CS598JHM: Advanced NLP (Spring '10)

# More on EM and variational inference

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# **Today**

- -The connection between EM and variational inference
- Exponential families

Bishop (2006) sections 2.4, 9.3, 9.4, 10.1, 10.4

# **Exponential Families**

# **Exponential families**

 Most parametric distributions that we've seen so far belong to the exponential family of distributions

Distributions in the exponential family are nice because:

- They have conjugate priors (other distributions generally don't)
- The likelihood and posterior can be expressed in terms of **sufficient statistics**

## **Definition**

#### The **exponential family of distributions** over *x*

(x can be scalar or vector; discrete or continuous) given the "natural" parameters  $\eta$  is defined as the set of distributions

$$p(x|\boldsymbol{\eta}) = h(x)g(\boldsymbol{\eta})exp(\boldsymbol{\eta}^Tu(x))$$

 $-g(\eta)$ : normalization coefficient:

$$g(\boldsymbol{\eta}) = (\int x \, exp(\boldsymbol{\eta}^T u(x)))^{-1}$$

-u(x): some function of x

## Likelihood

Given a sequence of i.i.d observations  $Y=(y_1,...,y_n)$ , the likelihood  $P(Y|\eta)$  is:

$$P(Y|\boldsymbol{\eta}) = \left[\prod_{i=1}^{n} h(y_i)\right] g(\boldsymbol{\eta})^n \exp\left(\boldsymbol{\eta}^T \sum_{i=1}^{n} u(y_i)\right)$$

Define a function t(Y), called **sufficient statistics**:

$$t(Y) = \sum_{i=1}^{n} u(y_i)$$

Thus: 
$$P(Y|\boldsymbol{\eta}) = \left[\prod_{i=1}^n h(y_i)\right] g(\boldsymbol{\eta})^n \exp\left(\boldsymbol{\eta}^T t(Y)\right)$$

$$\propto g(\boldsymbol{\eta})^n \exp\left(\boldsymbol{\eta}^T t(Y)\right)$$

# **Conjugate priors**

It is straightforward to define a conjugate prior for members of the exponential family:

Likelihood 
$$P(Y|\boldsymbol{\eta}) \propto g(\boldsymbol{\eta})^n e^{\boldsymbol{\eta}^T t(Y)}$$
  
Prior  $P(\boldsymbol{\eta}) \propto g(\boldsymbol{\eta})^{\mu} e^{\boldsymbol{\eta}^T \nu}$   
Posterior  $P(\boldsymbol{\eta}|Y) \propto P(\boldsymbol{\eta})P(Y|\boldsymbol{\eta})$   
 $= g(\boldsymbol{\eta})^{\mu+n} e^{\boldsymbol{\eta}^T (\nu+t(Y))}$ 

# **Expectation Maximization revisited**

# The EM algorithm

The goal of EM: Find the maximum likelihood solution for a model consisting of parameters θ, given observed (incomplete) data **X** and latent variables **Z** 

$$\ln p(\mathbf{X}|\theta) = \ln \left\{ \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta) \right\}$$

Note: Even if complete likelihood  $p(X,Z \mid \theta)$  is in exponential family, incomplete likelihood  $p(X \mid \theta)$  may not be.

We just have **incomplete data X**, so don't know  $p(X,Z \mid \theta)$ . We can only infer **Z** from posterior  $p(Z \mid X,\theta)$ . We will compute the **expectation** of  $p(X,Z \mid \theta)$  wrt.  $p(Z \mid X,\theta)$ 

# The EM algorithm

1. **Initialization:** Choose initial  $\theta^{old}$ 

#### 2. Expectation step:

Compute posterior of the latent variables  $p(\mathbf{Z} \mid \mathbf{X}, \theta^{old})$ 

#### 3. Maximization step:

Find  $\theta^{new}$  which maximize the expected log-likelihood of the joint  $p(\mathbf{Z}, \mathbf{X} \mid \theta^{new})$  under  $p(\mathbf{Z} \mid \mathbf{X}, \theta^{old})$ :

$$\theta^{new} = \arg \max_{\theta} \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{old}) \ln p(\mathbf{X}, \mathbf{Z}|\theta)$$

4. Check for convergence.

Stop, or set  $\theta^{old} := \theta^{new}$  and go to 2.

## **Another view of EM**

We want to maximize 
$$\ln p(\mathbf{X}|\theta) = \ln \left\{ \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta) \right\}$$

By the product rule:  $\ln p(\mathbf{X}, \mathbf{Z}|\theta) = \ln p(\mathbf{Z}|\mathbf{X}\theta) + \ln p(\mathbf{X}|\theta)$ 

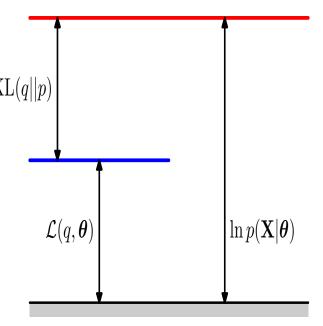
Define a functional of distribution  $q(\mathbf{Z})$ :

$$\mathcal{L}(q, \theta) = \sum_{\mathbf{Z}} q(\mathbf{Z}) \ln \frac{p(\mathbf{X}, \mathbf{Z}|\theta)}{q(\mathbf{Z})}$$

KL-divergence btw.  $q(\mathbf{Z})$  and posterior:

$$KL(q||p) = -\sum_{\mathbf{Z}} q(\mathbf{Z}) \ln \frac{p(\mathbf{Z}|\mathbf{X}, \theta)}{q(\mathbf{Z})}$$

Thus  $\ln p(\mathbf{X}|\theta) = \mathcal{L}(q,\theta) + KL(q||p)$ 



# EM again...

 $\mathcal{L}(q, \theta)$  is a lower bound on log-likelihood  $ln p(X | \theta)$ 

# KL(q||p) = 0

#### E-step:

Maximize  $\mathcal{L}(q, \theta^{old})$  wrt.  $q(\mathbf{Z})$ , keep  $\theta^{old}$  fixed.

This happens when KL(q||p) = 0.

# $\mathcal{L}(q, \boldsymbol{\theta}^{\mathrm{old}})$ $\ln p(\mathbf{X}|\boldsymbol{\theta}^{\mathrm{old}})$

#### M-step:

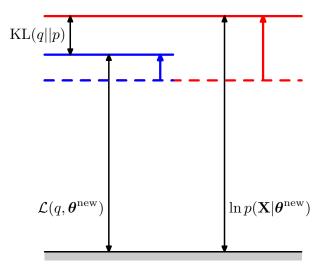
Maximize  $\mathcal{L}(q, \theta^{old})$  wrt.  $\theta$ ,

keep  $q(\mathbf{Z})$  fixed.

 $\mathcal{L}(q, \theta)$  will increase.

Thus  $\ln p(X | \theta)$  will increase.

Hence, now: KL(q||p) > 0



# Variational inference for Bayesian models

# **Bayesian model**

- In a fully Bayesian model, all parameters  $\theta$  are stochastic variables with priors.
- Now **Z** consists of latent variables and priors.
- We still want to maximize (incomplete) log-likelihood:

$$\ln p(\mathbf{X}) = \mathcal{L}(q) + KL(q||p)$$

$$\mathcal{L}(q) = \int q(\mathbf{Z}) \ln \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} d\mathbf{Z}$$

$$KL(q||p) = -\int q(\mathbf{Z}) \ln \frac{p(\mathbf{Z}|\mathbf{X})}{q(\mathbf{Z})} d\mathbf{Z}$$

## **Factorized distributions**

Assume *q* factorizes:

$$q(\mathbf{Z}) = \prod_{i=1}^{M} q_i(\mathbf{Z}_i)$$

We still want to maximize  $\mathcal{L}(q)$ .

We can do this by optimizing with respect to each factor  $q_i$  in turn

$$\mathcal{L}(q) = \int \prod_{i} q_{i} \left\{ \ln p(\mathbf{X}, \mathbf{Z}) - \sum_{i} \ln q_{i} \right\} d\mathbf{Z}$$
$$= \int q_{j} \langle \ln p(\mathbf{X}, \mathbf{Z}) \rangle_{i \neq j} + c' d\mathbf{Z}_{j} - \int q_{i} \ln q_{j} dz_{j} + c$$