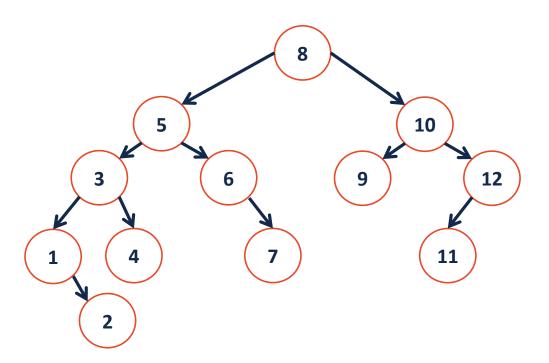
CS 225

Data Structures

October 11 – AVL Analysis
G Carl Evans

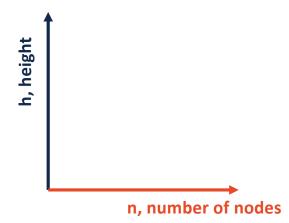


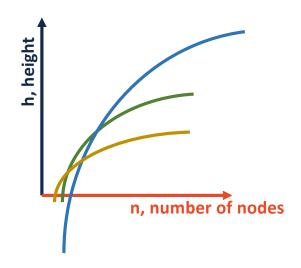
We know: insert, remove and find runs in: _____.

We will argue that: h is _____.

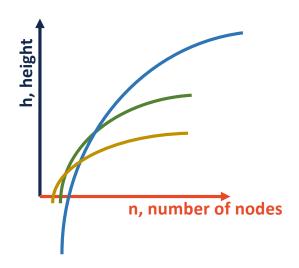
Definition of big-O:

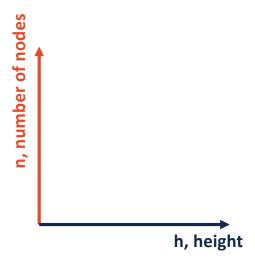
...or, with pictures:

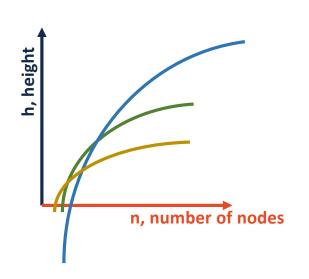


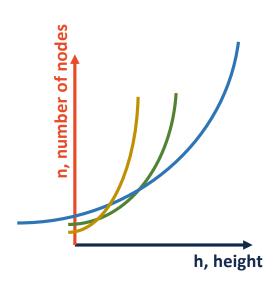


The height of the tree, f(n), will always be less than
 c × g(n) for all values where n > k.









• The number of nodes in the tree, $f^{-1}(h)$, will always be greater than $c \times g^{-1}(h)$ for all values where n > k.

Plan of Action

Since our goal is to find the lower bound on **n** given **h**, we can begin by defining a function given **h** which describes the smallest number of nodes in an AVL tree of height **h**:

Simplify the Recurrence

$$N(h) = 1 + N(h - 1) + N(h - 2)$$

State a Theorem

Theorem: An AVL tree of height h has at least _____.

Proof:

- I. Consider an AVL tree and let h denote its height.
- II. Case: _____

An AVL tree of height ____ has at least ____ nodes.

Prove a Theorem

III. Case: _____

An AVL tree of height ____ has at least ____ nodes.

Prove a Theorem

By an Inductive Hypothesis (IH):

We will show that:

An AVL tree of height ____ has at least ____ nodes.

Prove a Theorem

V. Using a proof by induction, we have shown that:

...and inverting:

Summary of Balanced BST

Red-Black Trees

- Max height: 2 * lg(n)
- Constant number of rotations on insert, remove, and find

AVL Trees

- Max height: 1.44 * lg(n)
- Rotations:

Summary of Balanced BST

Pros:

- Running Time:

- Improvement Over:

- Great for specific applications:

Summary of Balanced BST

Cons:

- Running Time:

- In-memory Requirement:

C++ provides us a balanced BST as part of the standard library:

```
std::map<K, V> map;
```

```
V & std::map<K, V>::operator[]( const K & )
```

```
V & std::map<K, V>::operator[]( const K & )
std::map<K, V>::erase( const K & )
```

```
iterator std::map<K, V>::lower_bound( const K & );
iterator std::map<K, V>::upper_bound( const K & );
```

Iterators

Why do we care?

```
DFS dfs(...);
for ( ImageTraversal::Iterator it = dfs.begin(); it != dfs.end(); ++it ) {
    std::cout << (*it) << std::endl;
}</pre>
```

Iterators

Why do we care?

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DFS dfs(...);
for ( ImageTraversal::Iterator it = dfs.begin(); it != dfs.end(); ++it ) {
    std::cout << (*it) << std::endl;
}</pre>
```

```
1 DFS dfs(...);
2 for ( const Point & p : dfs ) {
3   std::cout << p << std::endl;
4 }</pre>
```

Iterators

Why do we care?

```
DFS dfs(...);
for ( ImageTraversal::Iterator it = dfs.begin(); it != dfs.end(); ++it ) {
    std::cout << (*it) << std::endl;
}</pre>
```

```
1 DFS dfs(...);
2 for ( const Point & p : dfs ) {
3   std::cout << p << std::endl;
4 }</pre>
```

```
1 ImageTraversal & traversal = /* ... */;
2 for ( const Point & p : traversal ) {
3   std::cout << p << std::endl;
4 }</pre>
```

Every Data Structure So Far

	Unsorted Array	Sorted Array	Unsorted List	Sorted List	Binary Tree	BST	AVL
Find							
Insert							
Remove							
Traverse							