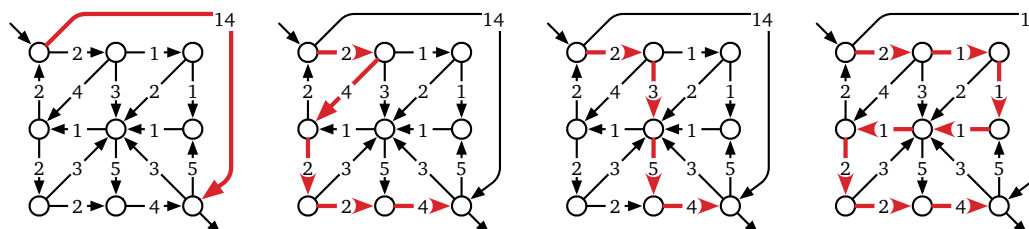


- 1 Although we typically speak of “the” shortest path between two nodes, a single graph could contain several minimum-length paths with the same endpoints.



Four (of many) equal-length shortest paths.

Describe and analyze an algorithm to determine the *number* of shortest paths from a source vertex s to a target vertex t in an arbitrary directed graph G with weighted edges. You may assume that all edge weights are positive and that all necessary arithmetic operations can be performed in $O(1)$ time.

(**Hint:** Compute shortest path distances from s to every other vertex. Throw away all edges that cannot be part of a shortest path from s to another vertex. What is left?)

Solution:

We start by computing shortest-path distances $dist(v)$ from s to v , for every vertex v , using Dijkstra’s algorithm. Call an edge $u \rightarrow v$ **tight** if $dist(u) + w(u \rightarrow v) = dist(v)$. Every edge in a shortest path from s to t must be tight. Conversely, every path from s to t that uses only tight edges has total length $dist(t)$ and is therefore a shortest path!

Let H be the subgraph of all tight edges in G . We can easily construct H in $O(V + E)$ time. Because all edge weights are positive, H is a directed acyclic graph. It remains only to count the number of paths from s to t in H .

For any vertex v , let $PathsToT(v)$ denote the number of paths in H from v to t ; we need to compute $PathsToT(s)$. This function satisfies the following simple recurrence:

$$PathsToT(v) = \begin{cases} 1 & \text{if } v = t \\ \sum_{v \rightarrow w} PathsToT(w) & \text{otherwise} \end{cases}$$

In particular, if v is a sink but $v \neq t$ (and thus there are no paths from v to t), this recurrence correctly gives us $PathsToT(v) = \sum \emptyset = 0$.

We can memoize this function into the graph itself, storing each value $PathsToT(v)$ at the corresponding vertex v . Since each subproblem depends only on its successors in H , we can compute $PathsToT(v)$ for all vertices v by considering the vertices in reverse topological order,

or equivalently, by performing a depth-first search of H starting at s . The resulting algorithm runs in $O(V + E)$ time.

The overall running time of the algorithm is dominated by Dijkstra's algorithm in the preprocessing phase, which runs in $O(E \log V)$ time.

Rubric: 10 points = 5 points for reduction to counting paths in a dag + 5 points for the path-counting algorithm (standard dynamic programming rubric)