



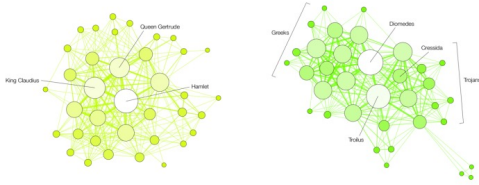
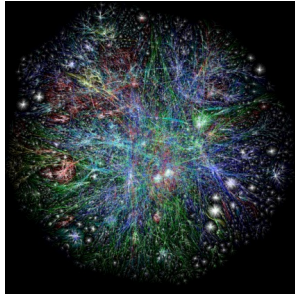
# CS 225

## Data Structures

*March 29 – Minimum Spanning Tree (Prim)*

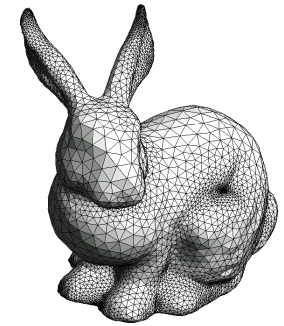
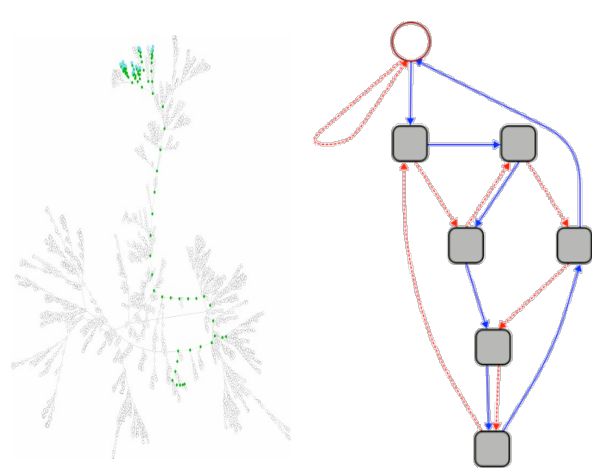
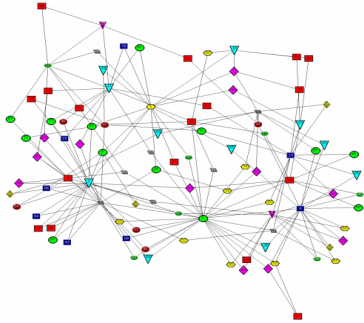
*G Carl Evans*

# Graphs



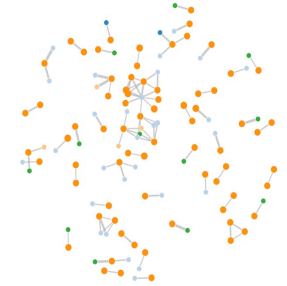
HAMLET

TROILUS AND CRESSIDA



To study all of these structures:

1. A common vocabulary
2. Graph implementations
3. Graph traversals
4. Graph algorithms



```
heapify(int* arr, unsigned int n){
    push arr;
    mov rsi, rdi;
    sub rdi, 25;
    mov dword ptr [rdi + 8], rsi;
    mov dword ptr [rdi + 12], rsi;
    jmp .LBB_0
```

```
heapify(int* arr, unsigned int n){
    mov rax, dword ptr [rdi + 8];
    mov ecx, dword ptr [rdi + 12];
    mov rax, qword ptr [rax + 4*rdi];
    mov rax, qword ptr [rdi + 8];
    mov esi, dword ptr [rdi + 12];
    shr esi, 1;
    mov ecx, esi;
    mov ecx, dword ptr [rax + 4*rdi];
    jmp .LBB_3
```

```
heapify(int* arr, unsigned int n){
    mov rax, qword ptr [rdi + 8];
    mov rax, dword ptr [rax - 8];
    mov ecx, dword ptr [rdi + 12];
    mov ecx, dword ptr [rax + 4*rdi];
    mov ecx, dword ptr [rdi + 8];
    mov esi, dword ptr [rdi + 12];
    shr esi, 1;
    mov ecx, esi;
    mov ecx, dword ptr [rax + 4*rdi];
    mov rax, qword ptr [rdi + 8];
    mov esi, dword ptr [rdi + 12];
    shr esi, 1;
    mov ecx, esi;
    mov ecx, dword ptr [rax + 4*rdi];
    mov rax, qword ptr [rdi + 8];
    mov ecx, dword ptr [rdi + 12];
    shr esi, 1;
    mov ecx, esi;
    mov ecx, dword ptr [rax + 4*rdi];
    call heapify(int*, unsigned int)
```

```
.LBB_3:
    jmp .LBB_1
```

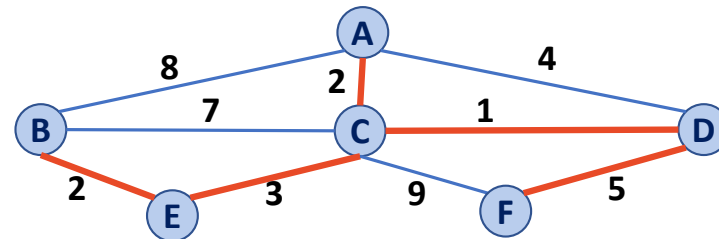
```
.LBB_4:
    add rsp, 25;
    pop rdi;
    ret
```

# Minimum Spanning Tree Algorithms

**Input:** Connected, undirected graph  $G$  with edge weights (unconstrained, but must be additive)

**Output:** A graph  $G'$  with the following properties:

- $G'$  is a spanning graph of  $G$
- $G'$  is a tree (connected, acyclic)
- $G'$  has a minimal total weight among all spanning trees

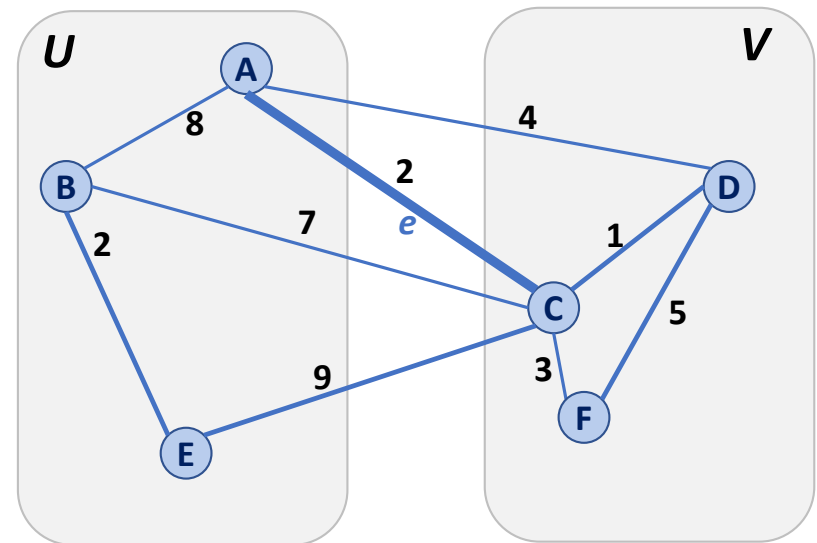


## Partition Property

Consider an arbitrary partition of the vertices on  $G$  into two subsets  $U$  and  $V$ .

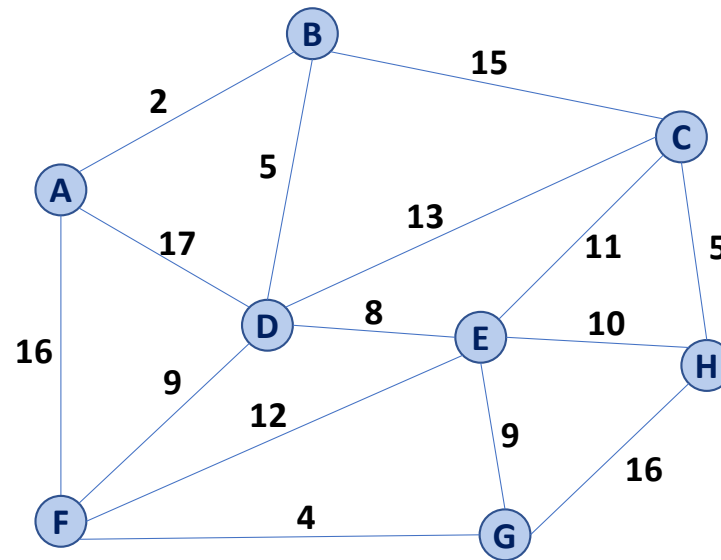
Let  $e$  be an edge of minimum weight across the partition.

Then  $e$  is part of some minimum spanning tree.

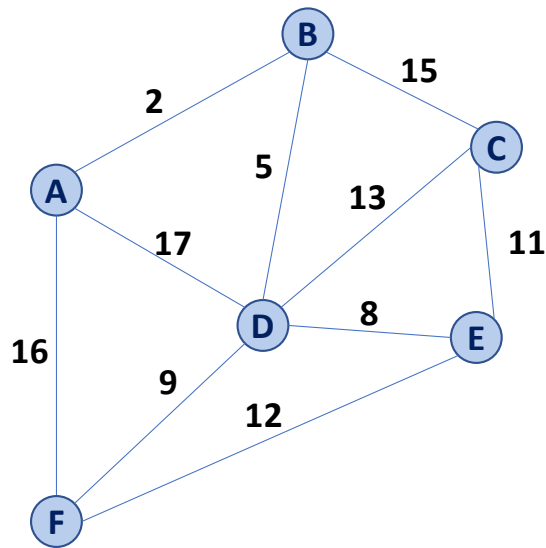


# Partition Property

The partition property suggests an algorithm:



# Prim's Algorithm



```
1 PrimMST(G, s):
2   Input: G, Graph;
3         s, vertex in G, starting vertex
4   Output: T, a minimum spanning tree (MST) of G
5
6   foreach (Vertex v : G):
7     d[v] = +inf
8     p[v] = NULL
9   d[s] = 0
10
11  PriorityQueue Q // min distance, defined by d[v]
12  Q.buildHeap(G.vertices())
13  Graph T // "labeled set"
14
15  repeat n times:
16    Vertex m = Q.removeMin()
17    T.add(m)
18    foreach (Vertex v : neighbors of m not in T):
19      if cost(v, m) < d[v]:
20        d[v] = cost(v, m)
21        p[v] = m
22
23  return T
```

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	Adj. Matrix	Adj. List
Heap		
Unsorted Array		



# Prim's Algorithm

**Sparse Graph:**

**Dense Graph:**

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```

	Adj. Matrix	Adj. List
Heap	$O(n \lg(n) + n^2 \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array	$O(n^2)$	$O(n^2)$



## MST Algorithm Runtime:

We know that MSTs are always run on a minimally connected graph:

$$n-1 \leq m \leq n(n-1) / 2$$

$$O(n) \leq O(m) \leq O(n^2)$$



## MST Algorithm Runtime:

- Kruskal's Algorithm:

$$O(n + m \lg(n))$$

Sparse Graph:

Dense Graph:

- Prim's Algorithm:

$$O(n \lg(n) + m \lg(n))$$

Sparse Graph:

Dense Graph:

# Suppose I have a new heap:

	Binary Heap	Fibonacci Heap
Remove Min	$O(\lg(n))$	$O(\lg(n))$
Decrease Key	$O(\lg(n))$	$O(1)^*$

## What's the updated running time?

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PrimMST(G, s):
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```



## MST Algorithm Runtimes:

- Kruskal's Algorithm:  
 $O(m \lg(n))$

- Prim's Algorithm:  
 $O(n \lg(n) + m \lg(n))$

# Shortest Path

