

# Filesystems

Based on slides by Matt Welsh, Harvard

# [ Announcements ]

- MP8 due tomorrow night
- Finals approaching, know your times and conflicts
  - Ours: Friday May 11, 1:30 – 4:30 pm
- Review material similar to midterm released by Friday
  - Topic outline
  - Practice final exam
- Review sessions
  - Vote on Piazza for times that work for you
  - Do this by midnight Tuesday; results announced Wed.
- Honors section demos
  - Vote on Piazza for times that work for you
  - Do this by Wednesday



# Filesystems

- A filesystem provides a high-level application access to disk
  - As well as CD, DVD, tape, floppy, etc...
  - Masks the details of low-level sector-based I/O operations
  - Provides structured access to data (files and directories)
  - Caches recently-accessed data in memory
- Hierarchical filesystems: Most common type
  - Organized as a tree of directories and files
- Byte-oriented vs. record-oriented files
  - UNIX, Windows, etc. all provide byte-oriented file access
    - May read and write files a byte at a time
  - Many older OS's provided only record-oriented files
    - File composed of a set of records; may only read and write a record at a time
- Versioning filesystems
  - Keep track of older versions of files
  - e.g., VMS filesystem: Could refer to specific file versions:foo.txt;1, foo.txt;2



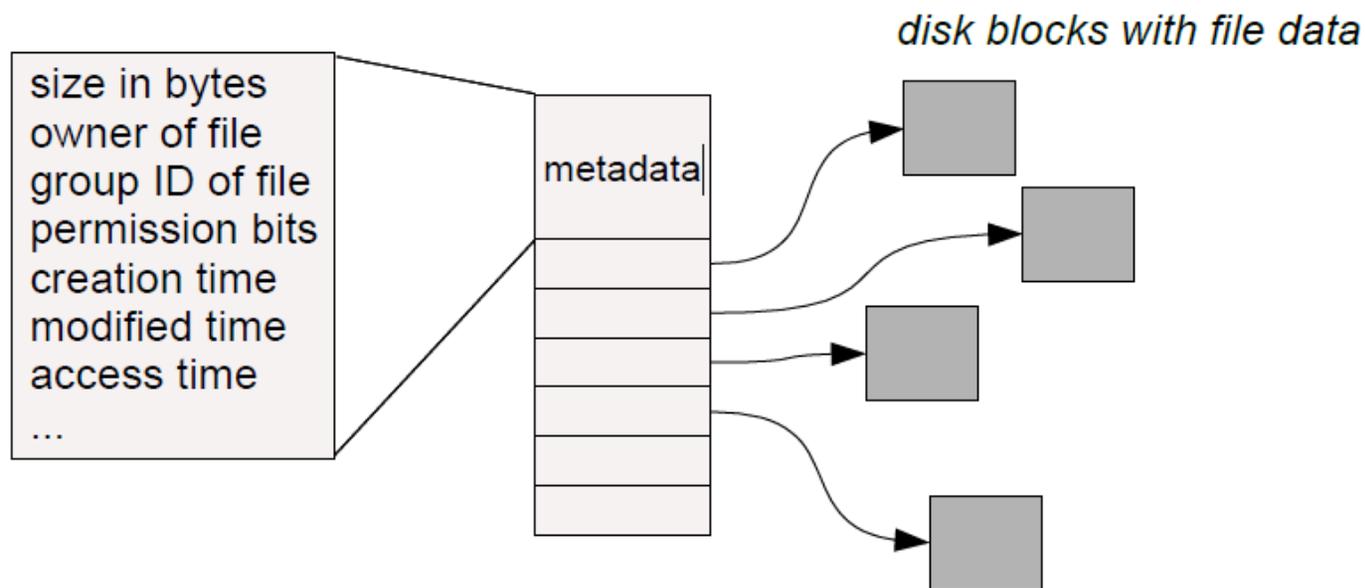
# Filesystem Operations

- Filesystems provide a standard interface to files and directories:
  - Create a file or directory
  - Delete a file or directory
  - Open a file or directory – allows subsequent access
  - Read, write, append to file contents
  - Add or remove directory entries
  - Close a file or directory – terminates access
- What other features do filesystems provide?
  - Accounting and quotas – prevent your classmates from hogging the disks
  - Backup – some filesystems have a “\$HOME/.backup” containing automatic snapshots
  - Indexing and search capabilities
  - File versioning
  - Encryption
  - Automatic compression of infrequently-used files
- Should this functionality be part of the filesystem or built on top?
  - Classic OS community debate: Where is the best place to put functionality?



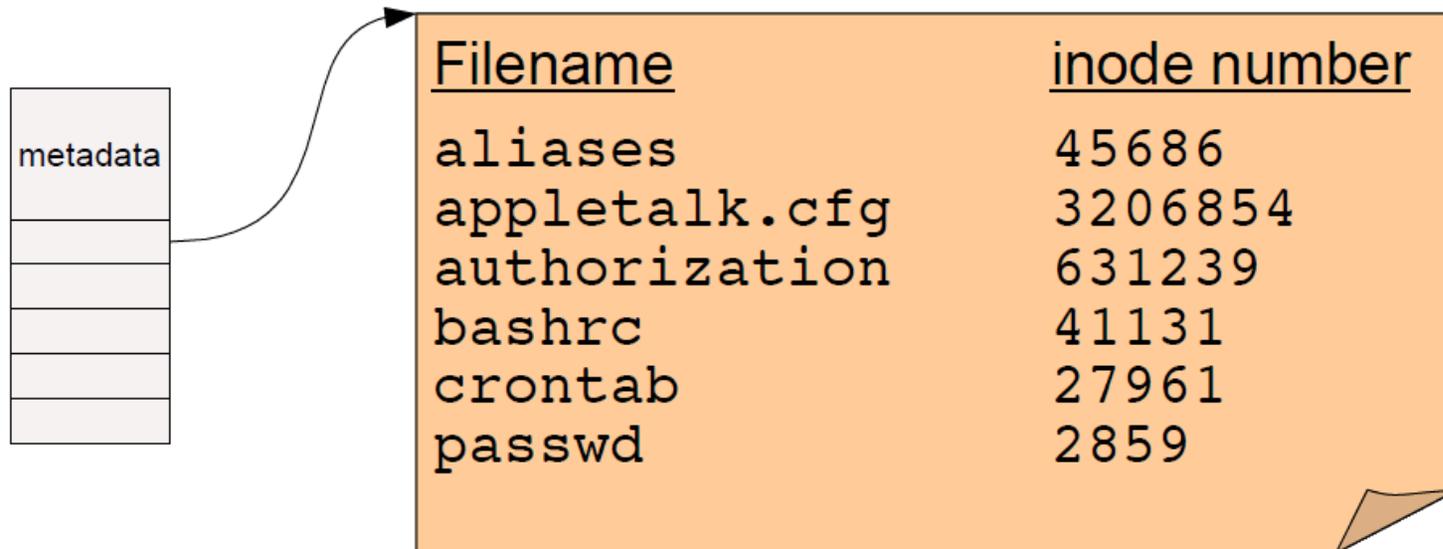
# Basic Filesystem Structures

- Every file and directory is represented by an inode
  - Stands for “index node”
- Contains two kinds of information:
  - 1) Metadata describing the file's owner, access rights, etc.
  - 2) Location of the file's blocks on disk



# Directories

- A directory is a special kind of file that contains a list of (filename, inode number) pairs

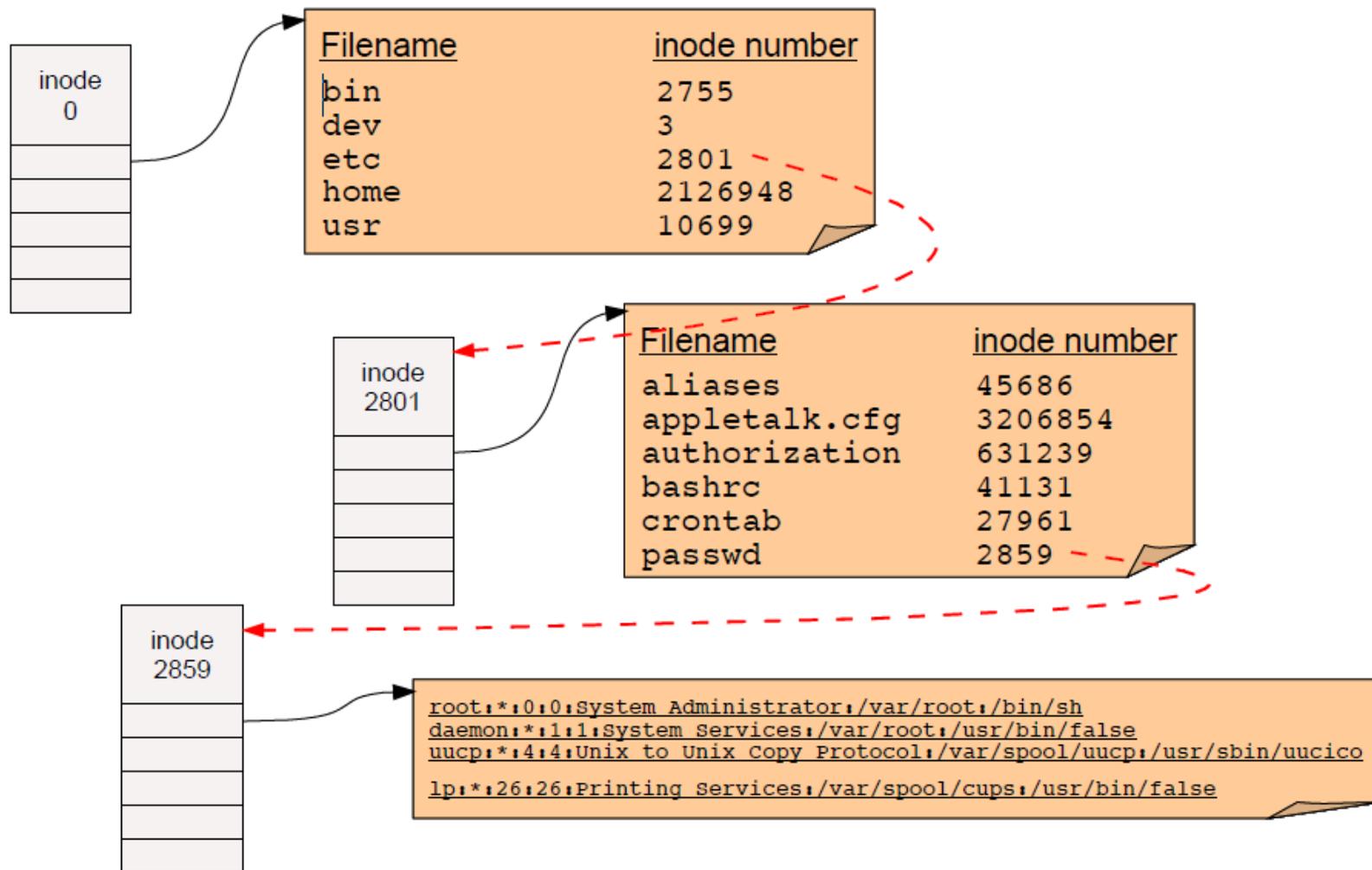


- These are the contents of the directory “file data” itself – NOT the directory's inode!
- Filenames (in UNIX) are not stored in the inode at all!
- Two open questions:
  - How do we find the root directory (“ / “ on UNIX systems)?
  - How do we get from an inode number to the location of the inode on disk?



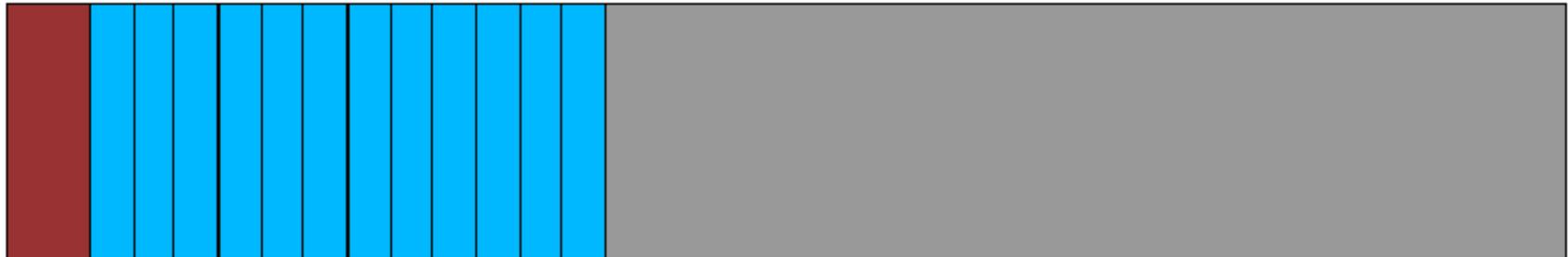
# Pathname resolution

- To look up a pathname “/etc/passwd”, start at root directory and walk down chain of inodes...



# [ Locating inodes on disk ]

- All right, so directories tell us the **inode number** of a file.
  - How the heck do we find the inode itself on disk?
- Basic idea: Top part of filesystem contains **all** of the inodes!



*superblock*

*inodes*

*File and directory data blocks*

- inode number is just the “index” of the inode
- Easy to compute the block address of a given inode:
  - $\text{block\_addr}(\text{inode\_num}) = \text{block\_offset\_of\_first\_inode} + (\text{inode\_num} * \text{inode\_size})$
- This implies that a filesystem has a fixed number of potential inodes
  - This number is generally set when the filesystem is created
- The superblock stores important metadata on filesystem layout, list of free blocks, etc.



# Stupid directory tricks

- Directories map filenames to inode numbers. What does this imply?
- We can create multiple pointers to the same inode in different directories
  - Or even the same directory with different filenames
- In UNIX this is called a “hard link” and can be done using “ln”

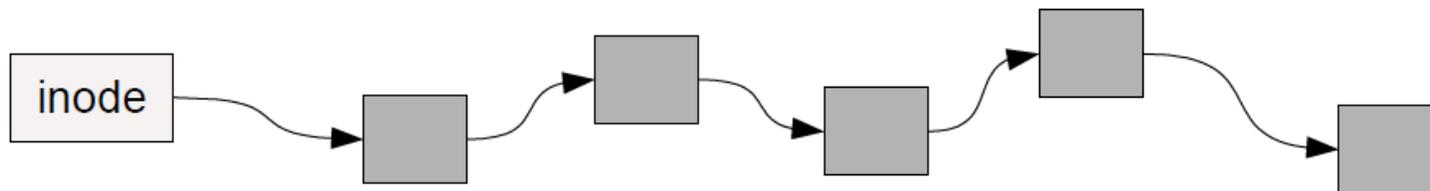
```
bash$ ls -i /home/foo
287663 /home/foo          (This is the inode number of “foo”)
bash$ ln /home/foo /tmp/foo
bash$ ls -i /home/foo /tmp/foo
287663 /home/foo
287663 /tmp/foo
```

- “/home/foo” and “/tmp/foo” now refer to the same file on disk
  - Not a copy! You will always see identical data no matter which filename you use to read or write the file.
- Note: This is not the same as a “symbolic link”, which only links one filename to another.

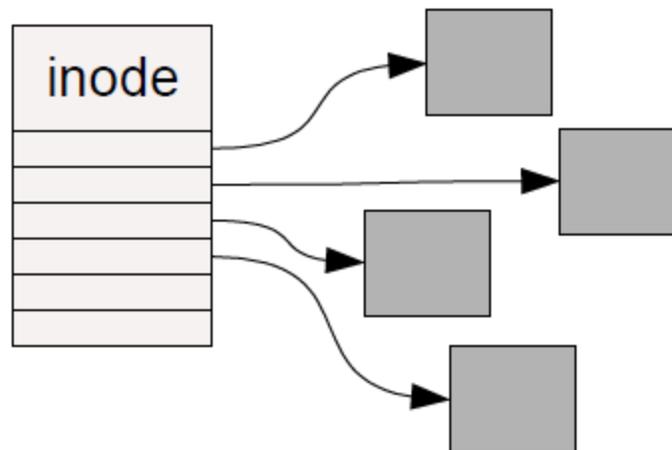


# How should we organize blocks on a disk?

- Very simple policy: A file consists of linked blocks
  - inode points to the first block of the file
  - Each block points to the next block in the file (just a linked list on disk)
    - What are the advantages and disadvantages??

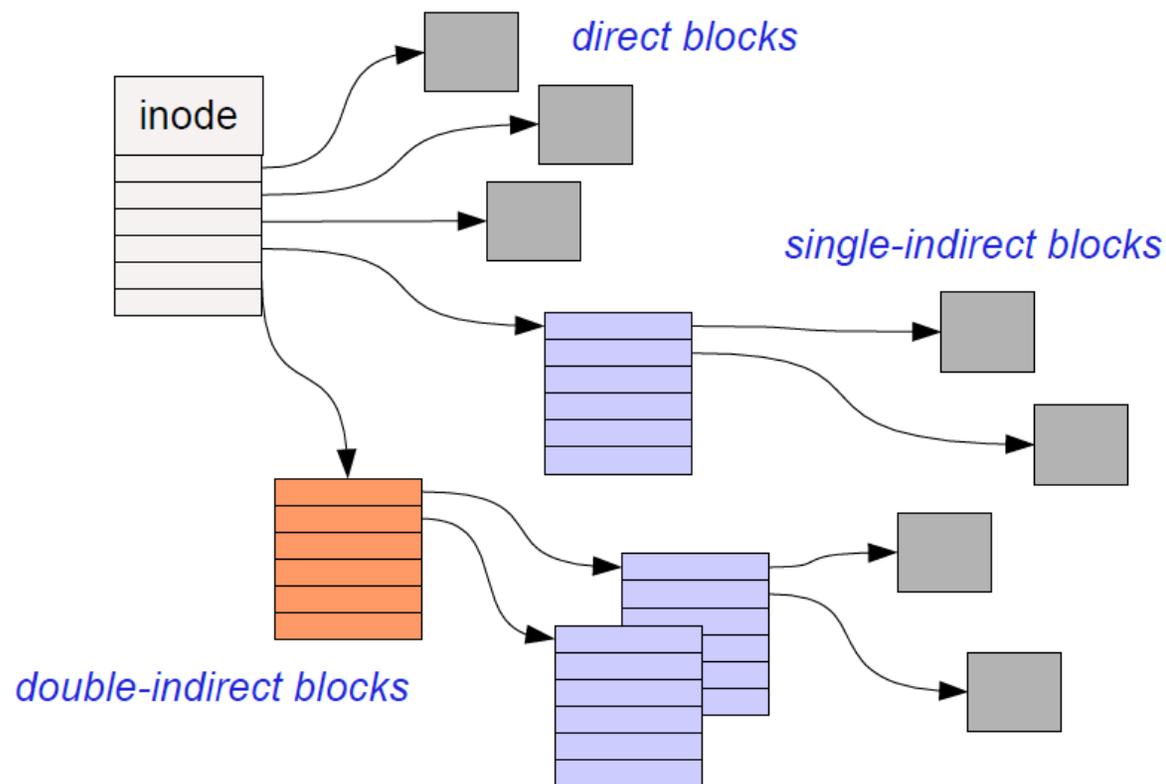


- Indexed files
  - inode contains a list of block numbers containing the file
  - Array is allocated when the file is created
    - What are the advantages and disadvantages??



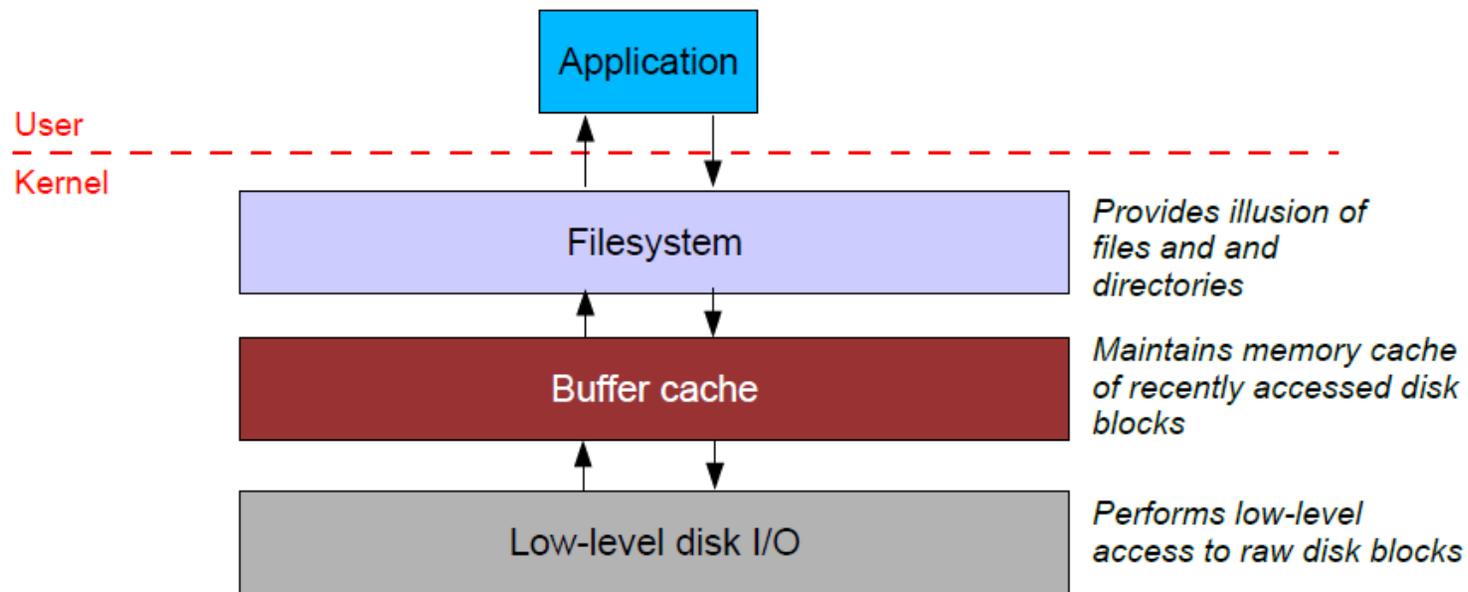
# Multilevel indexed files

- inode contains a list of 10-15 **direct block pointers**
  - First few blocks of file can be referred to by the inode itself
- inode also contains a pointer to a **single indirect, double indirect, and triple indirect blocks**
  - Allows file to grow to be incredibly large!!!



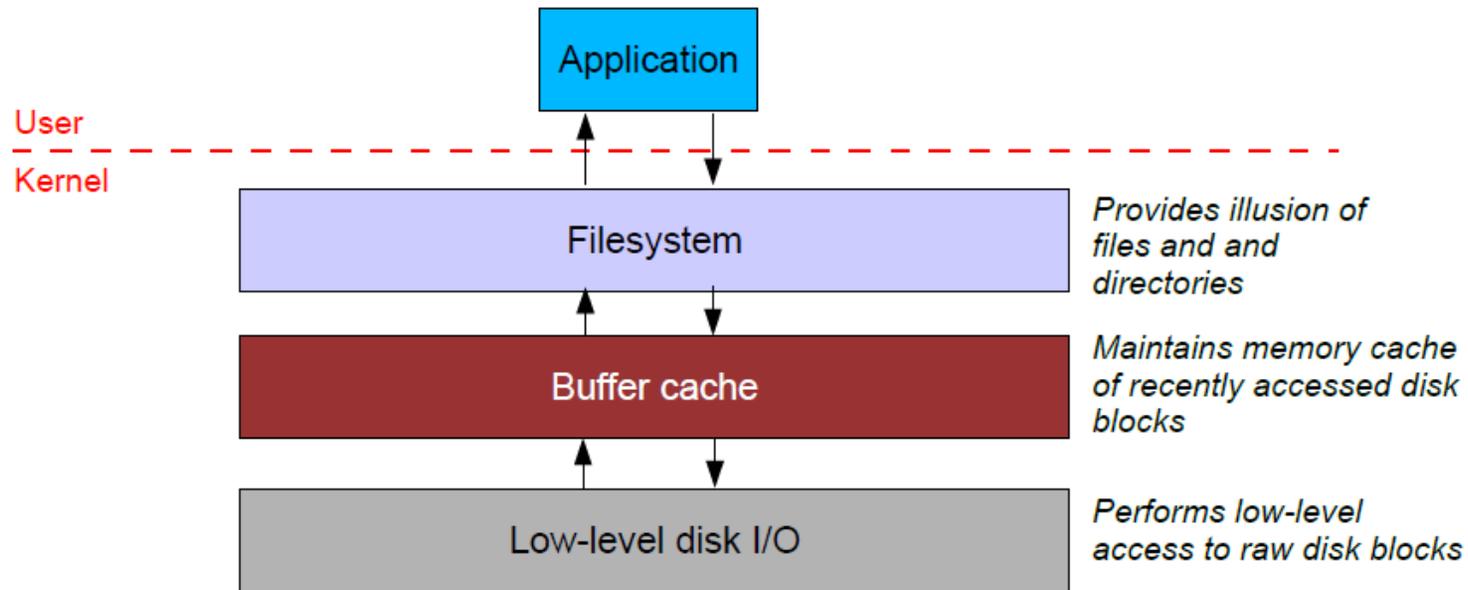
# File system caching

- Most filesystems cache significant amounts of disk in memory
  - e.g., Linux tries to use all “free” physical memory as a giant cache
  - Avoids huge overhead for going to disk for every I/O



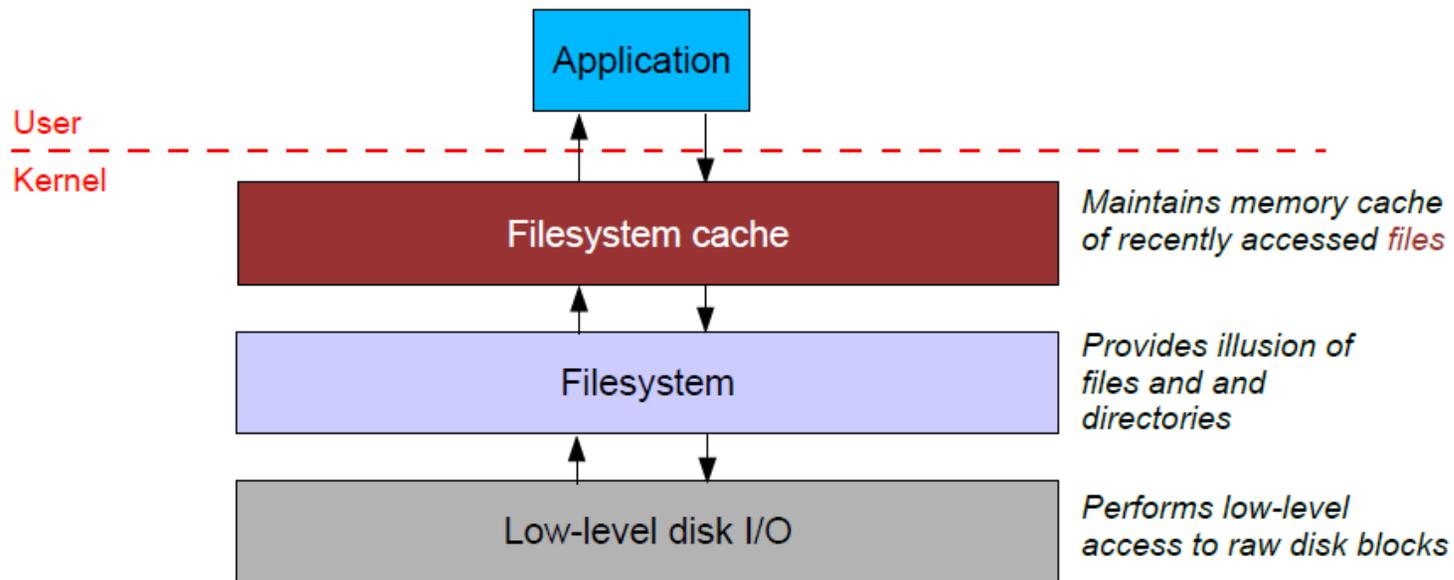
# Caching issues

- Where should the cache go?
  - Below the filesystem layer: Cache individual disk blocks
  - Above the filesystem layer: Cache entire files and directories
  - Which is better??



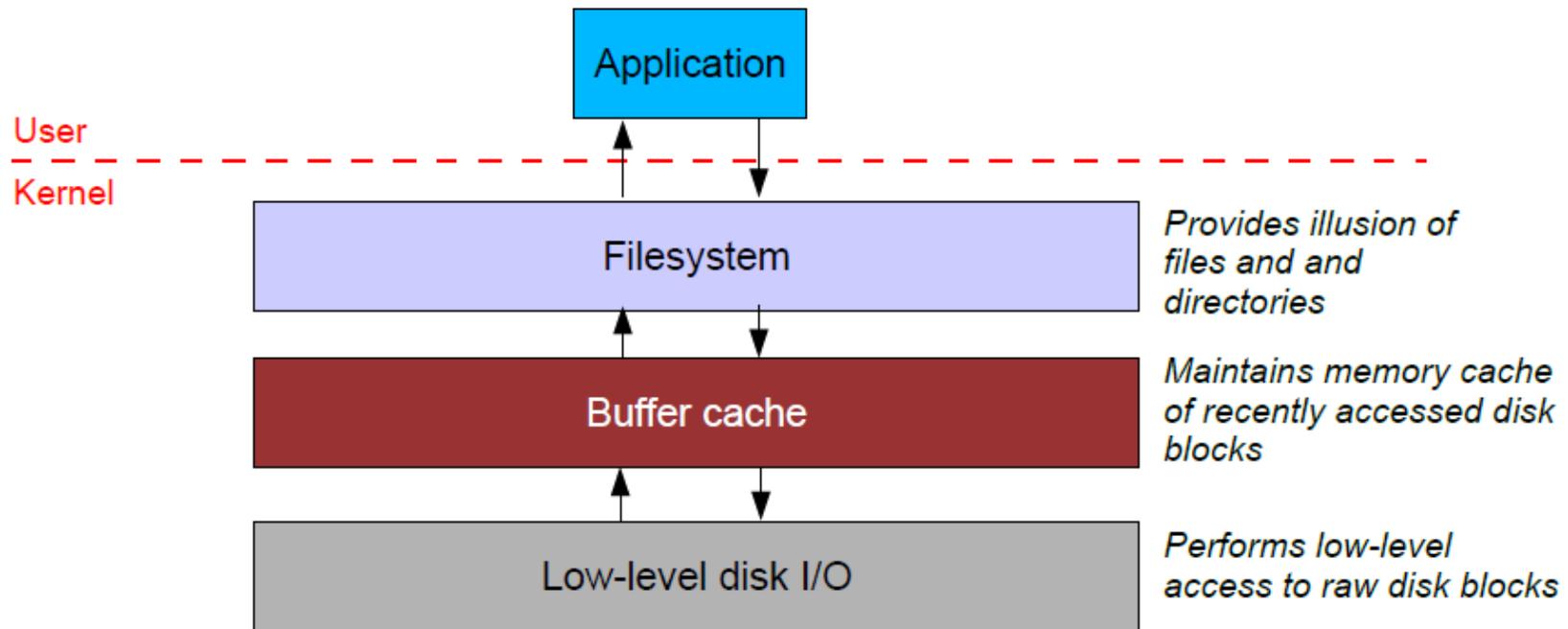
# Caching issues

- Where should the cache go?
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  - Which is better??



# Caching issues (2)

- Reliability issues
  - What happens when you write to the cache but the system crashes?
  - What if you update some of the blocks on disk but not others?
    - Example: Update the inode on disk but not the data blocks?
  - **Write-through cache:** All writes immediately sent to disk
  - **Write-back cache:** Cache writes stored in memory until evicted (then written to disk)
    - Which is better for performance? For reliability?



# Caching issues (2)

- “Syncing” a filesystem writes back any dirty cache blocks to disk
  - UNIX “sync” command achieves this.
  - Can also use fsync() system call to sync any blocks for a given file.
    - Warning – not all UNIX systems guarantee that after sync returns that the data has really been written to the disk!
    - This is also complicated by memory caching on the disk itself.
- Crash recovery
  - If system crashes before sync occurs, “fsck” checks the filesystem for errors
  - Example: an inode pointing to a block that is marked as free in the free block list
  - Another example: An inode with no directory entry pointing to it
    - These usually get linked into a “lost+found” directory
    - inode does not contain the filename so need the sysadmin to look at the file data and guess where it might belong!



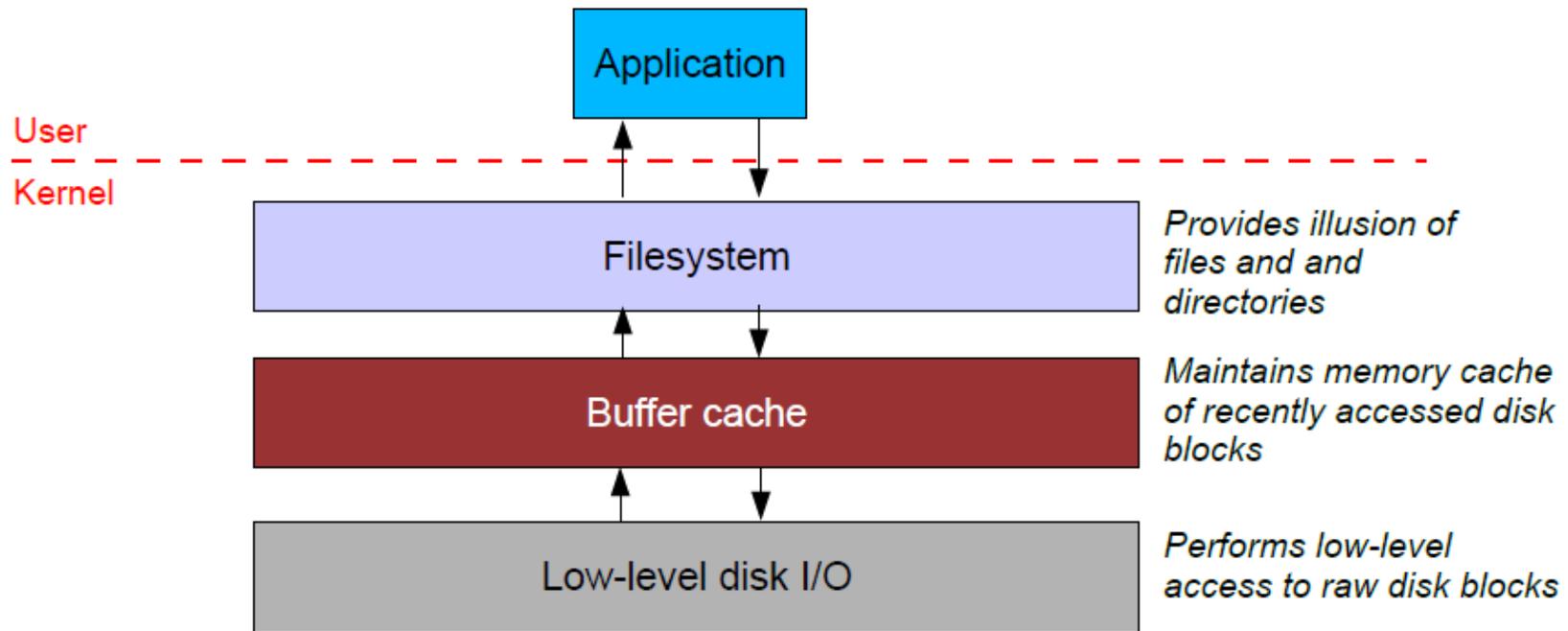
# [ Caching and fsync() example ]

- Running the `copy` example from last time,
  - How fast is it the first time, vs. the second time you copy the same file?
  - What happens if we `fsync()` after each iteration?



# Caching issues (3)

- Read ahead
  - Recall: Seek time dominates overhead of disk I/O
  - So, would ideally like to read multiple blocks into memory when you have a cache miss
    - Amortize the cost of the seek for multiple reads
  - Useful if file data is laid out in contiguous blocks on disk
    - Especially if the application is performing sequential access to the file

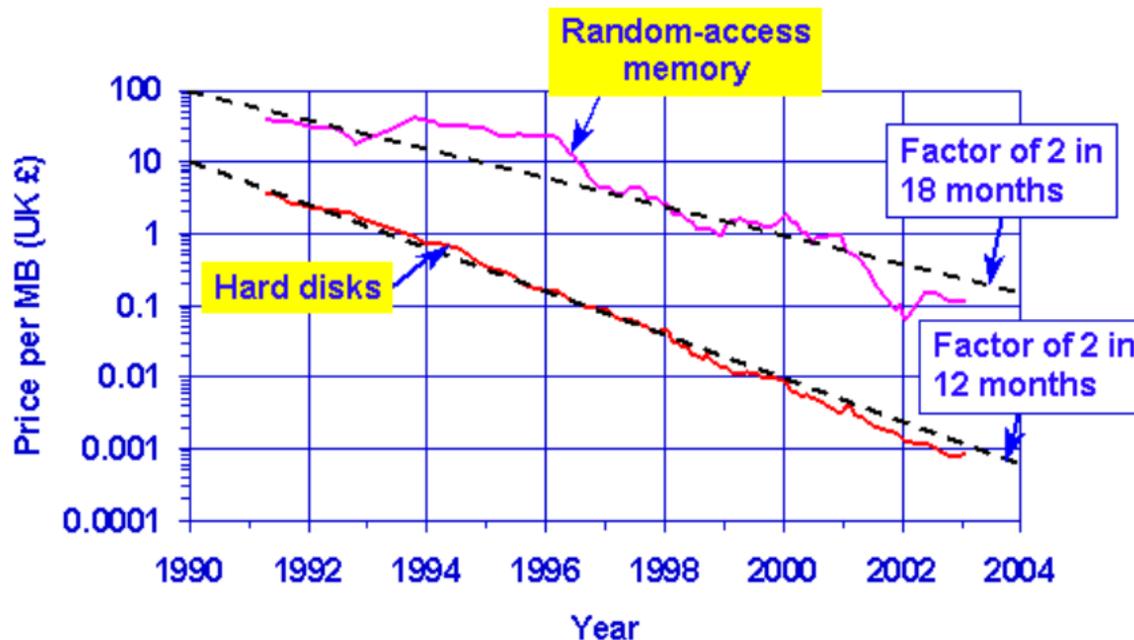




# Making filesystems resilient: RAID

# RAID Motivation

- Speed of disks not matching other components
  - Moore's law: CPU speed doubles every 18 months
  - SRAM speeds increasing by 40-100% a year
  - In contrast, disk seek time only improving 7% a year
    - Although greater density leads to improved transfer times once seek is done
- Emergence of PCs starting to drive down costs of disks
  - (This is 1988 after all)
  - PC-class disks were smaller, cheaper, and only marginally slower



# RAID Motivation

- Basic idea: Build I/O systems as arrays of cheap disks
  - Allow data to be **striped** across multiple disks
  - Means you can read/write multiple disks in parallel – greatly improve performance
- Problem: disks are extremely unreliable
- Mean Time to Failure (MTTF)
  - $MTTF(\text{disk array}) = MTTF(\text{single disk}) / \# \text{ disks}$
  - Adding more disks means that failures happen more frequently..
  - **An array of 100 disks with an MTTF of 30,000 hours = just under 2 weeks for the array's MTTF!**



# Increasing reliability

- Idea: Replicate data across multiple disks
  - When a disk fails, lost information can be regenerated from the redundant data
- Simplest form: Mirroring (also called “RAID 1”)
  - All data is mirrored across two disks
- Advantages:
  - Reads are faster, since both disks can be read in parallel
  - Higher reliability (of course)
- Disadvantages:
  - Writes are slightly slower, since OS must wait for both disks to do write
  - Doubles the cost of the storage system!

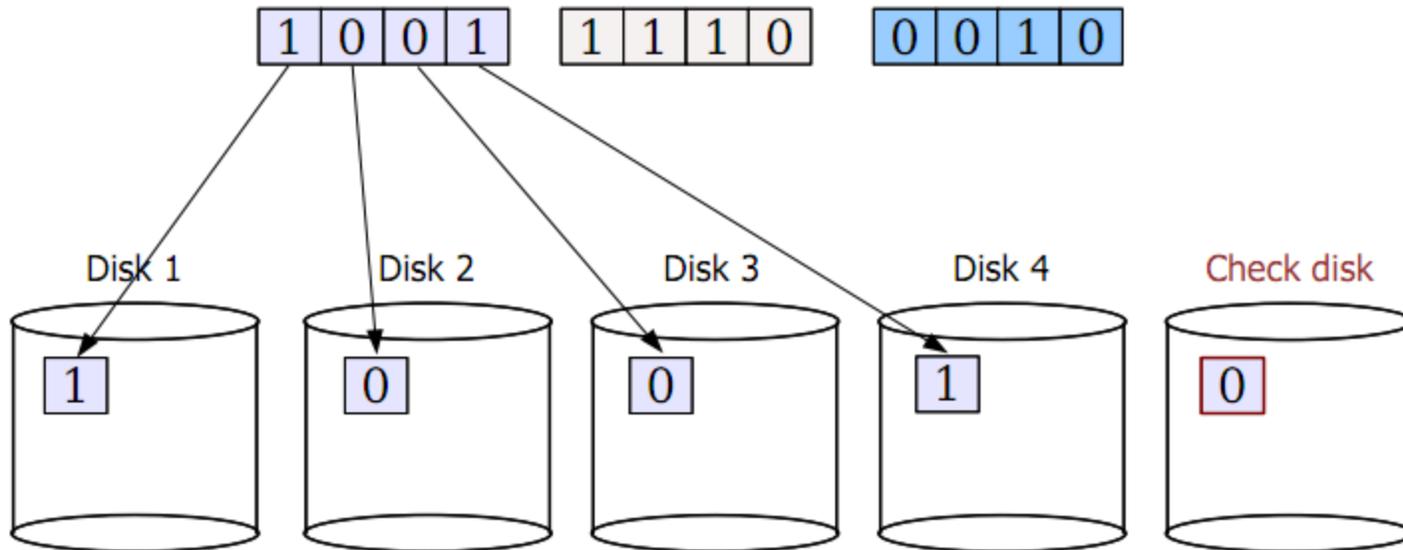


# [ RAID 3 ]

- Rather than mirroring, use **parity codes**
  - Given  $N$  bits  $\{b_1, b_2, \dots, b_N\}$ , the **parity bit**  $P$  is the bit  $\{0,1\}$  that yields an even number of “1” bits in the set  $\{b_1, b_2, \dots, b_N, P\}$
  - Idea: If any bit in  $\{b_1, b_2, \dots, b_N\}$  is lost, can use the remaining bits (plus  $P$ ) to recover it.
- Where to store the parity codes?
  - Add an extra “check disk” that stores parity bits for the data stored on the rest of the  $N$  disks
- Advantages:
  - If a single disk fails, can easily recompute the lost data from the parity code
  - Can use one parity disk for **several** data disks (reduces cost)
- Disadvantages:
  - Each write to a block must update the corresponding parity block as well

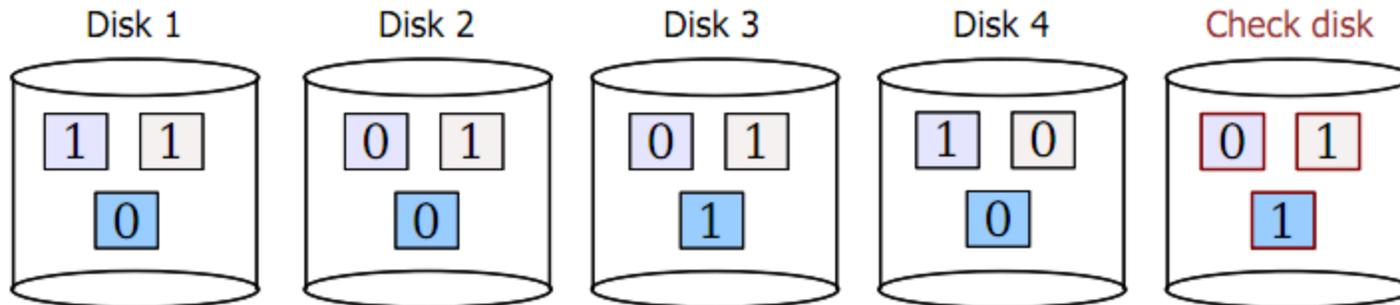


# [ RAID 3 example ]

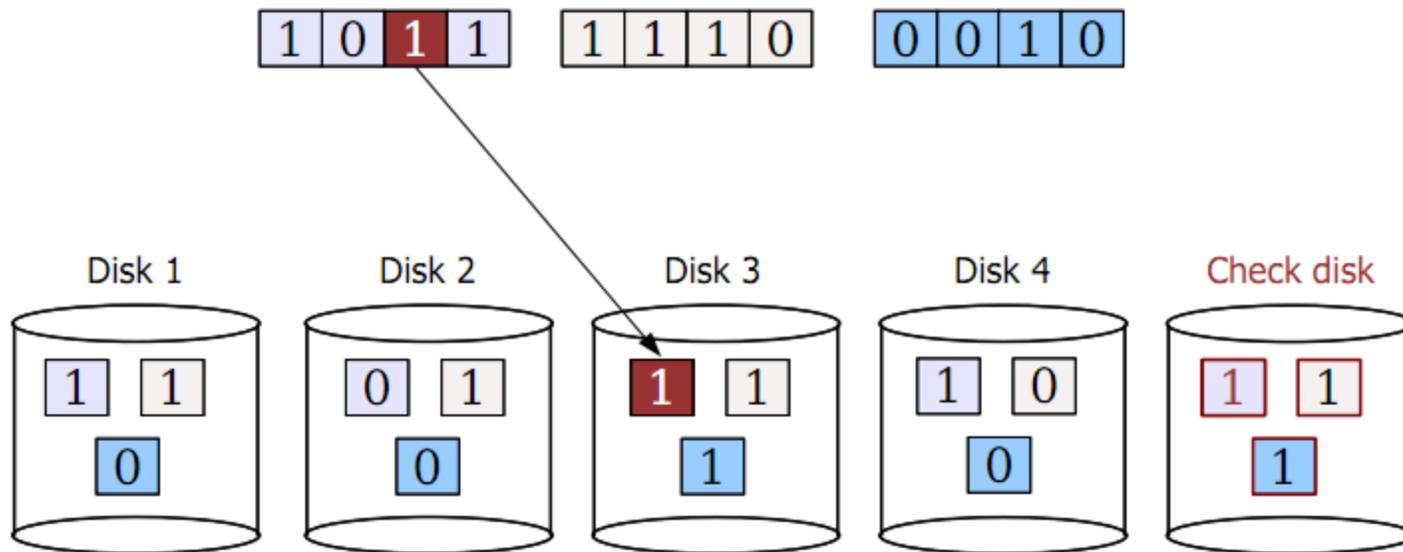


# [ RAID 3 example ]

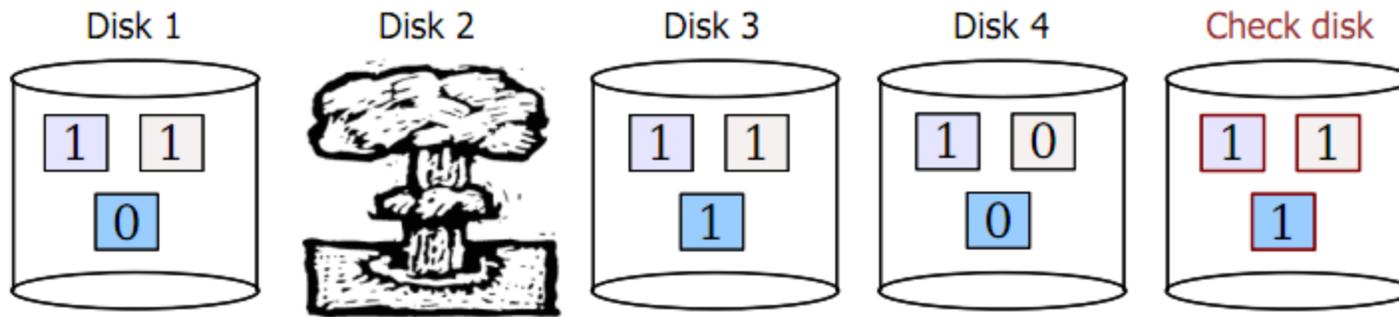
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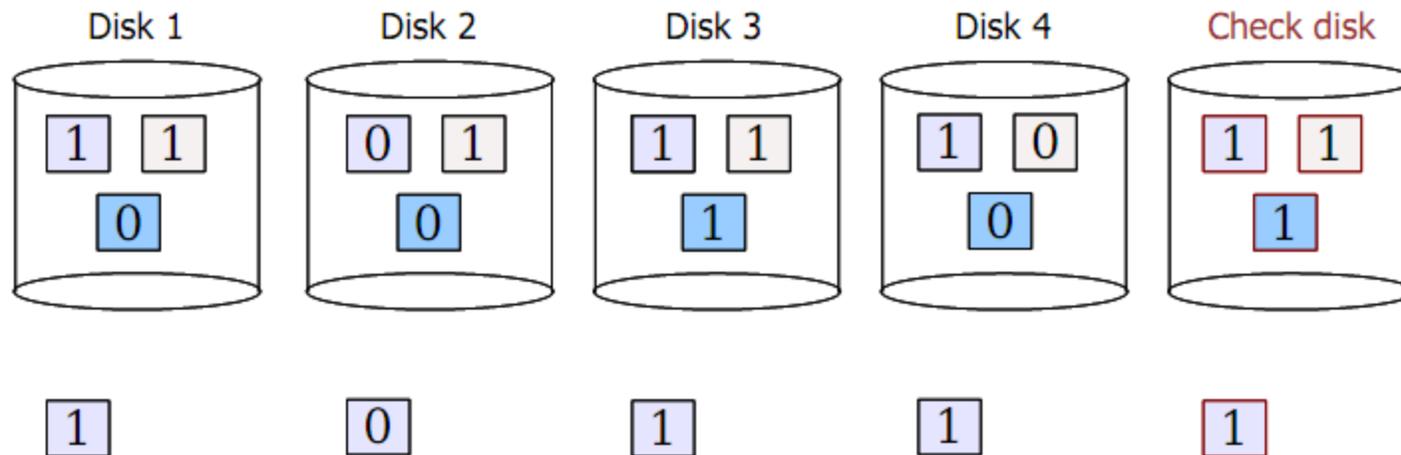
# [ RAID 3 example ]



# [ RAID 3 example ]



# [ RAID 3 example ]



- 1. Read back data from other disks
- 2. Recalculate lost data from parity code
- 3. Rebuild data on lost disk



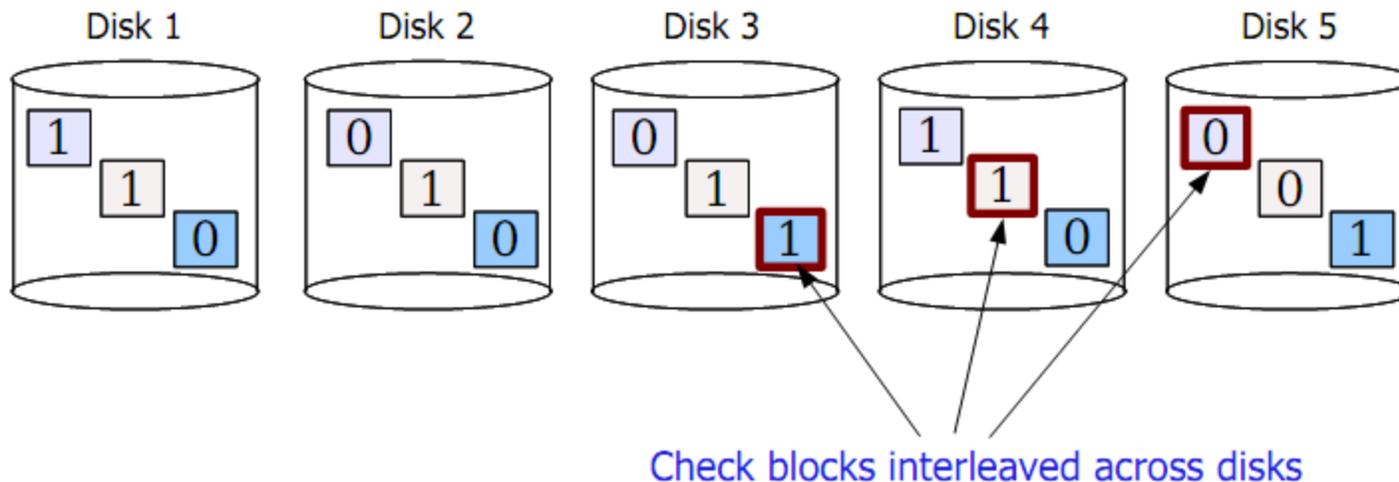
# RAID 3 issues

- Terminology
  - MTTF = mean time to failure
  - MTTR = mean time to repair
- What is the MTTF of RAID?
  - Both RAID 1 and RAID 3 tolerate the failure of a single disk
  - As long as a second disk does not die while we are repairing the first failure, we are in good shape!
- So, what is the probability of a second disk failure?
- $P(\text{2nd failure}) \approx \text{MTTR} / (\text{MTTF of one disk} / \# \text{ disks} - 1)$ 
  - Assumes independent, exponential failure rates; see Patterson RAID paper for derivation
  - 10 disks, MTTF (disk) = 1000 days, MTTR = 1 day
    - $P(\text{2nd failure}) \approx 1 \text{ day} / (1000 / 9) = 0.009$
- What is the performance of RAID 3?
  - Check disk must be updated each time there is a write
  - Problem: The check disk is then a performance bottleneck
    - Only a single read/write can be done at once on the whole system!



# [ RAID 5 ]

- Another approach: Interleaved check blocks (“RAID 5”)
  - Rotate the assignment of data blocks and check blocks across disks
  - Avoids the bottleneck of a single disk for storing check data
  - Allows multiple reads/writes to occur in parallel (since different disks affected)



# [ Reliable distributed storage ]

- Today, giant data stores distributed across 100s of thousands of disks across the world
  - e.g., your mail on gmail
- *“You know you have a large storage system when you get paged at 1 AM because you only have a few petabytes of storage left.”*
  - – a “note from the trenches” at Google



# Reliable distributed storage

## ■ Issues

- Failure is the common case
  - Google reports 2-10% of disks fail per year
  - Now multiply that by 60,000+ disks in a single warehouse...
- Must survive failure of not just a disk, but a rack of servers or a whole data center

## ■ Solutions

- Simple redundancy (2 or 3 copies of each file)
  - e.g., Google GFS (2001)
- More efficient redundancy (analogous to RAID 3++)
  - e.g., Google Colossus filesystem (~2010): customizable replication including Reed-Solomon codes with 1.5x redundancy

- More interesting tidbits: <http://goo.gl/LwFly>



[ Today only! ]



Randy Katz  
Distinguished Professor,  
University of California at  
Berkeley

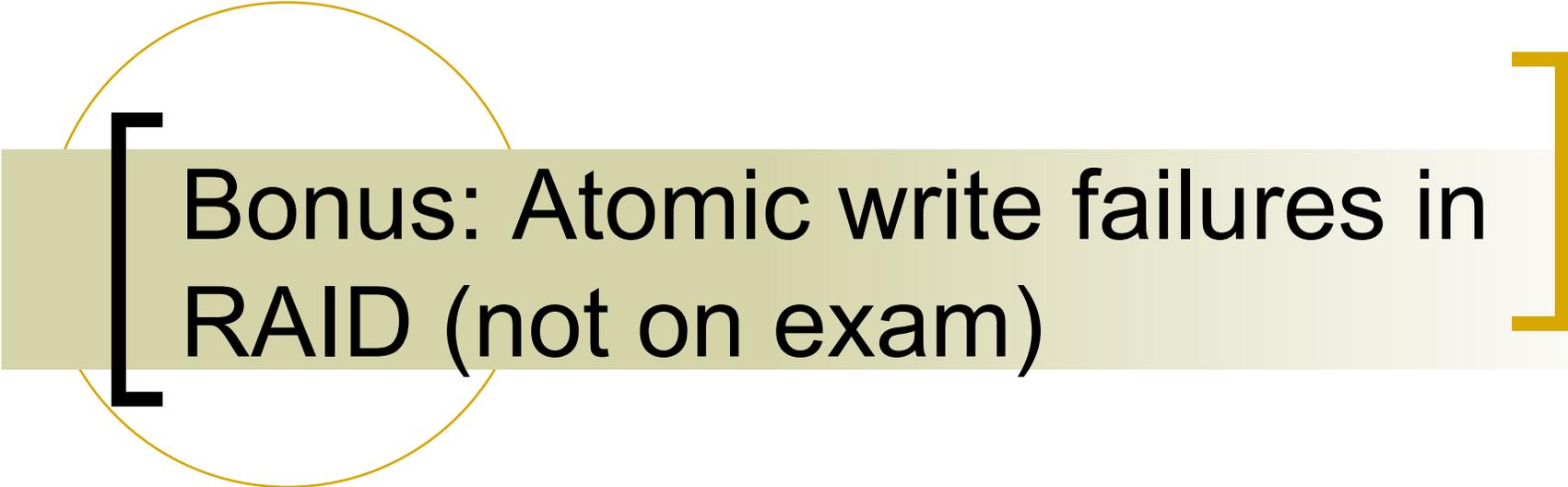


DONALD B. GILLIES MEMORIAL LECTURE

**“Mesos: A Platform for  
Fine-Grained Resource  
Sharing in the Data Center”**

4:00 p.m. Today  
2405 Siebel Center

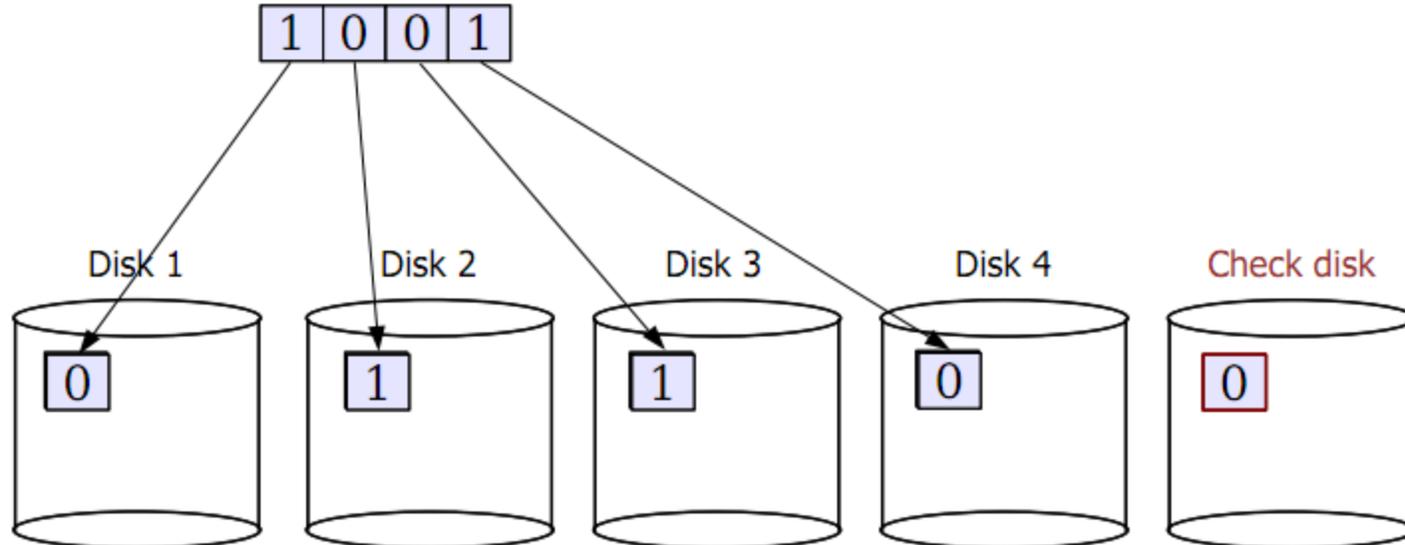




Bonus: Atomic write failures in  
RAID (not on exam)

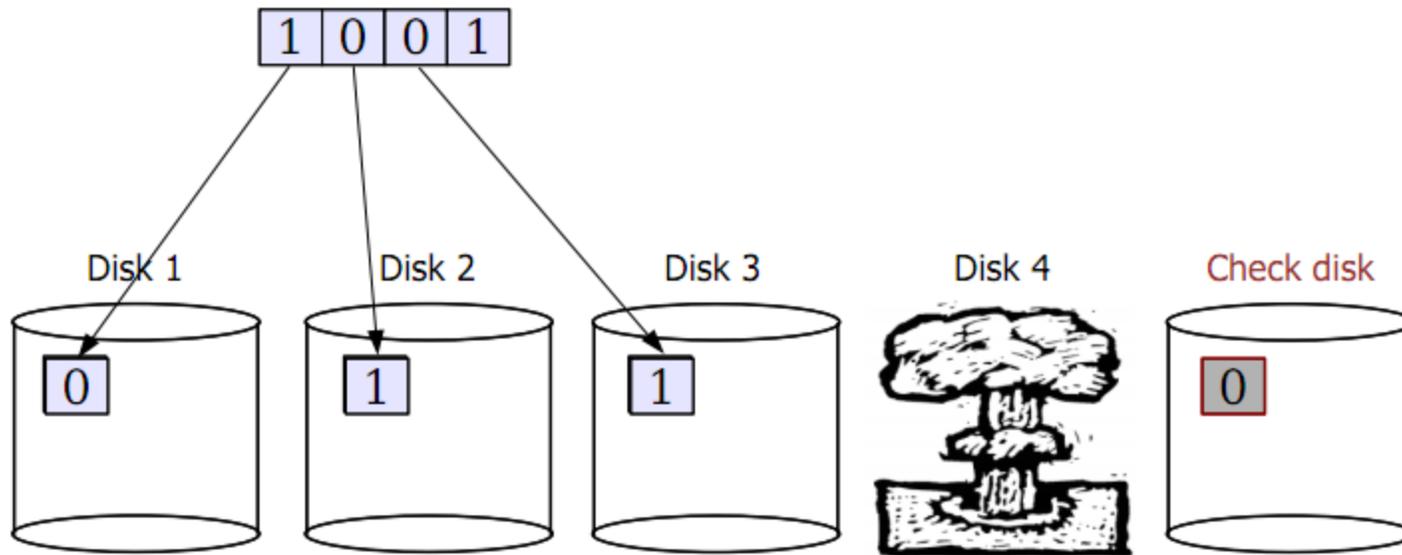
# [ Atomic Write Failure ]

- Many applications perform “update in place”
  - They change a file on disk by **overwriting** it with a new version
- What happens with RAID?



# [ Atomic Write Failure ]

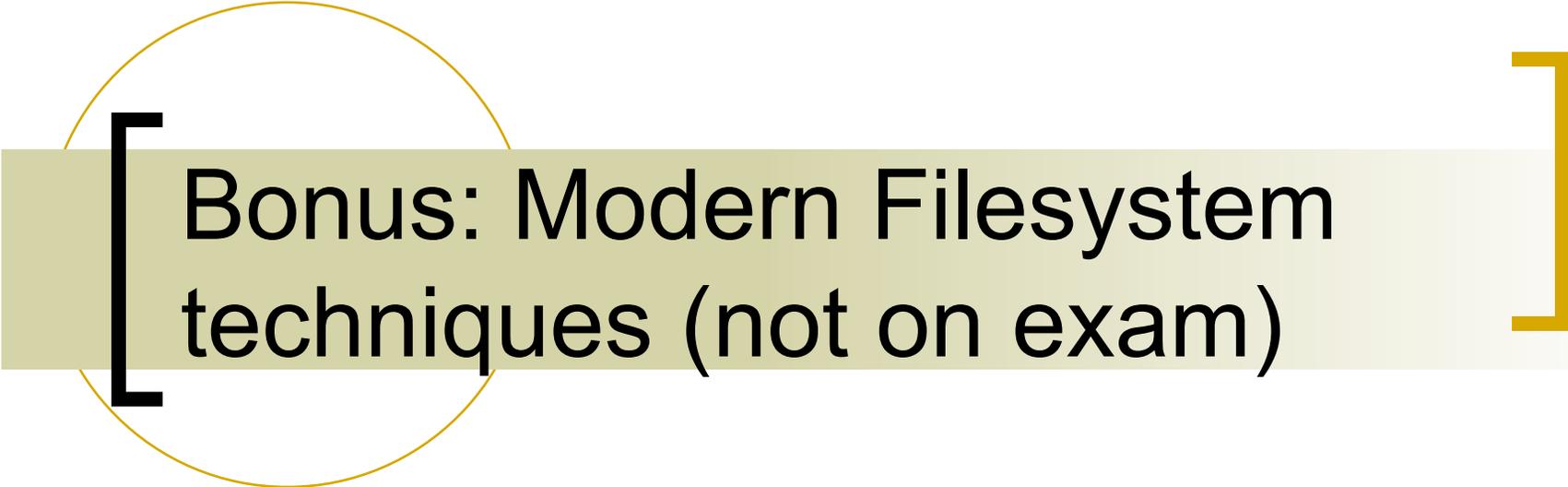
- But is the complete write to all disks really atomic?
  - Generally, no!



# [ Atomic Write Failure ]

- But is the complete write to all disks really atomic?
  - Generally, no!
- What does this mean?
  - Data can be left in an inconsistent state across the different disks!
  - Really hard to recover from this.
- Problem: Most applications assume the storage system has atomic write semantics.
- Possible fixes?
  - Use a journaling filesystem-like approach: Record changes to data objects transactionally.
    - Requires extensive changes to filesystem sitting on top of the RAID.
  - Battery-backed write cache:
    - RAID controller remembers all writes in a battery-backed cache
    - When recovery occurs, flush all writes out to the physical disks
    - Doesn't solve the problem in general but gives you some insurance.





**Bonus: Modern Filesystem  
techniques (not on exam)**

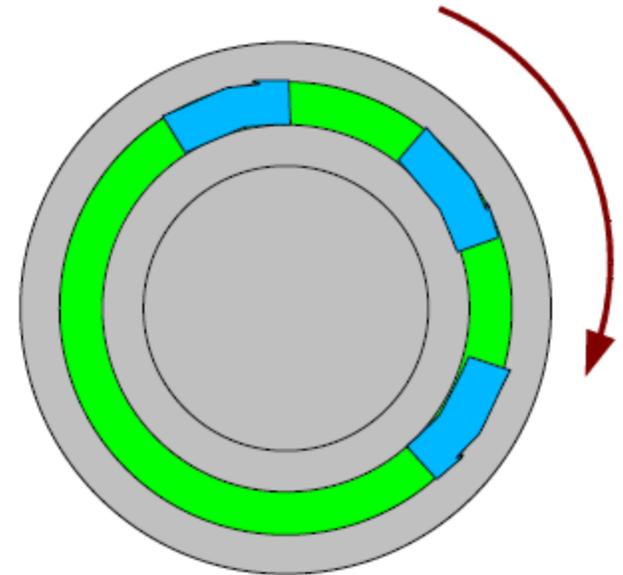
# [ Modern Filesystem Tricks ]

- Extents
- Pre-allocation
- Delayed allocation (Block remapping)
- Colocating inodes and directories
- Soft metadata updates
- Journaling
- These tricks are used by many modern filesystems
  - E.g., ext3 and ext4



# Extent-based transfers

- One idea: a gap between sectors on a track
  - Try to take advantage of rotational latency for performing next read or write operation
  - Problem: Hurts performance for multi-sector I/O!
  - Cannot achieve the full transfer rate of the disk for large, contiguous reads or writes.
- Possible fix: Just get rid of the gap between sectors
  - Problem: “Dropped rotation” between consecutive reads or writes: have to wait for next sector to come around under the heads.
- Hybrid approach - “extents” [McVoy, USENIX'91]
  - Group blocks into “extents” or clusters of contiguous blocks
  - Try to do all I/O on extents rather than individual blocks
  - To avoid wasting I/O bandwidth, only do this when FS detects sequential access
    - Kind of like just increasing the block size...



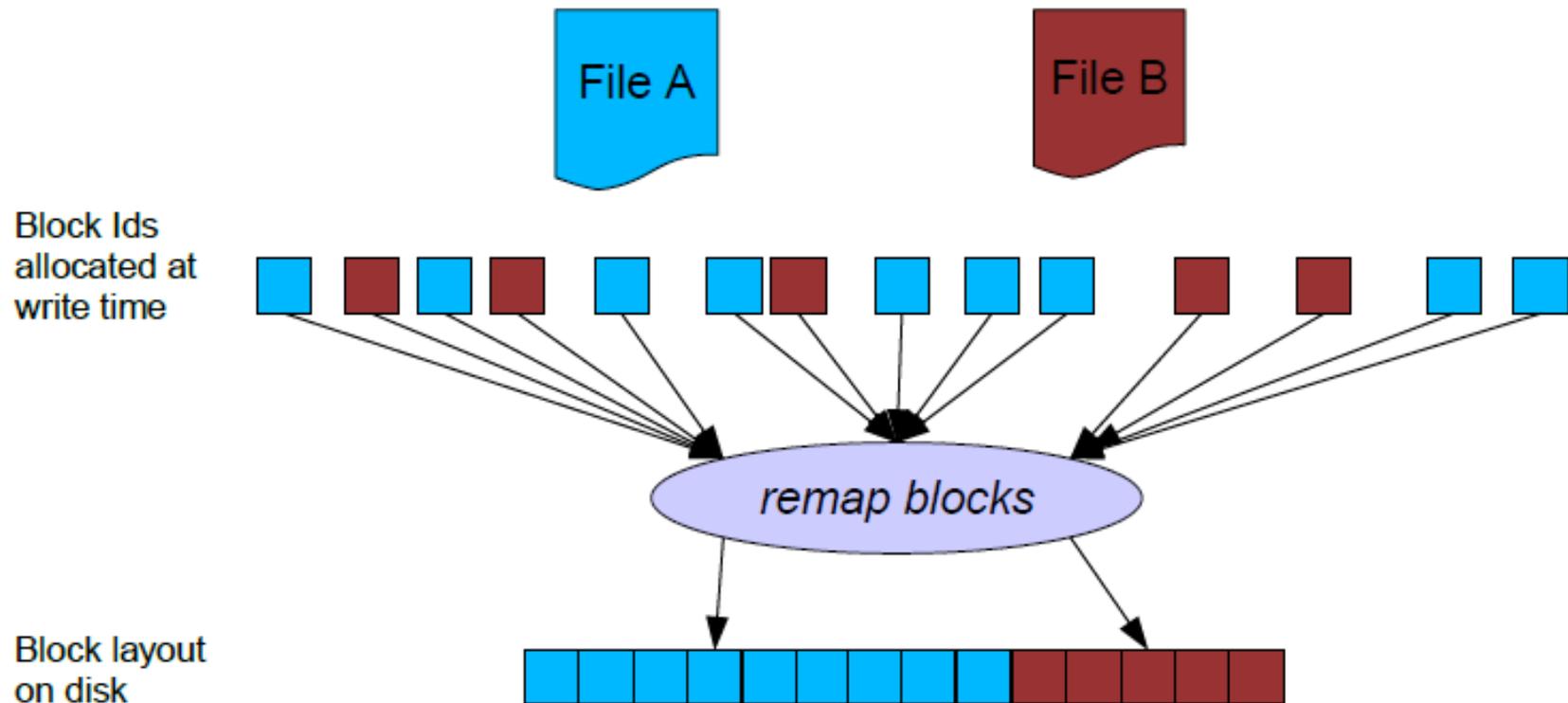
# [ Block remapping ]

- Problem: Block numbers are allocated when they are first written
  - FS maintains a free list of blocks and simply picks the first block off the list
    - No guarantee that these blocks will be contiguous for a large write!
  - A single file may end up with blocks scattered across the disk
- Why can't we maintain the free list in some sorted order?
  - Problem: Interleaved writes to multiple files may end up causing each file to be discontinuous.



# Block remapping

- Idea: Delay determination of block address until cache is flushed
  - Hope that multiple block writes will accumulate in the cache
  - Can remap the block addresses for each file's writes to a contiguous set
    - This is kind of a hack, introduced “underneath” the FFS block allocation layer.
    - Meant fewer changes to the rest of the FFS code.
    - Sometimes building real systems means making these kinds of tradeoffs!



# Colocating inodes and directories

- Problem: Reading small files is slow. Why?
  - What happens when you try to read all files in a directory (e.g., “ls -l” or “grep foo \*”) ?
  - Must first read directory.
  - Then read inode for each file.
  - Then read data pointed to by inode.
- Solution: Embed the inodes in the directory itself!
  - Recall: Directory just a set of <name, inode #> values
  - Why not stuff inode contents in the directory file itself?
- Problem #2: Must still seek to read contents of each file in the directory.
  - Solution: Pack all files in a directory in a contiguous set of blocks.



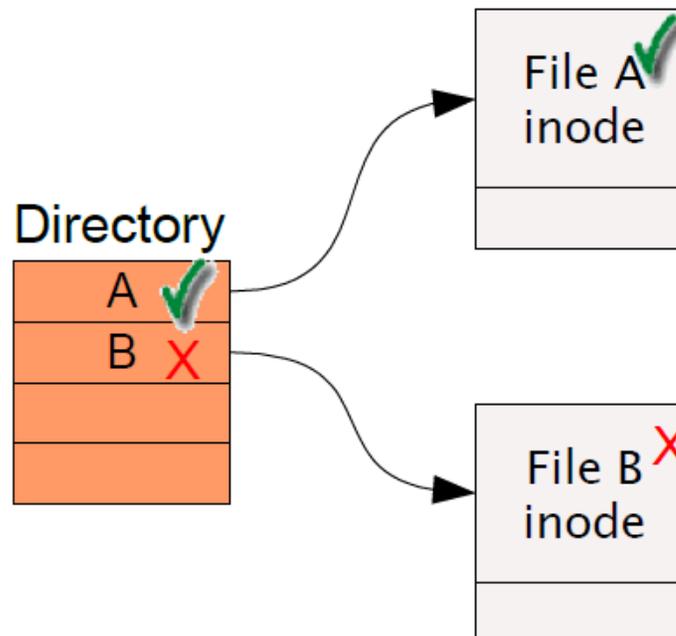
# [ Synchronous metadata updates ]

- Problem: Some updates to metadata require synchronous writes
  - Means the data has to “hit the disk” before anything else can be done.
- Example #1: Creating a file
  - Must write the new file's inode to disk before the corresponding directory entry.
    - Why???
- Example #2: Deleting a file
  - Must clear out the directory entry before marking the inode as “free”
    - Why???



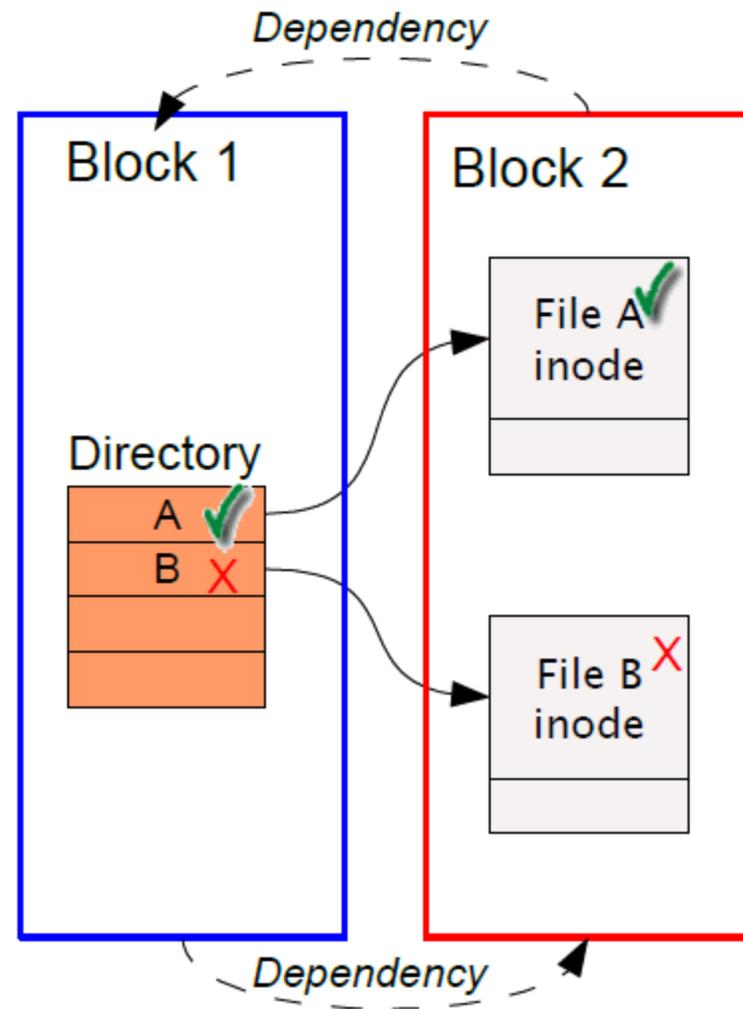
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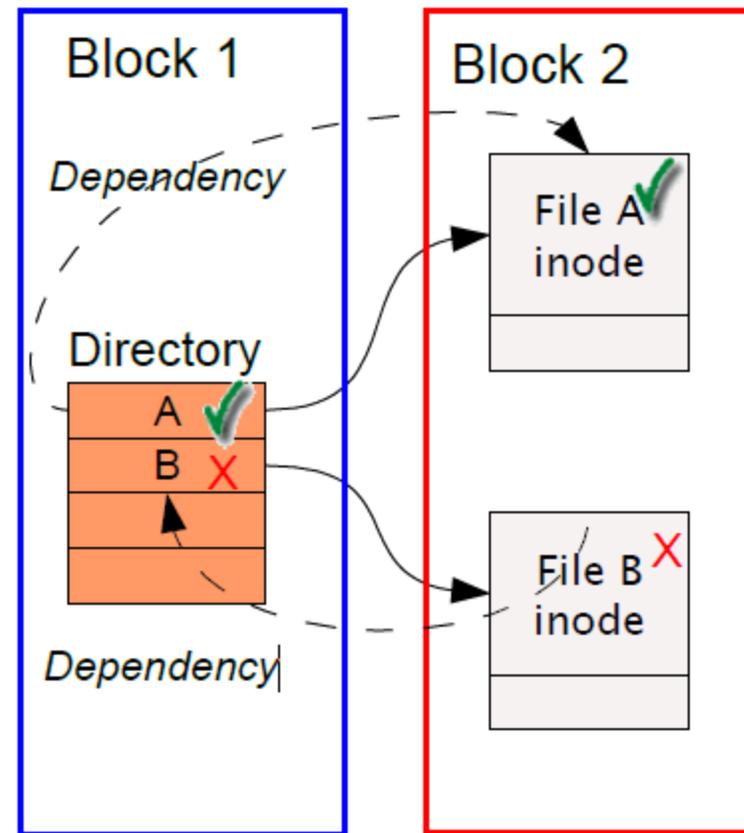
# [ Synchronous metadata updates ]

- Say that ...
  - 1) Both inodes are in the same disk block.
  - 2) Both the file create and file delete have happened in the cache, but neither has hit the disk yet.
  - Given this, what order are we allowed to write the disk blocks out?
    - *We have a cyclic dependency here!!!  
Argggghhhh ....*



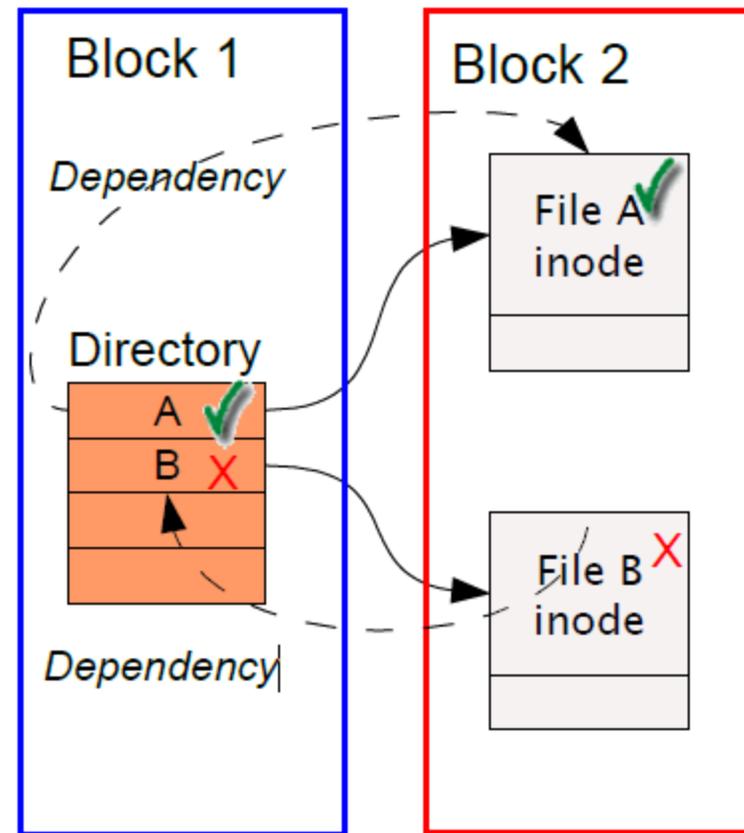
# [ Solution: Soft Updates ]

- Idea: Keep track of dependencies on a finer granularity
  - Rather than at a block level, do this at a “data structure level”
  - Example: Track dependencies on individual inodes or directory entries.



# Soft Updates - Example

- How to break the cyclic dependency?
  - “Roll back” one of the changes before writing the data out to disk!
- When flushing inode block (Block 2) to disk...
  - **Undo** the file delete operation (as if it never happened!)
  - Write out the inode block (Block 2) – still contains B!
  - Then write out the directory block (Block 1) – still contains entry for B!
  - Then **redo** the file delete operation ... can now proceed.



# [ Log-structured Filesystems (LFS) ]

- Around '91, two trends in disk technology were emerging:
  - Disk bandwidth was increasing rapidly (over 40% a year)
  - Seek latency not improving much at all
  - Machines had increasingly large main memories
    - Large buffer caches absorb a large fraction of read I/Os
  - Can use for writes as well!
    - Coalesce several small writes into one larger write
- Some lingering problems with earlier filesystems...
  - Writing to file metadata (inodes) was required to be synchronous
    - Couldn't buffer metadata writes in memory
  - Lots of small writes to file metadata means lots of seeks!
- LFS takes advantage of both to increase FS performance
  - Started as a grad-school research project at Berkeley
  - Mendel Rosenblum and John Ousterhout

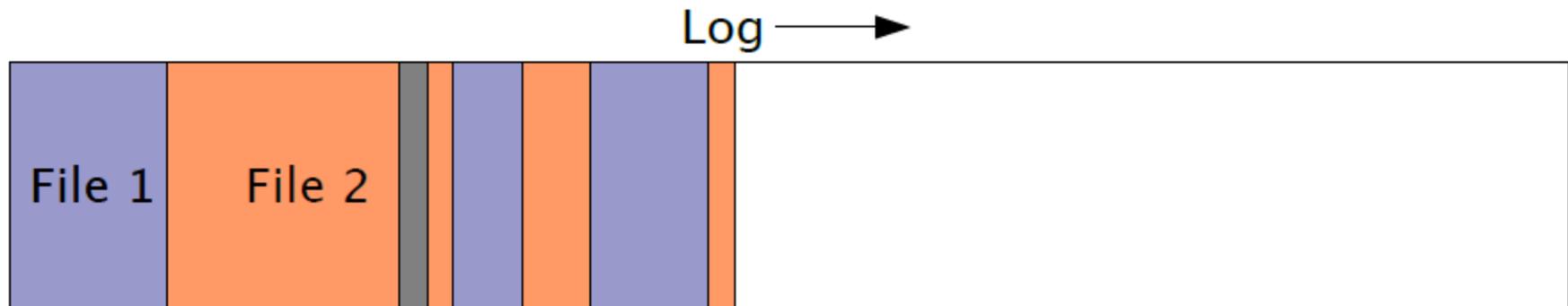


# LFS: The basic idea

- Treat the entire disk as *one big append-only log for writes!*
  - Don't try to lay out blocks on disk in some predetermined order
  - Whenever a file write occurs, append it to the *end of the log*
  - Whenever file metadata changes, append it to the *end of the log*
- Collect pending writes in memory and stream out in one big write
  - Maximizes disk bandwidth
  - No “extra” seeks required (only those to move the end of the log)
- When do writes to the actual disk happen?
  - When a user calls `sync()` -- synchronize data on disk for whole filesystem
  - When a user calls `fsync()` -- synchronize data on disk for one file
  - When OS needs to reclaim dirty buffer cache pages
    - *Note that this can often be avoided, eg., by preferring clean pages*
- Sounds simple ...
  - But lots of hairy details to deal with!



# [ LFS Example ]

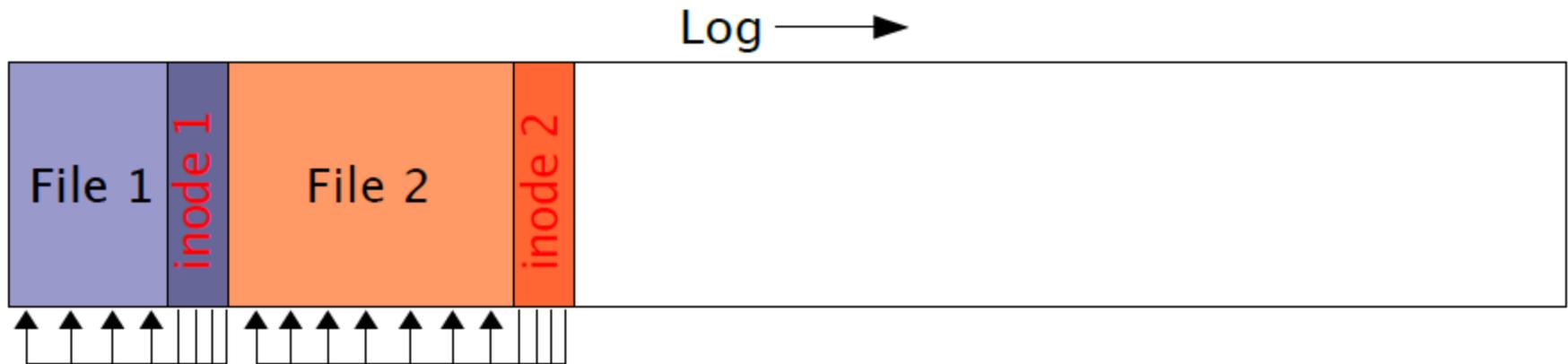


- Just append every new write that happens to the end of the log
  - Writing a block in the middle of the file just appends that block to the end of the log



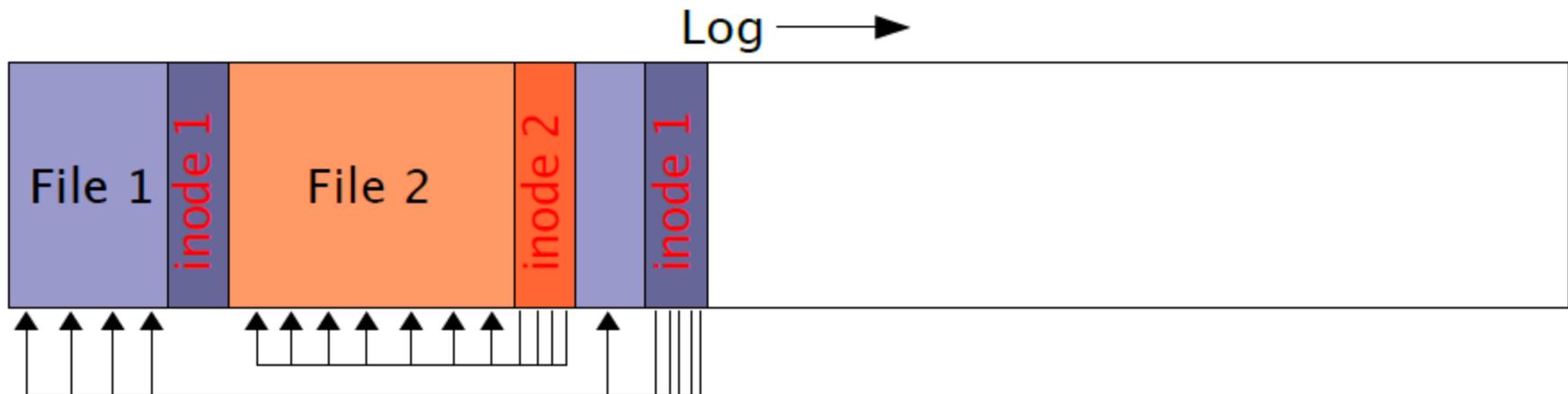
# [ LFS and inodes ]

- How do you locate file data?
  - Sequential scan of the log is probably a bad idea ...
- Solution: Write the inodes to the tail of the log! (just like regular data)



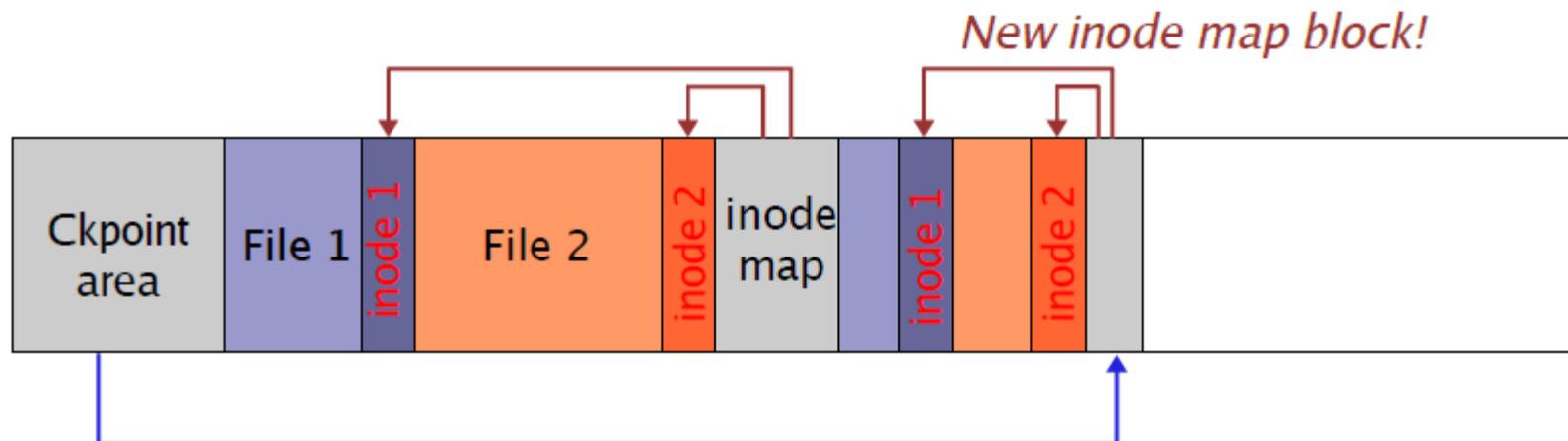
# [ LFS and inodes ]

- How do you locate file data?
  - Sequential scan of the log is probably a bad idea ...
- Solution: Use FFS-style inodes!



# [ inode map (this is getting fun) ]

- Well, now, how do you find the inodes??
  - Could also be anywhere in the log!
- Solution: *inode maps*
  - Maps “file number” to the location of its inode in the log
  - Note that inode map is *also written to the log!!!!*
  - Cache inode maps in memory for performance



*Fixed checkpoint region tracks location of inode map blocks in log*



# [ Reading from LFS ]

- But wait ... now file data is scattered all over the disk!
  - Seems to obviate all of the benefits of grouping data on common cylinders
- Basic assumption: Buffer cache will handle most read traffic
  - Or at least, reads will happen to data roughly in the order in which it was written
  - Take advantage of huge system memories to cache the heck out of the FS!



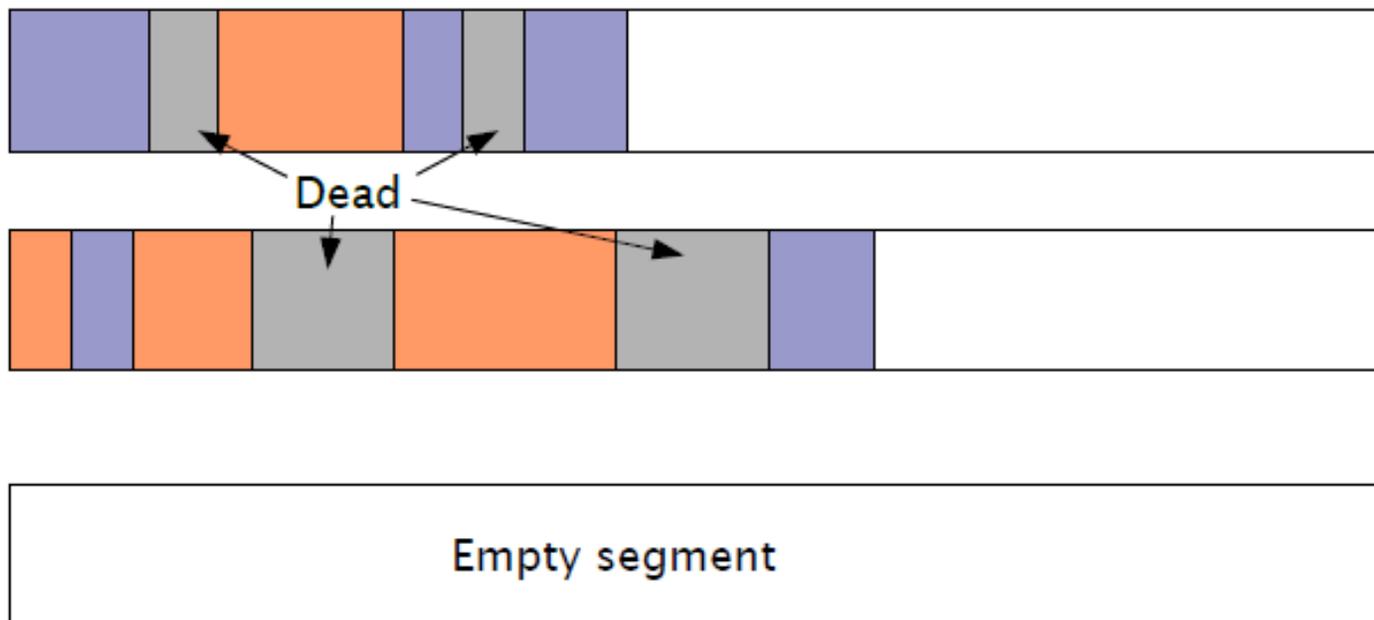
# [ Log cleaner ]

- With LFS, eventually the disk will fill up!
  - Need some way to reclaim “dead space”
- What constitutes “dead space?”
  - Deleted files
  - File blocks that have been “overwritten”
- Solution: Periodic “log cleaning”
- Scan the log and look for deleted or overwritten blocks
  - Effectively, clear out stale log entries
- Copy *live data to the end of the log*
  - The rest of the log (at the beginning) can now be reused!



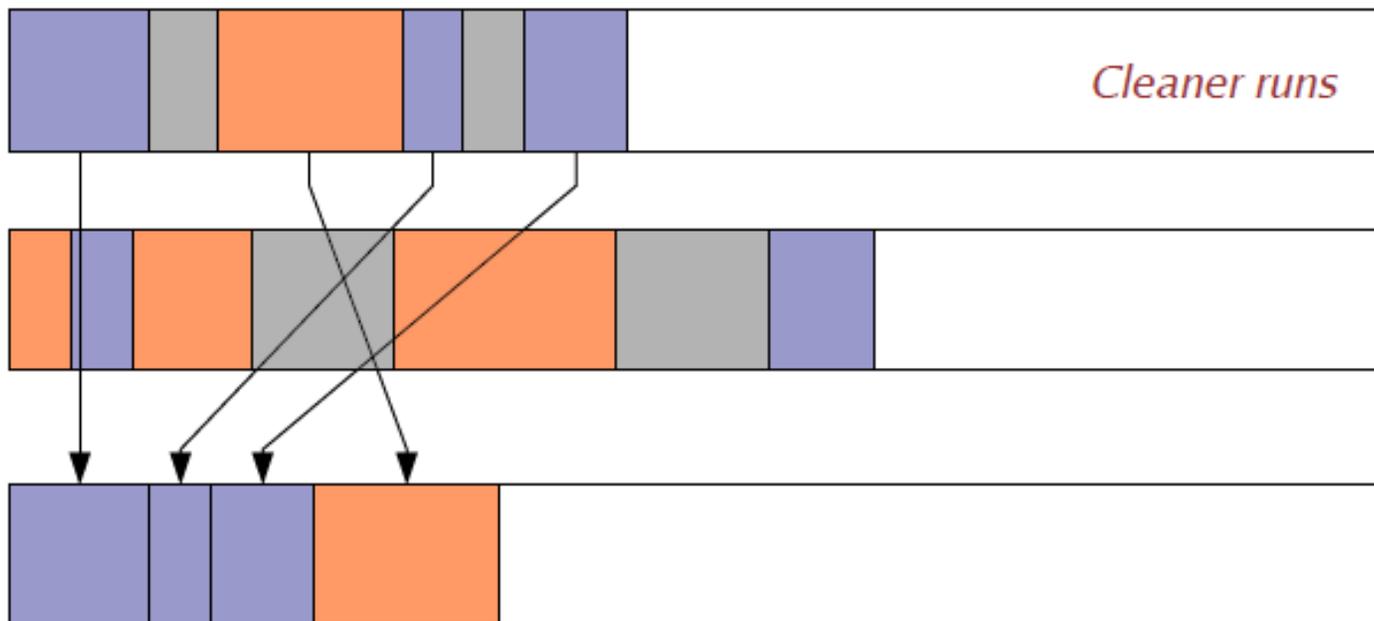
# [ Log cleaning example ]

- LFS cleaner breaks log into *segments*
  - Each segment is scanned by the cleaner
  - Live blocks from a segment are copied into a new segment
  - The entire scanned segment can then be reclaimed



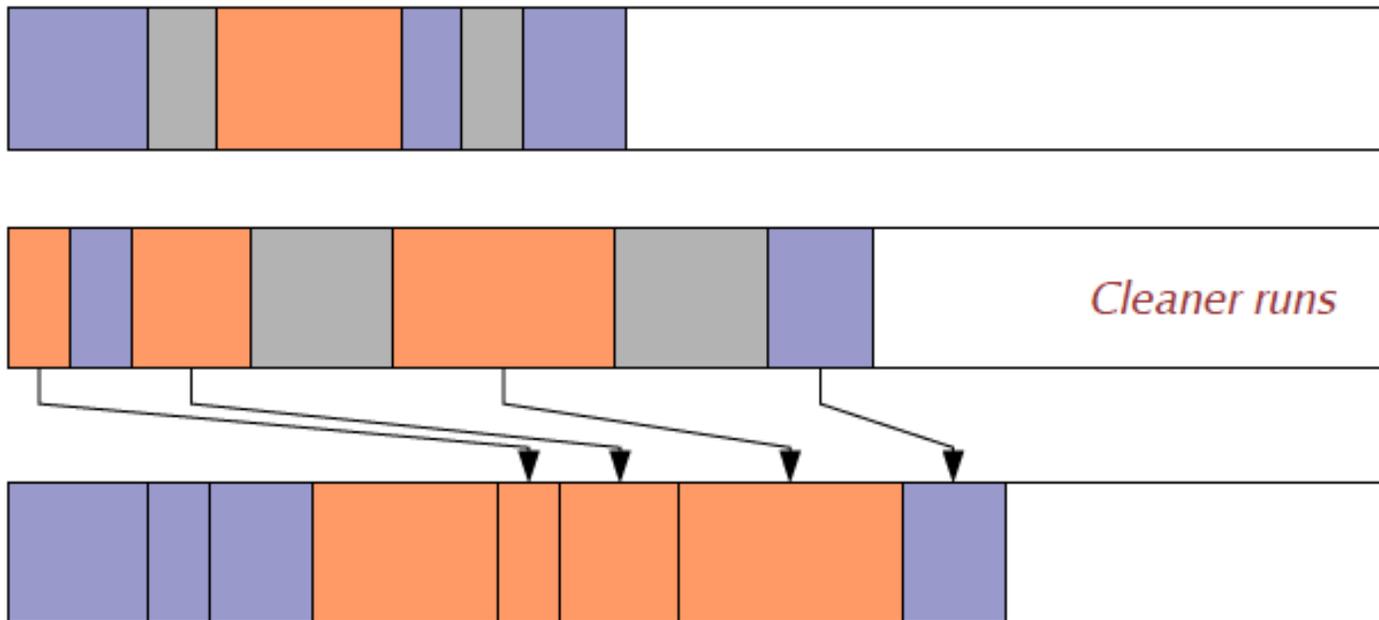
# Log cleaning example

- LFS cleaner breaks log into *segments*
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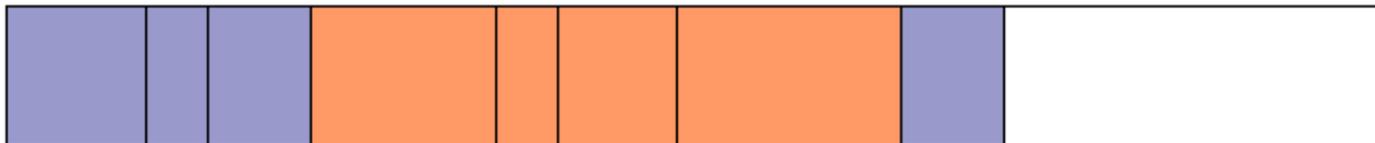
# Log cleaning example

- LFS cleaner breaks log into *segments*
  - Each segment is scanned by the cleaner
  - Live blocks from a segment are copied into a new segment
  - The entire scanned segment can then be reclaimed



# [ Log cleaning example ]

- LFS cleaner breaks log into *segments*
  - Each segment is scanned by the cleaner
  - Live blocks from a segment are copied into a new segment
  - The entire scanned segment can then be reclaimed



# [ Properties of LFS ]

- Advantages
  - High write throughput
  - Few in-place writes
    - Some kinds of storage media have limited write/erase cycles per location (e.g., flash memory, CD-RW)
    - LFS prolongs life of media through [write-leveling](#)
- Disadvantages
  - Increases file fragmentation, can harm performance on systems with high seek times
  - Less throughputs on flash memory, where write fragmentation has much less of an impact on write throughput
- “Lies, damn lies, and benchmarks”
  - It is very difficult to come up with definitive benchmarks proving that one system is better than another
  - Can always find a scenario where one system design outperforms another



# Filesystem corruption

- What happens when you are making changes to a filesystem and the system crashes?
  - Example: Modifying block 5 of a large directory, adding lots of new file entries
  - System crashes while the block is being written
  - The new files are “lost!”
- System runs `fsck` program on reboot
  - Scans through the entire filesystem and locates corrupted inodes and directories
  - Can typically find the bad directory, but may not be able to repair it!
  - *The directory could have been left in any state during the write*
- `fsck` can take a very long time on large filesystems
  - And, no guarantees that it fixes the problems anyway



# [ Journaling filesystems ]

- Ensure that changes to the filesystem are made *atomically*
  - That is, a group of changes are made all together, or not at all
- Example: creating a new file
  - Need to write both the inode for the new file and the directory entry “together”
  - Otherwise, if a crash happens between the two writes, either..
    - 1) Directory points to a file that does not exist
    - 2) Or, file is on disk but not included in any directory



# Journaling filesystems

- Goal: Make updates to filesystems appear to be atomic
  - The directory either looks exactly as it did **before the file was created**
  - Or the directory looks exactly as it did **after the file was created**
  - Cannot leave an FS entity (data block, inode, directory, etc.) in an intermediate state!
- Idea: Maintain a **log of all changes to the filesystem**
  - Log contains information on any operations performed to the filesystem state
  - e.g., “Directory 2841 had inodes 404, 407, and 408 added to it”
- To make a filesystem change:
  - 1. Write an *intent-to-commit* record to the log
  - 2. Write the appropriate **changes to the log**
    - *Do not modify the filesystem data directly!!!*
  - 3. Write a *commit record* to the log
- This is very similar to the notion of database *transactions*<sup>64</sup>

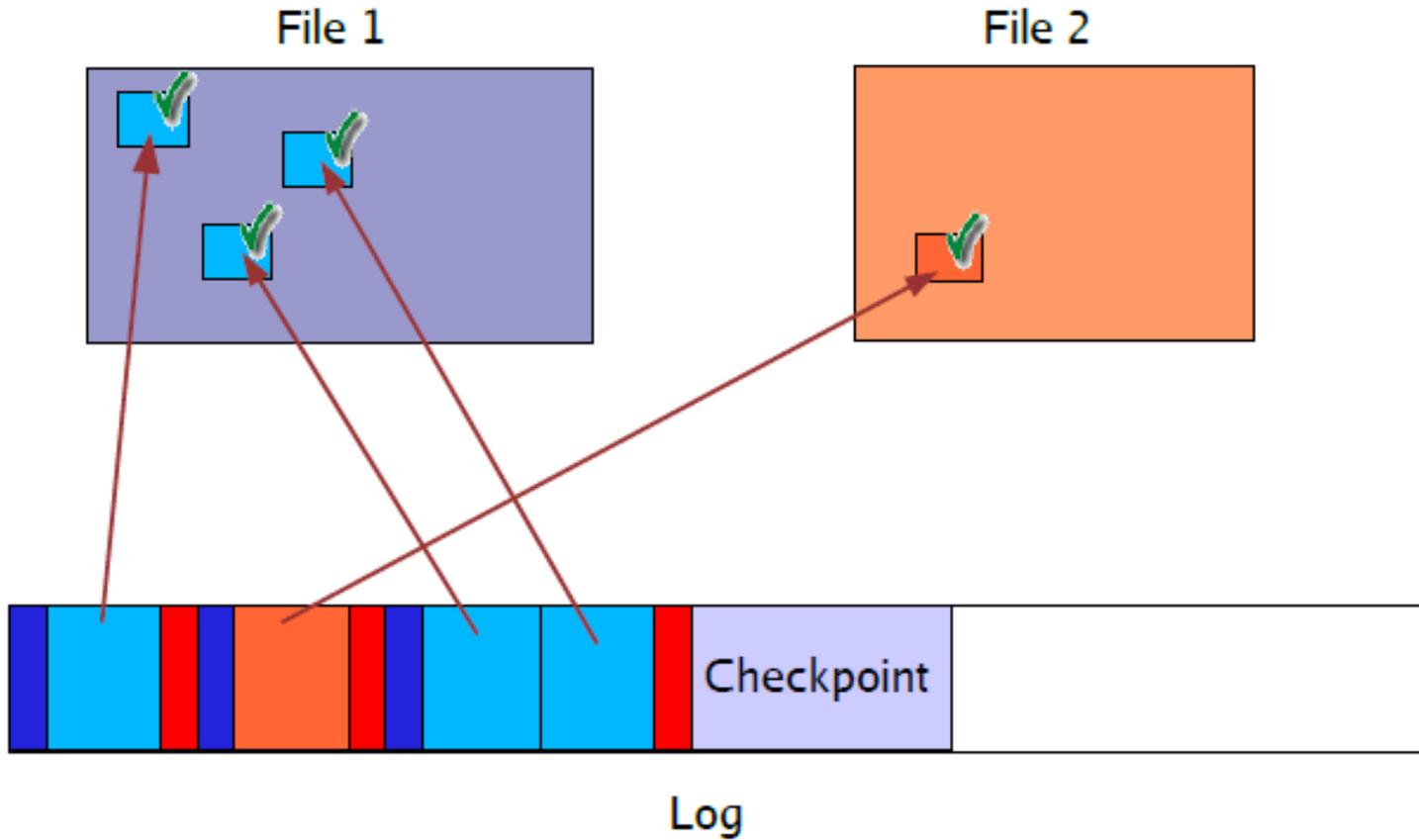


# [ Journaling FS Recovery ]

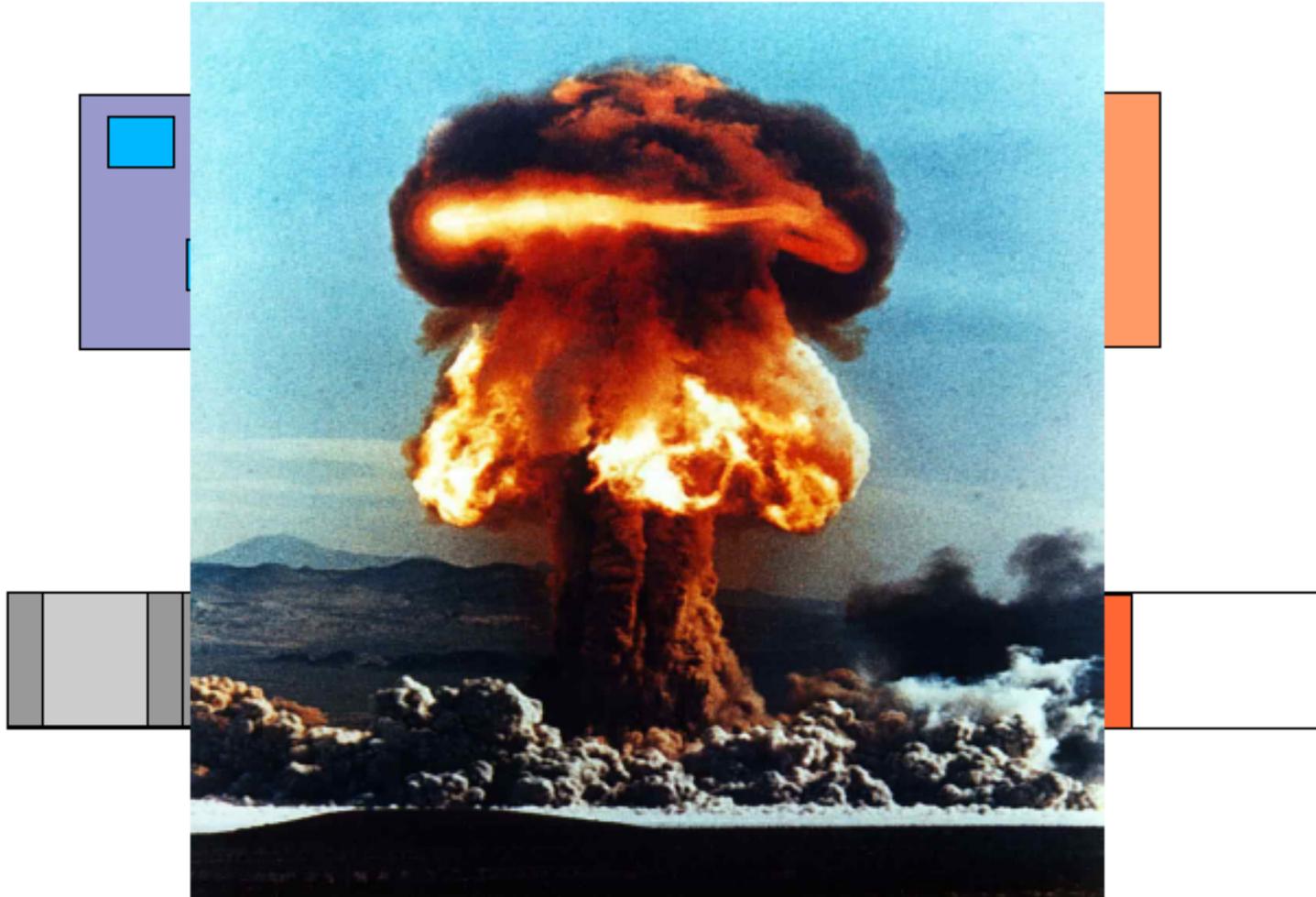
- What happens when the system crashes?
  - Filesystem data has not actually been modified, just the log!
  - So, the FS itself reflects only what happened *before the crash*
- Periodically synchronize the log with the filesystem data
  - Called a *checkpoint*
  - Ensures that the FS data reflects all of the changes in the log
- No need to scan the entire filesystem after a crash...
  - Only need to look at the log entries **since the last checkpoint!**
- For each log entry, see if the commit record is there
  - If not, consider the changes incomplete, and don't try to make them



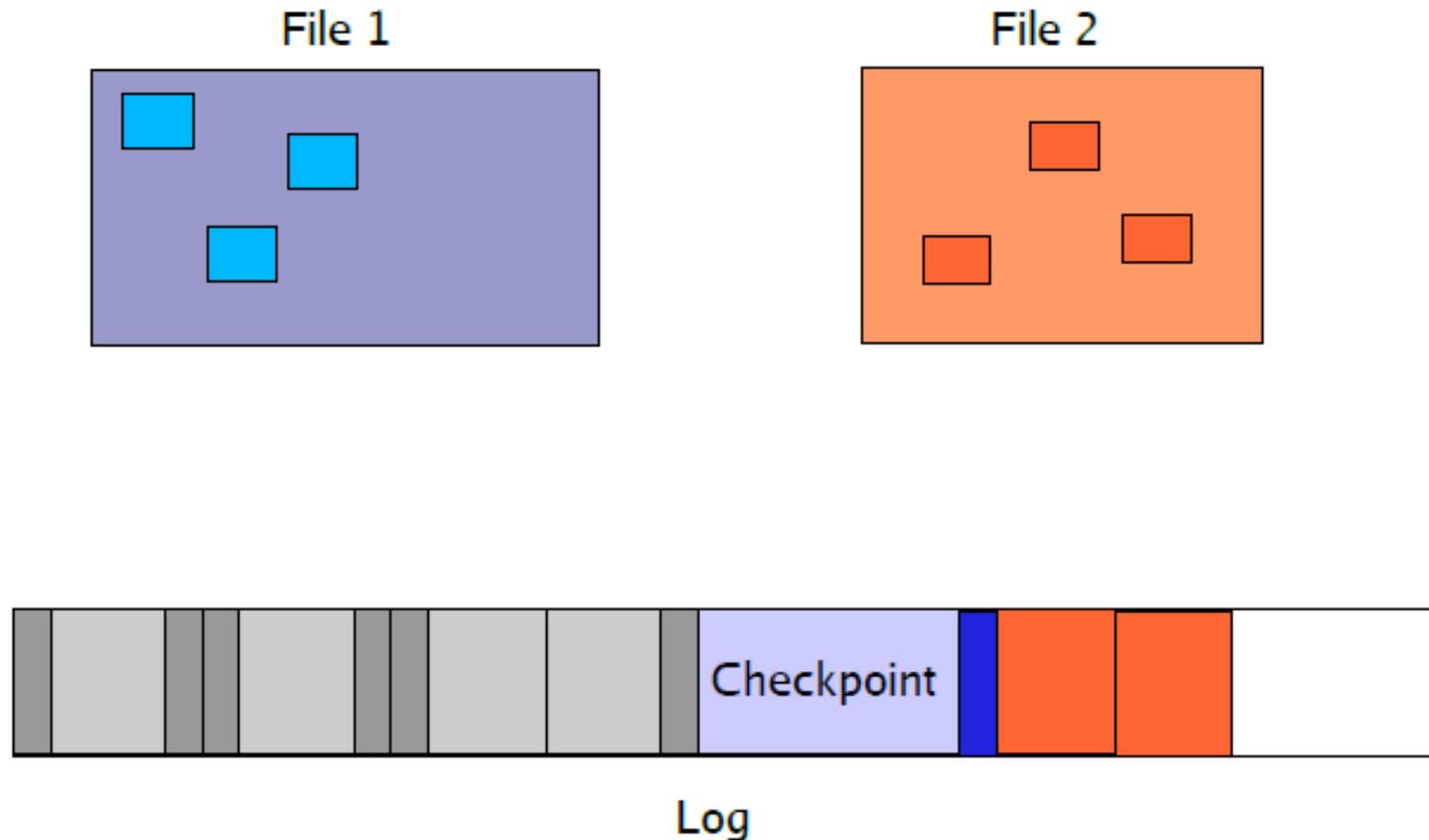
# [ Journaling FS Example ]



# Journaling FS Example



# [ Journaling FS Example ]



- Filesystem reflects changes up to last checkpoint
- Fscck scans changelog from last checkpoint forward
- Doesn't find a commit record ... changes are simply ignored





# Bonus: NFS

# [ More recent filesystems ]

- How can we share filesystems over a network?
  - NFS, SAN, NAS, Hadoop
- How can we make a filesystem resilient to failures?
  - RAID (covered in earlier slides)



# [ Networked File System (NFS) ]

- NFS allows a system to access files over a network
  - One of many distributed file systems
  - Extremely successful and widely used
    - You use NFS on all your shared files in the lab machines



# Networked File System (NFS)

- Development of LANs made it really attractive to provide shared file systems to all machines on a network
  - Login to any machine and see the same set of files
  - Install software on a single server that all machines can run
  - Let users collaborate on shared set of files (before CVS)
- Why might this be hard to do?
  - Clients and servers might be running different OS
  - Clients and servers might be using different CPU architecture with differing byte ordering (**endianess**)
  - Client or server might crash independently of each other
    - Must be easy to recover from crashes
  - Potentially very large number of client machines on a network
  - Different users might be trying to modify a shared file at the same time
  - Transparency: Allow user programs to access remote files just like local files
    - No special libraries, recompilation, etc.

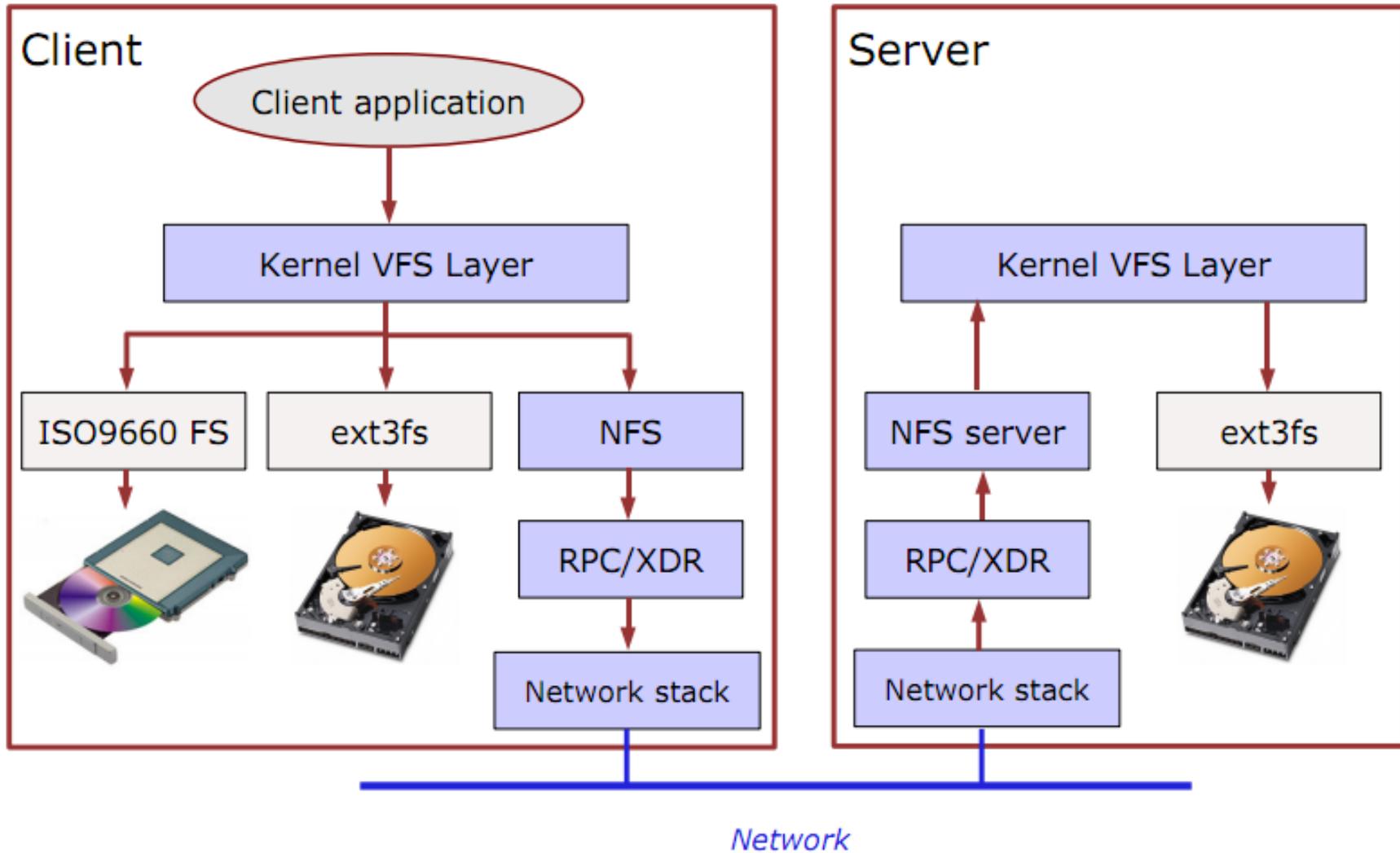


# NFS Overview

- NFS was developed by Sun Microsystems in the mid-80s
  - Networked machines at the time were predominantly UNIX-based workstations
  - Various vendors: Sun, DEC, IBM, etc.
  - Different CPU architectures and OS implementations
    - But, all used UNIX filesystem structure and semantics
- NFS is based on Remote Procedure Call (RPC)
  - Allows a client machine to invoke a function on a server machine, over a network
  - Client sends a message with the function arguments
  - Server replies with a message with the return value.
- External Data Representation (XDR) to represent data types
  - Canonical network representation for ints, longs, byte arrays, etc.
  - Clients and servers must translate parameters and return values of RPC calls into XDR before shipping on the network
  - Otherwise, a little-endian machine and a big-endian machine would disagree on what is meant by the stream of bytes “fe 07 89 da” interpreted as an “int”



# [ NFS Design ]



# Stateless Protocol

- The NFS protocol is *stateless*
  - The server maintains no information about individual clients!
  - This means that NFS does not support any notion of “opening” or “closing” files
  - Each client simply issues read and write requests specifying the file, offset in the file, and the requested size
- Advantages:
  - Server doesn't need to keep track of open/close status of files
  - Server doesn't need to keep track of “file offset” for each client's open files
    - Clients do this themselves
  - Server doesn't have to do anything to recover from a crash!
    - Clients simply retry NFS operations until the server comes back up
- Disadvantages:
  - Server doesn't keep track of concurrent access to same file
  - Multiple clients might be modifying a file at the same time
    - NFS does not provide any consistency guarantees!!!
  - However, there is a separate **locking protocol** – discussed later



# [ NFS Protocol Overview ]

- **mount()** returns filehandle for root of filesystem
  - Actually a separate protocol from NFS...
- **lookup(dir-handle, filename)** returns filehandle, attribs
  - Returns unique file handle for a given file
  - File handle used in subsequent read/write/etc. calls
- **create(dir-handle, filename, attributes)** returns filehandle
- **remove(dir-handle, filename)** returns status
- **getattr(filehandle)** returns attribs
  - Returns attributes of the file, e.g., permissions, owner, group ID, size, access time, last-modified time
- **setattr(filehandle, attribs)** returns attribs
- **read(filehandle, offset, size)** returns attribs, data
- **write(filehandle, offset, count, data)** returns attribs



# [ NFS Caching ]

- NFS clients are responsible for caching recently-accessed data
  - Remember: the server is stateless!
- The NFS protocol does not *require* that clients cache data ...
  - But, it provides support allowing a range of client-side caching techniques
- This is accomplished through the `getattr()` call
  - Returns size, permissions, and last-modified time of file
  - This can tell a client whether a file has changed since it last read it
  - **Read/write calls also return attributes so client can tell if object was modified since the last `getattr()` call**
- How often should the client use `getattr()`?
  - Whenever the file is accessed?
    - **Could lead to a lot of `getattr` calls!**
  - Only if the file has not been accessed for some time?
    - **e.g., If the file has not been accessed in 30 sec?**
  - Different OSs implement this differently!



# [ NFS Locking ]

- NFS does not prevent multiple clients from modifying a file simultaneously
  - Clearly, this can be a Bad Thing for some applications...
- Solution: Network Lock Manager (NLM) protocol
  - Works alongside NFS to provide file locking
  - NFS itself does not know anything about locks
    - Clients have to use NLM “voluntarily” to avoid stomping on each other
  - NLM has to be **stateful**
    - Why?

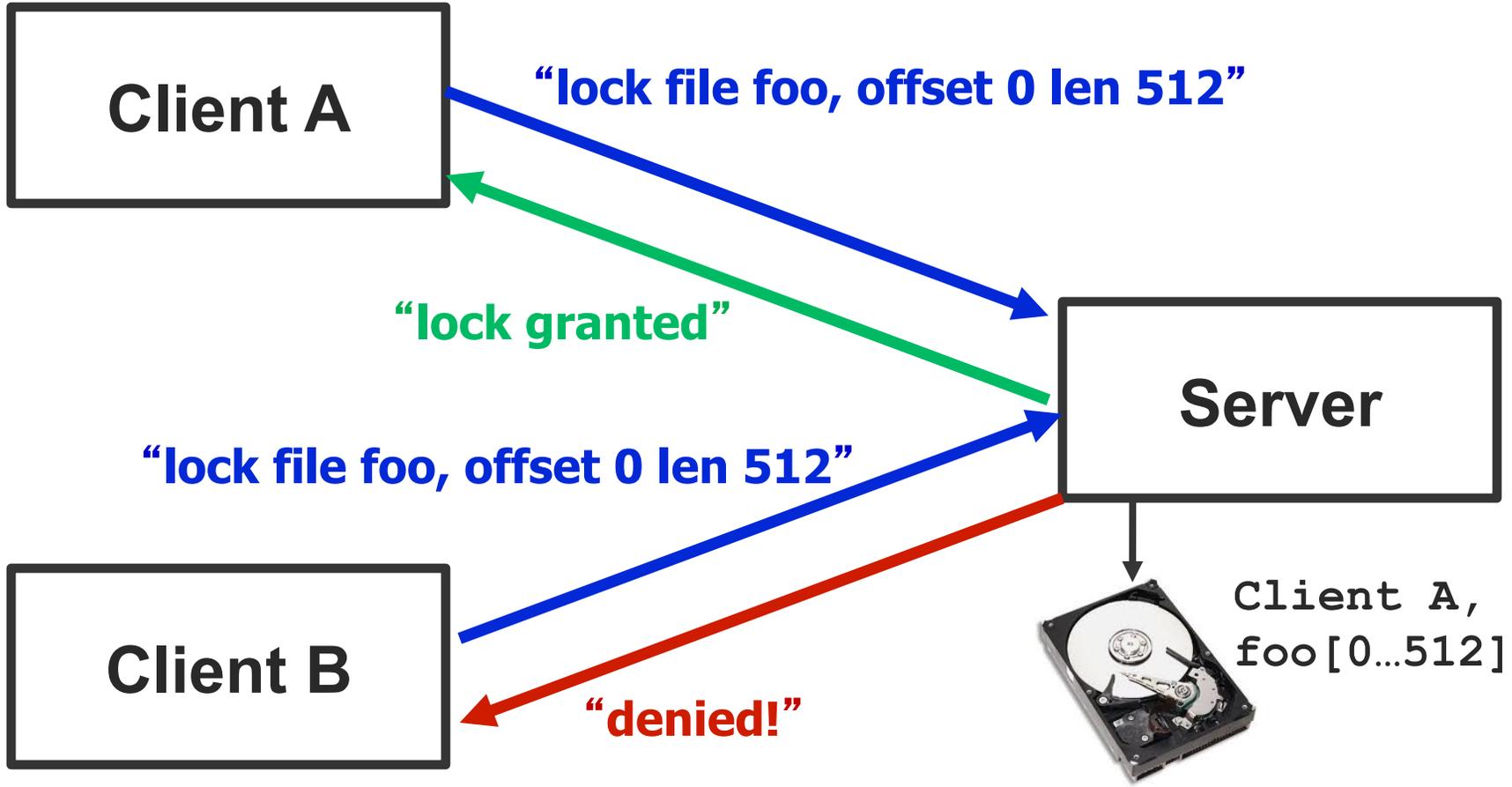


# [ NLM Protocol ]

- NLM server has to keep track of locks held by clients
- If the NLM server crashes...
  - All locks are released!
  - BUT ... clients can reestablish locks during a “grace period” after the server recovers
    - No new locks are granted during the grace period
    - Server has to remember which locks were previously held by clients
- If an NLM client crashes...
  - The server is notified when the client recovers and releases all of its locks
    - What happens if a client crashes and does not come back up for a while?
- Servers and clients must be notified when they crash and recover
  - This is done with the simple “Network Status Monitor” (NSM) protocol
  - Essentially, send a notification to the other host when you reboot



# [ NLM Example ]



# [ NLM Example ]

Client A

Client B

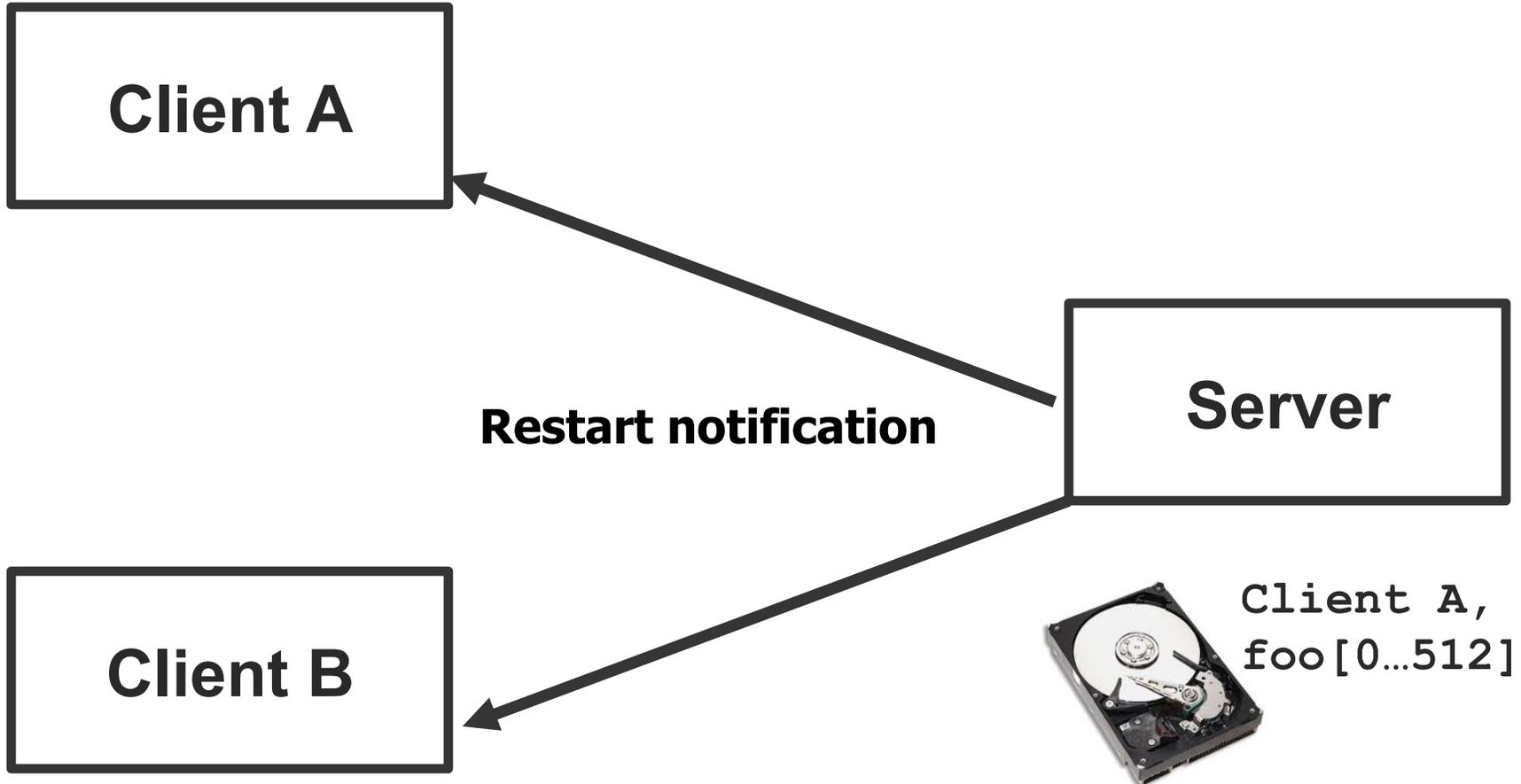


er



Client A,  
foo[0..512]

# [ NLM Example ]



# [ NLM Example ]

