



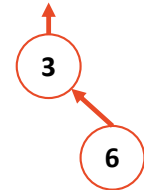
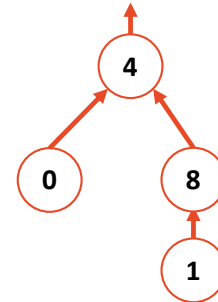
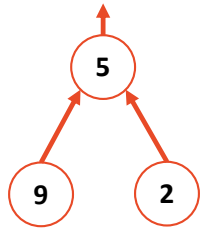
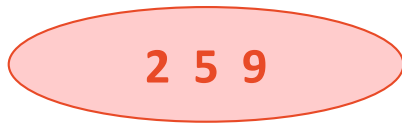
# CS 225

## Data Structures

*November 6 – Disjoint Sets Finale + Graphs*

*G Carl Evans*

# Disjoint Sets



0	1	2	3	4	5	6	7	8	9
4	8	5	-1	-1	-1	3	-1	4	5

# Disjoint Sets Find

```
1 int DisjointSets::find() {  
2     if ( s[i] < 0 ) { return i; }  
3     else { return _find( s[i] ); }  
4 }
```

Running time?

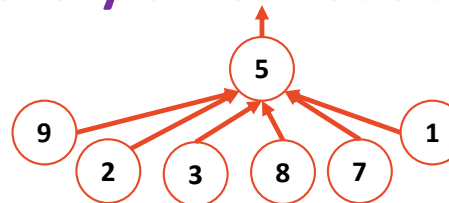
**Structure:** A structure similar to a linked list

**Running time:**  $O(h) < O(n)$

What is the ideal UpTree?

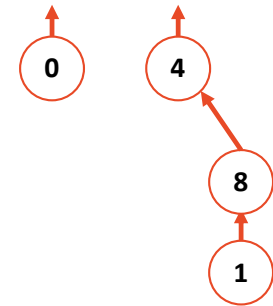
**Structure:** One root node with every other node as it's child

**Running Time:**  $O(1)$

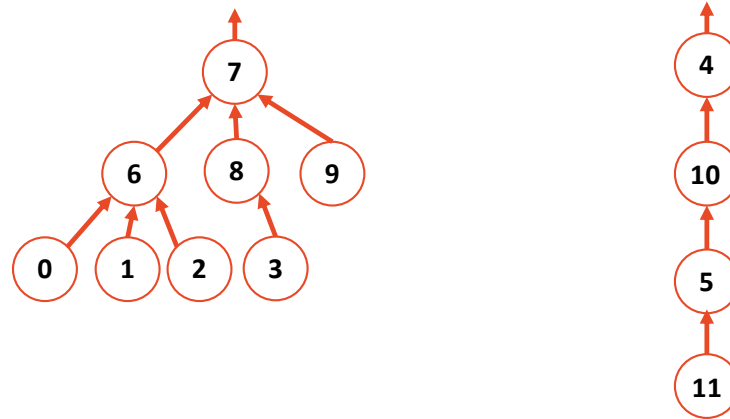


# Disjoint Sets Union

```
1 void DisjointSets::union(int r1, int r2) {  
2  
3  
4 }
```

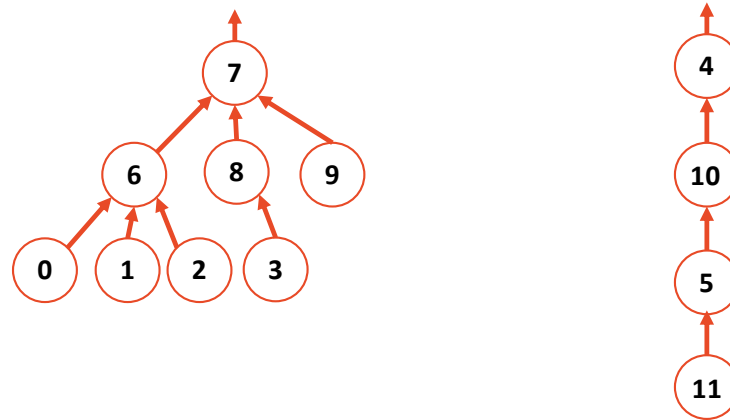


# Disjoint Sets – Union



0	1	2	3	4	5	6	7	8	9	10	11
6	6	6	8	-1	10	7	-1	7	7	4	5

# Disjoint Sets – Smart Union

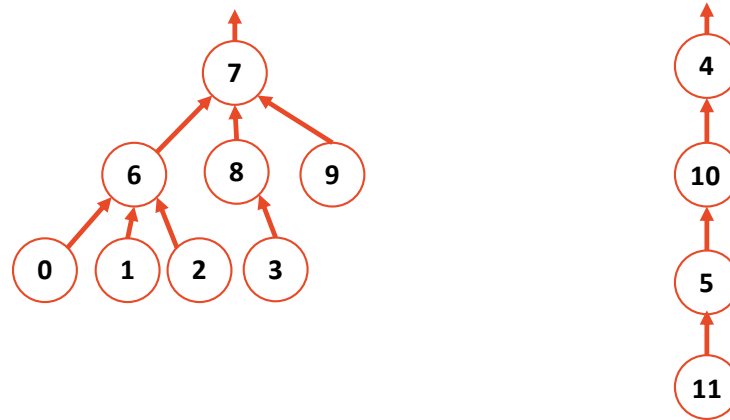


**Union by height**

0	1	2	3	4	5	6	7	8	9	10	11
6	6	6	8		10	7		7	7	4	5

*Idea: Keep the height of the tree as small as possible.*

# Disjoint Sets – Smart Union



**Union by height**

0	1	2	3	4	5	6	7	8	9	10	11
6	6	6	8	-4	10	7	-3	7	7	4	5

*Idea: Keep the height of the tree as small as possible.*

**Union by size**

0	1	2	3	4	5	6	7	8	9	10	11
6	6	6	8	-4	10	7	-8	7	7	4	5

*Idea: Minimize the number of nodes that increase in height*

**Both guarantee the height of the tree is:**

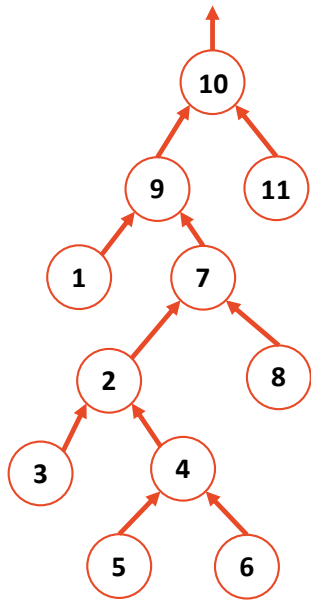
# Disjoint Sets Find and Union

```
1 int DisjointSets::find(int i) {
2     if ( arr_[i] < 0 ) { return i; }
3     else { return _find( arr_[i] ); }
4 }
```

```
1 void DisjointSets::unionBySize(int root1, int root2) {
2     int newSize = arr_[root1] + arr_[root2];
3
4     // If arr_[root1] is less than (more negative), it is the larger set;
5     // we union the smaller set, root2, with root1.
6     if ( arr_[root1] < arr_[root2] ) {
7         arr_[root2] = root1;
8         arr_[root1] = newSize;
9     }
10
11     // Otherwise, do the opposite:
12     else {
13         arr_[root1] = root2;
14         arr_[root2] = newSize;
15     }
16 }
```



# Path Compression



# Disjoint Sets Find with Compression

```
1 int DisjointSets::find(int i) {
2     // At root return the index
3     if ( arr_[i] < 0 ) {
4         return i;
5     }
6
7     // If not at the root recurse and on the return update parent
8     // to be the root.
9     else {
10        int root = find( arr_[i] );
11        arr_[i] = root;
12        return root;
13    }
14 }
15
16
```



# Disjoint Sets Analysis

The **iterated log** function:

*The number of times you can take a log of a number.*

$\log^*(n) =$

0,  $n \leq 1$

$1 + \log^*(\log(n))$ ,  $n > 1$

What is  $\lg^*(2^{65536})$ ?



## Disjoint Sets Analysis

In an Disjoint Sets implemented with smart **unions** and path compression on **find**:

Any sequence of **m union** and **find** operations result in the worse case running time of  $O(\text{_____})$ ,  
where **n** is the number of items in the Disjoint Sets.



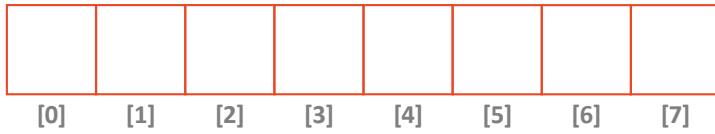
# In Review: Data Structures

## Array

- Sorted Array
- Unsorted Array
  - Stacks
  - Queues
  - Hashing
  - Heaps
    - Priority Queues
  - UpTrees
    - Disjoint Sets

## Linked

- Doubly Linked List
- Trees
  - BTree
  - Binary Tree
    - Huffman Encoding
    - kd-Tree
    - AVL Tree

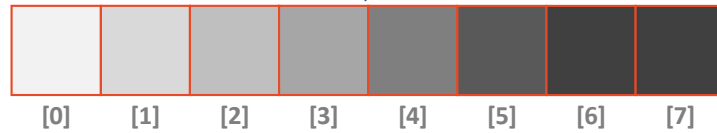


## Array

- **Constant time access to any element, given an index**  
 **$a[k]$  is accessed in  $O(1)$  time, no matter how large the array grows**
- **Cache-optimized**  
**Many modern systems cache or pre-fetch nearby memory values due the “Principle of Locality”. Therefore, arrays often perform faster than lists in identical operations.**

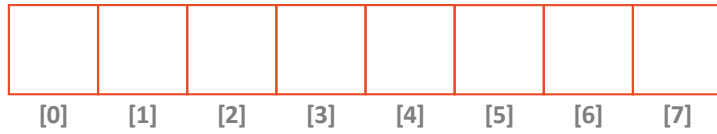


Array

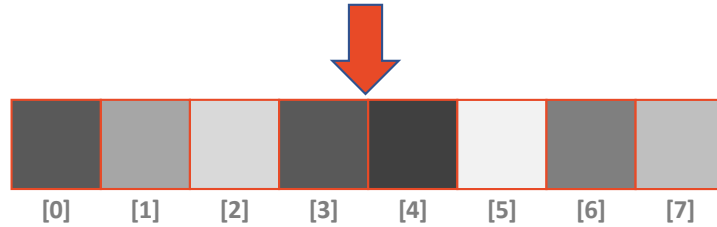


Sorted Array

- **Efficient general search structure**  
**Searches on the sort property run in  $O(\lg(n))$  with Binary Search**
- **Inefficient insert/remove**  
**Elements must be inserted and removed at the location dictated by the sort property, resulting shifting the array in memory – an  $O(n)$  operation**



Array



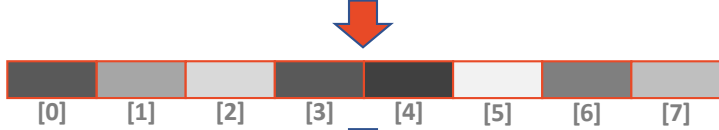
Unsorted Array

- Constant time add/remove at the beginning/end  
**Amortized  $O(1)$  insert and remove from the front and of the array**  
**Idea: Double on resize**
- Inefficient global search structure  
**With no sort property, all searches must iterate the entire array;  $O(1)$  time**





Array



Unsorted Array

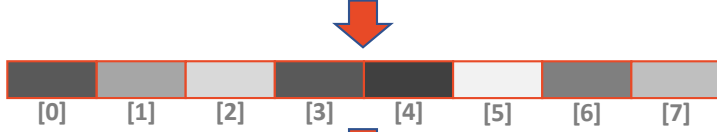


Queue (FIFO)

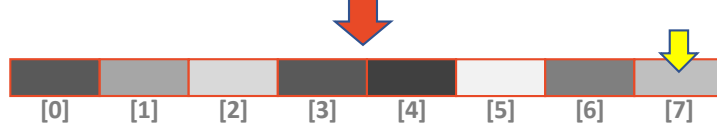
- **First In First Out (FIFO) ordering of data**  
**Maintains an arrival ordering of tasks, jobs, or data**
- **All ADT operations are constant time operations**  
**enqueue() and dequeue() both run in  $O(1)$  time**



Array



Unsorted Array



Stack (LIFO)

- Last In First Out (LIFO) ordering of data  
Maintains a “most recently added” list of data
- All ADT operations are constant time operations  
`push()` and `pop()` both run in  $O(1)$  time



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  - Disjoint Sets

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# In Review: Data Structures

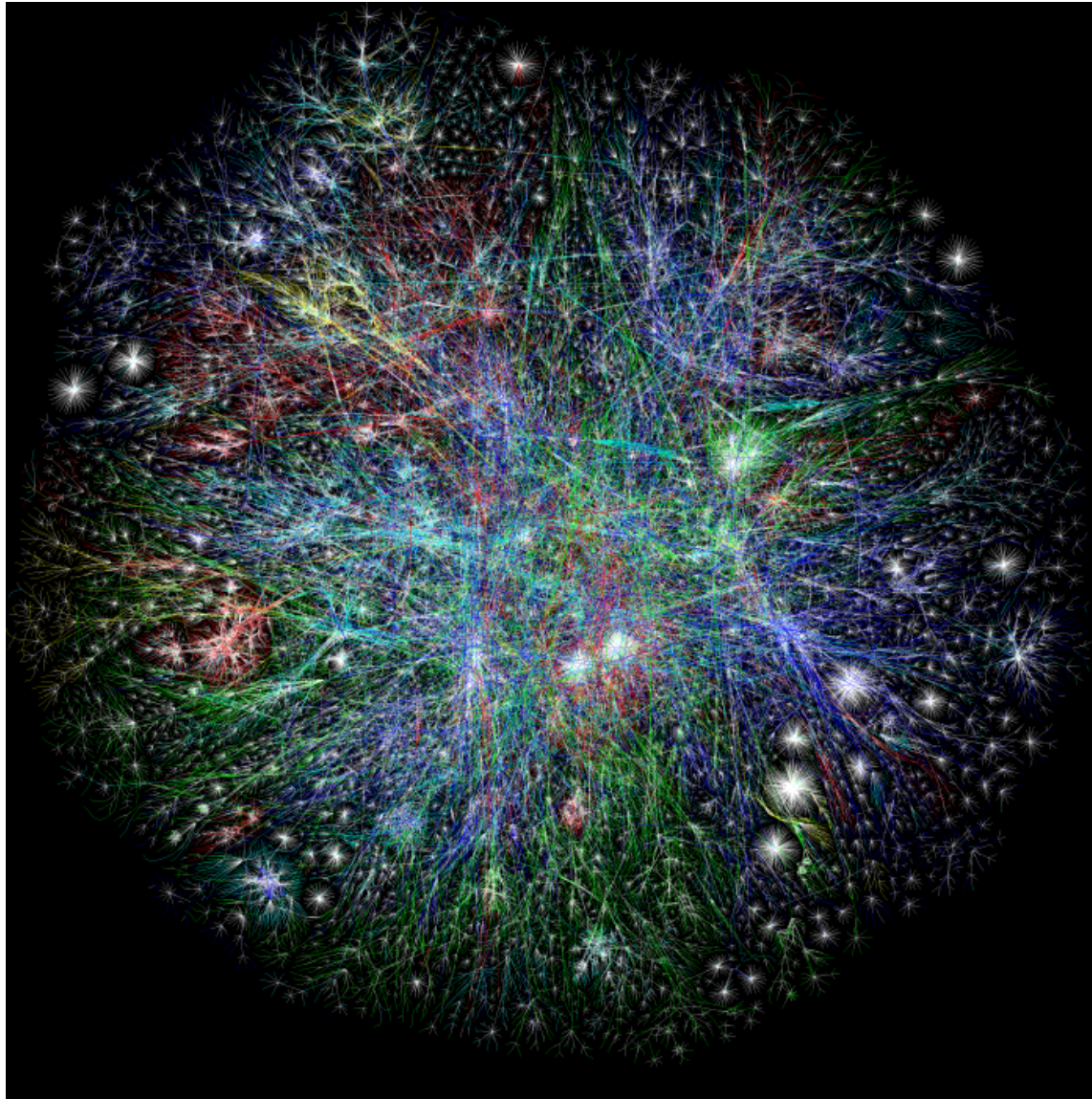
## Array

- Sorted Array
- Unsorted Array
- Stacks
- Queues
- Hashing
- Heaps
  - Priority Queues
- UpTrees
  - Disjoint Sets

## Graphs

## Linked

- Doubly Linked List
- Skip List
- Trees
  - BTree
  - Binary Tree
    - Huffman Encoding
    - kd-Tree
    - AVL Tree



## **The Internet 2003**

*The OPTE Project (2003)*

Map of the entire internet; nodes are routers; edges are connections.

# HeapifyUp BasicBlock Graph

```
heapifyUp(int*, unsigned int):  
  push  rbp  
  mov   rbp, rsp  
  sub   rsp, 16  
  mov   qword ptr [rbp - 8], rdi  
  mov   dword ptr [rbp - 12], esi  
  cmp   dword ptr [rbp - 12], 1  
  jbe   .LBB0_4
```

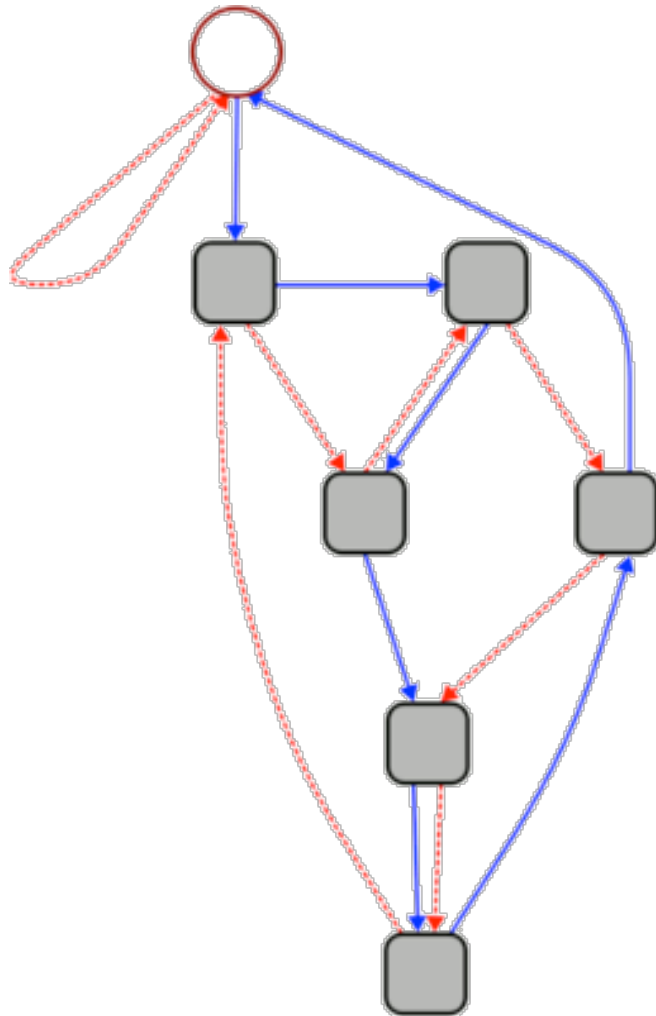
```
heapifyUp(int*, unsigned int):@@  
  mov   rax, qword ptr [rbp - 8]  
  mov   ecx, dword ptr [rbp - 12]  
  mov   edx, ecx  
  mov   ecx, dword ptr [rax + 4*rdx]  
  mov   rax, qword ptr [rbp - 8]  
  mov   esi, dword ptr [rbp - 12]  
  shr   esi, 1  
  mov   esi, esi  
  mov   edx, esi  
  cmp   ecx, dword ptr [rax + 4*rdx]  
  jge   .LBB0_3
```

```
heapifyUp(int*, unsigned int):@19  
  mov   rax, qword ptr [rbp - 8]  
  mov   ecx, dword ptr [rbp - 12]  
  mov   edx, ecx  
  mov   ecx, dword ptr [rax + 4*rdx]  
  mov   dword ptr [rbp - 16], ecx  
  mov   rax, qword ptr [rbp - 8]  
  mov   ecx, dword ptr [rbp - 12]  
  shr   ecx, 1  
  mov   ecx, ecx  
  mov   edx, ecx  
  mov   ecx, dword ptr [rax + 4*rdx]  
  mov   rax, qword ptr [rbp - 8]  
  mov   esi, dword ptr [rbp - 12]  
  mov   edx, esi  
  mov   dword ptr [rax + 4*rdx], ecx  
  mov   ecx, dword ptr [rbp - 16]  
  mov   rax, qword ptr [rbp - 8]  
  mov   esi, dword ptr [rbp - 12]  
  shr   esi, 1  
  mov   esi, esi  
  mov   edx, esi  
  mov   dword ptr [rax + 4*rdx], ecx  
  mov   rdi, qword ptr [rbp - 8]  
  mov   ecx, dword ptr [rbp - 12]  
  shr   ecx, 1  
  mov   esi, ecx  
  call  heapifyUp(int*, unsigned int)
```

```
.LBB0_3:  
  jmp   .LBB0_4
```

```
.LBB0_4:  
  add   rsp, 16  
  pop   rbp  
  ret
```

Generated using tools at  
<https://godbolt.org>



This graph can be used to quickly calculate whether a given number is divisible by 7.

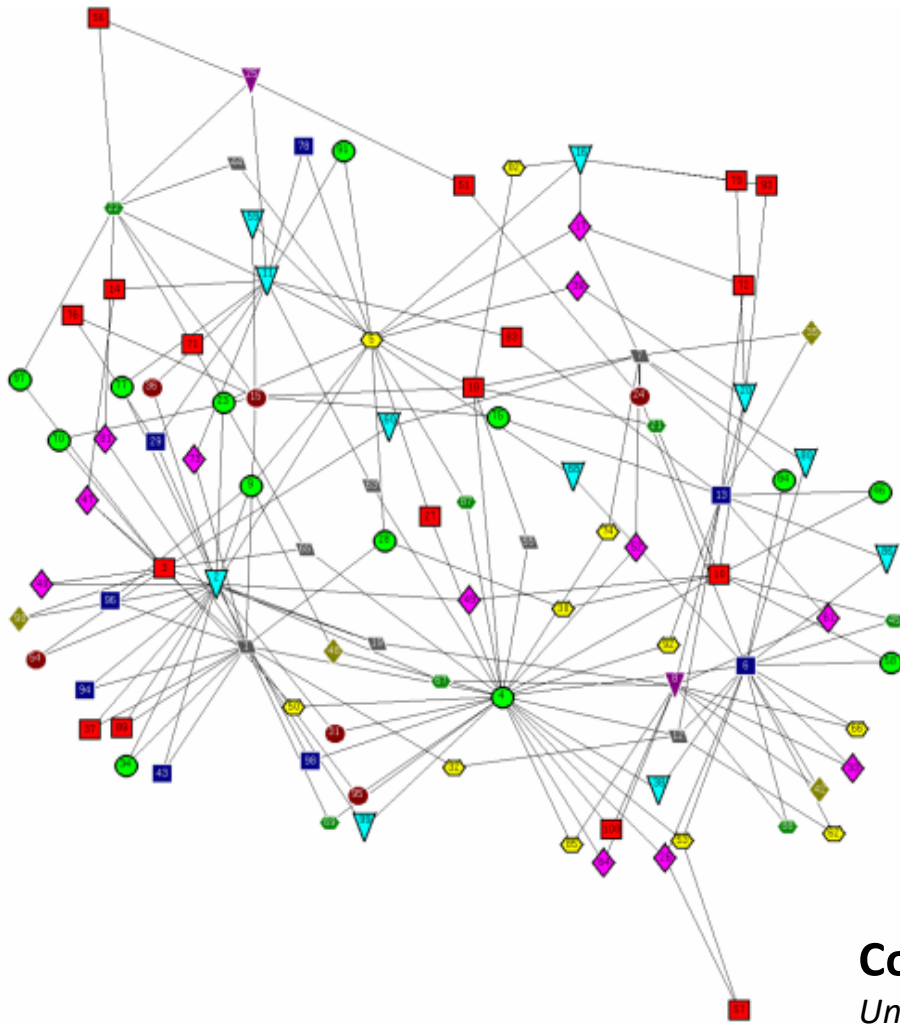
1. Start at the circle node at the top.
2. For each digit **d** in the given number, follow **d** blue (solid) edges in succession. As you move from one digit to the next, follow **1** red (dashed) edge.
3. If you end up back at the circle node, your number is divisible by 7.

3703

### “Rule of 7”

*Unknown Source*

*Presented by Cinda Heeren, 2016*

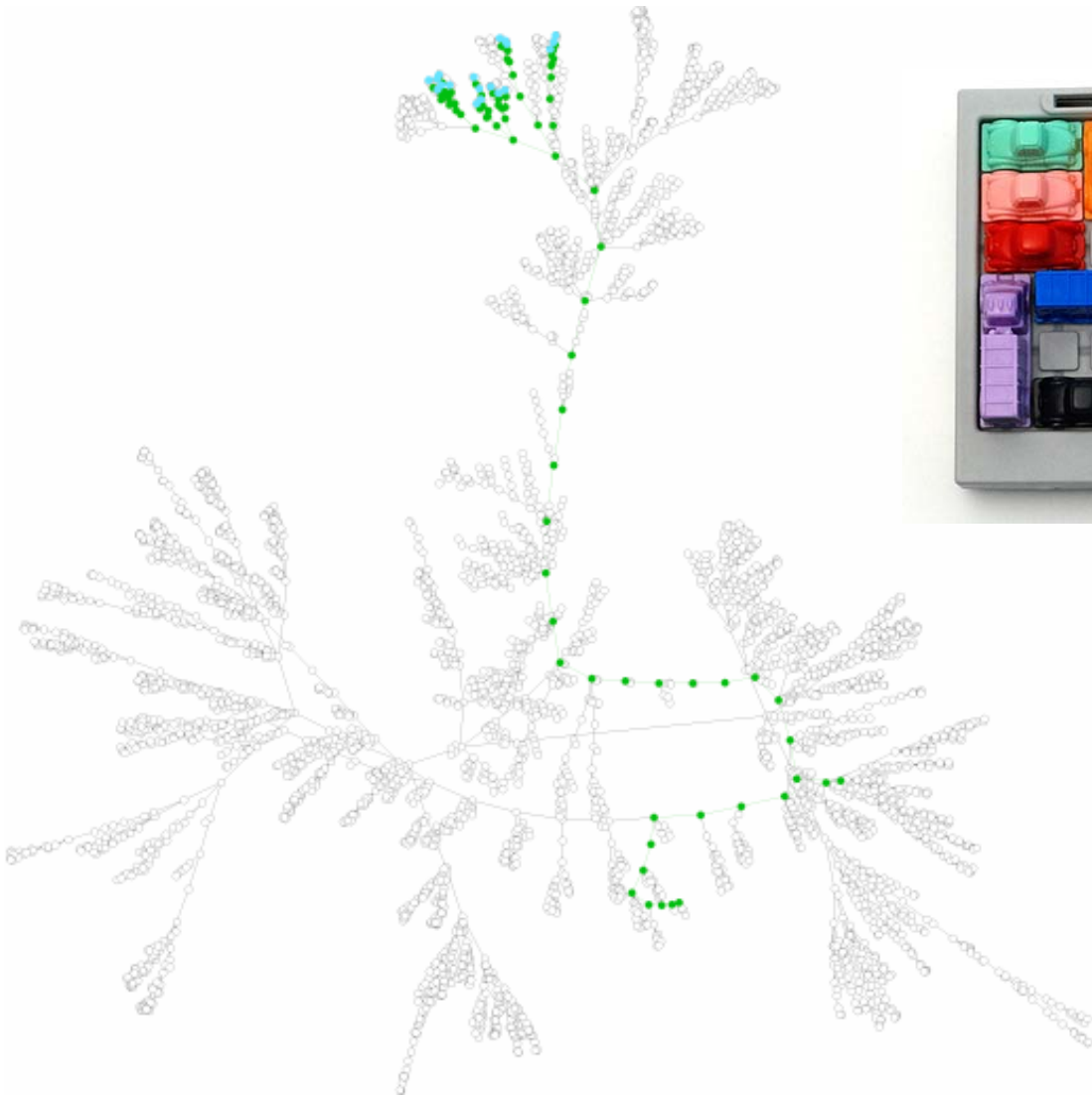


## Conflict-Free Final Exam Scheduling Graph

*Unknown Source*

*Presented by Cinda Heeren, 2016*

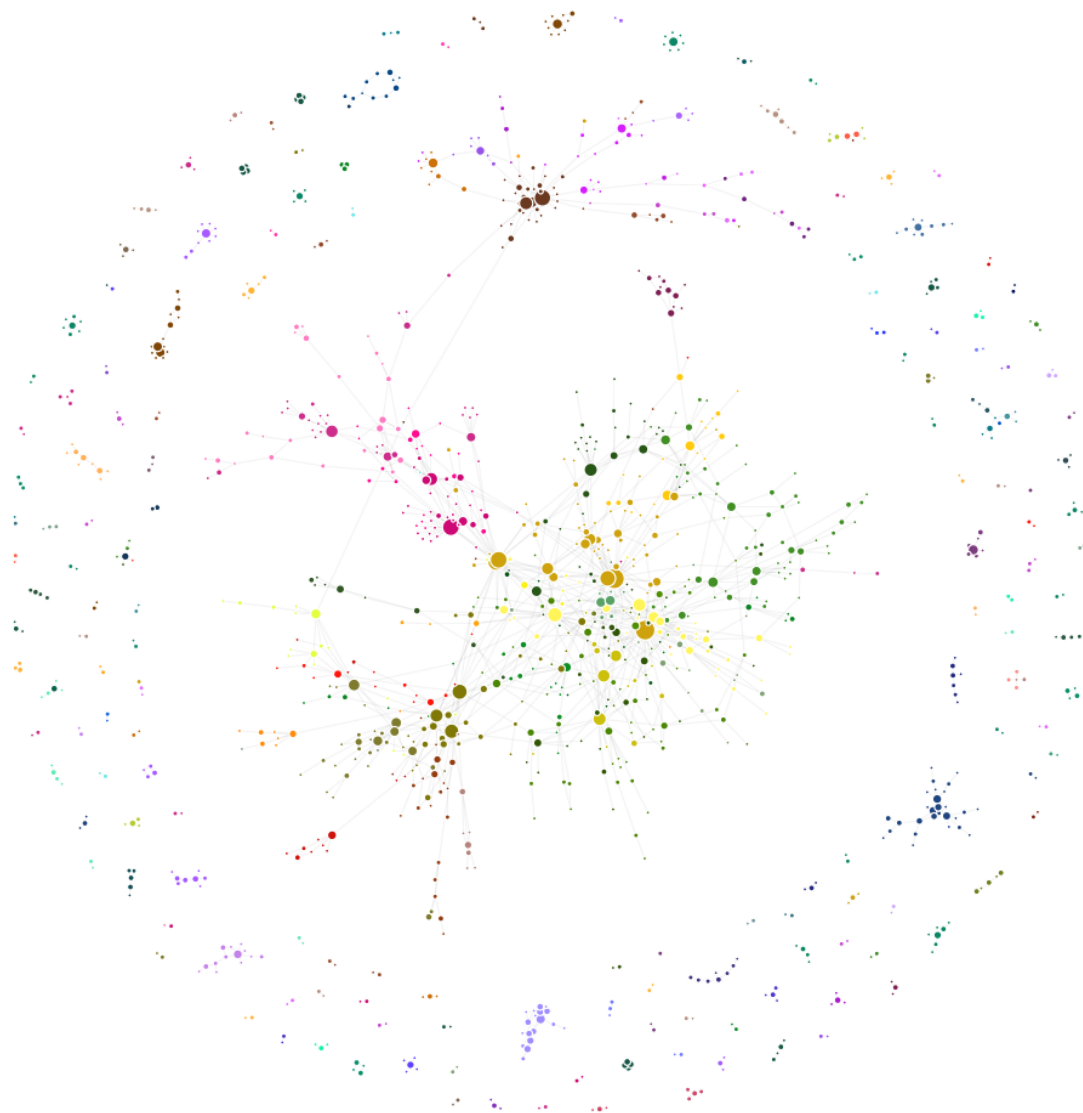




## “Rush Hour” Solution

*Unknown Source*

*Presented by Cinda Heeren, 2016*

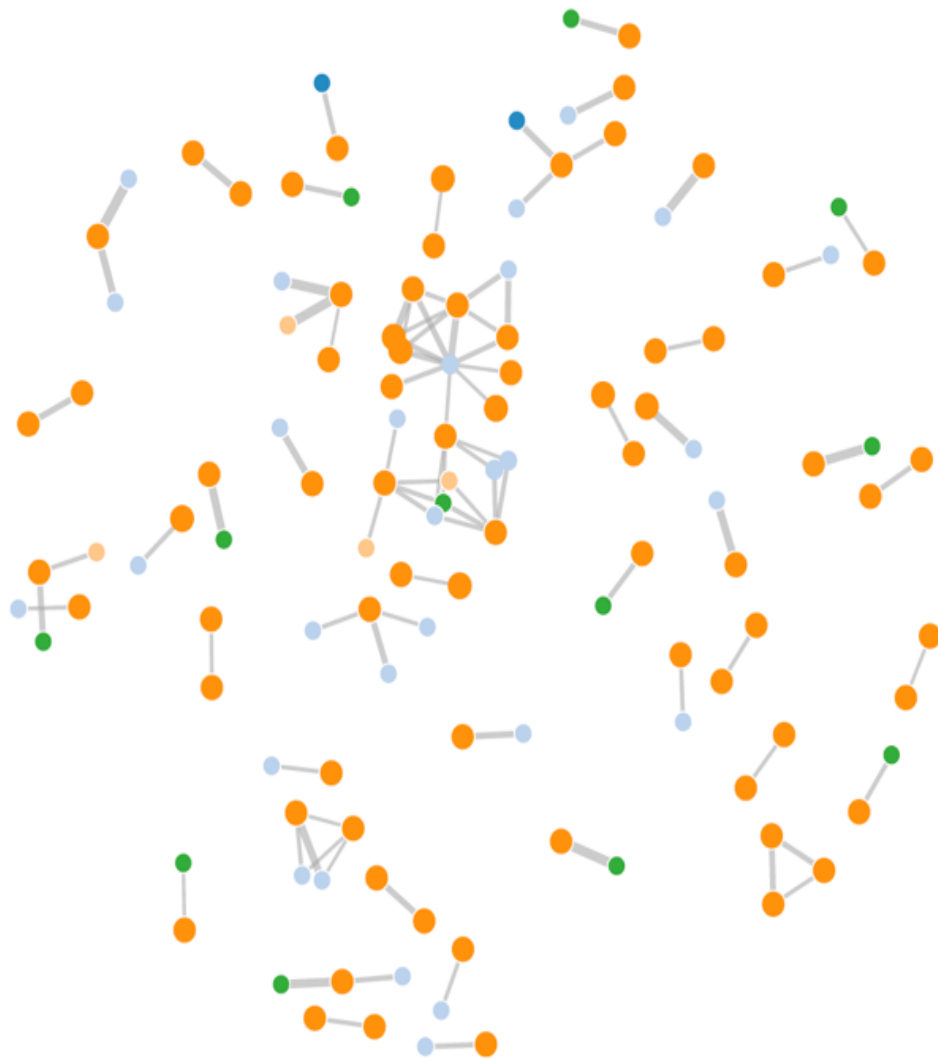


## Class Hierarchy At University of Illinois Urbana-Champaign

*A. Mori, W. Fagen-Ulmschneider, C. Heeren*

Graph of every course at UIUC; nodes are courses, edges are prerequisites

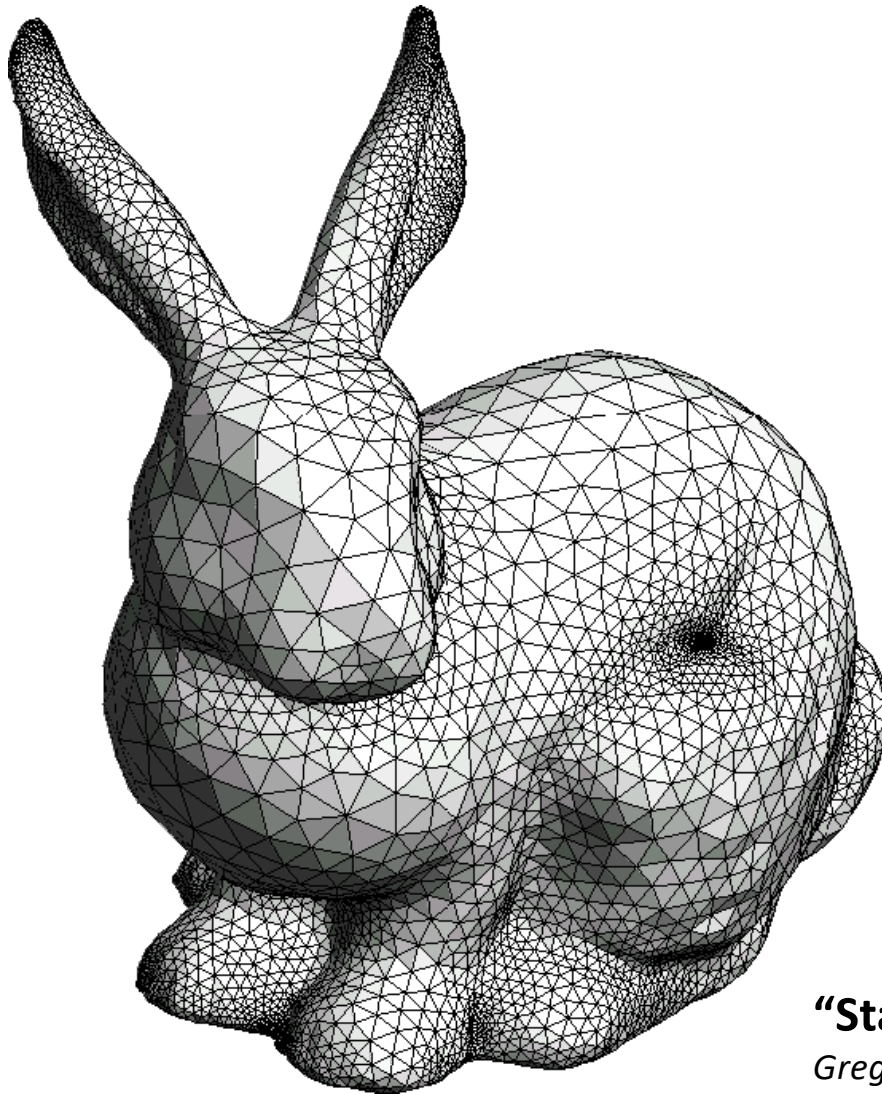
[http://waf.cs.illinois.edu/discovery/class\\_hierarchy\\_at\\_illinois/](http://waf.cs.illinois.edu/discovery/class_hierarchy_at_illinois/)



## MP Collaborations in CS 225

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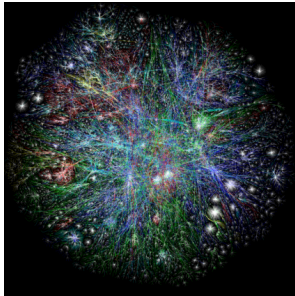
*Presented by Cinda Heeren, 2016*



**“Stanford Bunny”**  
*Greg Turk and Mark Levoy (1994)*

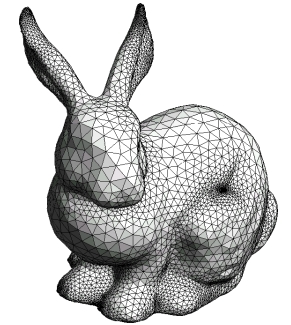


# Graphs



**To study all of these structures:**

1. A common vocabulary
2. Graph implementations
3. Graph traversals
4. Graph algorithms



HAMLET

TROIUS AND CRESSIDA

