

# Sampling (Koller/Friedman '09, Ch.12)

Julia Hockenmaier

juliahmr@illinois.edu  
3324 Siebel Center

<http://www.cs.uiuc.edu/class/sp10/cs598jhm>

## Sampling methods

Task: Compute the expectation  $f(x)$  relative to  $P(x)$

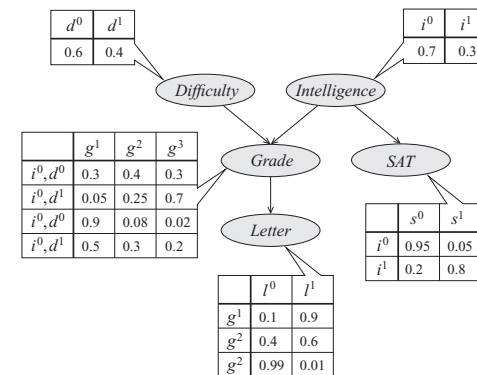
Approximate this through sampling:

Draw a finite number of samples from  $P(x)$

Also known as particle-based approximate inference

## Forward sampling

## The *Student* network: writing letters of recommendation



## Forward sampling in a Bayesian Network

1. Sort the nodes  $X_1 \dots X_n$  topologically (i.e. such that parents precede their descendants)
2. For  $i=1 \dots n$ :
  - 2.1. Let  $\mathbf{u}_i$  be the current assignment to the parents of  $X_i$
  - 2.2. Sample  $x_i$  from  $P(x_i | \mathbf{u}_i)$
3. Return  $(x_1, \dots, x_n)$

## Sampling from a conditional distribution $P(y | e)$

### Rejection Sampling

Sample from  $P(x)$  and reject when  $E \neq e$

Problem:  $P(e)$  may be very low.  
Now we require  $P(e)^{-1}$  more samples

## Likelihood weighting

**Task:** sample  $P(y|e)$  given multiple observations  $e_1 \dots e_n$

We can use forward sampling, but need to take the probability  $P(e_i | \dots)$  into account.

### Likelihood weighting:

- Weight each sample by  $w = \prod_i P(e_i | \dots)$
- Estimate conditional probability  $P(y|e)$  as a weighted average of samples

## Likelihood-weighted sampling in a Bayesian Network

1. Sort the nodes  $X_1 \dots X_n$  topologically (i.e. such that parents precede their descendants)
2. Initialize  $w = 1$
3. For  $i=1 \dots n$ :
  - 3.1. Let  $\mathbf{u}_i$  be the current assignment to the parents of  $X_i$
  - 3.2. If  $x_i \notin e$ : sample  $x_i$  from  $P(x_i | \mathbf{u}_i)$
  - 3.3. If  $x_i \in e$ : 1) set  $x_i$  to  $e_i$ . 2) multiply  $w$  by  $P(e_i | \mathbf{u}_i)$
4. Return  $(x_1, \dots, x_n), w$

## Importance sampling

Likelihood weighted sampling is a special case of **importance sampling**

- We cannot always sample efficiently from  $P(x)$
- But we may be able to **evaluate**  $P(x)$  efficiently
- And we may be able to sample efficiently from some **proposal distribution**  $Q(x)$
- If  $Q(x) \neq 0$  whenever  $P(x) \neq 0$ , we can compute  $E_{P(x)}[f(x)]$

$$\begin{aligned} E_{P(x)}[f(x)] &= E_{Q(x)}\left[f(x)\frac{P(x)}{Q(x)}\right] \\ &= \sum_x Q(x)f(x)\frac{P(x)}{Q(x)} \\ &= \sum_x f(x)P(x) \end{aligned}$$

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## Normalized importance sampling

Instead of  $P(x)$ , we often know only some **unnormalized** probability  $P'(x)$  with  $P(x) = P'(x)/Z$

We may want to sample from  $P(x|e)$ , but only have  $P(x,e)$

Define a weight  $w(x) = P'(x)/Q(x)$

Now we can compute  $E_Q[w(x)] \dots$

$$\begin{aligned} E_{Q(x)}[w(x)] &= \sum_x Q(x)\frac{P'(x)}{Q(x)} \\ &= \sum_x P'(x) = Z \end{aligned}$$

.... and hence estimate  $Z$

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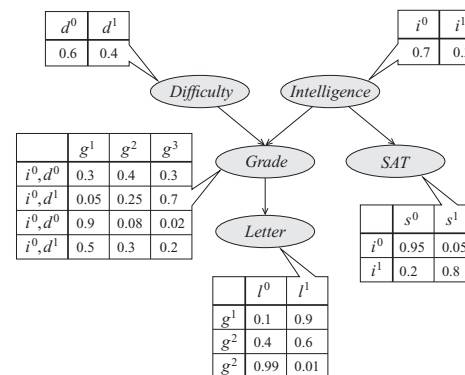
## Putting things together....:

Normalized/Weighted importance sampling

$$\begin{aligned} E_{P(x)}[f(x)] &= \sum_x f(x)P(x) \\ &= \sum_x Q(x)f(x)\frac{P(x)}{Q(x)} \\ &= \frac{1}{Z} \sum_x Q(x)f(x)\frac{P'(x)}{Q(x)} \\ &= \frac{1}{Z} E_{Q(x)}[f(x)w(x)] \\ &= \frac{E_{Q(x)}[f(x)w(x)]}{E_{Q(x)}[w(x)]} \end{aligned}$$

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## Importance sampling in practice



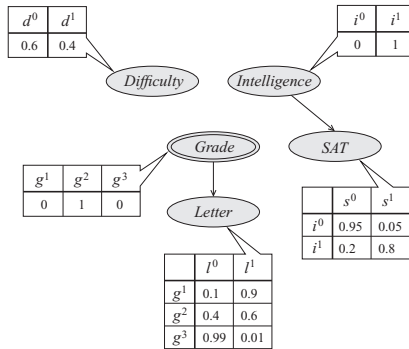
Sample from  $P(D,I,S,L | G=g^2)$

What is a good proposal distribution  $Q$ ?

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## Constructing $Q$

- The proposal distribution sets all (conditioning) variables in  $Z$  to their known value.
- It also decouples all variables in  $Z$  from their parents



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## Limitations of likelihood weighting

- Evidence nodes affect sampling only for their descendants
- The effect of the evidence on other nodes is only captured by the weight
- When evidence is mostly at the leaf nodes, we effectively sample from the prior distribution (which can be very different from the posterior)
- Markov Chain Monte Carlo sampling methods generate a sequence of samples which may start out as the prior, but will approximate the posterior

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