## $1 \quad T$-joins and Applications

This material is based on [1] (Chapter 5), and also [2] (Chapter 29).
Edmonds was motivated to study $T$-joins by the Chinese postman problem which is the following.

Problem 1 Let $G=(V, E)$ be an undirected graph and $c: E \rightarrow \mathbb{R}^{+}$be non-negative edge weights on the edges. A Chinese postman tour is a walk that starts at some arbitrary vertex and returns to it after traversing each edge of $E$. Note that an edge may be traversed more than once. The goal is to find a postman tour of minimum total edge cost.

Proposition 1 If $G$ is Eulerian then the optimal postman tour is an Eulerian tour of $G$ and has cost equal to $\sum_{e \in E} c(e)$.

Thus the interesting case is when $G$ is not Eulerian. Let $T \subseteq V$ be the nodes with odd degree in $G$.

Fact $1|T|$ is even.
Consider a postman tour and say it visits an edge $x(e)$ times, where $x(e) \geq 1$ is an integer. Then, it is easy to see that the multigraph induced by placing $x(e)$ copies of $e$ is in fact Eulerian. Conversely if $x(e) \geq 1$ and $x(e) \in \mathbb{Z}^{+}$such that the graph is Eulerian, then it induces a postman tour of cost $\sum_{e \in E} c(e) x(e)$.

We observe that if $x(e)>2$ then reducing $x(e)$ by 2 maintains feasibility. Thus $x(e) \in\{1,2\}$ for each $e$ in any minimal solution. If we consider the graph induced by $x(e)^{\prime}=x(e)-1$ we see that each node in $T$ has odd degree and every other node has even degree. This motivates the definition of $T$-joins.

Definition 2 Given a graph, $G=(V, E)$, and a set, $T \subseteq V$, a $T$-join is a subset $J \subseteq E$ such that in the graph $(V, J), T$ is the set of nodes with odd degree.

Proposition 3 There is a $T$-join in $G$ iff $|K \cap T|$ is even for each connected component $K$ of $G$. In particular, if $G$ is connected then there exists a $T$-join iff $|T|$ is even.
Proof: Necessity is clear. For sufficiency, assume $G$ is connected, otherwise we can work with each connected component separately. Let $T=\left\{v_{1}, v_{2}, \ldots, v_{2 k}\right\}$. Let $P_{i}$ be an arbitrary path joining $v_{i}$ and $v_{i+k}$. Then the union of the paths $P_{1}, P_{2}, \ldots, P_{k}$ induces a multigraph in which the nodes in $T$ are the only ones with odd degree. Let $x(e)$ be the number of copies of $e$ in the above union. Then $x^{\prime}(e)=x(e) \bmod 2$, is the desired $T$-join. (Note that the pairing of the vertices was arbitrary and hence any pairing would work.)
Proposition $4 J$ is a $T$-join iff $J$ is the union of edge disjoint cycles and $\frac{1}{2}|T|$ paths connecting disjoint pairs of nodes in $T$.
Proof: This is left as an exercise.

### 1.1 Algorithm for Min-cost $T$-joins

Given $G=(V, E), c: E \rightarrow \mathbb{R}$ and $T \subseteq V$, where $|T|$ even, we want to find the min-cost $T$-join. If all edge costs are non-negative then one can easily reduce the problem to a matching problem as follows. Assume without loss of generality that $G$ is connected.

1. For each pair $u, v \in T$ let $w(u v)$ be the shortest path distance between $u$ and $v$ in $G$, with edge length given by $c$. Let $P_{u v}$ be the shortest path between $u$ and $v$.
2. Let $H$ be the complete graph on $T$ with edge weights $w(u v)$.
3. Compute a minimum weight perfect matching $M$ in $H$.
4. Let $J=\left\{e \mid e\right.$ occurs in an odd number of paths $\left.P_{u v}, u v \in M\right\}$. Output $J$.

Theorem 5 There is a strongly polynomial time algorithm to compute a min-cost $T$-join in a graph, $G=(V, E)$ with $c \geq 0$.

Proof Sketch. To see the correctness of this algorithm first note that it creates a $T$-join since it will return a collection of $\frac{1}{2}|T|$ disjoint paths, which by Proposition 4 is a $T$-join (Note the fourth step in the algorithm is required to handle zero cost edges, and is not necessary if $c>0$ ). It can be seen that this $T$-join is of min-cost since the matching is of min-cost (and since, ignoring zero cost edges, the matching returned must correspond to disjoint paths in $G$ ).

The interesting thing is that min-cost $T$-joins can be computed even when edge lengths can be negative. This has several non-trivial applications. We reduce the general case to the non-negative cost case by making the following observations.

Fact 2 If $A, B$ are two subsets of $U$ then $|A \Delta B|$ is even iff $|A|$ and $|B|$ have the same parity, where we define $X \Delta Y$ as the symmetric difference of $X$ and $Y$.

Proposition 6 Let $J$ be a $T$-join and $J^{\prime}$ be a $T^{\prime}$-join then $J \Delta J^{\prime}$ is a $\left(T \Delta T^{\prime}\right)$-join.
Proof: Verify using the above fact that each $v \in T \Delta T^{\prime}$ has odd degree and every other node has even degree in $J \Delta J^{\prime}$.

Corollary 7 If $J^{\prime}$ is a $T^{\prime}$-join and $J \Delta J^{\prime}$ is a $\left(T \Delta T^{\prime}\right)$-join then $J$ is a $T$-join.
Proof: Note that $\left(T \Delta T^{\prime}\right) \Delta T^{\prime}=T$ and similarly $\left(J \Delta J^{\prime}\right) \Delta J^{\prime}=J$. Hence the corollary is implied by application of the above proposition.

Given $G=(V, E)$ with $c: E \rightarrow \mathbb{R}$, let $N=\{e \in E \mid c(e)<0\}$. Let $T^{\prime}$ be the set of nodes with odd degree in $G[N]$. Clearly $N$ is a $T^{\prime}$-join by definition. Let $J^{\prime \prime}$ be a $\left(T \Delta T^{\prime}\right)$-join in $G$ with the costs on edges in $N$ negated (i.e. $c(e)=|c(e)|, \forall e \in E)$.

Claim $8 J=J^{\prime \prime} \Delta N$ is a $T$-join, where $N=\{e \in E \mid c(e)<0\}, T^{\prime}=\left\{v \in G[N] \mid \delta_{G[N]}(v)\right.$ is odd $\}$, and $J^{\prime \prime}$ is a $\left(T \Delta T^{\prime}\right)$-join.

Proof: By the above corollary, since $J^{\prime \prime}$ is a $\left(T \Delta T^{\prime}\right)$-join and $N$ is a $T^{\prime}$-join, $J^{\prime \prime} \Delta N$ is a $\left(T \Delta T^{\prime}\right) \Delta T^{\prime}=$ $T$-join.

Claim $9 c(J)=|c|\left(J^{\prime \prime}\right)+c(N)$, where $|c|(X)=\sum_{x \in X}|c(x)|$ and $J$, $J^{\prime \prime}$, and $N$ are as defined above.

Proof:

$$
\begin{aligned}
c(J) & =c\left(J^{\prime \prime} \Delta N\right)=c\left(J^{\prime \prime} \backslash N\right)+c\left(N \backslash J^{\prime \prime}\right) \\
& =c\left(J^{\prime \prime} \backslash N\right)-c\left(J^{\prime \prime} \cap N\right)+c\left(J^{\prime \prime} \cap N\right)+c\left(N \backslash J^{\prime \prime}\right) \\
& =c\left(J^{\prime \prime} \backslash N\right)+|c|\left(J^{\prime \prime} \cap N\right)+c(N)=|c|\left(J^{\prime \prime}\right)+c(N) .
\end{aligned}
$$

Corollary $10 J=J^{\prime \prime} \Delta N$ is a min cost $T$-join in $G$ iff $J^{\prime \prime}$ is a min cost $\left(T \Delta T^{\prime}\right)$-join in $G$ with edge costs $|c|$, where $N=\{e \in E \mid c(e)<0\}$, $T^{\prime}=\left\{v \in G[N] \mid \delta_{G[N]}(v)\right.$ is odd $\}$, and $J^{\prime \prime}$ is a $\left(T \Delta T^{\prime}\right)$-join.

Proof Sketch. By using the last claim, necessity is clear since $c(N)$ is a constant and hence when $c(J)$ is minimized so is $|c|\left(J^{\prime \prime}\right)$. To use the same argument for sufficiency, one must argue that for any $T$-join, $J$, we have that $J=J^{\prime \prime} \Delta N$ for some $\left(T \Delta T^{\prime}\right)$-join, $J^{\prime \prime}$.

The above corollary gives a natural algorithm to solve the general case by first reducing it to the non-negative case. In the algorithm below, let $c: E \rightarrow \mathbb{R},|c|: E \rightarrow \mathbb{R}^{+}$such that $|c|(e)=|c(e)|, G_{|c|}$ be the graph with the weight function $|c|, N=\{e \in E \mid c(e)<0\}$, and $T^{\prime}=\left\{v \in G[N] \mid \delta_{G[N]}(v)\right.$ is odd $\}$.

1. Compute a $\left(T \Delta T^{\prime}\right)$-join, $J^{\prime \prime}$, on $G_{|c|}$ using the algorithm above for $c \geq 0$
2. Output $J=J^{\prime \prime} \Delta N$.

Theorem 11 There is a strongly polynomial time algorithm for computing a min-cost $T$-join in a graph, even with negative costs on the edges.
Proof: We know the above algorithm outputs a $T$-join by Claim 8 Since $J^{\prime \prime}$ was computed on $G_{|c|}$, which has non-negative edge weights, by the proof of Theorem 5. $\mathrm{J}^{\prime \prime}$ is a min-cost $T$-join. Hence by Corollary $10 J$ is a min-cost $T$-join.

### 1.2 Applications

### 1.2.1 Chinese Postman

We saw earlier that a min-cost postman tour in $G$ is the union of $E$ and a $T$-join where $T$ is the set of odd degree nodes in $G$. Hence we can compute a min-cost postman tour.

### 1.2.2 Shortest Paths and Negative lengths

In directed graphs the well known Bellman-Ford and Floyd-Warshall algorithms can be used to check whether a given directed graph, $D=(V, A)$, has negative length cycles or not in $O(m n)$ and $O\left(n^{3}\right)$ time respectively. Moreover, if there is no negative length cycle then the shortest $s$ - $t$ path can be found in the same time. However, one cannot use directed graph algorithms for undirected graphs when there are negative lengths, since bi-directing an undirected edge creates a negative length cycle. However, we can use $T$-join techniques.

Proposition 12 An undirected graph, $G=(V, E)$, with $c: E \rightarrow \mathbb{R}$ has a negative length cycle iff an $\emptyset$-join has negative cost.


Figure 1: An example of a graph with a negative cost $\emptyset$-join

Proposition 13 If $G$ has no negative length cycle then the min-cost $\{s, t\}$-join gives an s-t shortest path.

Remark 14 It is important to first check for negative length cycles before finding an $\{s, t\}$-join.
Theorem 15 There is a strongly polynomial time algorithm that given an undirected graph, $G(V, E)$, with $c: E \rightarrow \mathbb{R}$, either outputs a negative length cycle or an s-t shortest path.

Proof Sketch. We first compute a min-cost $\emptyset$-join. By Proposition 12 we know that if this $\emptyset$-join has negative cost then we can produce a negative length cycle. Otherwise, we know there is no negative length cycle and hence by Proposition 13 we can compute a min-cost $\{s, t\}$-join in order to find an $s$ - $t$ shortest path. (In each case the $\bar{T}$-join can be computed using the algorithm from the previous section.)

### 1.2.3 Max-cut in planar graphs

Since one can compute min-cost $T$-joins with negative costs, one can compute max-cost $T$-joins as well. The max-cut problem is the following.

Problem 2 Given an undirected graph with non-negative edge weights, find a partition of $V$ into $(S, S \backslash V)$ so as to maximize $w(\delta(S))$.

Max-cut is NP-hard in general graphs, but Hadlock showed how $T$-joins can be used to solve it in polynomial time for planar graphs. A basic fact is that in planar graphs, cuts in $G$ correspond to collections of edge disjoint cycles in the dual graph $G^{*}$. Thus to find a max-cut in $G$ we compute a max $\emptyset$-join in $G^{*}$ where the weight of an edge in $G^{*}$ is the same as its corresponding edge in the primal.


Figure 2: A planar graph, $G$, in black, and its dual, $G^{*}$, in dashed red.

### 1.2.4 Polyhedral aspects

The following set of inequalities can be shown to determine the characteristic vectors of the set of $T$-joins in a graph $G$.

$$
\begin{aligned}
0 \leq x(e) & \leq 1 \\
x(\delta(U) \backslash F)-x(F) & \geq 1-|F| \quad U \subseteq V, F \subseteq \delta(U),|U \cap T|+|F| \text { is odd }
\end{aligned}
$$

## References

[1] W.J. Cook, W.H. Cunningham, W.R. Pulleyblank, and A. Schrijver. Combinatorial Optimization. Wiley, 1998.
[2] A. Schrijver. Theory of Linear and Integer Programming (Paperback). Wiley, 1998.

