

CS 225

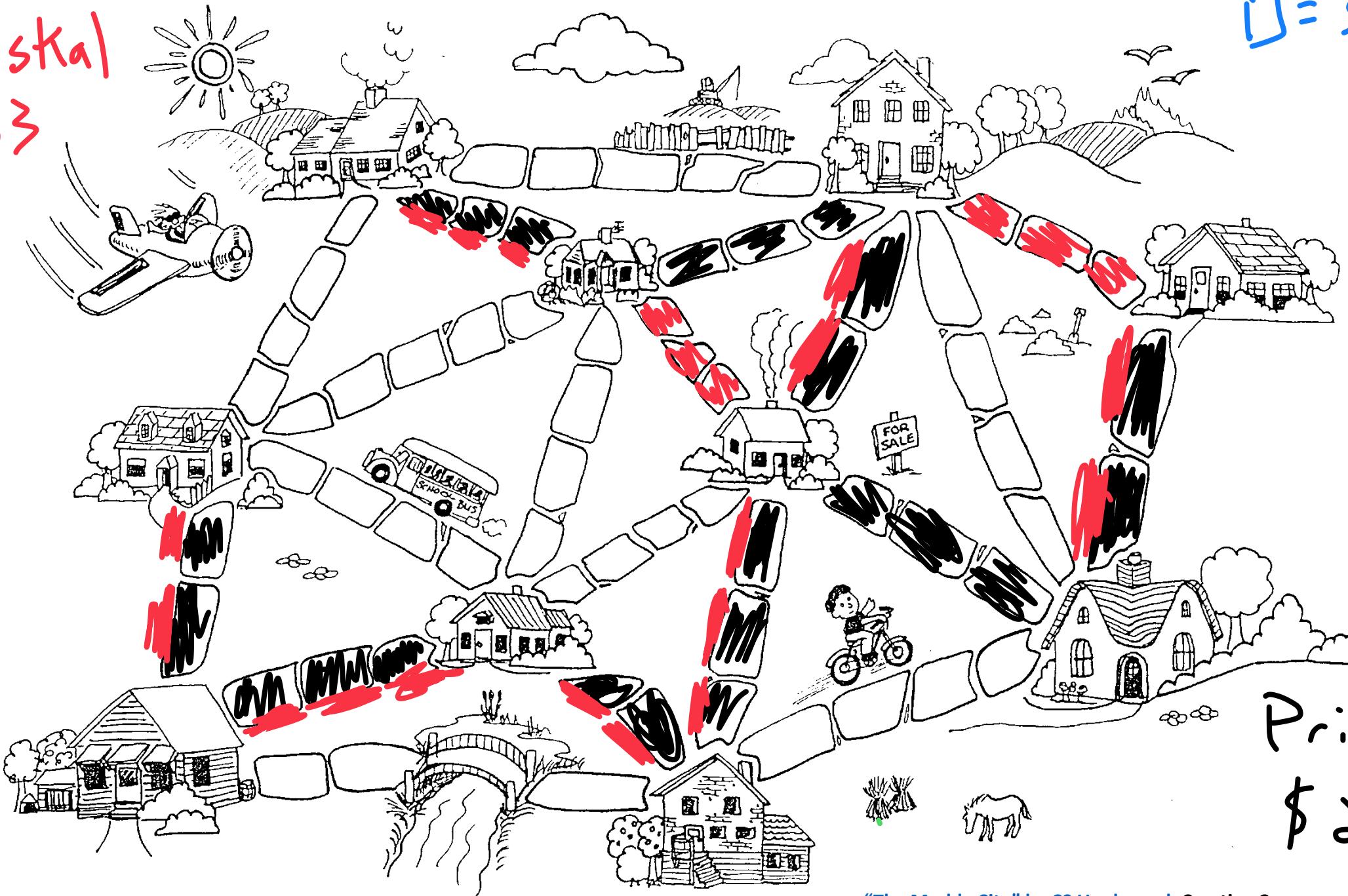
Data Structures

April 23 – MST II
Brad Solomon

Learning Objectives

- Formalize Minimum Spanning Tree (MST)
- Analyze Kruskal and Prims' respective algorithms
- Compare runtimes and implementation strategies

Kruskal
\$23



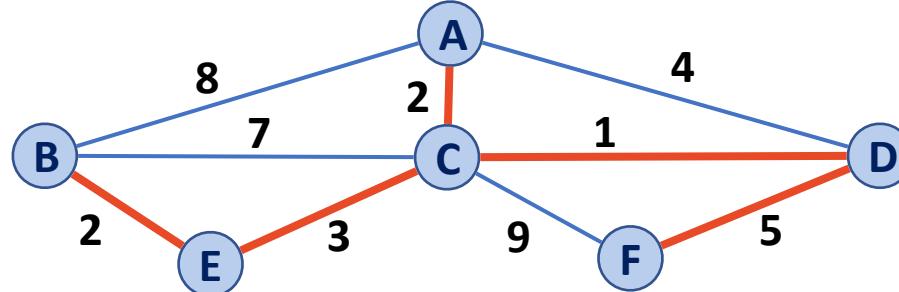
□ = \$1
Prim
\$23

Minimum Spanning Tree Algorithms

Input: Connected, undirected graph \mathbf{G} with edge weights (unconstrained, but must be additive)

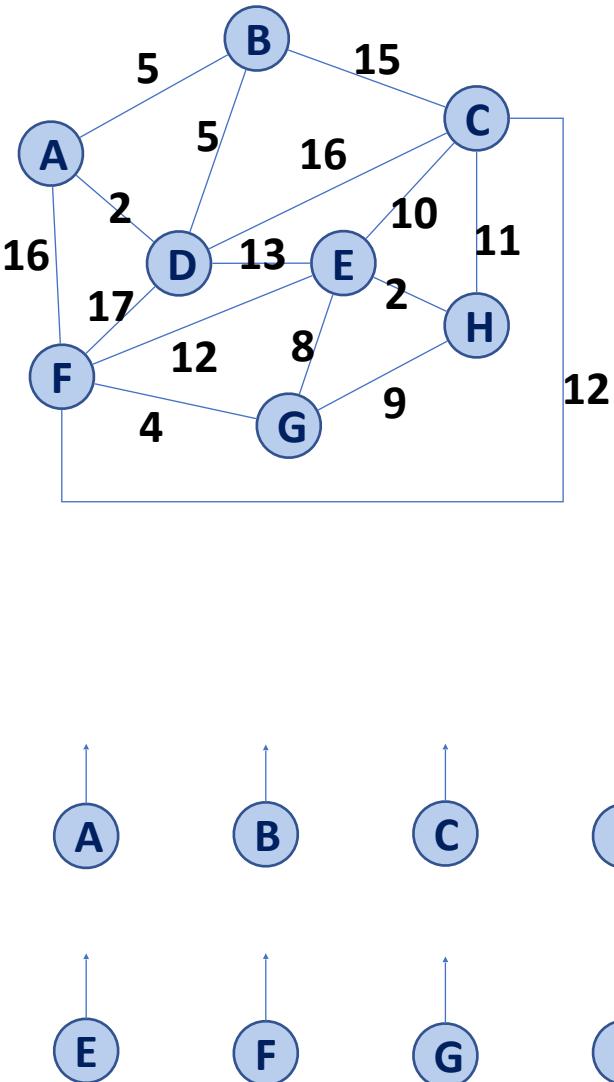
Output: A graph \mathbf{G}' with the following properties:

- \mathbf{G}' is a spanning graph of \mathbf{G}
- \mathbf{G}' is a tree (connected, acyclic)
- \mathbf{G}' has a minimal total weight among all spanning trees



Kruskal's Algorithm

(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)



Kruskal's Algorithm

Priority Queue:	Heap	Sorted Array
Building (Line 6-8)		
Each removeMin (Line 13)		

```
1 KruskalMST (G) :  
2     DisjointSets forest  
3     foreach (Vertex v : G) :  
4         forest.makeSet(v)  
5  
6     PriorityQueue Q      // min edge weight  
7     foreach (Edge e : G) :  
8         Q.insert(e)  
9  
10    Graph T = (V, {})  
11  
12    while |T.edges()| < n-1:  
13        Vertex (u, v) = Q.removeMin()  
14        if forest.find(u) != forest.find(v) :  
15            T.addEdge(u, v)  
16            forest.union( forest.find(u) ,  
17                                forest.find(v) )  
18  
19    return T
```

Kruskal's Algorithm

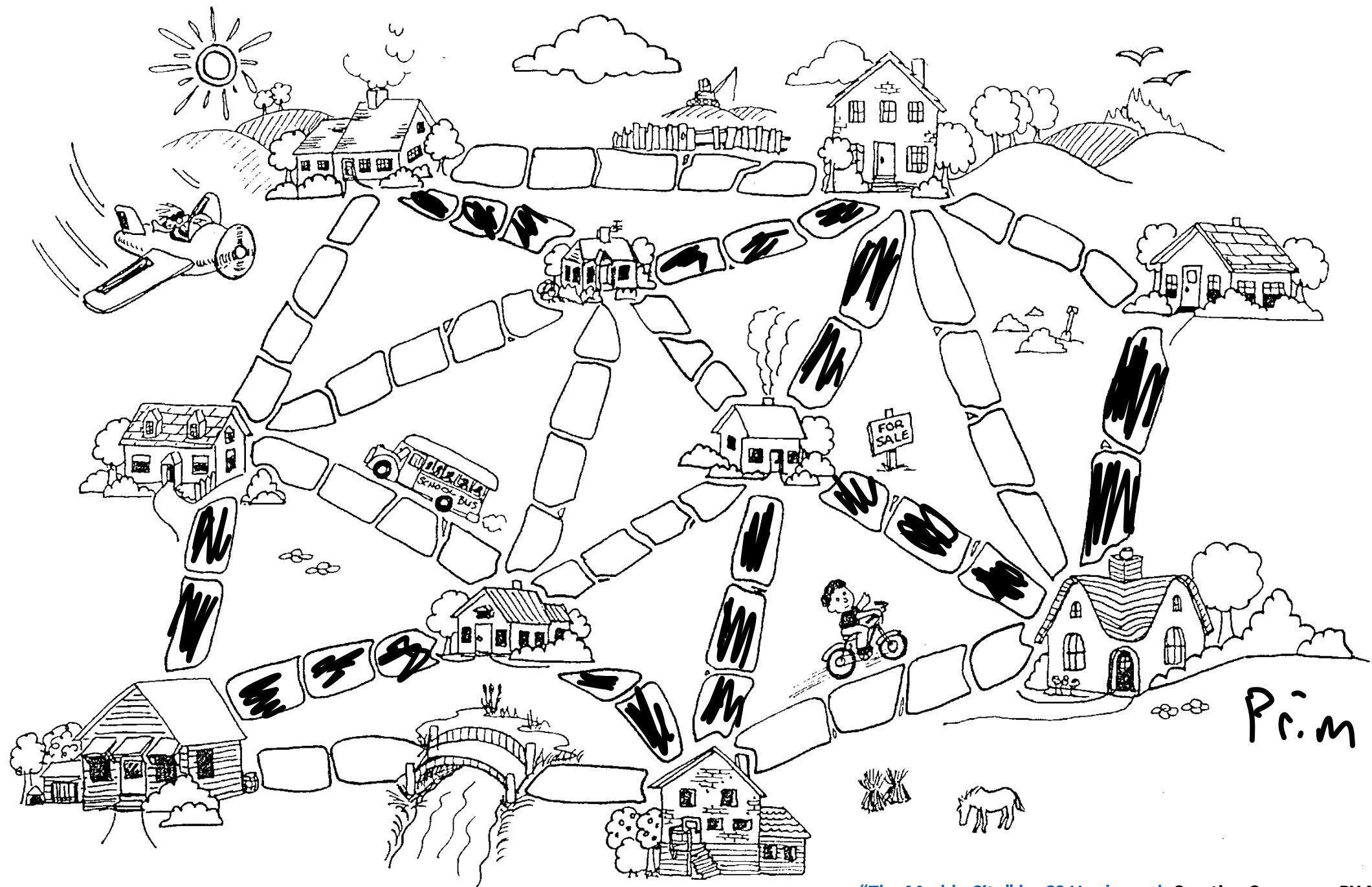
Priority Queue:	Total Running Time
Heap	
Sorted Array	

```
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Kruskal's Algorithm

Which Priority Queue Implementation is better for running Kruskal's Algorithm?

- Heap:
- Sorted Array:

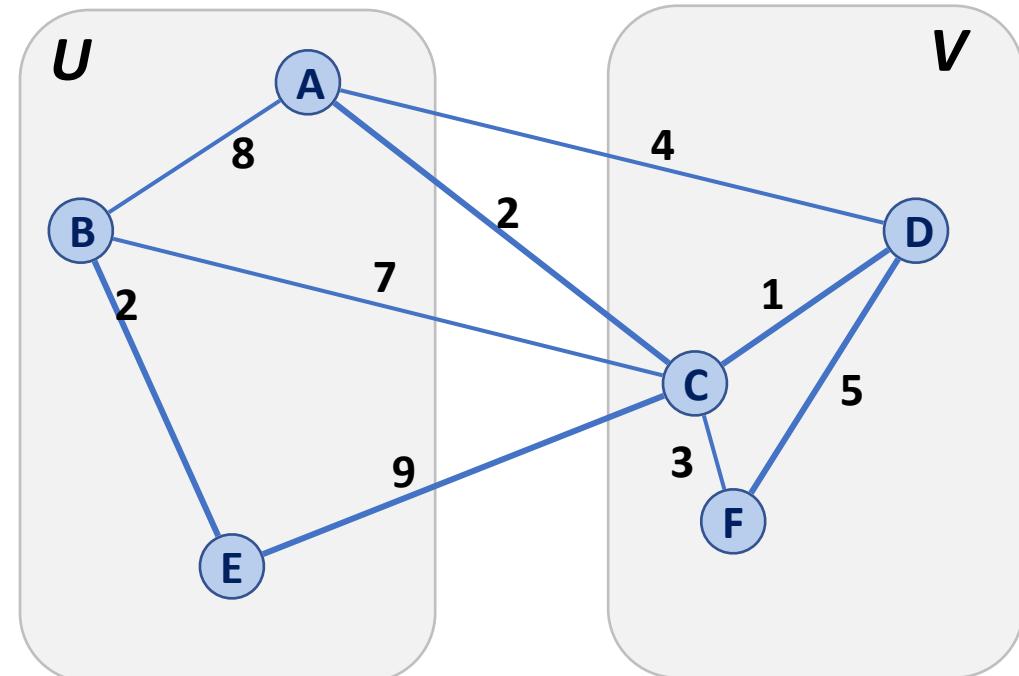


Partition Property

Consider an arbitrary partition of the vertices on G into two subsets U and V .

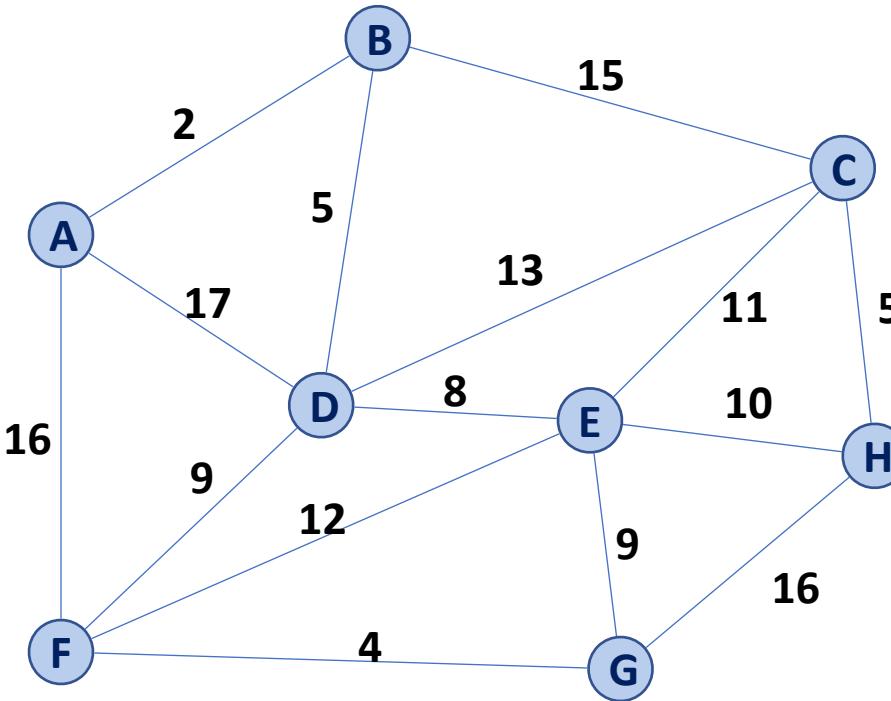
Let e be an edge of minimum weight across the partition.

Then e is part of some minimum spanning tree.

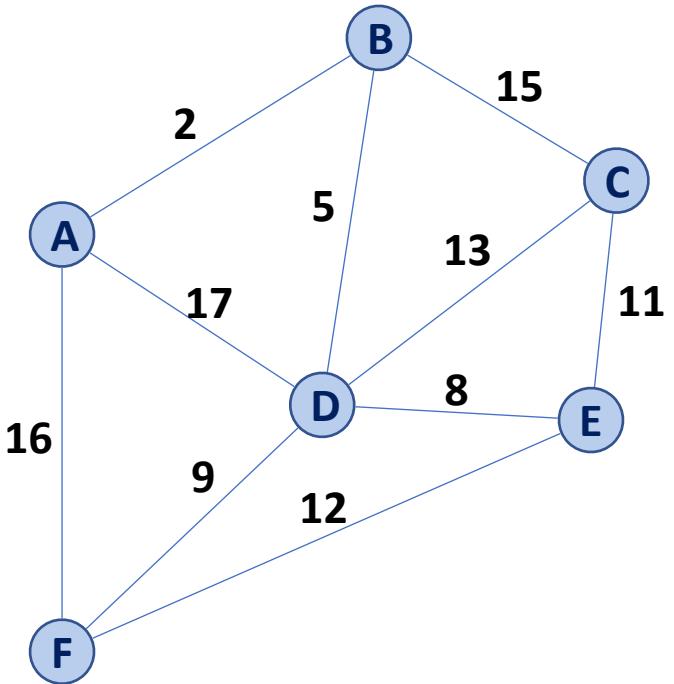


Partition Property

The partition property suggests an algorithm:



Prim's Algorithm



```
1 PrimMST(G, s):
2     Input: G, Graph;
3             s, vertex in G, starting vertex
4     Output: T, a minimum spanning tree (MST) of G
5
6     foreach (Vertex v : G):
7         d[v] = +inf
8         p[v] = NULL
9     d[s] = 0
10
11    PriorityQueue Q      // min distance, defined by d[v]
12    Q.buildHeap(G.vertices())
13    Graph T               // "labeled set"
14
15    repeat n times:
16        Vertex u = Q.removeMin()
17        T.add(u)
18        foreach (Vertex v : neighbors of u not in T):
19            if cost(v, u) < d[v]:
20                d[v] = cost(v, u)
21                p[v] = u
22
23    return T
```

Prim's Algorithm

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	Adj. Matrix	Adj. List
Heap		
Unsorted Array		

Prim's Algorithm

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```

	Adj. Matrix	Adj. List
Heap	$O(n^2 + m \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array	$O(n^2)$	$O(n^2)$

MST Algorithm Runtime:

- Kruskal's Algorithm:
 $O(n + m \lg(n))$
- Prim's Algorithm:
 $O(n \lg(n) + m \lg(n))$
- What must be true about the connectivity of a graph when running an MST algorithm?
- How does n and m relate?

MST Algorithm Runtime:

- Kruskal's Algorithm:
 $O(n + m \lg(n))$
- Prim's Algorithm:
 $O(n \lg(n) + m \lg(n))$

Sparse Graph:

Dense Graph:

Suppose I have a new heap:

	Binary Heap	Fibonacci Heap
Remove Min	$O(\lg(n))$	$O(\lg(n))$
Decrease Key	$O(\lg(n))$	$O(1)^*$

What's the updated running time?

```
6  PrimMST(G, s) :  
7      foreach (Vertex v : G) :  
8          d[v] = +inf  
9          p[v] = NULL  
10         d[s] = 0  
11  
12         PriorityQueue Q // min distance, defined by d[v]  
13         Q.buildHeap(G.vertices())  
14         Graph T           // "labeled set"  
15  
16         repeat n times:  
17             Vertex m = Q.removeMin()  
18             T.add(m)  
19             foreach (Vertex v : neighbors of m not in T) :  
20                 if cost(v, m) < d[v] :  
21                     d[v] = cost(v, m)  
22                     p[v] = m
```

Final Big-O MST Algorithm Runtimes:

- Kruskal's Algorithm:

$O(m \lg(n))$

- Prim's Algorithm:

$O(n \lg(n) + m)$

Sparse Graph:

Dense Graph: