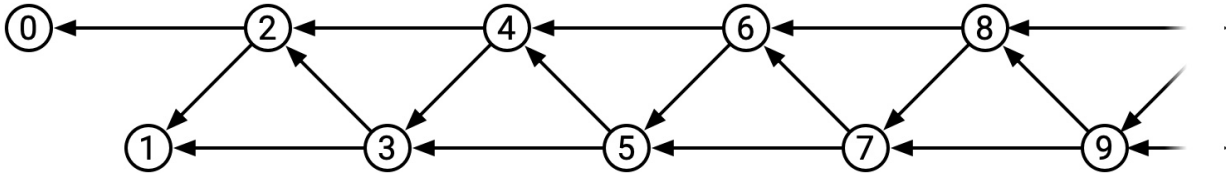
intersection graphs





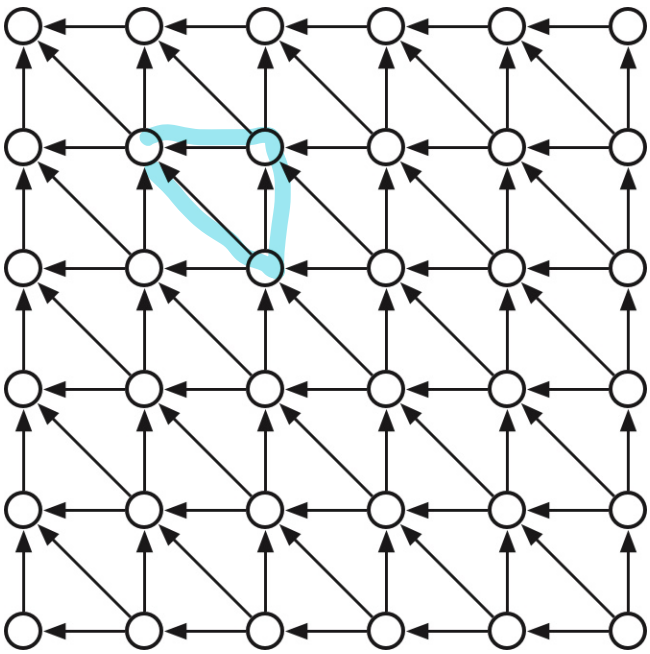




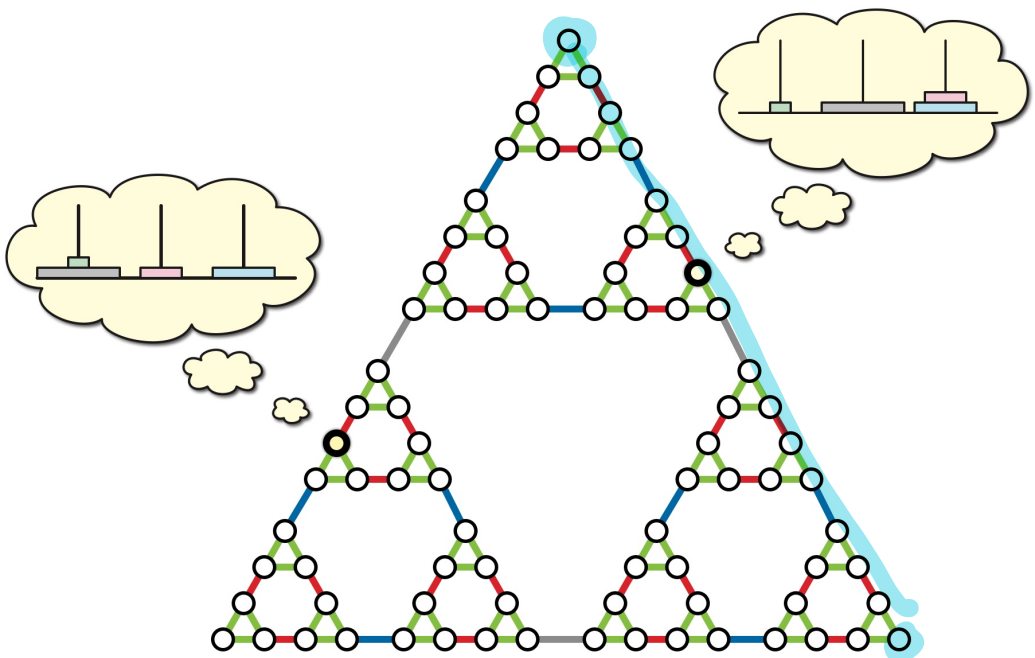


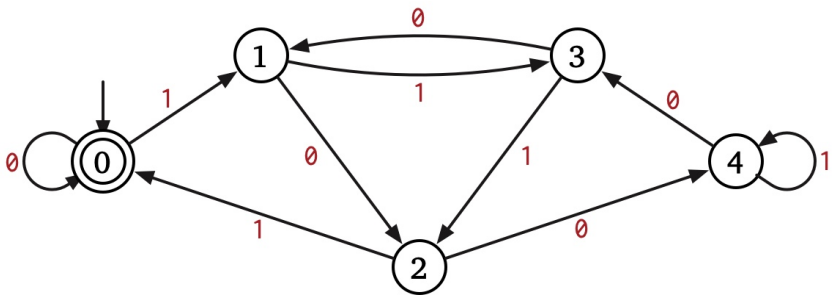
$F_n = F_{n-1} + F_{n-2}$

Edit distance $\Longrightarrow$



Directed acyclic graphs

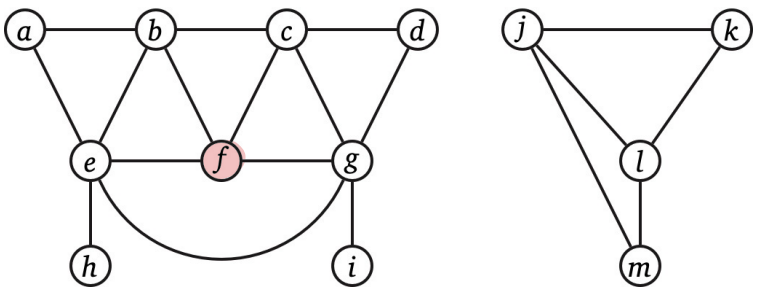


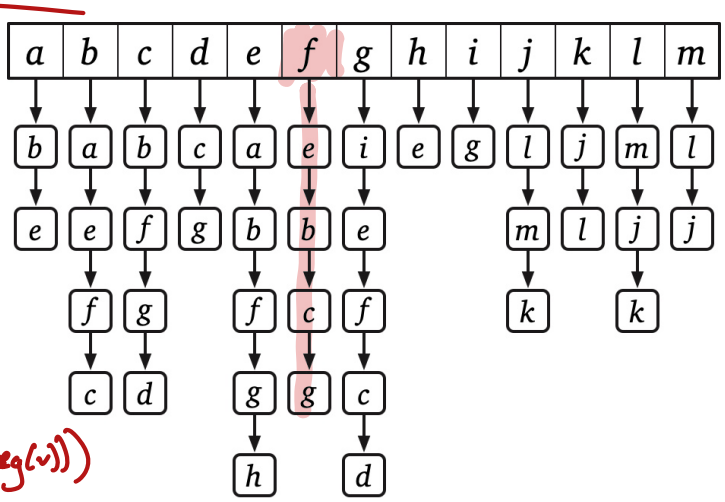


Data structures

v.color color[v]
v.mark mark[v]

DEFAULT:



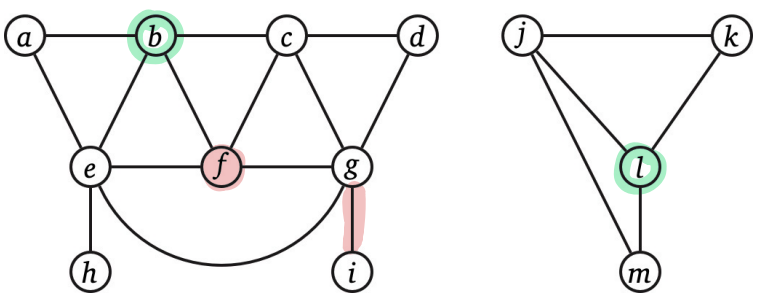


adjacency list

check if u∨e E $O(\min(\deg(u), \deg(v)))$

list all neighbors of v in $O(\deg(v))$

$O(V+E)$ space



	a	b	c	d	e	f	g	h	i	j	k	l	m
a	0	1	0	0	1	0	0	0	0	0	0	0	0
b	1	0	1	0	1	1	0	0	0	0	0	0	0
c	0	1	0	1	0	1	1	0	0	0	0	0	0
d	0	0	1	0	0	0	1	0	0	0	0	0	0
e	1	1	0	0	0	1	1	1	0	0	0	0	0
f	0	1	1	0	1	0	1	0	0	0	0	0	0
g	0	0	1	1	1	1	0	0	1	0	0	0	0
h	0	0	0	0	1	0	0	0	0	0	0	0	0
i	0	0	0	0	0	0	1	0	0	0	0	0	0
j	0	0	0	0	0	0	0	0	0	0	1	1	1
k	0	0	0	0	0	0	0	0	0	1	0	1	0
l	0	0	0	0	0	0	0	0	0	1	1	0	1
m	0	0	0	0	0	0	0	0	0	1	0	1	0

Adjacency matrix:

u∨e E? $O(1)$ time

list all neighbors of v $O(V)$ time

$O(V^2)$ space

Depth-first search

```
RecursiveDFS(v):
  if v is unmarked
      mark v
      for each edge vw
          RecursiveDFS(w)
```

```
IterativeDFS(s):
  Push(s)
  while the stack is not empty
      v ← Pop
      if v is unmarked
          mark v
          for each edge vw
              Push(w)
```

```
WhateverFirstSearch(s):
  put s into the bag
  while the bag is not empty
      take v from the bag
      if v is unmarked
          mark v
          for each edge vw
              put w into the bag
```

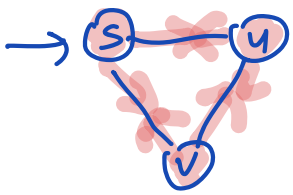
O(V+E)

insert
remove one
empty?

take v from the bag ⇐ O(E) times

mark v ⇐ O(V) times

put w into the bag ⇐ ** O(E) times



BAG: ~~s~~ ~~u~~ ~~v~~ u ~~s~~ s v

```
WhateverFirstSearch(s):
  put (∅, s) in bag
  while the bag is not empty
      take (p, v) from the bag                (⋆)
      if v is unmarked
          mark v
          parent(v) ← p
          for each edge vw                    (†)
              put (v, w) into the bag         (⋆⋆)
```

```
WFSALL(G):
  for all vertices v
      unmark v
  for all vertices v
      if v is unmarked
          WHATEVERFIRSTSEARCH(v)
```

```
COUNTCOMPONENTS(G):
  count ← 0
  for all vertices v
      unmark v
  for all vertices v
      if v is unmarked
          count ← count + 1
          WHATEVERFIRSTSEARCH(v)
  return count
```

O(V+E) time

```
COUNTANDLABEL(G):
  count ← 0
  for all vertices v
      unmark v
  for all vertices v
      if v is unmarked
          count ← count + 1
          LABELONE(v, count)
  return count
```

```
⟨⟨Label one component⟩⟩
LABELONE(v, count):
  while the bag is not empty
      take v from the bag
      if v is unmarked
          mark v
          comp(v) ← count
          for each edge vw
              put w into the bag
```