Exam #1 A Thursday, March 1st

READ and complete the following:

- Bubble your Scantron only with a No. 2 pencil.
- On your Scantron (shown in the figure below), bubble :
 - 1. Your Name
 - 2. Your NetID
 - **3.** Form letter "**A**"



- No electronic devices or books are allowed while taking this exam. However, you may use a "cheat sheet" a single sheet of size 8.5" x 11" or smaller.
- Please fill in the most correct answer on the provided Scantron sheet.
- We will not answer any questions during the exam.
- Each question has only ONE correct answer.
- You must stop writing when time is called by the proctors.
- Hand in both these exam pages and the Scantron.
- DO NOT turn this page UNTIL the proctor instructs you to.

- 1. (True/False) Double precision positive floating point numbers in IEEE-754 are equally spaced.
 - (a) True
 - (b) False
- 2. (True/False) If a matrix is singular then it cannot have an LU factorization.
 - (a) True
 - (b) False
- **3.** Which of the following is **NOT** true about machine epsilon (ϵ_m) ?
 - (a) $(3 + \epsilon_m) 2 = 1$ in floating point arithmetic .
 - (b) $\frac{\epsilon_m}{2}$ is the maximum relative error in representing nonzero real numbers.
 - (c) $\epsilon_{\tt m}$ is the smallest representable positive normalized machine number.
 - (d) ϵ_{m} is the smallest floating point number for which $(1 + \epsilon_{m}) > 1$.
- 4. What is the output of the following Matlab script?

```
i = 3.0;
while i ~= 2.0
i = i - 0.1;
end
(a) 2.0
(b) 0.0
(c) machine epsilon (ε<sub>m</sub>)
(d) non-terminating loop
```

5. Consider computing the LU factorization (in IEEE double-precision) of the following matrix

$$A = \left[\begin{array}{cc} k & 1 \\ -1 & 1 \end{array} \right]$$

When is pivoting necessary for accuracy?

- (a) When |k| is larger than $\frac{1}{\epsilon_m}$.
- (b) When |k| is smaller than ϵ_m .
- (c) When |k| is near 1.
- (d) The LU factorization will be relatively accurate for all machine numbers k.
- 6. Statement A: The digits lost in cancellation are the most significant digits. Statement B: The digits lost in rounding are the least significant digits.
 - (a) Both A and B are true
 - (b) A is true, B is false
 - (c) A is false, B is true
 - (d) Both A and B are false

7. What is the Jacobian of the function

$$\mathbf{f}(x_1, x_2, x_3) = \begin{bmatrix} 3x_1^2x_2 + x_3^2\\ 2x_1^2 + x_1x_3\\ 3x_2^2 + x_3^3 \end{bmatrix}$$

at the point (1, 2, 3)?

(a)
$$\begin{pmatrix} 3 & 4 & 9 \\ 3 & 0 & 3 \end{pmatrix}$$

(b) $\begin{pmatrix} 12 & 3 & 6 \\ 7 & 0 & 1 \\ 0 & 12 & 27 \end{pmatrix}$
(c) $\begin{pmatrix} 12 & 7 & 0 \\ 3 & 0 & 12 \\ 6 & 1 & 27 \end{pmatrix}$
(d) $\begin{pmatrix} 15 \\ 5 \end{pmatrix}$

8. Suppose at the n^{th} step of finding the roots of the function using the secant method,

$$f(x) = x - x^2 - 1,$$

we get $x_n = 1$ and $x_{n-1} = -1$. What is the next value by this method?

- (a) $x_{n+1} = 0$
- (b) $x_{n+1} = 1$
- (c) $x_{n+1} = 2$
- (d) $x_{n+1} = 3$
- 9. Which of the following is NOT TRUE about the secant method?
 - (a) Its converging rate is normally slower than of the Newton's method.
 - (b) It might not converge if $f'(x) \approx 0$ is encountered.
 - (c) It needs more function evaluations than Newton's method.
 - (d) Iterates are not confined to the initial bracket.

- 10. What is the BEST asymptotic bound for the number of floating point operations in multiplying two $n \times n$ matrices based on the value n?
 - (a) $\mathcal{O}(n)$
 - (b) $O(n^2)$
 - (c) $O(n^3)$
 - (d) $\mathcal{O}(n!)$
- 11. What is true about the following equation?

	1	2	3	$\begin{bmatrix} x_1 \end{bmatrix}$		[0]	
Ax =	0	5	1	x_2	=	2	
	0	0	3 _	x_3		1	

- (a) There is a unique solution.
- (b) There are infinitely many solutions.
- (c) There is no solution.
- (d) There are exactly two solutions.
- 12. Use the bisection method to find a root of the function $f(x) = x^2 1$ starting from interval [0.9, 1.3]. What is the size(diameter) of the interval when a root is found? Note that the root will be the midpoint value of the interval.
 - (a) 0.05
 - (b) 0.2
 - (c) 0.4
 - (d) 1.0

- 13. Using Newton's method to find a root of the function $f(x) = x^2 1$, which of the following starting values will converge to the root x = 1?
 - (a) 2.0
 - (b) 0.0
 - (c) -2.0
 - (d) all of above
- 14. What is the convergence rate of following sequence?

 $10^{-1}, \ 10^{-3}, \ 10^{-6}, \ 10^{-10}, \ 10^{-15}$

- (a) superlinear
- (b) quadratic
- (c) linear
- (d) sublinear
- **15.** What is the next term in the Taylor expansion $e^x = 1 + x + x^2/2 + \dots$?
 - (a) x³
 - (b) $x^3/6$
 - (c) $x^4/24$
 - (d) x^2

- **16.** What is the Taylor expansion of function $f(x, y, z) = x \sin(y) + 3z^2 x$ about (x, y, z) = (0, 0, 0) for terms $x^{k_1}y^{k_2}z^{k_3}$ where |k| = 0, 1, 2, 3, 4, 5 and $|k| = k_1 + k_2 + k_3$?
 - (a) $xy + 3z^2x$
 - (b) $xy xy^3/6 + 6zx$
 - (c) $xy xy^3/6 + 3z^2x$
 - (d) x + y + 6z
- 17. Mesopotamian culture had iterative formulas for computing algebraic quantities such as roots. In particular, they approximated \sqrt{N} by repeatedly applying the formula obtained by Newtons method. The formula for n = 0, 1, 2, 3, ... is :
 - (a) $x_{n+1} = \frac{1}{2}(x_n + N)$
 - (b) $x_{n+1} = (x_n + \frac{N}{2x_n})$
 - (c) $x_{n+1} = \frac{1}{2}(x_n + \frac{N}{x_n})$
 - (d) None of the above
- **18.** Given the $n \times 1$ vectors u and v, what is the cost in floating point operations of computing uv^T ?
 - (a) O(1)
 - (b) $\mathcal{O}(n)$
 - (c) $\mathcal{O}(n^2)$
 - (d) $O(n^3)$

19. What is the relative condition number (C) of $f(x) = \sqrt{x}$ for x > 0?

- (a) C = $\frac{1}{4}$
- (b) C = $\frac{1}{2}$
- (c) C = 1
- (d) C = 2

20. What is the inverse of the following 2 by 2 matrix?

$$A = \begin{bmatrix} 2 & 4 \\ -3 & 1 \end{bmatrix}$$

- (a) $\begin{bmatrix} \frac{1}{14} & \frac{1}{7} \\ \frac{1}{2} & \frac{3}{14} \end{bmatrix}$ (b) $\begin{bmatrix} \frac{1}{14} & \frac{-2}{7} \\ \frac{3}{14} & \frac{1}{7} \end{bmatrix}$ (c) $\begin{bmatrix} \frac{3}{7} & \frac{1}{14} \\ \frac{2}{7} & \frac{5}{14} \end{bmatrix}$ (d) $\begin{bmatrix} \frac{3}{14} & \frac{1}{7} \\ \frac{1}{14} & \frac{-3}{14} \end{bmatrix}$
- **21.** What is the interval value of [1, 2]/[5, 10] where / is interval divide?
 - (a) [0.1, 0.4]
 - **(b)** [0.2, 0.4]
 - (c) [0.1, 0.2]
 - (d) [0.0, 0.4]
- 22. In the LU-decomposition of a matrix A we get

$$LU = PA$$
,

where

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 0.25 & 1 & 0 \\ 0.5 & 0 & 1 \end{bmatrix}, U = \begin{bmatrix} 4 & 2 & 2 \\ 0 & 1.5 & 3.5 \\ 0 & 0 & 1 \end{bmatrix}, P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}.$$

What is the determinant of A?

(a)
$$det(A) = 1$$

- (b) det(A) = -1
- (c) $\det(A) = 6$
- (d) det(A) = -6

23. Given the code below, compute the BEST asymptotic bound for the number of floating point operations needed to compute \mathbf{x} based on the value n.

 $\begin{array}{ll} x\,(1) \ = \ b\,(1)/L\,(1\,,1)\,; \\ for \ i \ = \ 2\,:n \\ s \ = \ b\,(i\,)\,; \\ for \ j \ = \ 1\,:\,i-1 \\ s \ = \ s \ - \ L\,(i\,,j\,)\,*\,x\,(j\,)\,; \\ end \\ x\,(\,i\,) \ = \ s/L(\,i\,,i\,)\,; \\ end \end{array}$

- (a) *O*(*n*)
- (b) $O(n^2)$
- (c) $O(n^3)$
- (d) *O*(*n*⁴)

24. Gaussian elimination without pivoting on the matrix,

$$A = \left[\begin{array}{rrrr} 1 & 2 & 2 \\ 4 & 4 & 2 \\ 4 & 6 & 5 \end{array} \right]$$

would produce which of the following?

(a)
$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & -4 & 0 \\ 2 & -6 & 0 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 1 & 2 & 2 \\ 0 & -4 & -6 \\ 0 & 0 & 0 \end{bmatrix}$$

(c)
$$\begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & -6 \\ 0 & 0 & 1 \end{bmatrix}$$

(d)
$$\begin{bmatrix} 1 & 2 & 2 \\ -6 & -4 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

25. If you perform LU factoring with partial pivoting on the matrix,

$$A = \left[\begin{array}{rrr} 2 & 0 & 2 \\ -4 & 6 & 0 \\ 0 & 0 & 4 \end{array} \right]$$

so that P * A = L * U and you are given that,

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ What are } L \text{ and } U?$$

(a) $L = \begin{bmatrix} -4 & 6 & 0 \\ 0 & 3 & 2 \\ 0 & 0 & 4 \end{bmatrix}, U = \begin{bmatrix} 1 & 0 & 0 \\ -0.5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
(b) $L = \begin{bmatrix} 1 & -0.5 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, U = \begin{bmatrix} -4 & 0 & 0 \\ 6 & 3 & 0 \\ 0 & 2 & 4 \end{bmatrix}$
(c) $L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, U = \begin{bmatrix} -4 & 6 & 0 \\ 0 & 3 & 2 \\ 0 & 0 & 4 \end{bmatrix}$
(d) $L = \begin{bmatrix} 1 & 0 & 0 \\ -0.5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, U = \begin{bmatrix} -4 & 6 & 0 \\ 0 & 3 & 2 \\ 0 & 0 & 4 \end{bmatrix}$