Breadth First Search, Dijkstra’s Algorithm for Shortest Paths

Lecture 17
March 16
Part I

Breadth First Search
Breadth First Search (BFS)

Overview

(A) **BFS** is obtained from **BasicSearch** by processing edges using a data structure called a *queue*.
(B) It processes the vertices in the graph in the order of their shortest distance from the vertex *s* (the start vertex).

As such...

1. **DFS** good for exploring graph structure
2. **BFS** good for exploring *distances*
xkcd take on DFS

PREPARING FOR A DATE:
WHAT SITUATIONS MIGHT I PREPARE FOR?
1) MEDICAL EMERGENCY
2) DANCING
3) FOOD TOO EXPENSIVE

OKAY, WHAT KINDS OF EMERGENCIES CAN HAPPEN?
A) SNAKEBITE
B) LIGHTNING STROKE
C) FALL FROM CHAIR

HMM, WHICH SNAKES ARE DANGEROUS? LET'S SEE...
A) CORN SNAKE
B) DARTER SNAKE
C) COPPERHEAD

THE RESEARCH COMPARING SNAKE VENOMS IS SCATTERED AND INCONSISTENT. I'LL MAKE A SPREADSHEET TO ORGANIZE IT

I'M HERE TO PICK YOU UP. YOU'RE NOT DRESSED?

BY UD, THE INLAND TaIPAN HAS THE DEADIEST VENOM OF ANY SNAKE!

I REALLY NEED TO STOP USING DEPTH-FIRST SEARCHES.
A queue is a list of elements which supports the operations:

1. **enqueue**: Adds an element to the end of the list
2. **dequeue**: Removes an element from the front of the list

Elements are extracted in *first-in first-out (FIFO)* order, i.e., elements are picked in the order in which they were inserted.
BFS Algorithm

Given (undirected or directed) graph $G = (V, E)$ and node $s \in V$

BFS$(s)$
Mark all vertices as unvisited
Initialize search tree $T$ to be empty
Mark vertex $s$ as visited
set $Q$ to be the empty queue
enq$(s)$
while $Q$ is nonempty do
  $u = \text{deq}(Q)$
  for each vertex $v \in \text{Adj}(u)$
    if $v$ is not visited then
      add edge $(u, v)$ to $T$
      Mark $v$ as visited and enq$(v)$

Proposition

BFS$(s)$ runs in $O(n + m)$ time.
BFS: An Example in Undirected Graphs

1. \([1]\)
2. \([2,3]\)
3. \([3,4,5]\)
4. \([4,5,7,8]\)
5. \([5,7,8]\)
6. \([7,8,6]\)
7. \([8,6]\)
8. \([6]\)
9. \([]\)

BFS tree is the set of black edges.
BFS: An Example in Undirected Graphs


**BFS** tree is the set of black edges.
BFS: An Example in Undirected Graphs

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3. [3, 4, 5]  
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5. [5, 7, 8]  
6. [7, 8, 6]  
7. [8, 6]  
8. [6]  
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BFS tree is the set of black edges.

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BFS: An Example in Undirected Graphs


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BFS: An Example in Undirected Graphs

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9. []

BFS tree is the set of black edges.
BFS: An Example in Directed Graphs

A directed graph (also called a digraph) is \( G = (V, E) \), where
- \( V \) is a set of vertices or nodes
- \( E \subseteq V \times V \) is the set of ordered pairs of vertices called edges

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BFS with Distance

**BFS**$(s)$

Mark all vertices as unvisited; for each $v$ set $\text{dist}(v) = \infty$

Initialize search tree $T$ to be empty

Mark vertex $s$ as visited and set $\text{dist}(s) = 0$

set $Q$ to be the empty queue

$\text{enq}(s)$

while $Q$ is nonempty do

\[ u = \text{deq}(Q) \]

for each vertex $v \in \text{Adj}(u)$ do

if $v$ is not visited do

add edge $(u, v)$ to $T$

Mark $v$ as visited, $\text{enq}(v)$

and set $\text{dist}(v) = \text{dist}(u) + 1$
Properties of BFS: Undirected Graphs

Theorem

The following properties hold upon termination of BFS(s)

(A) The search tree contains exactly the set of vertices in the connected component of s.

(B) If dist(u) < dist(v) then u is visited before v.

(C) For every vertex u, dist(u) is the length of a shortest path (in terms of number of edges) from s to u.

(D) If u, v are in connected component of s and e = \{u, v\} is an edge of G, then |dist(u) − dist(v)| ≤ 1.
Properties of BFS: Directed Graphs

Theorem

The following properties hold upon termination of $\text{BFS}(s)$:

(A) The search tree contains exactly the set of vertices reachable from $s$

(B) If $\text{dist}(u) < \text{dist}(v)$ then $u$ is visited before $v$

(C) For every vertex $u$, $\text{dist}(u)$ is indeed the length of shortest path from $s$ to $u$

(D) If $u$ is reachable from $s$ and $e = (u, v)$ is an edge of $G$, then $\text{dist}(v) - \text{dist}(u) \leq 1$.

Not necessarily the case that $\text{dist}(u) - \text{dist}(v) \leq 1$. 
**BFS with Layers**

**BFSLayers**($s$):
Mark all vertices as unvisited and initialize $T$ to be empty
Mark $s$ as visited and set $L_0 = \{s\}$
$i = 0$
while $L_i$ is not empty do
    initialize $L_{i+1}$ to be an empty list
    for each $u$ in $L_i$ do
        for each edge $(u, v) \in \text{Adj}(u)$ do
            if $v$ is not visited
                mark $v$ as visited
                add $(u, v)$ to tree $T$
                add $v$ to $L_{i+1}$
    $i = i + 1$

Running time: $O(n + m)$
BFS with Layers

**BFS Layers**$(s)$:

- Mark all vertices as unvisited and initialize $T$ to be empty.
- Mark $s$ as visited and set $L_0 = \{s\}$
- $i = 0$

  while $L_i$ is not empty do

    initialize $L_{i+1}$ to be an empty list

    for each $u$ in $L_i$ do

      for each edge $(u, v) \in \text{Adj}(u)$ do

        if $v$ is not visited

          mark $v$ as visited

          add $(u, v)$ to tree $T$

        add $v$ to $L_{i+1}$

    $i = i + 1$

Running time: $O(n + m)$
The following properties hold on termination of \texttt{BFSLayers}(s).

1. \texttt{BFSLayers}(s) outputs a \textbf{BFS} tree.
2. \(L_i\) is the set of vertices at distance exactly \(i\) from \(s\).
3. If \(G\) is undirected, each edge \(e = \{u, v\}\) is one of three types:
   
   1. \textit{tree} edge between two consecutive layers
   2. non-tree \textit{forward/backward} edge between two consecutive layers
   3. non-tree \textit{cross-edge} with both \(u, v\) in same layer
   4. \(\implies\) Every edge in the graph is either between two vertices that are either (i) in the same layer, or (ii) in two consecutive layers.
A directed graph (also called a digraph) is $G = (V, E)$, where $V$ is a set of vertices or nodes and $E \subseteq V \times V$ is a set of ordered pairs of vertices called edges.
Proposition

The following properties hold on termination of $\text{BFSLayers}(s)$, if $G$ is directed.

For each edge $e = (u, v)$ is one of four types:

1. a **tree** edge between consecutive layers, $u \in L_i$, $v \in L_{i+1}$ for some $i \geq 0$
2. a non-tree **forward** edge between consecutive layers
3. a non-tree **backward** edge
4. a **cross-edge** with both $u$, $v$ in same layer
Part II

Shortest Paths and Dijkstra’s Algorithm
Shortest Path Problems

Input A (undirected or directed) graph \( G = (V, E) \) with edge lengths (or costs). For edge \( e = (u, v) \), 
\[ \ell(e) = \ell(u, v) \] is its length.

1. Given nodes \( s, t \) find shortest path from \( s \) to \( t \).
2. Given node \( s \) find shortest path from \( s \) to all other nodes.
3. Find shortest paths for all pairs of nodes.

Many applications!
Shortest Path Problems

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Many applications!
Single-Source Shortest Paths:
Non-Negative Edge Lengths

Single-Source Shortest Path Problems

1. Input: A (undirected or directed) graph \( G = (V, E) \) with non-negative edge lengths. For edge \( e = (u, v) \), \( \ell(e) = \ell(u, v) \) is its length.

2. Given nodes \( s, t \) find shortest path from \( s \) to \( t \).

3. Given node \( s \) find shortest path from \( s \) to all other nodes.

Restrict attention to directed graphs

Undirected graph problem can be reduced to directed graph problem - how?

1. Given undirected graph \( G \), create a new directed graph \( G' \) by replacing each edge \( \{u, v\} \) in \( G \) by \( (u, v) \) and \( (v, u) \) in \( G' \).

2. set \( \ell(u, v) = \ell(v, u) = \ell(\{u, v\}) \)

3. Exercise: show reduction works. Relies on non-negativity!
## Single-Source Shortest Path Problems

1. **Input:** A (undirected or directed) graph $G = (V, E)$ with non-negative edge lengths. For edge $e = (u, v)$, $\ell(e) = \ell(u, v)$ is its length.

2. **Given nodes $s, t$:** find shortest path from $s$ to $t$.

3. **Given node $s$:** find shortest path from $s$ to all other nodes.

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1. Restrict attention to directed graphs

2. Undirected graph problem can be reduced to directed graph problem - how?

   1. Given undirected graph $G$, create a new directed graph $G'$ by replacing each edge $\{u, v\}$ in $G$ by $(u, v)$ and $(v, u)$ in $G'$.
   
   2. Set $\ell(u, v) = \ell(v, u) = \ell(\{u, v\})$

   3. Exercise: show reduction works. Relies on non-negativity!
# Single-Source Shortest Paths: Non-Negative Edge Lengths

## Single-Source Shortest Path Problems

1. **Input:** A (undirected or directed) graph $G = (V, E)$ with non-negative edge lengths. For edge $e = (u, v)$, $\ell(e) = \ell(u, v)$ is its length.

2. **Given nodes** $s, t$ find shortest path from $s$ to $t$.

3. **Given node** $s$ find shortest path from $s$ to all other nodes.

### Restrict attention to directed graphs

### Undirected graph problem can be reduced to directed graph problem - how?

1. Given undirected graph $G$, create a new directed graph $G'$ by replacing each edge $\{u, v\}$ in $G$ by $(u, v)$ and $(v, u)$ in $G'$.

2. Set $\ell(u, v) = \ell(v, u) = \ell(\{u, v\})$

3. **Exercise:** show reduction works. Relies on non-negativity!
**Special case:** All edge lengths are 1.

1. Run **BFS**($s$) to get shortest path distances from $s$ to all other nodes.
2. $O(m + n)$ time algorithm.

**Special case:** Suppose $\ell(e)$ is an integer for all $e$? Can we use **BFS**? Reduce to unit edge-length problem by placing $\ell(e) - 1$ dummy nodes on $e$.

Let $L = \max_e \ell(e)$. New graph has $O(mL)$ edges and $O(mL + n)$ nodes. **BFS** takes $O(mL + n)$ time. Not efficient if $L$ is large.
**Single-Source Shortest Paths via BFS**

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Towards an algorithm

Why does **BFS** work?

**BFS**($s$) explores nodes in increasing distance from $s$

### Lemma

Let $G$ be a directed graph with non-negative edge lengths. Let $\text{dist}(s, v)$ denote the shortest path length from $s$ to $v$. If $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_k$ is a shortest path from $s$ to $v_k$, then for $1 \leq i < k$:

1. $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$ is a shortest path from $s$ to $v_i$
2. $\text{dist}(s, v_i) \leq \text{dist}(s, v_k)$. Relies on non-neg edge lengths.

### Proof.

Suppose not. Then for some $i < k$ there is a path $P'$ from $s$ to $v_i$ of length strictly less than that of $s = v_0 \rightarrow v_1 \rightarrow \ldots \rightarrow v_i$. Then $P'$
Towards an algorithm

Why does **BFS** work?

**BFS(s)** explores nodes in increasing distance from **s**

**Lemma**

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1. s = v_0 \to v_1 \to v_2 \to \ldots \to v_i is a shortest path from **s** to **v_i**
2. dist \((s, v_i)\) \leq dist \((s, v_k)\). Relies on non-neg edge lengths.

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Suppose not. Then for some \( i < k \) there is a path \( P' \) from **s** to **v_i** of length strictly less than that of s = v_0 \to v_1 \to \ldots \to v_i. Then \( P' \)
Towards an algorithm

Why does BFS work?
BFS(s) explores nodes in increasing distance from s

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Towards an algorithm

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2. $\text{dist}(s, v_i) \leq \text{dist}(s, v_k)$. Relies on non-neg edge lengths.

Proof.

Suppose not. Then for some $i < k$ there is a path $P'$ from $s$ to $v_i$ of length strictly less than that of $s = v_0 \rightarrow v_1 \rightarrow \ldots \rightarrow v_i$. Then $P'$ concatenated with $v_i \rightarrow v_{i+1} \ldots \rightarrow v_k$ contains a strictly shorter path to $v_k$ than $s = v_0 \rightarrow v_1 \ldots \rightarrow v_k$. For the second part, observe that edge lengths are non-negative.
A proof by picture

$s = v_0$

Shortest path from $v_0$ to $v_6$
A proof by picture

Shorter path from $v_0$ to $v_4$

$s = v_0$

Shortest path from $v_0$ to $v_6$
A proof by picture

$s = v_0$

A shorter path from $v_0$ to $v_6$. A contradiction.

Shortest path from $v_0$ to $v_6$
A Basic Strategy

Explore vertices in increasing order of distance from $s$: (For simplicity assume that nodes are at different distances from $s$ and that no edge has zero length)

Initialize for each node $v$, $\text{dist}(s, v) = \infty$
Initialize $X = \{s\}$,
for $i = 2$ to $|\mathcal{V}|$ do

(* Invariant: $X$ contains the $i - 1$ closest nodes to $s$ *)
Among nodes in $\mathcal{V} - X$, find the node $v$ that is the $i$'th closest to $s$
Update $\text{dist}(s, v)$
$X = X \cup \{v\}$

How can we implement the step in the for loop?
A Basic Strategy

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(For simplicity assume that nodes are at different distances from $s$
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Initialize $X = \{s\}$,
for $i = 2$ to $|V|$ do
(* Invariant: $X$ contains the $i-1$ closest nodes to $s$ *)
Among nodes in $V - X$, find the node $v$ that is the
$i$'th closest to $s$
Update $\text{dist}(s, v)$
$X = X \cup \{v\}$

How can we implement the step in the for loop?
Finding the $i$th closest node

1. $X$ contains the $i - 1$ closest nodes to $s$
2. Want to find the $i$th closest node from $V - X$.

What do we know about the $i$th closest node?

**Claim**

Let $P$ be a shortest path from $s$ to $v$ where $v$ is the $i$th closest node. Then, all intermediate nodes in $P$ belong to $X$.

**Proof.**

If $P$ had an intermediate node $u$ not in $X$ then $u$ will be closer to $s$ than $v$. Implies $v$ is not the $i$’th closest node to $s$ - recall that $X$ already has the $i - 1$ closest nodes.
Finding the $i$th closest node

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Finding the $i$th closest node repeatedly

An example
Finding the $i$th closest node repeatedly

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An example
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An example

Sariel Har-Peled (UIUC)
Finding the $i$th closest node repeatedly

An example
Finding the $i$th closest node

Corollary

*The $i$th closest node is adjacent to $X$.*
Finding the $i$th closest node

1. $X$ contains the $i - 1$ closest nodes to $s$
2. Want to find the $i$th closest node from $V - X$.

1. For each $u \in V - X$ let $P(s, u, X)$ be a shortest path from $s$ to $u$ using only nodes in $X$ as intermediate vertices.
2. Let $d'(s, u)$ be the length of $P(s, u, X)$

Observations: for each $u \in V - X$,

1. $\text{dist}(s, u) \leq d'(s, u)$ since we are constraining the paths
2. $d'(s, u) = \min_{t \in X} (\text{dist}(s, t) + \ell(t, u))$ - Why?

Lemma

If $v$ is the $i$th closest node to $s$, then $d'(s, v) = \text{dist}(s, v)$. 
Finding the $i$th closest node

1. $X$ contains the $i - 1$ closest nodes to $s$
2. Want to find the $i$th closest node from $V - X$.

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1. $X$ contains the $i - 1$ closest nodes to $s$
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For each $u \in V - X$ let $P(s, u, X)$ be a shortest path from $s$ to $u$ using only nodes in $X$ as intermediate vertices.

Let $d'(s, u)$ be the length of $P(s, u, X)$

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Lemma

*If $v$ is the $i$th closest node to $s$, then $d'(s, v) = \text{dist}(s, v)$.*
Finding the $i$th closest node

**Lemma**

Given:

1. $X$: Set of $i - 1$ closest nodes to $s$.
2. $d'(s, u) = \min_{t \in X} (\text{dist}(s, t) + \ell(t, u))$

If $v$ is an $i$th closest node to $s$, then $d'(s, v) = \text{dist}(s, v)$.

**Proof.**

Let $v$ be the $i$th closest node to $s$. Then there is a shortest path $P$ from $s$ to $v$ that contains only nodes in $X$ as intermediate nodes (see previous claim). Therefore $d'(s, v) = \text{dist}(s, v)$. \[\square\]
Finding the $i$th closest node

**Lemma**

If $v$ is an $i$th closest node to $s$, then $d'(s, v) = \text{dist}(s, v)$.

**Corollary**

The $i$th closest node to $s$ is the node $v \in V - X$ such that $d'(s, v) = \min_{u \in V - X} d'(s, u)$.

**Proof.**

For every node $u \in V - X$, $\text{dist}(s, u) \leq d'(s, u)$ and for the $i$th closest node $v$, $\text{dist}(s, v) = d'(s, v)$. Moreover, $\text{dist}(s, u) \geq \text{dist}(s, v)$ for each $u \in V - X$. \[\square\]
Algorithm

Initialize for each node \( v \): \( \text{dist}(s, v) = \infty \)
Initialize \( X = \emptyset \), \( d'(s, s) = 0 \)

for \( i = 1 \) to \( |V| \) do

(* Invariant: \( X \) contains the \( i - 1 \) closest nodes to \( s \) *)
(* Invariant: \( d'(s, u) \) is shortest path distance from \( u \) to \( s \) using only \( X \) as intermediate nodes*)

Let \( v \) be such that \( d'(s, v) = \min_{u \in V - X} d'(s, u) \)
\( \text{dist}(s, v) = d'(s, v) \)
\( X = X \cup \{v\} \)

for each node \( u \) in \( V - X \) do

\( d'(s, u) = \min_{t \in X} \left( \text{dist}(s, t) + \ell(t, u) \right) \)

Correctness: By induction on \( i \) using previous lemmas.

Running time: \( O(n \cdot (n + m)) \) time.

4 \( n \) outer iterations. In each iteration, \( d'(s, u) \) for each \( u \) by scanning all edges out of nodes in \( X \); \( O(m + n) \) time/iteration.
Algorithm

Initialize for each node \( v \): \( \text{dist}(s, v) = \infty \)

Initialize \( X = \emptyset, \ d'(s, s) = 0 \)

for \( i = 1 \) to \( |V| \) do

(* Invariant: \( X \) contains the \( i - 1 \) closest nodes to \( s \) *)

(* Invariant: \( d'(s, u) \) is shortest path distance from \( u \) to \( s \) using only \( X \) as intermediate nodes*)

Let \( v \) be such that \( d'(s, v) = \min_{u \in V \setminus X} d'(s, u) \)

\( \text{dist}(s, v) = d'(s, v) \)

\( X = X \cup \{v\} \)

for each node \( u \) in \( V \setminus X \) do

\[ d'(s, u) = \min_{t \in X} \left( \text{dist}(s, t) + \ell(t, u) \right) \]

Correctness: By induction on \( i \) using previous lemmas.

Running time: \( O(n \cdot (n + m)) \) time.

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Algorithm

Initialize for each node $v$: $\text{dist}(s, v) = \infty$

Initialize $X = \emptyset$, $d'(s, s) = 0$

for $i = 1$ to $|V|$ do

(* Invariant: $X$ contains the $i-1$ closest nodes to $s$ *)

(* Invariant: $d'(s, u)$ is shortest path distance from $u$ to $s$ using only $X$ as intermediate nodes*)

Let $v$ be such that $d'(s, v) = \min_{u \in V - X} d'(s, u)$

$\text{dist}(s, v) = d'(s, v)$

$X = X \cup \{v\}$

for each node $u$ in $V - X$ do

$d'(s, u) = \min_{t \in X} \left( \text{dist}(s, t) + \ell(t, u) \right)$

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Example
Example
Example
Example
Example
Example
Example

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{example.png}
\caption{Example Graph}
\end{figure}
Improved Algorithm

1. Main work is to compute the $d'(s, u)$ values in each iteration.
2. $d'(s, u)$ changes from iteration $i$ to $i + 1$ only because of the node $v$ that is added to $X$ in iteration $i$.

```
Initialize for each node $v$, $\text{dist}(s, v) = d'(s, v) = \infty$
Initialize $X = \emptyset$, $d'(s, s) = 0$
for $i = 1$ to $|V|$ do
  // $X$ contains the $i - 1$ closest nodes to $s$,
  // and the values of $d'(s, u)$ are current
  Let $v$ be node realizing $d'(s, v) = \min_{u \in V - X} d'(s, u)$
  $\text{dist}(s, v) = d'(s, v)$
  $X = X \cup \{v\}$
  Update $d'(s, u)$ for each $u$ in $V - X$ as follows:
  \[
  d'(s, u) = \min \left( d'(s, u), \text{dist}(s, v) + \ell(v, u) \right)
  \]
```

Running time: $O(m + n^2)$ time.

1. $n$ outer iterations and in each iteration following steps
2. updating $d'(s, u)$ after $v$ is added takes $O(\deg(v))$ time so
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Update $d'(s, u)$ for each $u$ in $V - X$ as follows:

$$d'(s, u) = \min \left( d'(s, u), \text{dist}(s, v) + \ell(v, u) \right)$$

Running time: $O(m + n^2)$ time.

1. $n$ outer iterations and in each iteration following steps

2. updating $d'(s, u)$ after $v$ is added takes $O(\text{deg}(v))$ time so total work is $O(m)$ since a node enters $X$ only once

3. Finding $v$ from $d'(s, u)$ values is $O(n)$ time
Dijkstra’s Algorithm

1. eliminate $d'(s, u)$ and let $dist(s, u)$ maintain it
2. update $dist$ values after adding $v$ by scanning edges out of $v$

Initialize for each node $v$, $dist(s, v) = \infty$
Initialize $X = \emptyset$, $dist(s, s) = 0$
for $i = 1$ to $|V|$ do
    Let $v$ be such that $dist(s, v) = \min_{u \in V - X} dist(s, u)$
    $X = X \cup \{v\}$
    for each $u$ in $\text{Adj}(v)$ do
        $dist(s, u) = \min(dist(s, u), dist(s, v) + \ell(v, u))$

Priority Queues to maintain $dist$ values for faster running time

1. Using heaps and standard priority queues: $O((m + n) \log n)$
2. Using Fibonacci heaps: $O(m + n \log n)$.
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1. eliminate $d'(s, u)$ and let $\text{dist}(s, u)$ maintain it
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Priority Queues to maintain $\text{dist}$ values for faster running time

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Priority Queues

Data structure to store a set $S$ of $n$ elements where each element $v \in S$ has an associated real/integer key $k(v)$ such that the following operations:

1. **makePQ**: create an empty queue.
2. **findMin**: find the minimum key in $S$.
3. **extractMin**: Remove $v \in S$ with smallest key and return it.
4. **insert($v$, $k(v)$)**: Add new element $v$ with key $k(v)$ to $S$.
5. **delete($v$)**: Remove element $v$ from $S$.
6. **decreaseKey($v$, $k'(v)$)**: decrease key of $v$ from $k(v)$ (current key) to $k'(v)$ (new key). Assumption: $k'(v) \leq k(v)$.
7. **meld**: merge two separate priority queues into one.

All operations can be performed in $O(\log n)$ time. 

**decreaseKey** is implemented via **delete** and **insert**.
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All operations can be performed in $O(\log n)$ time.

**decreaseKey** is implemented via **delete** and **insert**.
Dijkstra’s Algorithm using Priority Queues

\[
\begin{align*}
Q & \leftarrow \text{makePQ}() \\
\text{insert}(Q, (s, 0)) \\
\text{for each node } u \neq s \text{ do} \\
& \quad \text{insert}(Q, (u, \infty)) \\
X & \leftarrow \emptyset \\
\text{for } i = 1 \text{ to } |V| \text{ do} \\
& \quad (v, \text{dist}(s, v)) = \text{extractMin}(Q) \\
& \quad X = X \cup \{v\} \\
& \quad \text{for each } u \text{ in } \text{Adj}(v) \text{ do} \\
& \quad \quad \text{decreaseKey}\left(Q, (u, \min(\text{dist}(s, u), \text{dist}(s, v) + \ell(v, u)))\right).
\end{align*}
\]

Priority Queue operations:

1. \(O(n)\) \text{ insert} operations
2. \(O(n)\) \text{ extractMin} operations
3. \(O(m)\) \text{ decreaseKey} operations
Implementing Priority Queues via Heaps

Using Heaps

Store elements in a heap based on the key value

1. All operations can be done in $O(\log n)$ time

Dijkstra’s algorithm can be implemented in $O((n + m) \log n)$ time.
Implementing Priority Queues via Heaps

Using Heaps

- Store elements in a heap based on the key value
- All operations can be done in \( O(\log n) \) time

Dijkstra’s algorithm can be implemented in \( O((n + m) \log n) \) time.
Fibonacci Heaps

1. \texttt{extractMin}, \texttt{insert}, \texttt{delete}, \texttt{meld} in $O(\log n)$ time
2. \texttt{decreaseKey} in $O(1)$ \textit{amortized} time: $\ell$ \texttt{decreaseKey} operations for $\ell \geq n$ take together $O(\ell)$ time
3. Relaxed Heaps: \texttt{decreaseKey} in $O(1)$ worst case time but at the expense of \texttt{meld} (not necessary for Dijkstra’s algorithm)

1. Dijkstra’s algorithm can be implemented in $O(n \log n + m)$ time. If $m = \Omega(n \log n)$, running time is linear in input size.
2. Data structures are complicated to analyze/implement. Recent work has obtained data structures that are easier to analyze and implement, and perform well in practice. Rank-Pairing Heaps (European Symposium on Algorithms, September 2009!)
Fibonacci Heaps

1. **extractMin, insert, delete, meld** in $O(\log n)$ time
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Priority Queues: Fibonacci Heaps/Relaxed Heaps

**Fibonacci Heaps**

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### Fibonacci Heaps

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Shortest Path Tree

Dijkstra’s algorithm finds the shortest path distances from \( s \) to \( V \).

**Question:** How do we find the paths themselves?

```
Q = makePQ()
insert(Q, (s, 0))
prev(s) ← null
for each node \( u \neq s \) do
  insert(Q, (u, ∞))
  prev(u) ← null
X = ∅
for \( i = 1 \) to \(|V|\) do
  \((v, dist(s, v)) = extractMin(Q)\)
  \(X = X \cup \{v\}\)
  for each \( u \) in \( \text{Adj}(v) \) do
    if \((dist(s, v) + ℓ(v, u) < dist(s, u))\) then
      decreaseKey(Q, (u, dist(s, v) + ℓ(v, u)))
      prev(u) = v
```
Dijkstra’s algorithm finds the shortest path distances from s to V.

**Question:** How do we find the paths themselves?

\[
\begin{align*}
Q &= \text{makePQ}() \\
\text{insert}(Q, (s, 0)) &\\
\text{prev}(s) &\leftarrow \text{null} \\
\text{for each node } u \neq s \text{ do} &\\
\text{insert}(Q, (u, \infty)) &\\
\text{prev}(u) &\leftarrow \text{null}
\end{align*}
\]

\[
\begin{align*}
X &= \emptyset \\
\text{for } i = 1 \text{ to } |V| \text{ do} &\\
(v, \text{dist}(s, v)) &= \text{extractMin}(Q) \\
X &= X \cup \{v\} \\
\text{for each } u \text{ in } \text{Adj}(v) \text{ do} &\\
\text{if } (\text{dist}(s, v) + \ell(v, u) < \text{dist}(s, u)) \text{ then} &\\
&\text{decreaseKey}(Q, (u, \text{dist}(s, v) + \ell(v, u))) \\
&\text{prev}(u) = v
\end{align*}
\]
Lemma

The edge set \((u, \text{prev}(u))\) is the reverse of a shortest path tree rooted at \(s\). For each \(u\), the reverse of the path from \(u\) to \(s\) in the tree is a shortest path from \(s\) to \(u\).

Proof Sketch.

1. The edge set \(\{(u, \text{prev}(u)) \mid u \in V\}\) induces a directed in-tree rooted at \(s\) (Why?)

2. Use induction on \(|X|\) to argue that the tree is a shortest path tree for nodes in \(V\).
Shortest paths to $s$

Dijkstra’s algorithm gives shortest paths from $s$ to all nodes in $V$. How do we find shortest paths from all of $V$ to $s$?

1. In undirected graphs shortest path from $s$ to $u$ is a shortest path from $u$ to $s$ so there is no need to distinguish.
2. In directed graphs, use Dijkstra’s algorithm in $G^{rev}$!
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2. In directed graphs, use Dijkstra’s algorithm in $G^{rev}$!
Shortest paths between sets of nodes

Suppose we are given $S \subset V$ and $T \subset V$. Want to find shortest path from $S$ to $T$ defined as:

$$\text{dist}(S, T) = \min_{s \in S, t \in T} \text{dist}(s, t)$$

How do we find $\text{dist}(S, T)$?
You want to go from your house to a friend’s house. Need to pick up some dessert along the way and hence need to stop at one of the many potential stores along the way. How do you calculate the “shortest” trip if you include this stop?

Given $G = (V, E)$ and edge lengths $\ell(e), e \in E$. Want to go from $s$ to $t$. A subset $X \subset V$ that corresponds to stores. Want to find $\min_{x \in X} d(s, x) + d(x, t)$.

Basic solution: Compute for each $x \in X$, $d(s, x)$ and $d(x, t)$ and take minimum. $2|X|$ shortest path computations. $O(|X|(m + n \log n))$.

Better solution: Compute shortest path distances from $s$ to every node $v \in V$ with one Dijkstra. Compute from every node $v \in V$ shortest path distance to $t$ with one Dijkstra.
Example Problem

You want to go from your house to a friend’s house. Need to pick up some dessert along the way and hence need to stop at one of the many potential stores along the way. How do you calculate the “shortest” trip if you include this stop?

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