

Effectiveness of Delaying Timestamp Computation

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System Model

- Asynchronous system
- n processes
- Pairwise message-passing channels
- Unicasts
- Incomplete network

Goal

Assign timestamp T_e to each event e

such that

$$T_e < T_f \quad \text{iff} \quad e \rightarrow f$$

Much Related Work

■ Message-passing

- Vector timestamps [Fidge-Mattern 1988]
- Vector lower bound [Charron-Bost 1991]
- Lower bound [Melideo 2001]
- Synchronous messages [Garg 2002]
- Causal separators [Rodriguez 1995]
- Exploiting locality [Meldal 1999]
- Plausible clocks [Torres-Rojas 1999]
- Cluster timestamps [Ward 2001]
- ...

■ Shared memory

- Lazy replication [Ladin 1992]
- SwiftCloud [Zawirski 2015]
- Version vectors, dotted version vectors [Almeida 2014]
- ...

Outline

- Vector timestamp bounds
- Alternate solution

Vector Timestamps

[Fidge-Mattern 1988]

- Timestamp T_e is a vector
- **Vector comparison:** $T_e < T_f$ if
 - $T_e[i] \leq T_f[i]$ for all i
 - There exists i such that $T_e[i] < T_f[i]$

Vector Timestamps

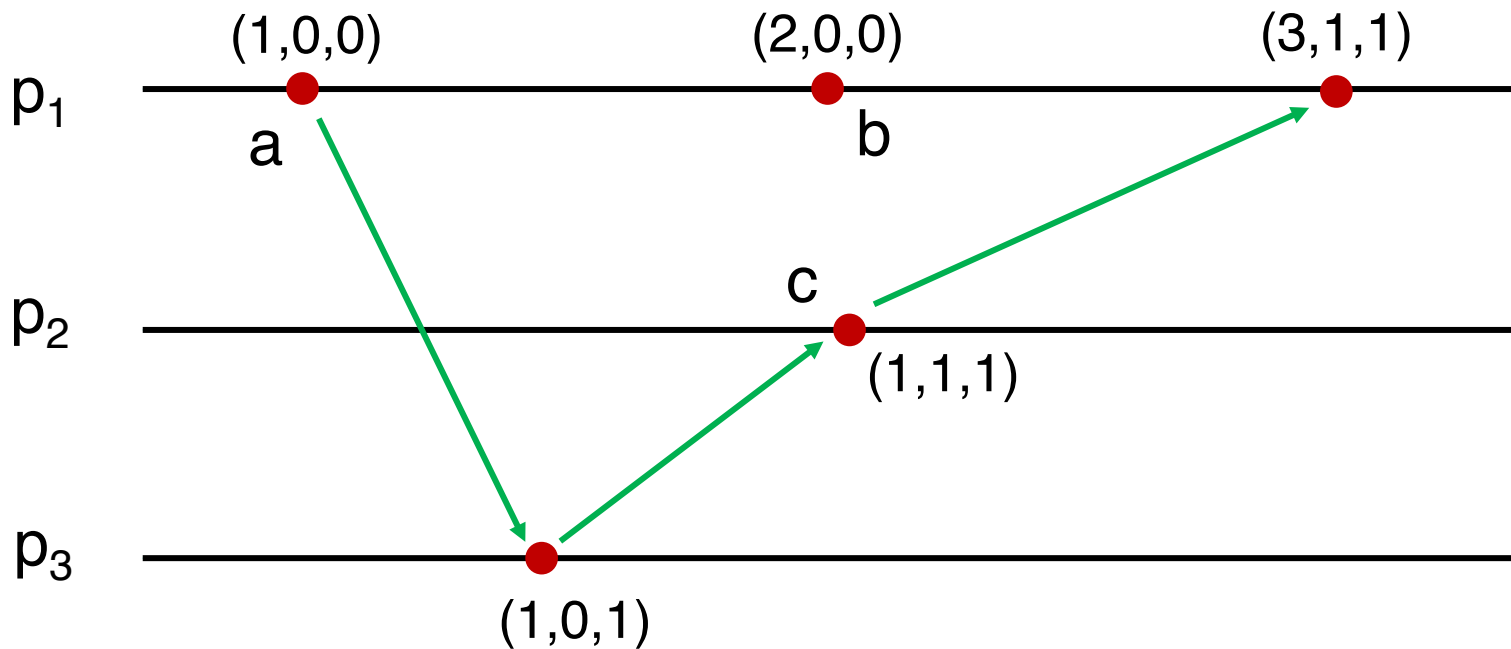
[Fidge-Mattern 1988]

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$$(0,1,2) < (0,1,3)$$

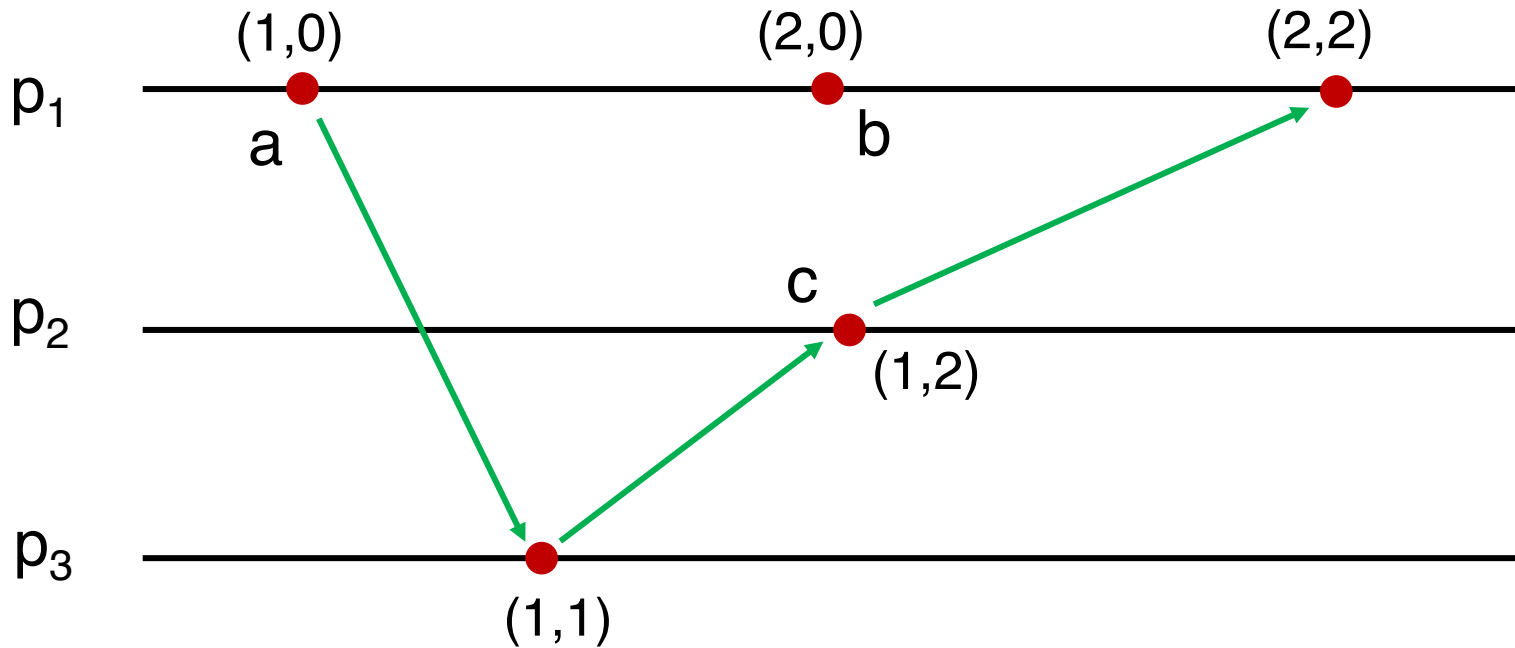
$$(0,1,2) \not< (2,1,1)$$

Vector Timestamps



Online algorithm → Assign timestamp when event occurs

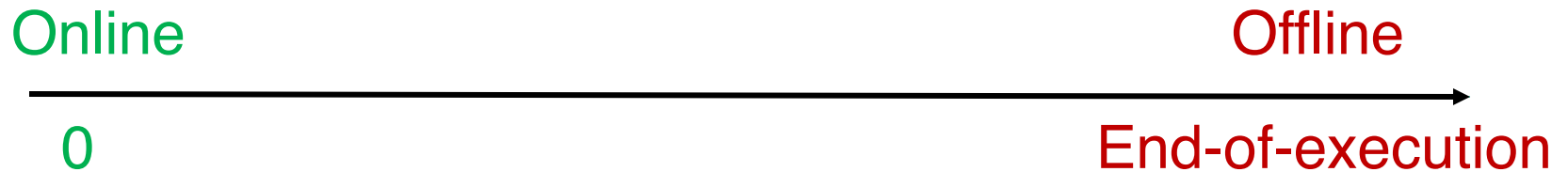
Offline Vector Timestamps



Offline algorithm can often reduce timestamp size

Delay versus Timestamp Size

Delay = Time between event & timestamp assignment



Lower Bound [Charron-Bost 1991]

- Worst-case bound: **Vector length n**
- Assuming **complete** communication graph

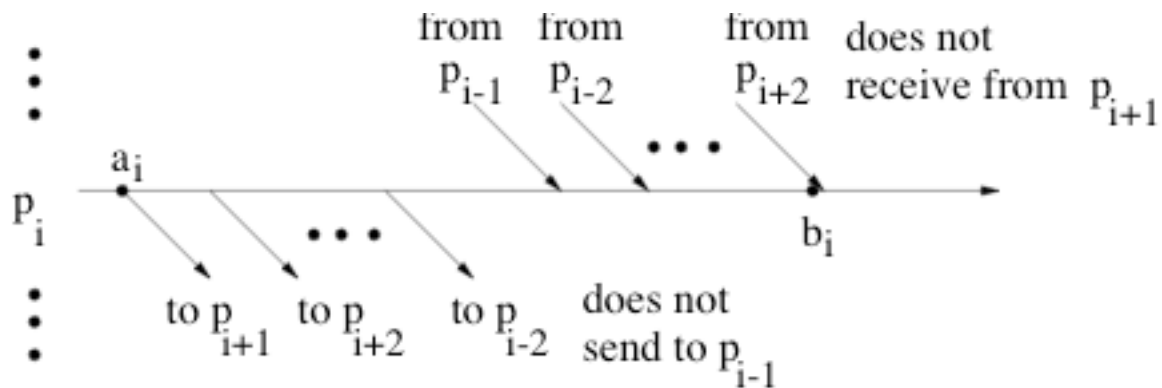


Figure from [Attiya-Welch]

Reduce online vector timestamp

- Exploit network topology ?

Vector Timestamps Lower Bounds

Star Graph		Connectivity	
Real-valued	Integer-valued	>1	1
$n-1$	n	n	$n - Z$

$Z = \#$ minimal
cuts

Vector Timestamps Lower Bounds

Star Graph		Connectivity	
Real-valued	Integer-valued	>1	1
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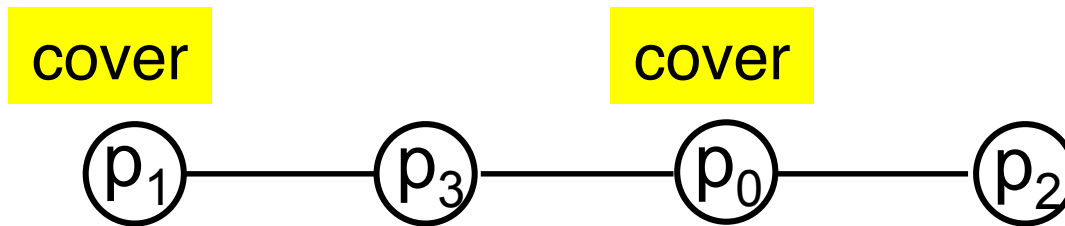
Z = network
parameter

Outline

- Vector timestamp bounds
- Alternate solution

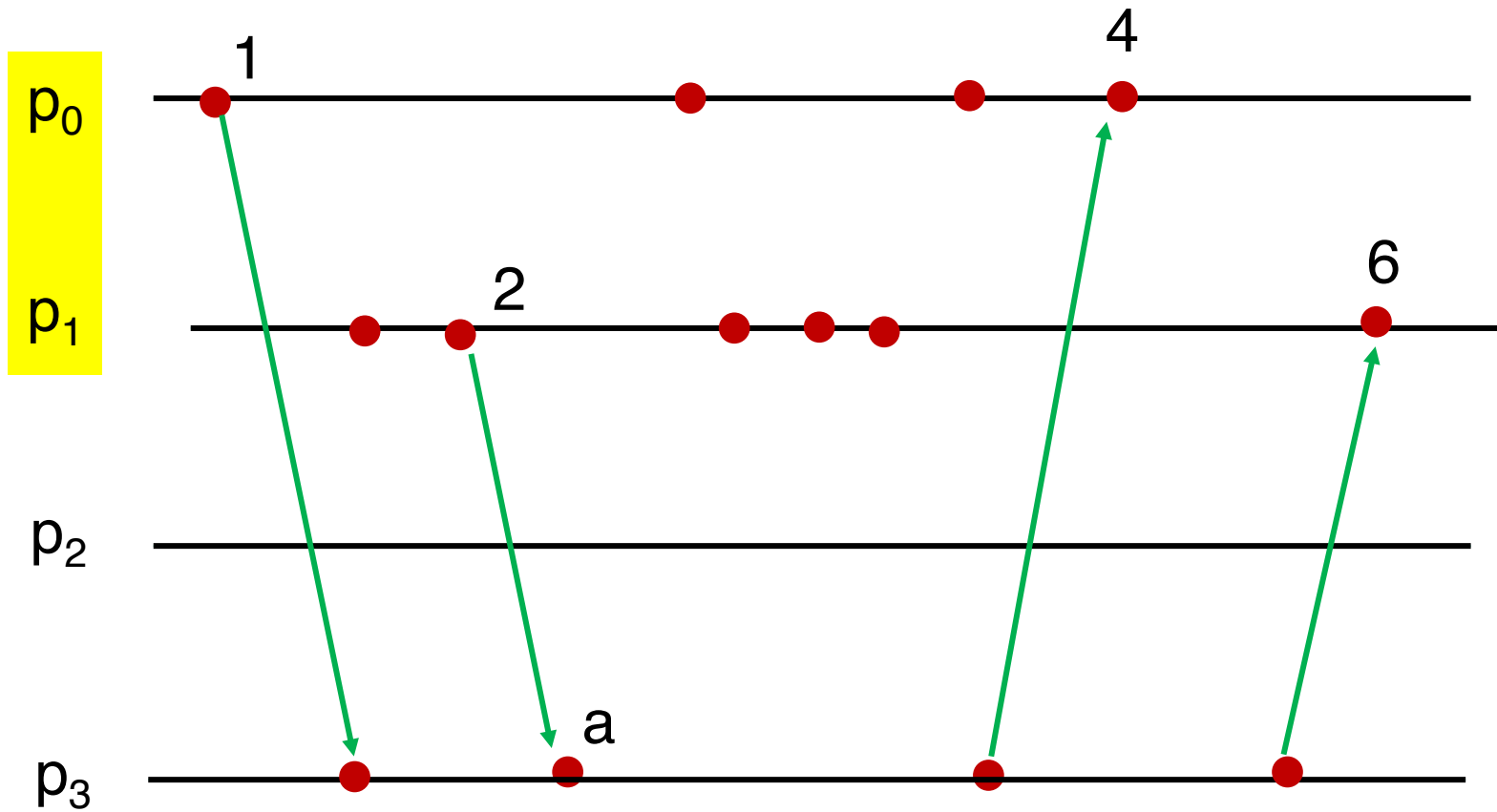
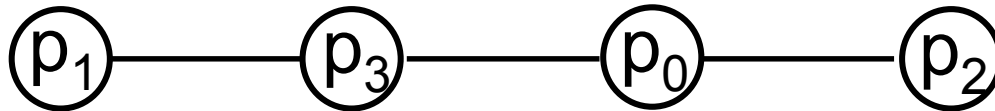
Alternative Solution

- Events at processes in a chosen vertex **cover** used to order all events



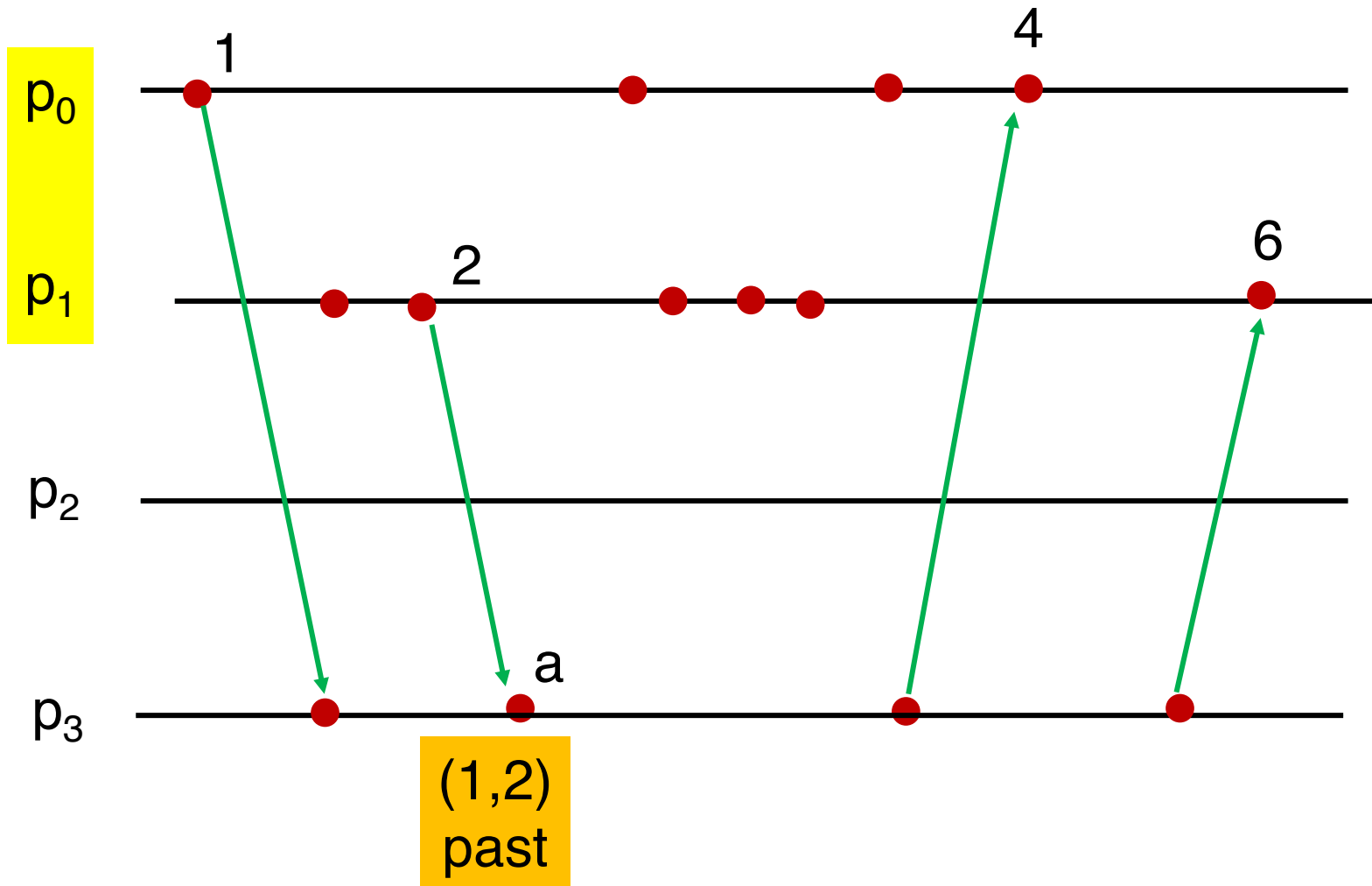
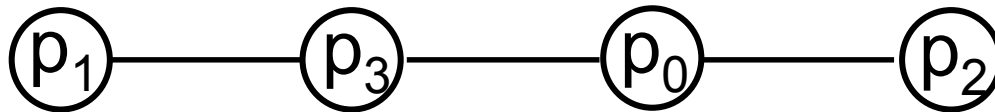
cover

cover



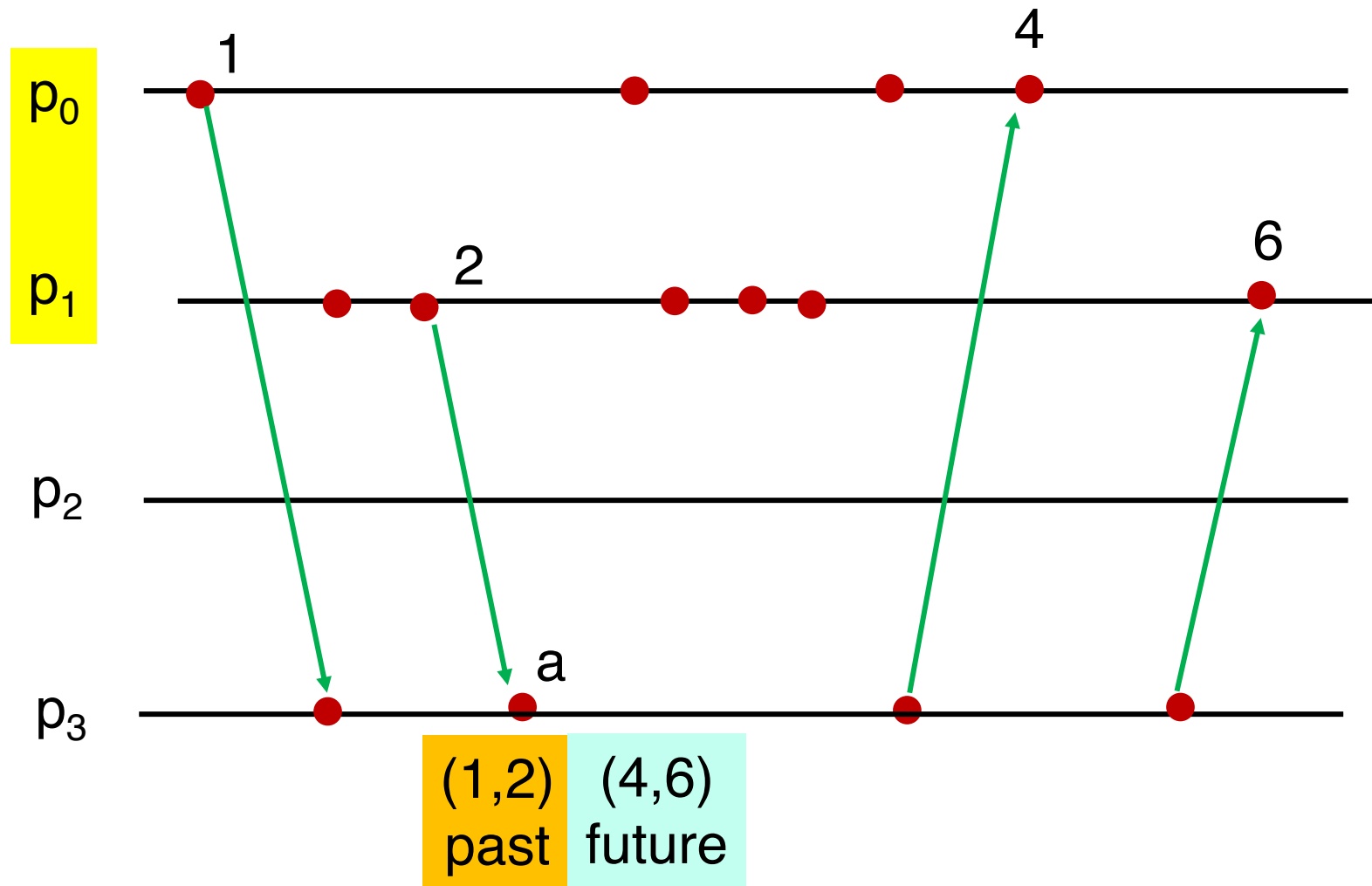
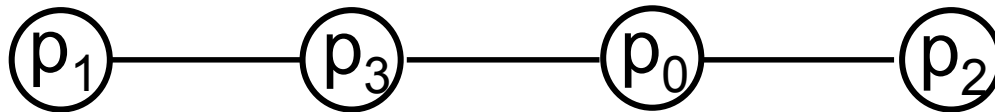
cover

cover



cover

cover



cover

cover

p_1

p_3

p_0

p_2

p_0
 p_1

1

2

p_2

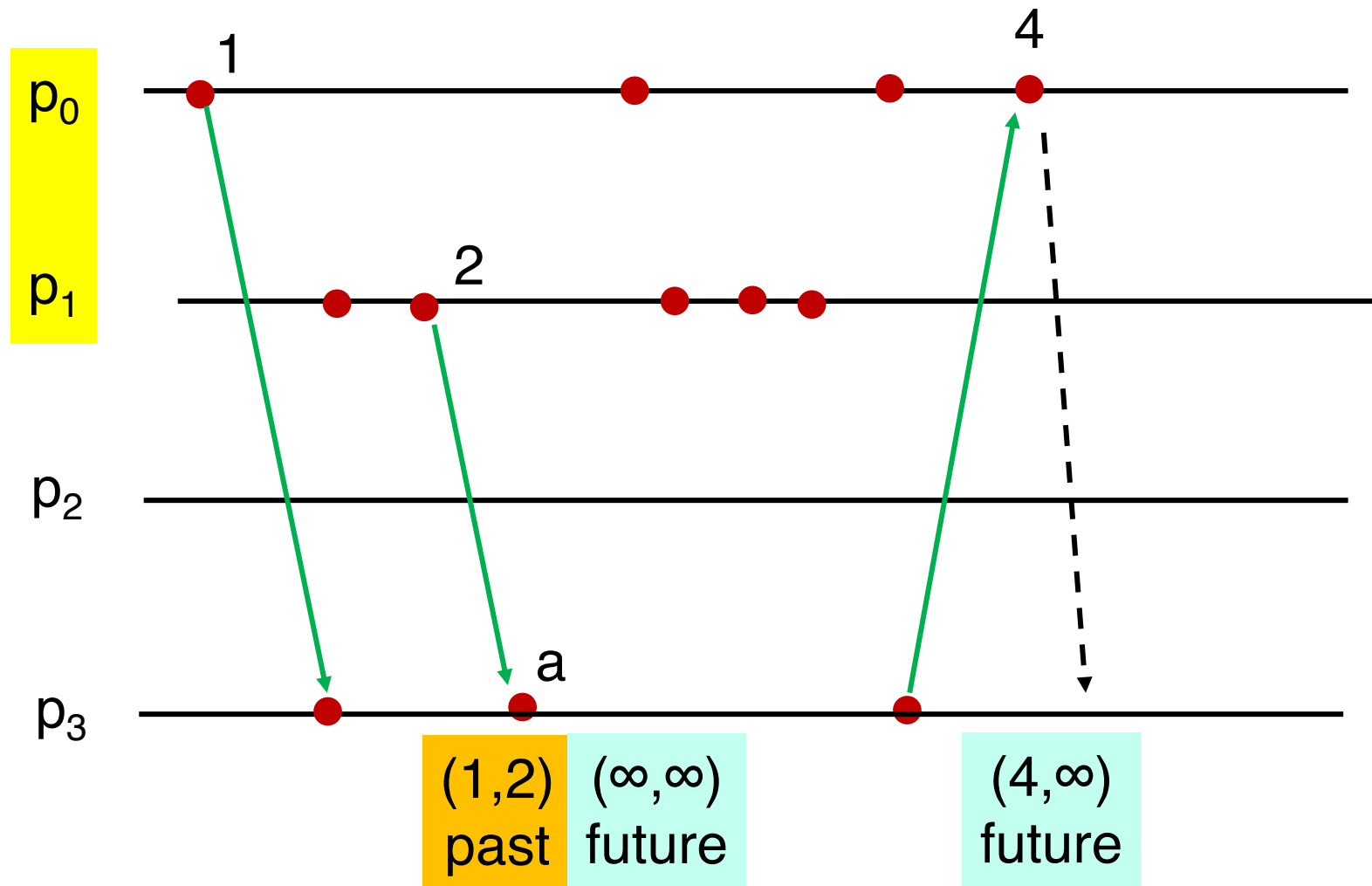
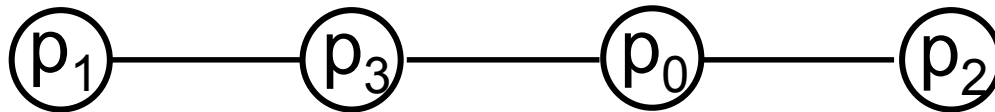
p_3

a

(1,2) past
(∞,∞) future

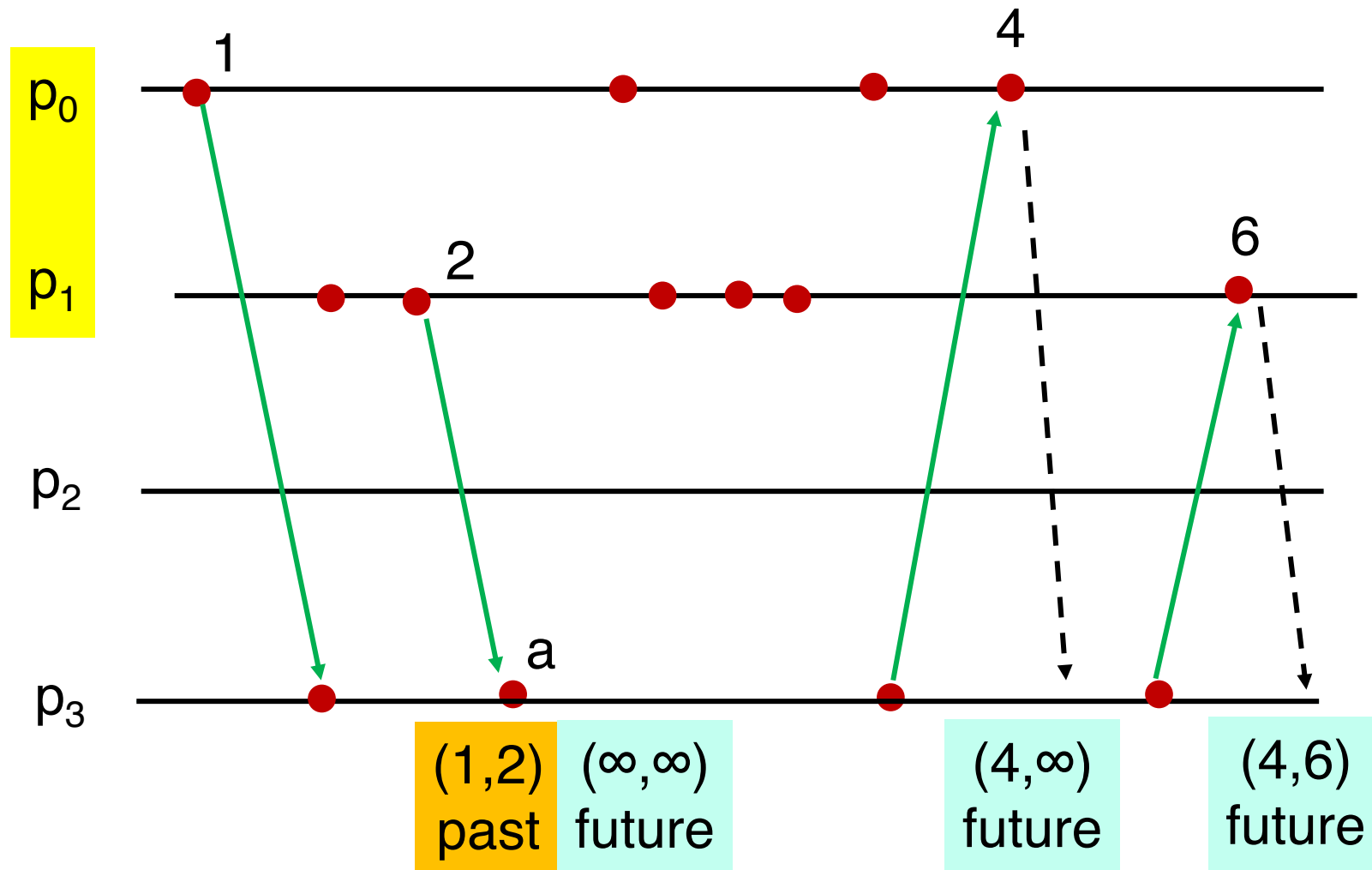
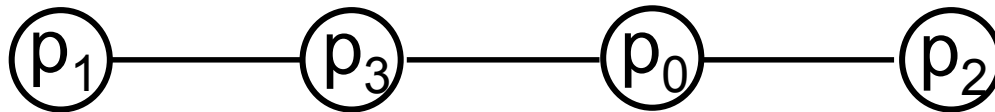
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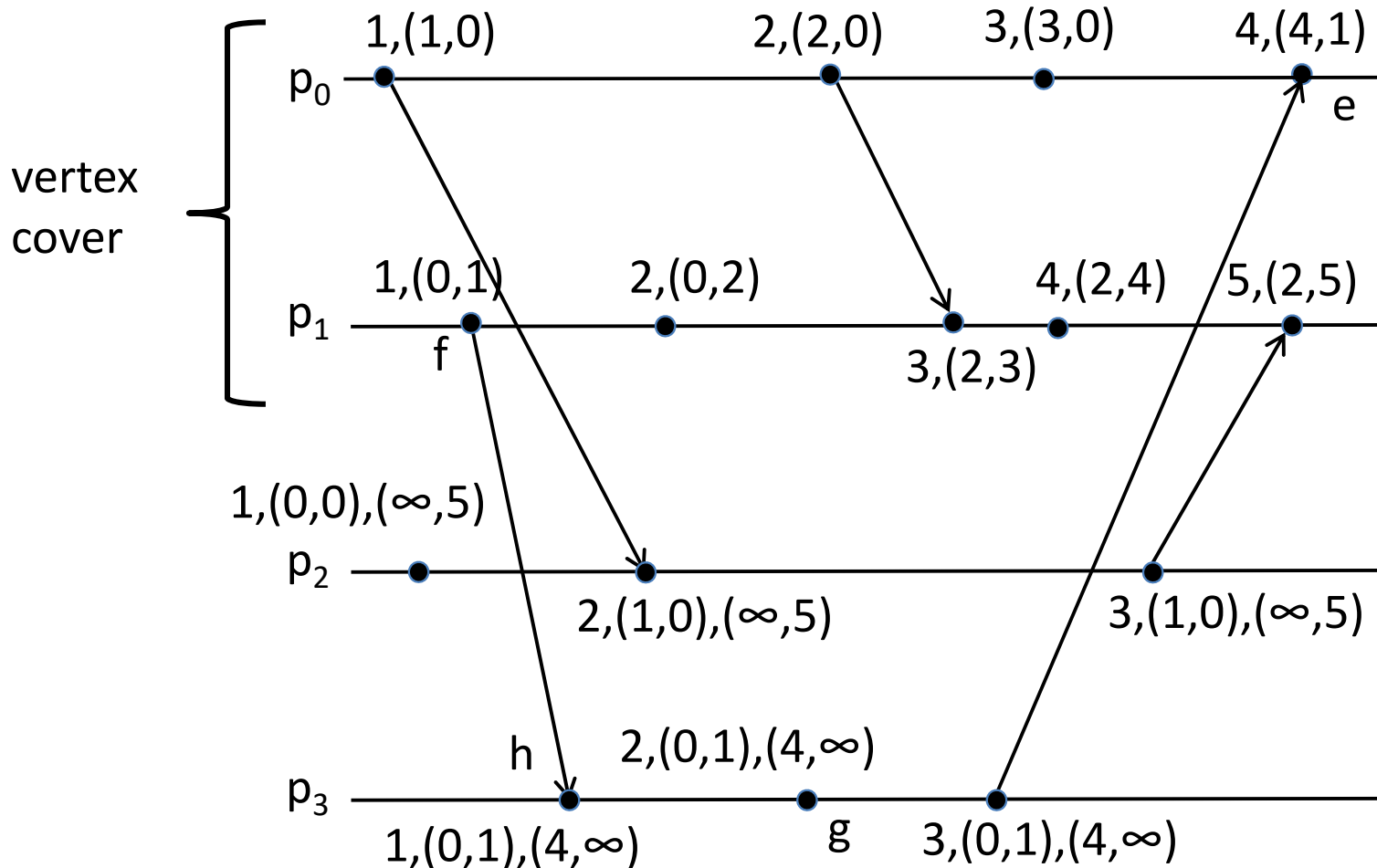
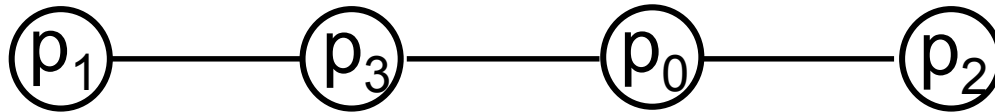
cover

cover



cover

cover



Happened-Before

Intuitively:

$$e \rightarrow f \quad \text{iff} \quad \text{future}(e) \leq \text{past}(f)$$

Alternate Timestamps

- Size proportional to cover size
- Minimum 1 round-trip delay in determining “future” component
 - Potentially much longer

Applications

Smaller timestamps **not interesting** if the cost of using them is too high

- → easy to verify
- Maximal consistent cuts (with a slightly modified timestamp)
- Predicate detection