

No computers, calculators, or books allowed.

Choose closest solution.

You may take with you two "cheat sheets" - two sheets of size 8.5" x 11" or smaller.

1. **True or False** A permutation matrix merely reorders the components of a vector and does not change their values, so it preserves the vector 1-norm. (T)
2. **True or False** A shortcoming of normal equations to solve the least square problems is that sensitivity of solution will worsen since $\text{cond}(\mathbf{A}^T \mathbf{A}) = [\text{cond}(\mathbf{A})]^2$ (T)
3. **True or False** The inverse of a tri-diagonal matrix is also tri-diagonal. (False)
4. **True or False** If \mathbf{A} is symmetric and positive definite, then Gaussian elimination without pivoting applied to the linear system $\mathbf{Ax} = \mathbf{b}$ is backwards stable. (True)
5. **True or False** Initial value Ordinary Differential Equation problems always have unique solution (F)
6. **True or False** For a **continuous** function on a fixed interval, the interpolating polynomial based on equally spaced points always converges to the function as the number of interpolating points increases. (F)
7. **True or False** The following loop terminates when $x = 1.0$.

```
x = 0.0;
while x ~ = 1.0
    x = x + 0.1;
    disp(x)
end
```

(F)

8. The product of the interval "numbers" $[-2, 3] * [4, 5]$ is
 - (a) $[8, 15]$
 - (b) $[-10, 15]$ (*)
 - (c) $[-12, 15]$
 - (d) $[-2, 5]$

9. The function $f : \mathbb{R} \rightarrow \mathbb{R}$ defined by $f(x) = x^4$ is

- (a) a Bijection
- (b) a Injection
- (c) a Surjection
- (d) none of the above (*)

The following are “mathematically equivalent” expressions for $x \in [-1, 1)$:

- (i) $\sqrt{1+x} - \sqrt{1-x}$
- (ii) $(\sqrt{1+x}/\sqrt{1-x} - 1)(\sqrt{1-x})$
- (iii) $\frac{2x}{\sqrt{1+x} + \sqrt{1-x}}$

10. Which of the following is true under IEEE double precision arithmetic?

- (a) For x near 0, expression (i) will be typically more accurate.
- (b) For x near 0, expression (ii) will be typically more accurate.
- (c) For x near 0, expression (iii) will be typically more accurate. (*)
- (d) All three will produce same result for $|x| < \epsilon_{\text{mach}}$

11. Let $F(\mathbf{x}) : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a differentiable function and $J_F|_{\mathbf{x}}$ be its Jacobian evaluated at the point $\mathbf{x} \in \mathbb{R}^n$. Which of the following gives the the first two terms of the Taylor series expansion of $F(\mathbf{y})$ about the point \mathbf{x} ?

- (a) $F(\mathbf{y}) \approx F(\mathbf{x}) - J_F|_{\mathbf{x}}(\mathbf{y} - \mathbf{x})$
- (b) $F(\mathbf{y}) \approx F(\mathbf{x}) + J_F|_{\mathbf{y}}(\mathbf{y} - \mathbf{x})$
- (c) $F(\mathbf{y}) \approx F(\mathbf{x}) + J_F|_{\mathbf{x}}(\mathbf{y} - \mathbf{x})$ (*)
- (d) $F(\mathbf{y}) \approx F(\mathbf{x}) + \frac{1}{2} J_F|_{\mathbf{x}}(\mathbf{y} - \mathbf{x})$

12. We approximate an infinitely differentiable function $f(x) : \mathbb{R} \rightarrow \mathbb{R}$ with a Taylor series until order 4 (5 terms) at $x = 0$. What is the maximum error for x near zero in Big O notation?

- (a) $\mathcal{O}(x^4)$
- (b) $\mathcal{O}(x^5)$ (*)
- (c) $\mathcal{O}(x^6)$
- (d) $\mathcal{O}(x^{10})$

13. The iterative solution using Newton's method to find a root of a system of non-linear equations is subject to

- (a) round-off error
- (b) truncation error
- (c) none of these
- (d) both 1 and 2 (*)

14. Consider the function

$$f(\mathbf{x}) = \begin{bmatrix} 3x_1^2 + 2x_2 \\ x_2 + 1 \end{bmatrix}.$$

Apply one iteration of Newton's method with initial guess $\mathbf{x}_0 = [1, 2]^T$. What is \mathbf{x}_1 ?

- (a) $[\frac{7}{6}, 5]^T$
- (b) $[\frac{5}{6}, -1]^T$ (*)
- (c) $[\frac{7}{6}, -1]^T$
- (d) $[\sqrt{\frac{2}{3}}, -1]^T$

15. Consider the function

$$f(x) = 1 - 3x^2$$

Apply one iteration of the secant method with initial guesses $x_0 = 0$ and $x_1 = 1$. What is x_2 ?

- (a) $-\frac{1}{3}$
- (b) 0
- (c) $\frac{1}{3}$ (*)
- (d) $\frac{5}{3}$

16. Which root finding method is the following algorithm representing

```
1 initialize:  $x_1 = \dots$ 
2 for  $k = 2, 3, \dots$ 
3  $x_k = x_{k-1} - f(x_{k-1})/f'(x_{k-1})$ 
4 if converged, stop
5 end
```

- (a) Bisection method
- (b) Secants method
- (c) Newton's method(*)

17. What is one advantage of the bisection method over the secant method?
- (a) Assuming the initial interval brackets a root, the bisection method guaranteed to converge. (*)
 - (b) The bisection method has faster asymptotic convergence.
 - (c) After the first iteration, the bisection method requires fewer new function evaluations.
 - (d) Bisection method has no advantage over secant method
18. Applying the Secant method to $f(x) = (x - 1)^2$ with initial guess $x_0 = 0$, what is the value of x after two iterations?
- (a) $1/2$
 - (b) $3/4$
 - (c) 1
 - (d) Insufficient data to solve using secant method (*)
19. When applying Newton's method to find a solution to the following system of nonlinear equations $x_1 * x_2 = 0$ and $2x_1 + x_2 = 1$ with the starting value $[x_1 \ x_2]^T = [1 \ 1]^T$, what is the result of a single iteration?
- (a) $[1/2 \ 0]^T$
 - (b) $[0 \ 1]^T$ (*)
 - (c) $[1 \ 1]^T$
 - (d) $[0.5 \ 0.5]^T$
20. Assume that we use a new root finding method. For this method, at the n^{th} step, the error is $1/n$. What is the convergence rate?
- (a) Cubic
 - (b) Super linear
 - (c) Quadratic
 - (d) Sublinear (*)
21. LU decomposition reduces solving a general linear system to solving two _____ systems.
- (a) Diagonal
 - (b) Triangular (*)
 - (c) Orthogonal
 - (d) Symmetric

22. What is the rank of the matrix

$$\begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix}$$

- (a) 0
- (b) 1 (*)
- (c) 2
- (d) 3

23. Which of the following is the inverse of the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$$

- (a) $\mathbf{A}^{-1} = \frac{1}{3} \begin{bmatrix} 3 & 0 & 0 \\ -2 & -1 & 2 \\ -2 & 2 & -1 \end{bmatrix}$ (*)
- (b) $\mathbf{A}^{-1} = \frac{1}{3} \begin{bmatrix} 3 & 0 & 1 \\ -2 & -1 & 2 \\ -2 & 2 & -1 \end{bmatrix}$
- (c) $\mathbf{A}^{-1} = \frac{1}{3} \begin{bmatrix} 3 & 1 & 0 \\ -2 & -1 & 2 \\ -2 & 2 & -1 \end{bmatrix}$
- (d) $\mathbf{A}^{-1} = \frac{1}{3} \begin{bmatrix} 3 & 0 & 0 \\ -2 & 2 & 2 \\ -2 & 3 & -1 \end{bmatrix}$

24. Let $\mathbf{PA} = \mathbf{LU}$ be the LUP-factorization of \mathbf{A} . Which of the following is always true?

- (a) $\det \mathbf{A} = \det \mathbf{L}$
- (b) $\det \mathbf{A} = \det \mathbf{U}$
- (c) $\det \mathbf{A} = \pm \det \mathbf{L}$, where the sign depends on the matrix \mathbf{P}
- (d) $\det \mathbf{A} = \pm \det \mathbf{U}$, where the sign depends on the matrix \mathbf{P} (*)

The next two questions concern the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

25. Let $\mathbf{A} = \mathbf{LU}$ be the LU-factorization of \mathbf{A} . What is \mathbf{L} ?

(a) $\mathbf{L} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix}$

(b) $\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 1 & -1 \end{bmatrix}$

(c) $\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix}$

(d) $\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & -1 & 1 \end{bmatrix}$ (*)

26. Let $\mathbf{A} = \mathbf{LU}$ be the LU-factorization of \mathbf{A} . What is \mathbf{U} ?

(a) $\mathbf{U} = \begin{bmatrix} -1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

(b) $\mathbf{U} = \begin{bmatrix} 1 & -1 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

(c) $\mathbf{U} = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$

(d) $\mathbf{U} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ (*)

Use the following matrix \mathbf{A} for the next 3 questions,

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ -1 & 2 \end{bmatrix}$$

27. What is the 2-norm of the matrix \mathbf{A} ?

- (a) $\sqrt{2}$
- (b) $2\sqrt{2}$ (*)
- (c) $3\sqrt{2}$
- (d) 2

28. What is the 2-norm condition number of the matrix \mathbf{A} ?

- (a) $\sqrt{2}$
- (b) $2\sqrt{2}$
- (c) $3\sqrt{2}$
- (d) 2 (*)

29. What are the singular values of the matrix \mathbf{A} .

- (a) 2 and 8
- (b) 10 and 16
- (c) $\sqrt{2}$ and $2\sqrt{2}$ (*)
- (d) $\sqrt{2}$ and $3\sqrt{2}$

30. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix}.$$

If partial pivoting is used, what is the **value** of the first pivot element?

- (a) 1
- (b) 7
- (c) 13 (*)
- (d) 16

31. Which of the following is true?

- (a) The QR factorization of a matrix is unique
- (b) The singular value decomposition of a matrix is unique
- (c) The solution of linear least squares problem is unique
- (d) If the null space of matrix A is zero, then the normal equations of the least square problem have a unique solution (*)

32. Consider $\mathbf{A} = \begin{bmatrix} 3 & 2 & 0 \\ 2 & 6 & 2 \\ 0 & 2 & 3 \end{bmatrix}$, $\mathbf{b} = \begin{bmatrix} 3 \\ 6 \\ 8 \end{bmatrix}$. Using Jacobi's iterative method to approximate the solution $\mathbf{Ax} = \mathbf{b}$ with a starting guess of

$$\mathbf{x}_0 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \text{ what is } \mathbf{x}_1?$$

(a) $\begin{bmatrix} 2 \\ 4/3 \\ 2 \end{bmatrix}$

(b) $\begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$

(c) $\begin{bmatrix} 1 \\ 0 \\ 3/2 \end{bmatrix}$

(d) $\begin{bmatrix} 1/3 \\ 0 \\ 2 \end{bmatrix}$ (*)

33. If a first-degree polynomial of the form $y = x_1 + x_2t$ is fit to the three data points $(t_i, y_i) = (1, 1), (2, 1), (3, 2)$ by linear least squares, what is the least squares solution?

- (a) $x_1 = 1/3, x_2 = 1/2$ (*)
- (b) $x_1 = 1, x_2 = 0$
- (c) $x_1 = -1, x_2 = 1$
- (d) $x_1 = 1/2, x_2 = 1/2$

34. Which matrix has the CSR representation

$$AA = [1 \ 2 \ 4 \ 3 \ 5]$$

$$JA = [1 \ 1 \ 2 \ 1 \ 3]$$

$$IA = [1 \ 2 \ 4 \ 6]$$

(a) $\begin{bmatrix} 1 & 0 & 0 \\ 2 & 4 & 0 \\ 3 & 0 & 5 \end{bmatrix}$ (*)

(b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 4 \\ 0 & 3 & 5 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

(d) $\begin{bmatrix} 1 & 0 & 2 \\ 0 & 4 & 0 \\ 3 & 5 & 0 \end{bmatrix}$

35. Apply two iterations of normalized power method to the matrix

$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ using $x_0 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ as starting vector. After normalization using the ∞ -norm, one entry of the resulting vector will be one. What is the value of the other entry?

(a) 7/13

(b) 8/13 (*)

(c) 9/13

(d) 10/13

36. Consider Compressed Sparse Row (CSR) of the matrix $\mathbf{A} = \begin{bmatrix} 4 & 0 & 6 \\ 0 & 7 & 9 \\ 8 & 0 & 10 \end{bmatrix}$, what is IA?

(a) [1357] (*)

(b) [2345]

(c) [3456]

(d) [5677]

37. Consider the following Matlab code

```
i = [2 5 3 4 4 5 1 3];
```

```
j = [1 1 2 2 3 3 5 5];
```

```
A = [1 2 3 4 5 6 7 8];
```

```
AA = sparse(i, j, A);
```

```
full(AA);
```

What is AA?

(a)
$$\begin{bmatrix} 0 & 0 & 0 & 7 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 8 \\ 0 & 4 & 0 & 0 & 5 \\ 2 & 0 & 6 & 0 & 0 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 3 & 4 & 0 \\ 0 & 0 & 0 & 5 & 6 \\ 0 & 0 & 0 & 0 & 0 \\ 7 & 0 & 8 & 0 & 0 \end{bmatrix}$$

(c)
$$\begin{bmatrix} 0 & 0 & 0 & 0 & 7 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 8 \\ 0 & 4 & 5 & 0 & 0 \\ 2 & 0 & 6 & 0 & 0 \end{bmatrix} (*)$$

(d)
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 2 \\ 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 5 & 0 & 6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 8 & 0 & 0 \end{bmatrix}$$

38. When interpolating a distinct data set of 7 values, the degree of a Lagrange basis function used in interpolation is

(a) 4

(b) 5

(c) 6 (*)

(d) 7

39. The Newton form of the quadratic interpolant of $f(x) = \frac{12}{2+x}$ using $x = 0, 1, 2$ is
- (a) $p_2(x) = 6 - 2x + 1/2x(x - 1)$ (*)
 - (b) $p_2(x) = 6 - 4x + 3x(x - 1)$
 - (c) $p_2(x) = 6 - 2x + 3/2x(x - 1)$
 - (d) $p_2(x) = 6x(x - 1) - 2x + 1/2$
40. The computational cost of evaluating a polynomial of degree n using Horner's method is
- (a) $O(n^{1/2})$
 - (b) $O(n)$ (*)
 - (c) $O(n^2)$
 - (d) $O(n^3)$
41. Approximate $\int_0^2 f(x)dx$ using Trapezoid rule, given that $f(0) = 1$ and $f(2) = 6$.
- (a) 3.5
 - (b) 7 (*)
 - (c) 4
 - (d) 5
42. Approximate $\int_0^2 f(x)dx$ using Simpson's rule, given that $f(0) = 1$, $f(1) = 2$ and $f(2) = 6$.
- (a) 3.5
 - (b) 7
 - (c) 4
 - (d) 5 (*)
43. Approximate the integral $\int_{-1}^1 x^3 dx$ using two point Gaussian quadrature. (the Gaussian nodes are $\pm \frac{1}{\sqrt{3}}$ and the corresponding weights are both 1)
- (a) $2 \left(\frac{\sqrt{3}}{3}\right)^3$
 - (b) $-2 \left(\frac{\sqrt{3}}{3}\right)^3$
 - (c) 0 (*)
 - (d) $\frac{2}{\sqrt{3}}$

44. Which of the following has the best error bound if the intervals are small enough?

- (a) Composite Trapezoid rule
- (b) Composite Simpson's 1/3 rule
- (c) Composite Simpson's 3/8 rule
- (d) Composite Boole's rule (*)

45. Which of the following values of k makes $y = 1000e^{kt}$ go to zero if $t \rightarrow \infty$.

- (a) 2
- (b) 1
- (c) 0
- (d) -1 (*)

46. What is the value of the first step z_1 of the forward Euler method for the following

problem with initial condition $z_0 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and time step 0.1? $z' = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} z$

- (a) $\begin{bmatrix} 0.4 \\ 0 \\ 0.3 \end{bmatrix}$
- (b) $\begin{bmatrix} 0.3 \\ 0 \\ 0.2 \end{bmatrix}$
- (c) $\begin{bmatrix} 1.39 \\ 0 \\ 1.29 \end{bmatrix}$
- (d) $\begin{bmatrix} 1.3 \\ 0 \\ 1.2 \end{bmatrix}$ (*)

47. Consider $\frac{d\mathbf{y}(t)}{dt} = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} * \mathbf{y}(t)$, what is the Taylor series for \mathbf{y} around $t_0 = 0$ where $\mathbf{y}(0) = [1 \ 1 \ 1]^T$?

(a) $\mathbf{y}(t) = [1 \ 1 \ 1]^T + t [3 \ 3 \ 3]^T + t^2 [4.5 \ 4.5 \ 4.5]^T + \dots$ (*)

(b) $\mathbf{y}(t) = [1 \ 1 \ 1]^T + t [3 \ 3 \ 3]^T + t^2 [3 \ 3 \ 3]^T + \dots$

(c) $\mathbf{y}(t) = [1 \ 1 \ 1]^T + t [1 \ 2 \ 3]^T + t^2 [1.5 \ 1.5 \ 1.5]^T + \dots$

(d) $\mathbf{y}(t) = [1 \ 1 \ 1]^T + t^2 [3 \ 3 \ 3]^T + t^4 [4 \ 3 \ 1]^T + \dots$

48. Let $B = \begin{bmatrix} 0 & 0 & 0.1 \\ 0.1 & 0 & 0 \\ 0 & 0.1 & 0 \end{bmatrix}$, which one is closest to e^B ?

(a) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(b) $\begin{bmatrix} 0 & 0 & 0.1 \\ 0.1 & 0 & 0 \\ 0 & 0.1 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 0 & 0.1 \\ 0.1 & 1 & 0 \\ 0 & 0.1 & 1 \end{bmatrix}$ (*)

(d) $\begin{bmatrix} e & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & e \end{bmatrix}$

49. Consider $\mathbf{y}' = \mathbf{A}\mathbf{y}$ and the diagonalization of A is $D = S^{-1}\mathbf{A}S$, what can you say about the eigenvalues of the matrix A ?

(a) The eigenvalues of \mathbf{A} are the same as the eigenvalues of $D^T D$.

(b) The eigenvalues of \mathbf{A} are the same as the eigenvalues of S .

(c) The eigenvalues of \mathbf{A} are the same as the eigenvalues of S^{-1} .

(d) The eigenvalues of \mathbf{A} are the same as the eigenvalues of D . (*)

50. Consider

$$\begin{aligned}x' &= xy + 2 \\y' &= z + x \\z' &= x + y + z\end{aligned}$$

If $[x_0 \ y_0 \ z_0]^T = [1 \ 1 \ 1]^T$ and time step is 0.1 what is the next step of forward Euler?

- (a) $[1.1 \ 1.1 \ 1.1]^T$
- (b) $[0.7 \ 0.8 \ 0.7]^T$
- (c) $[1.3 \ 1.2 \ 1.3]^T$ (*)
- (d) $[0.3 \ 0.2 \ 0.3]^T$