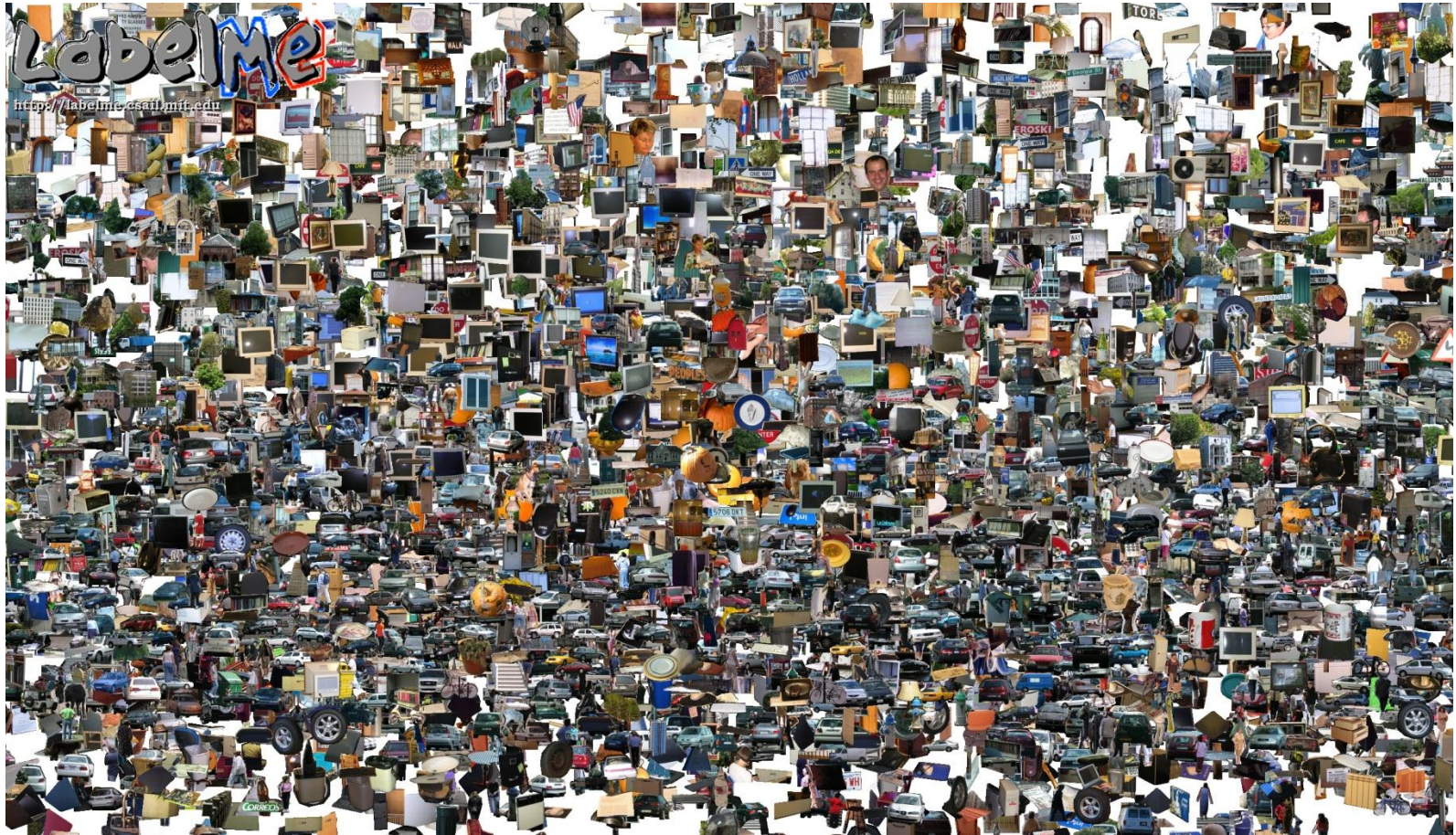


# Opportunities of Scale



Computer Vision

Derek Hoiem, University of Illinois

# Today's class

- Opportunities of Scale: Data-driven methods
  - Scene completion
  - Im2gps
  - Recognition via Tiny Images
  - More recognition by association

# Google and massive data-driven algorithms

A.I. for the postmodern world:

- all questions have already been answered...many times, in many ways
- Google is dumb, the “intelligence” is in the data



# Google Translate



From: English - detected ▼  To: Spanish ▼ [Translate](#)

My dog once ate three oranges, but then it died.

 [Listen](#)

**English to Spanish translation**

Mi perro se comió una vez tres naranjas, pero luego murió.

 [Listen](#)

# Chinese Room

- John Searle (1980)



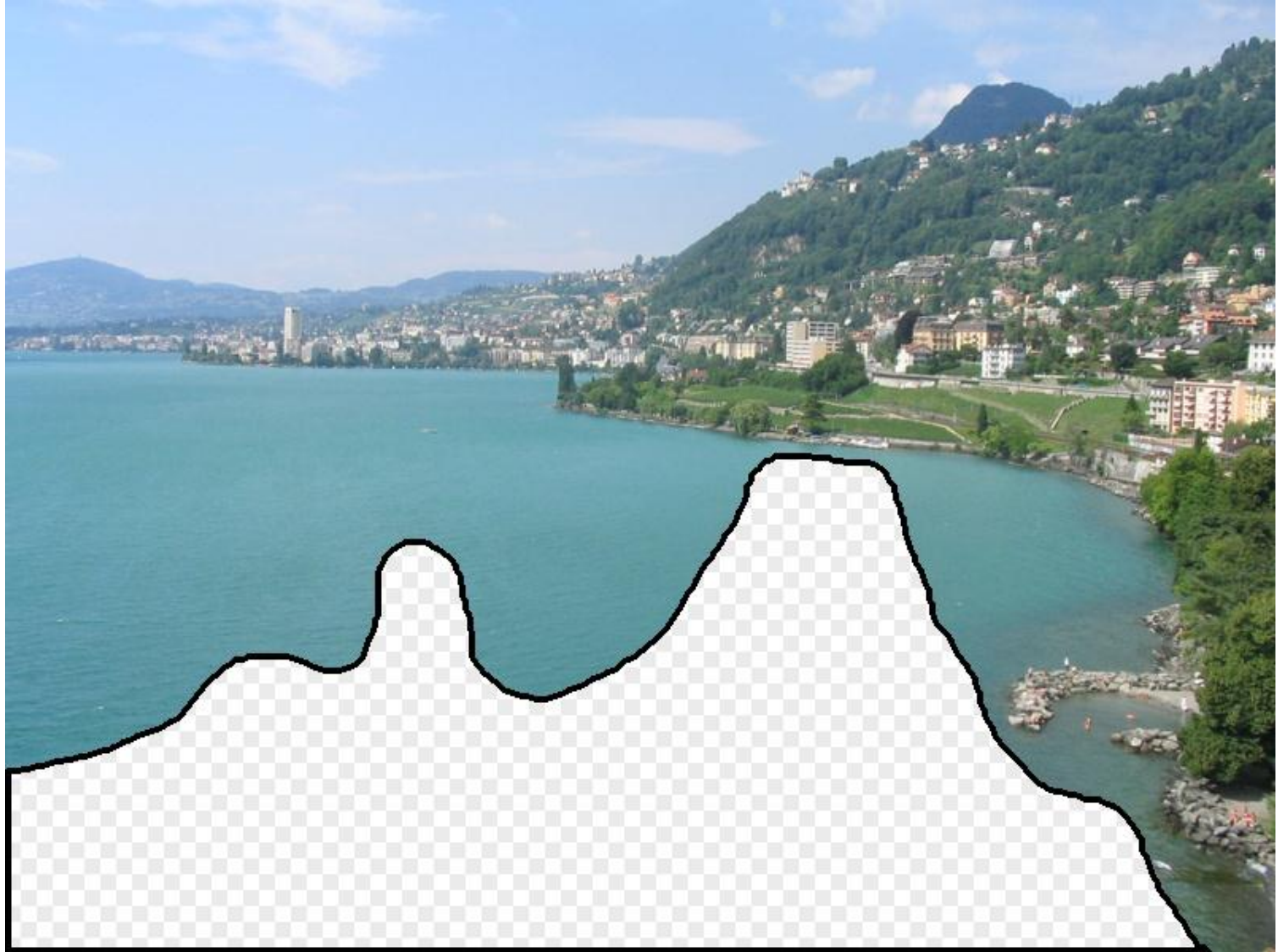
# Image Completion Example

[Hays and Efros. Scene Completion Using Millions of Photographs.  
SIGGRAPH 2007 and CACM October 2008.]

<http://graphics.cs.cmu.edu/projects/scene-completion/>



What should the missing region contain?













# Which is the original?



(a)



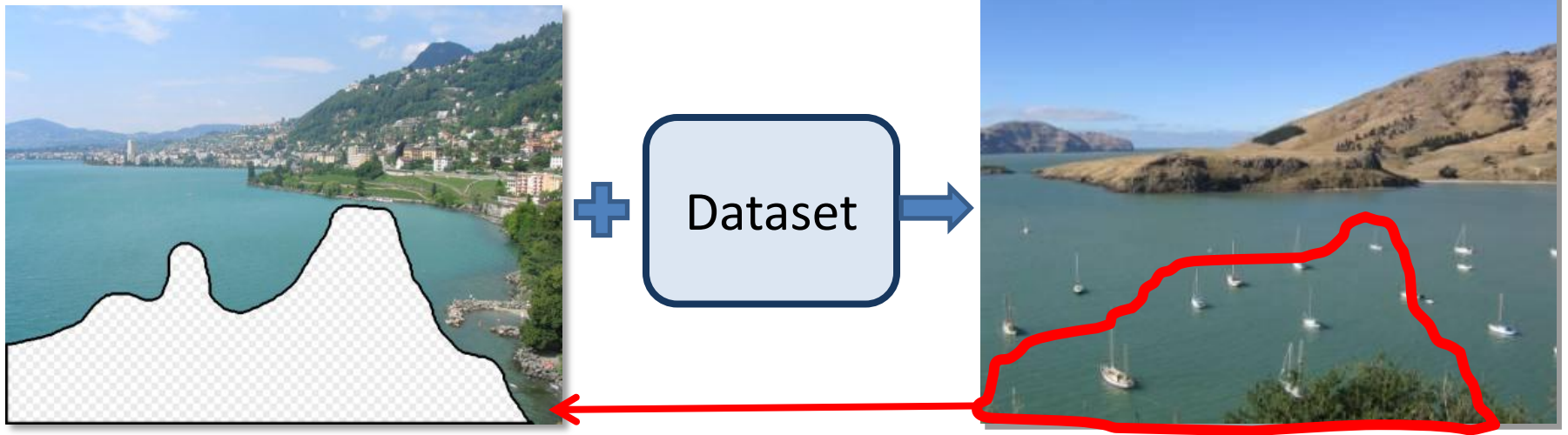
(c)



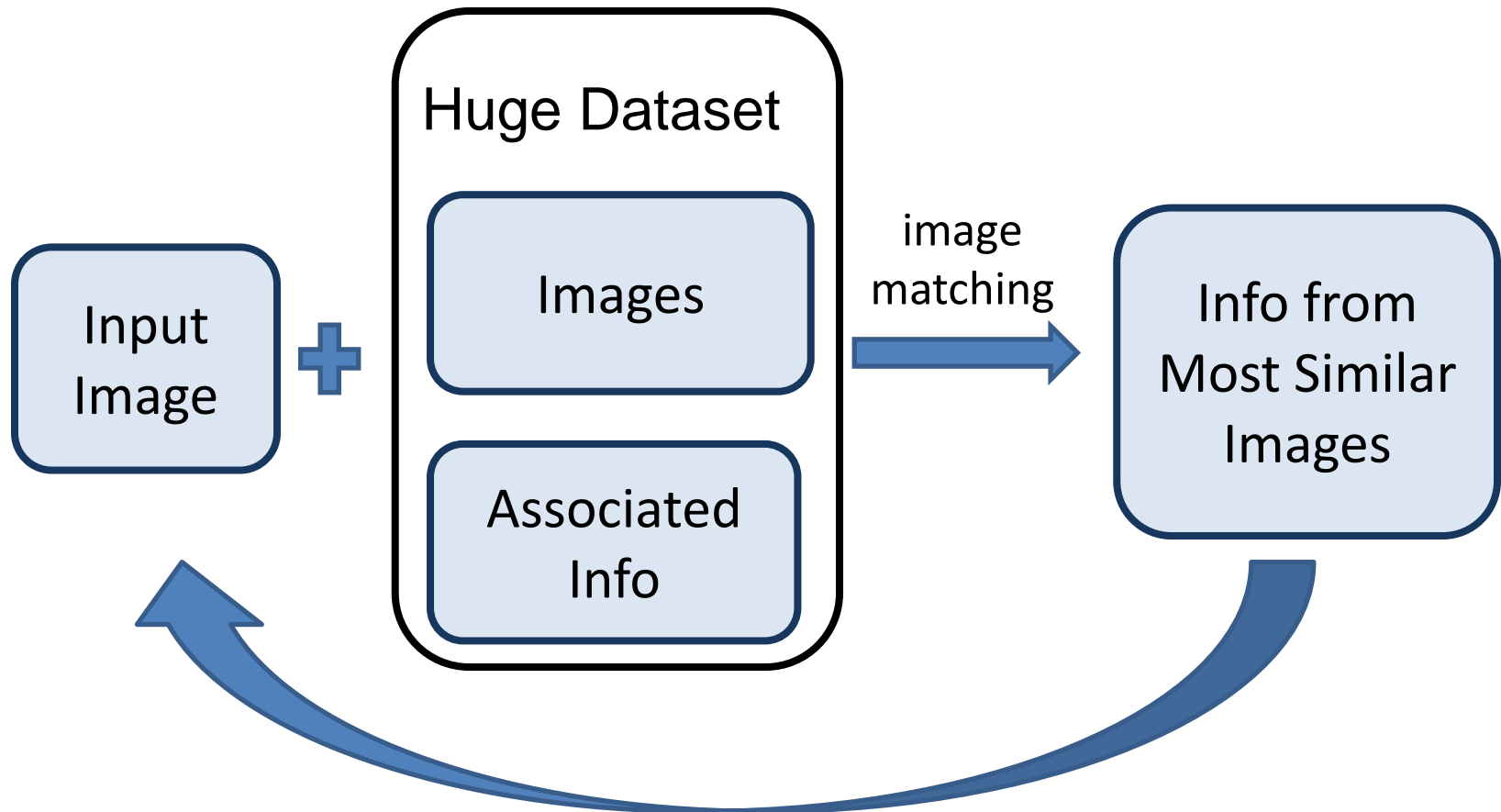
(b)

# How it works

- Find a similar image from a large dataset
- Blend a region from that image into the hole



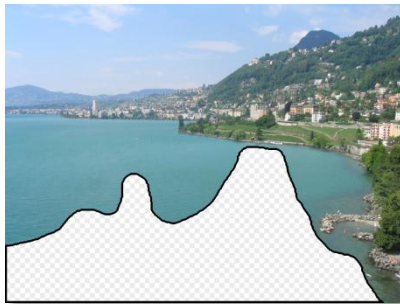
# General Principal

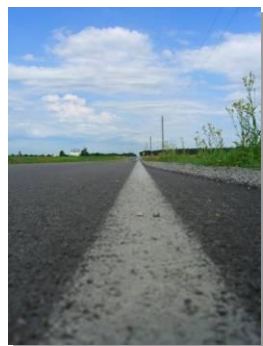
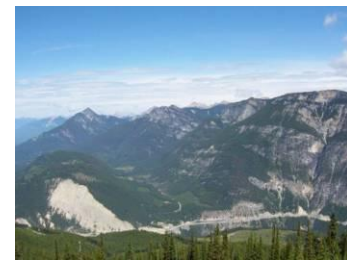
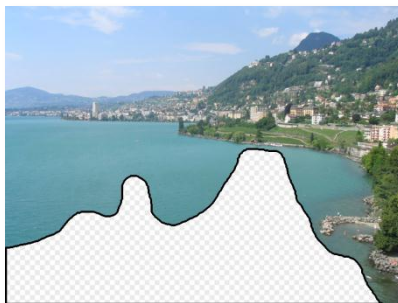
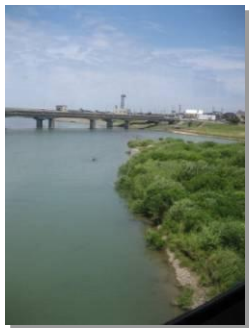


Trick: If you have enough images, the dataset will contain very similar images that you can find with simple matching methods.

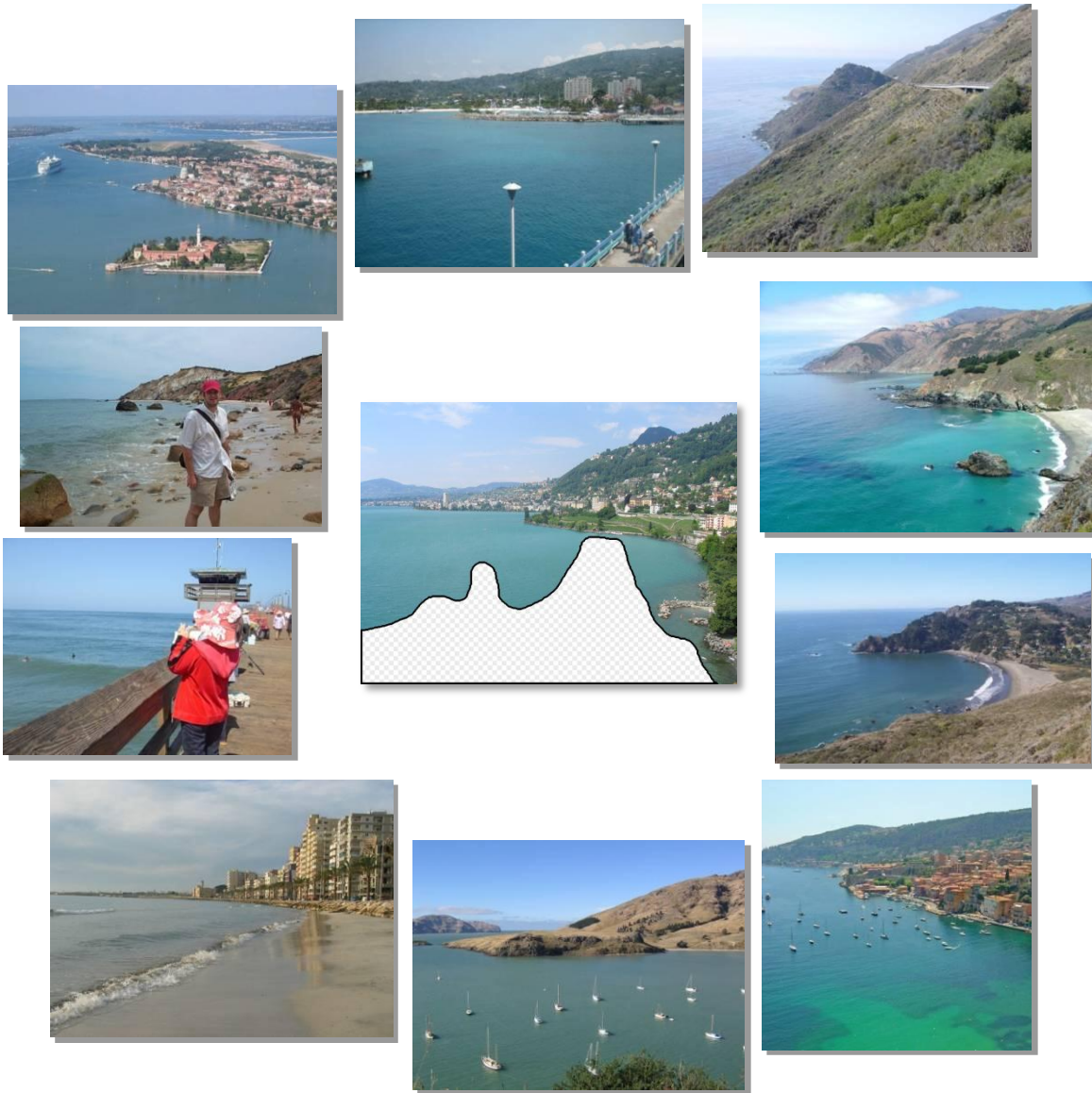


# How many images is enough?





Nearest neighbors from a  
collection of 20 thousand images



Nearest neighbors from a  
collection of 2 million images

# Image Data on the Internet

- Flickr (as of Sept. 19<sup>th</sup>, 2010)
  - 5 billion photographs
  - 100+ million geotagged images
- Imageshack (as of 2009)
  - 20 billion
- Facebook (as of 2009)
  - 15 billion

# Image completion: how it works

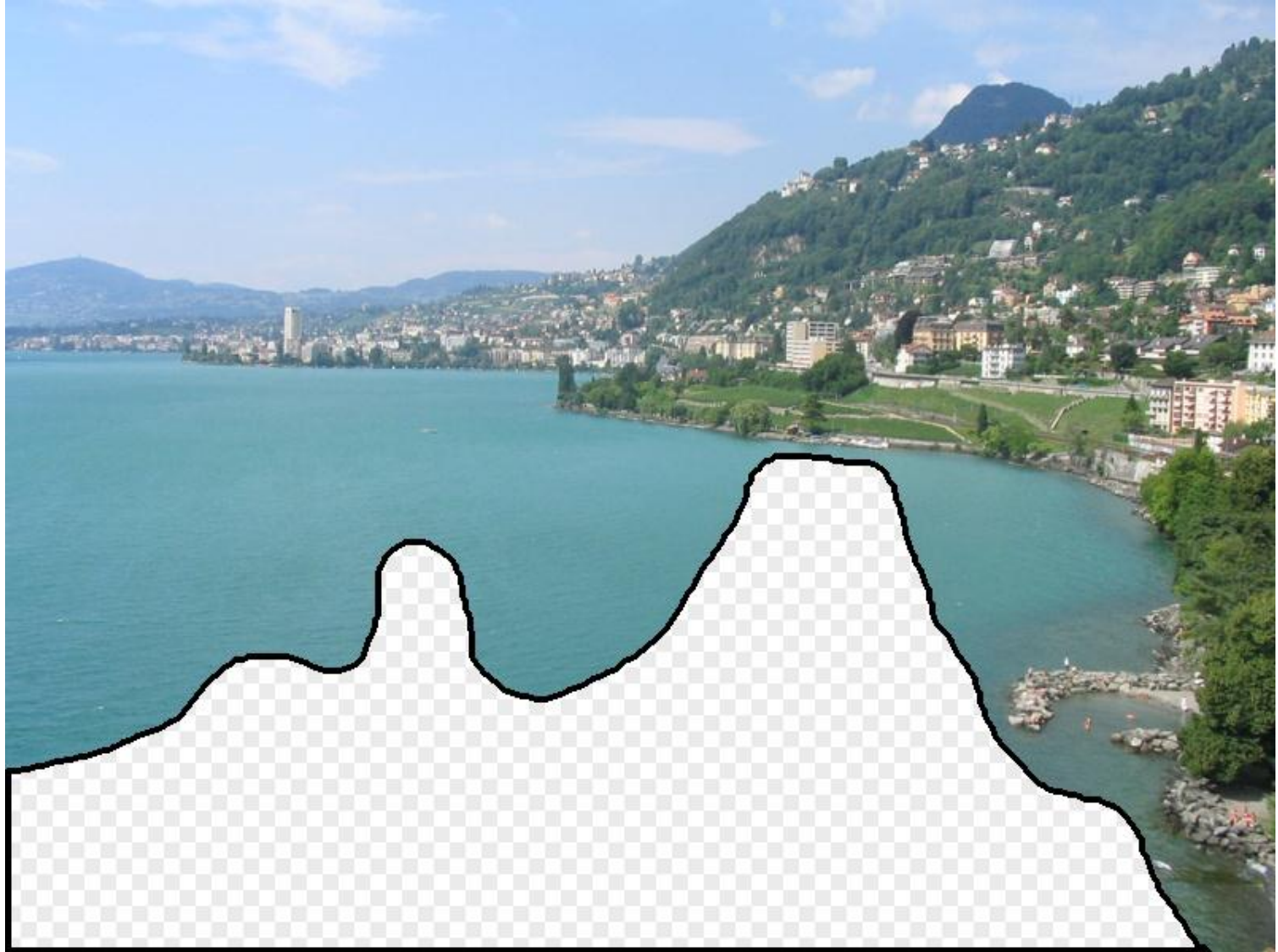
[Hays and Efros. Scene Completion Using Millions of Photographs.  
SIGGRAPH 2007 and CACM October 2008.]



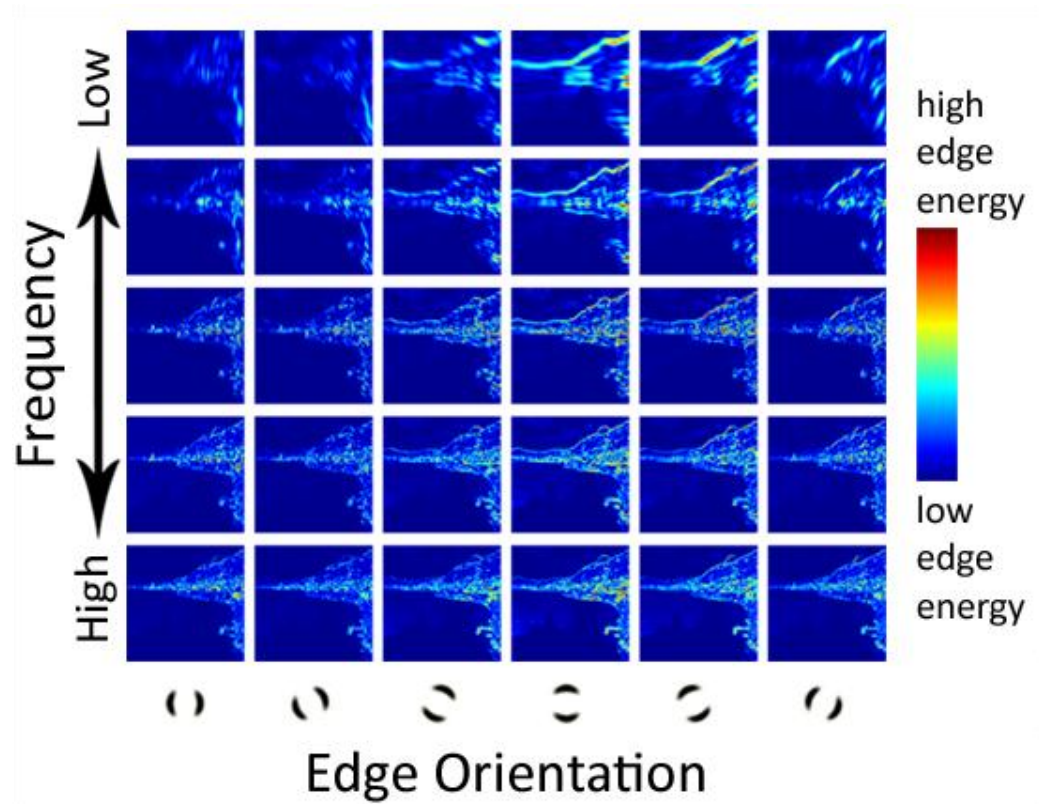
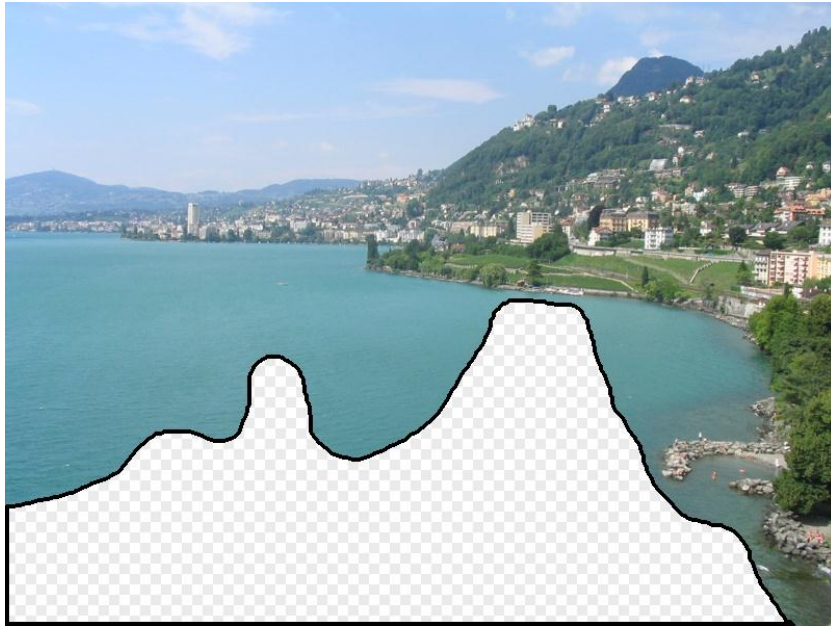
# The Algorithm



# Scene Matching

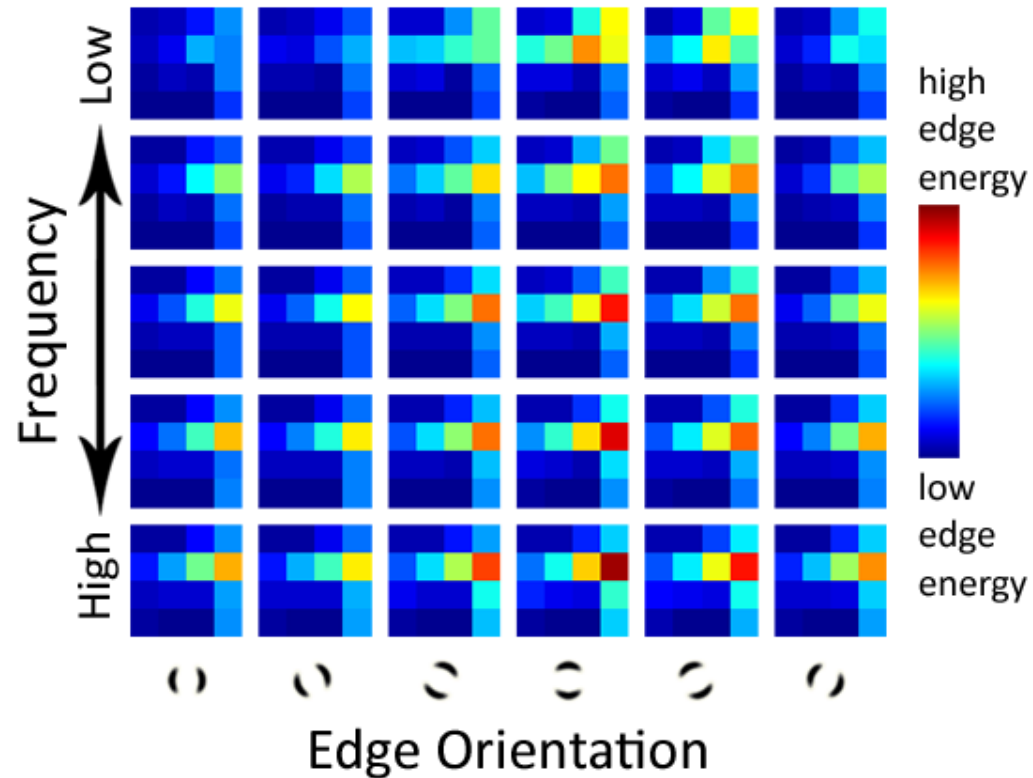
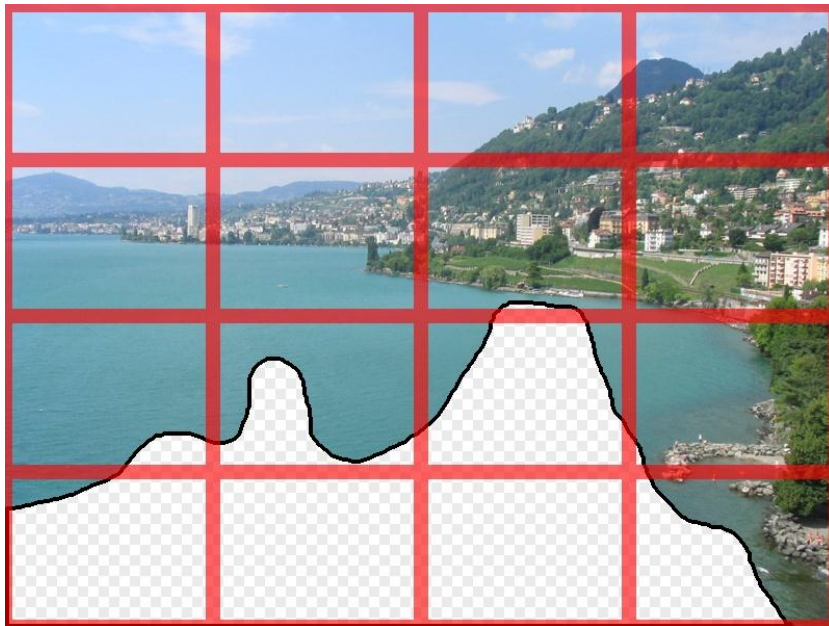


# Scene Descriptor



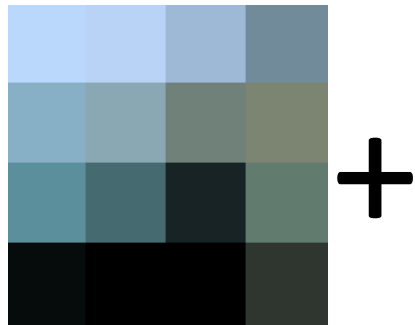


# Scene Descriptor

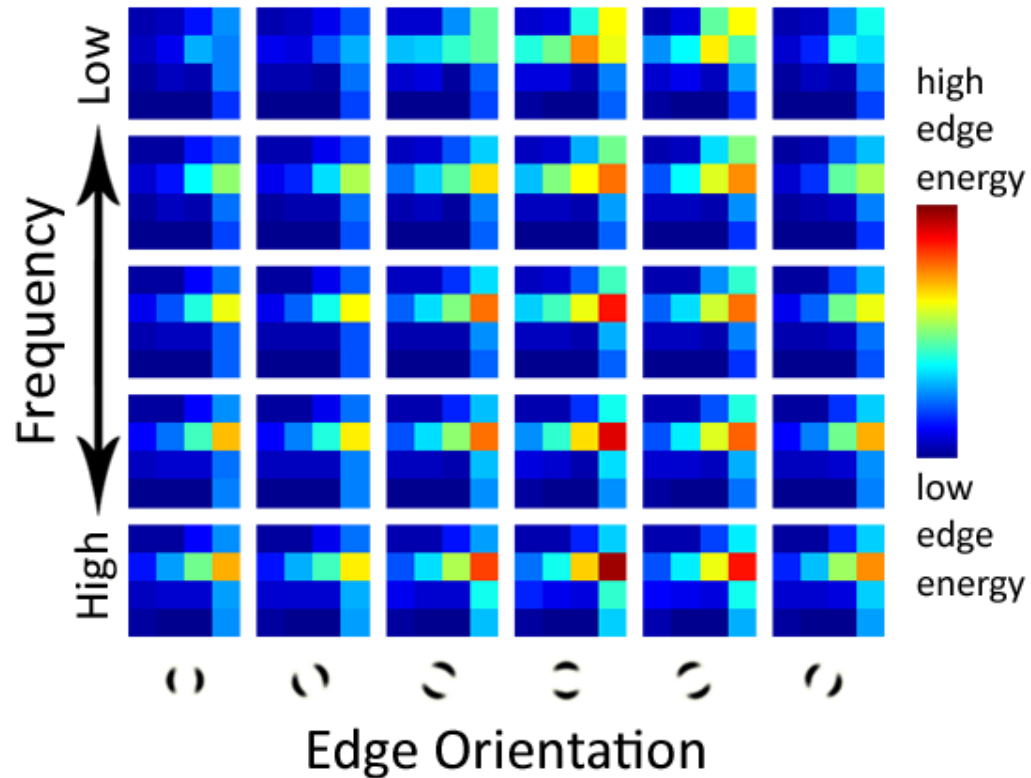


Scene Gist Descriptor  
(Oliva and Torralba 2001)

# Scene Descriptor



+

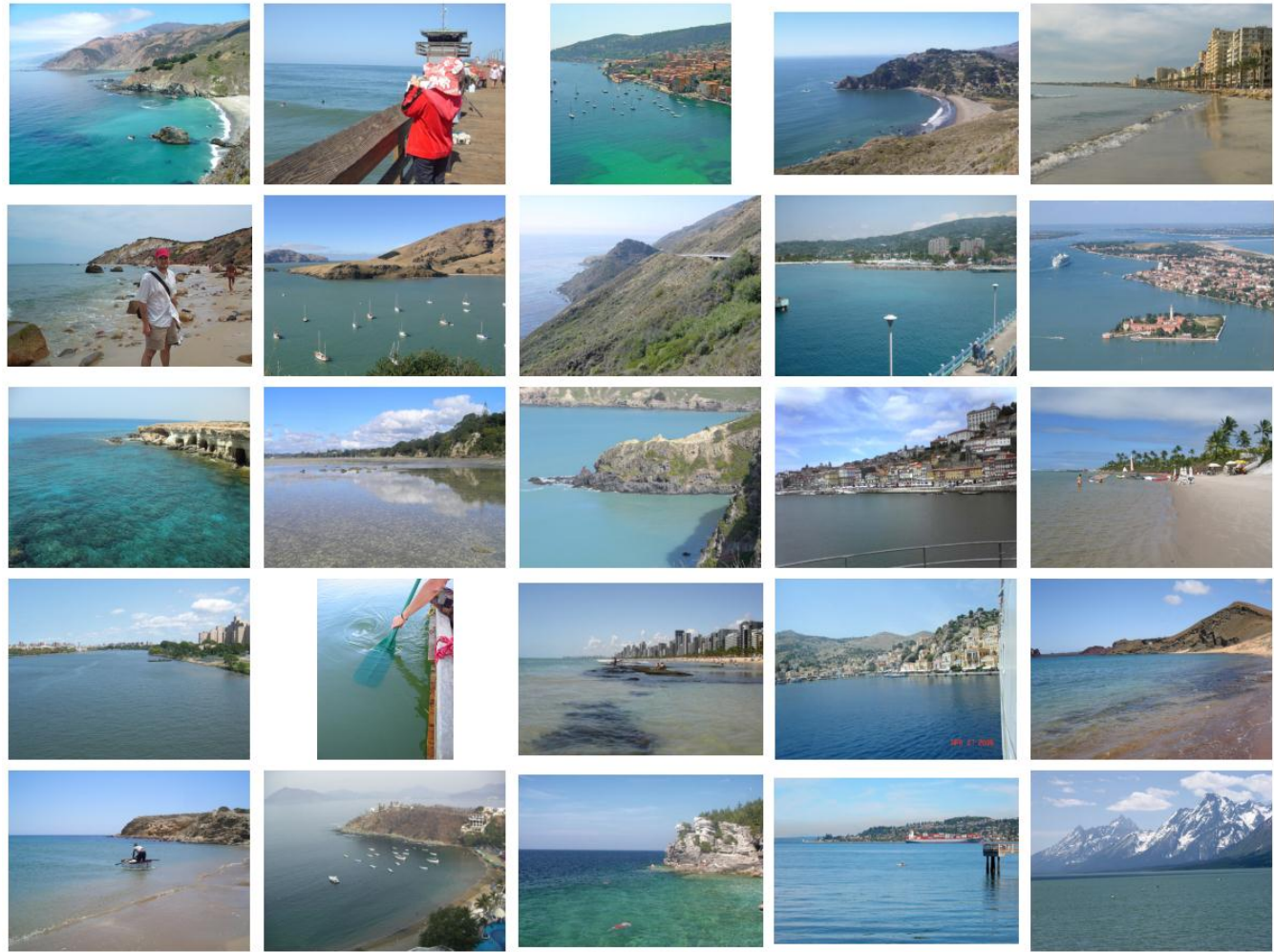
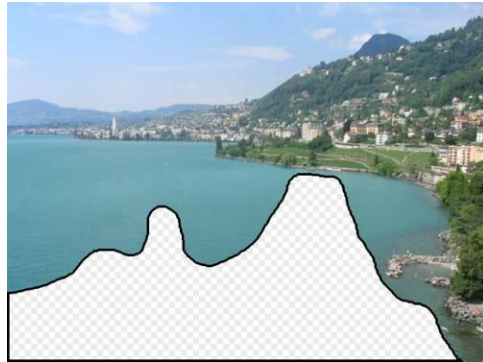


Scene Gist Descriptor  
(Oliva and Torralba 2001)



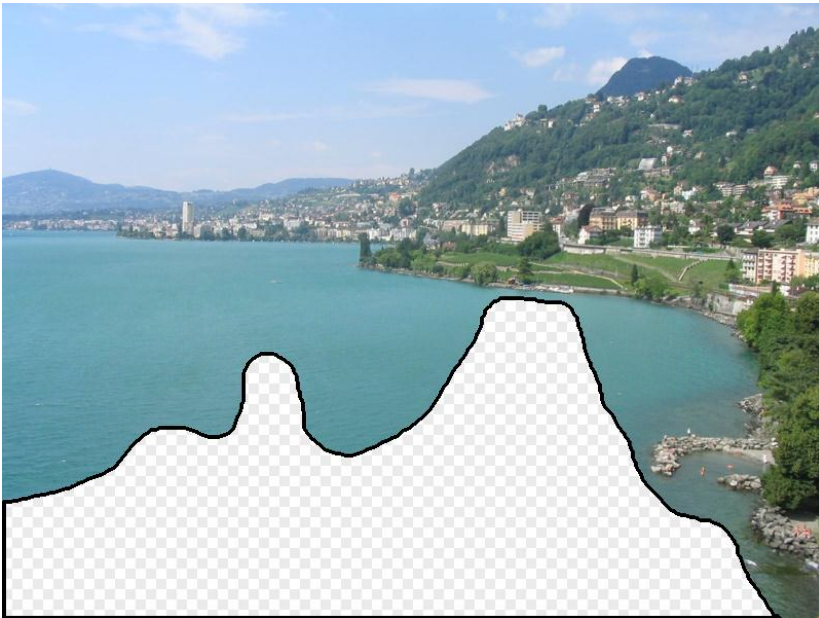
# 2 Million Flickr Images





... 200 total

# Context Matching



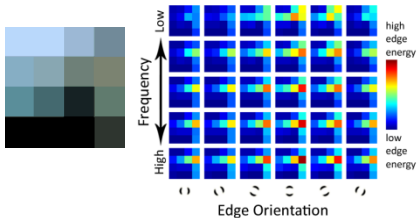




Graph cut + Poisson blending

# Result Ranking

We assign each of the 200 results a score which is the sum of:



The scene matching distance



The context matching distance  
(color + texture)



The graph cut cost







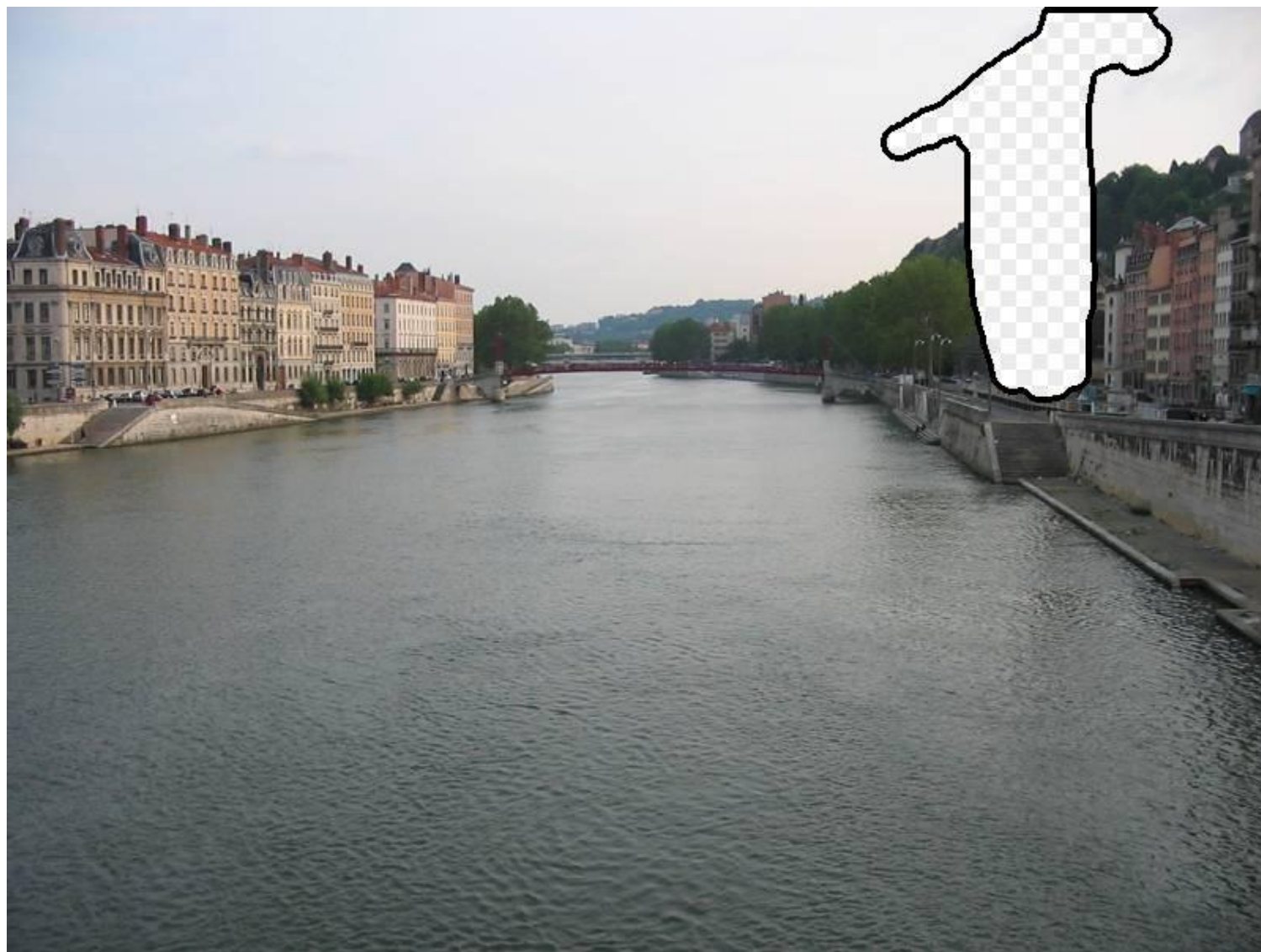




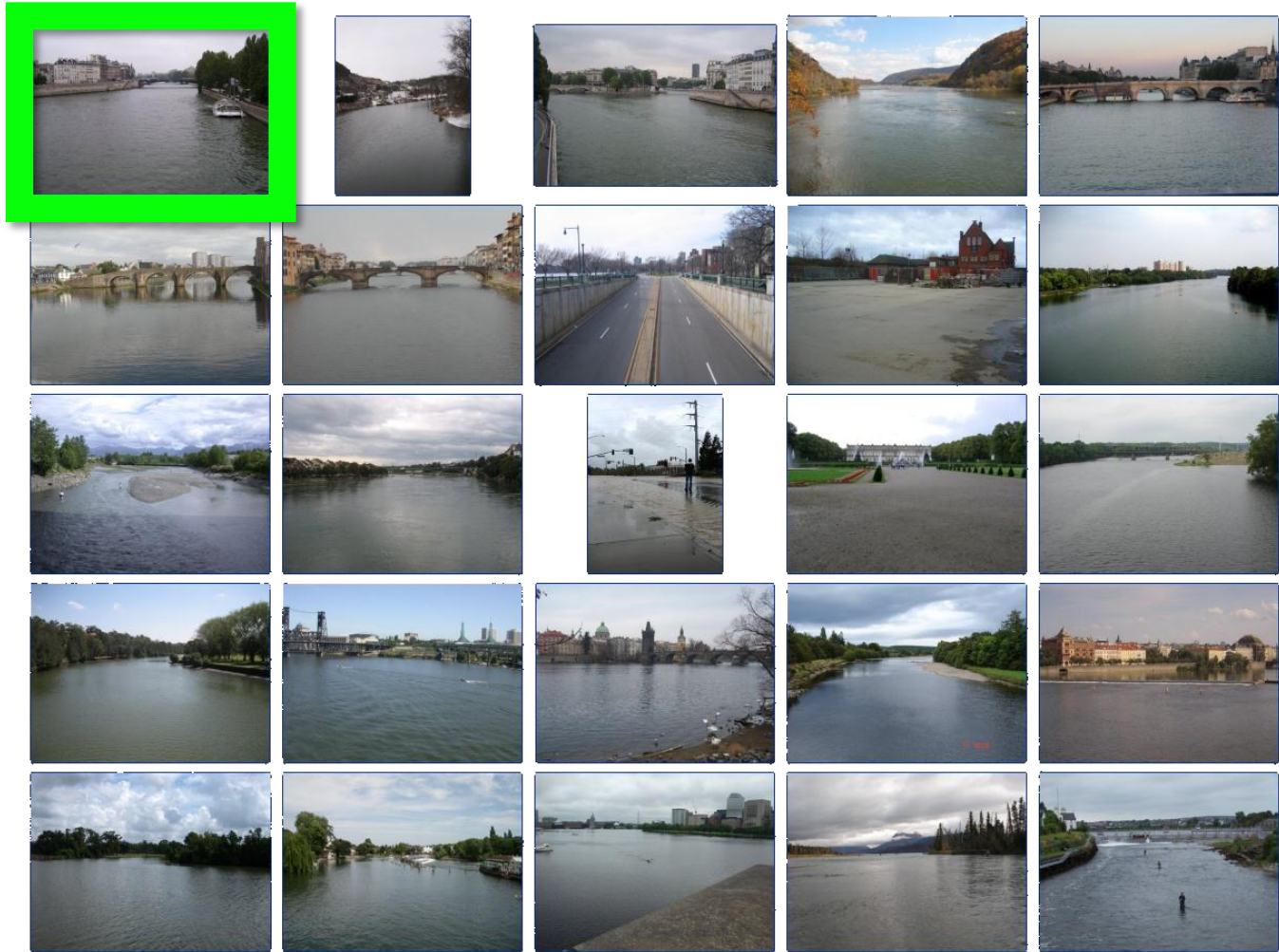












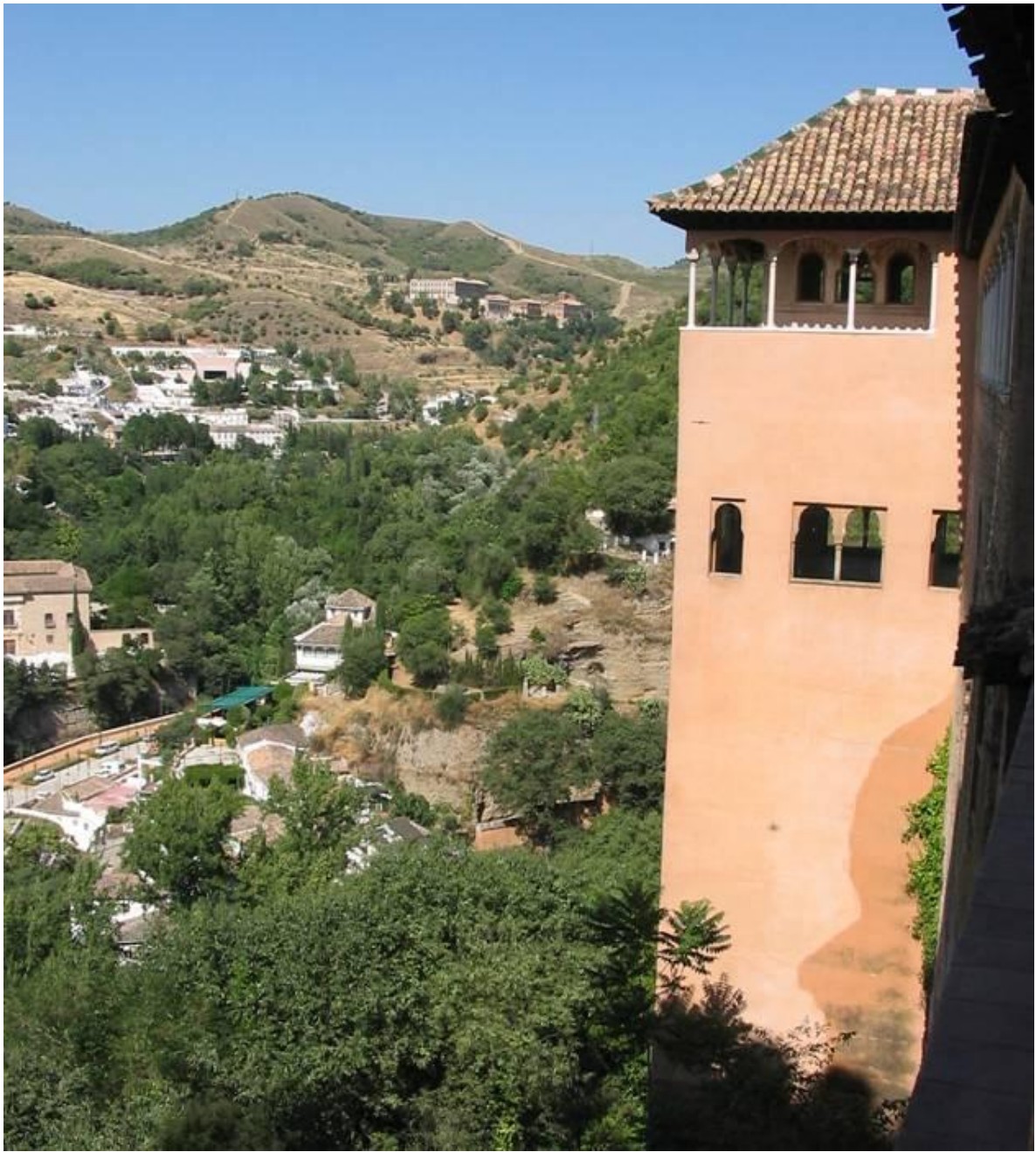
... 200 scene matches

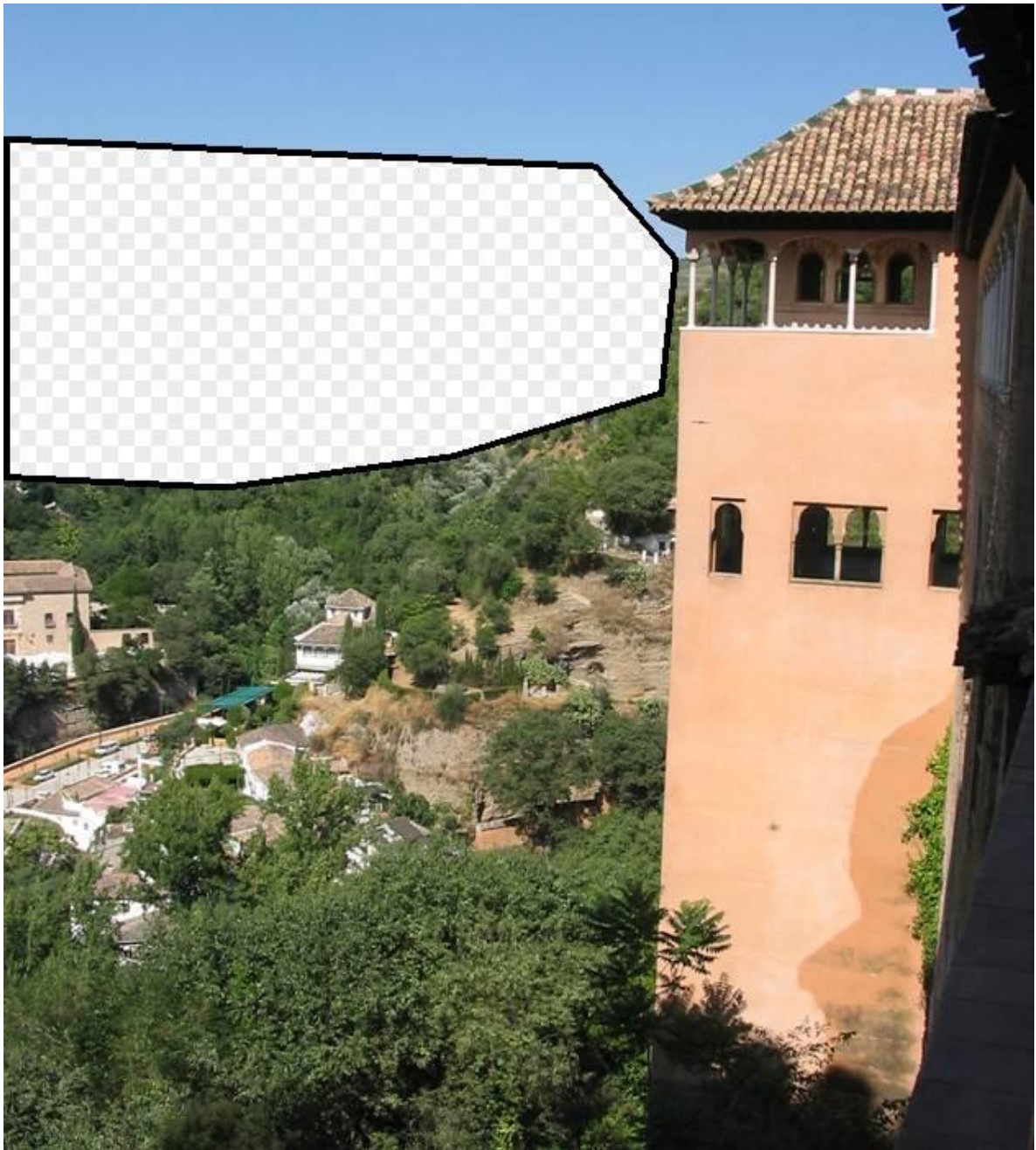
















# Which is the original?











Scene Completion Result

# im2gps (Hays & Efros, CVPR 2008)



6 million geo-tagged Flickr images

<http://graphics.cs.cmu.edu/projects/im2gps/>

How much can an image tell about its geographic location?







Paris



Paris



Paris



Paris



Paris



Paris



Paris



Madrid



Rome



Paris



Cuba



Paris



Paris



Poland



Paris



Paris





Im2gps





# Example Scene Matches



Madrid



england



France



Paris



Croatia



heidelberg



Macau



Malta



Cairo



Italy



Italy



Italy



Latvia



europe

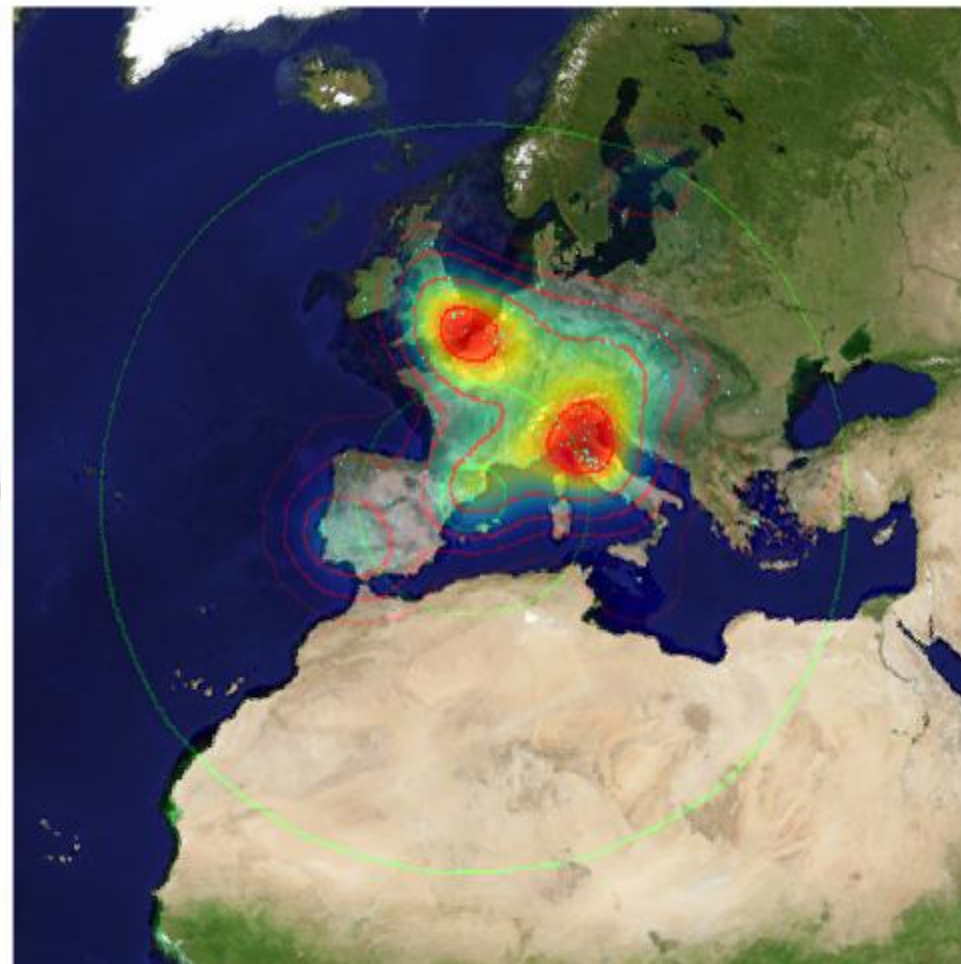
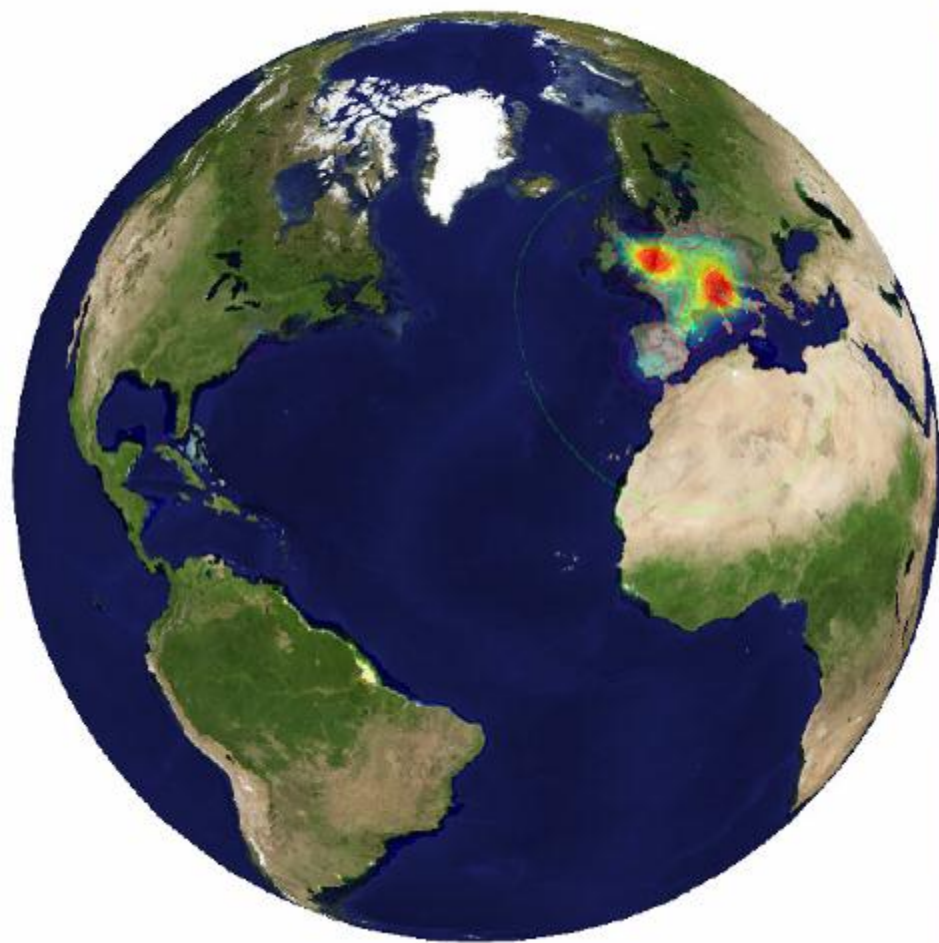


Barcelona



Austria

# Voting Scheme





im2gps







Philippines



Houston



Thailand



Houston



Maldives



Philippines



NewZealand



Bermuda



Palau



Mexico2



Brazil



Mendoza



Brazil



Thailand



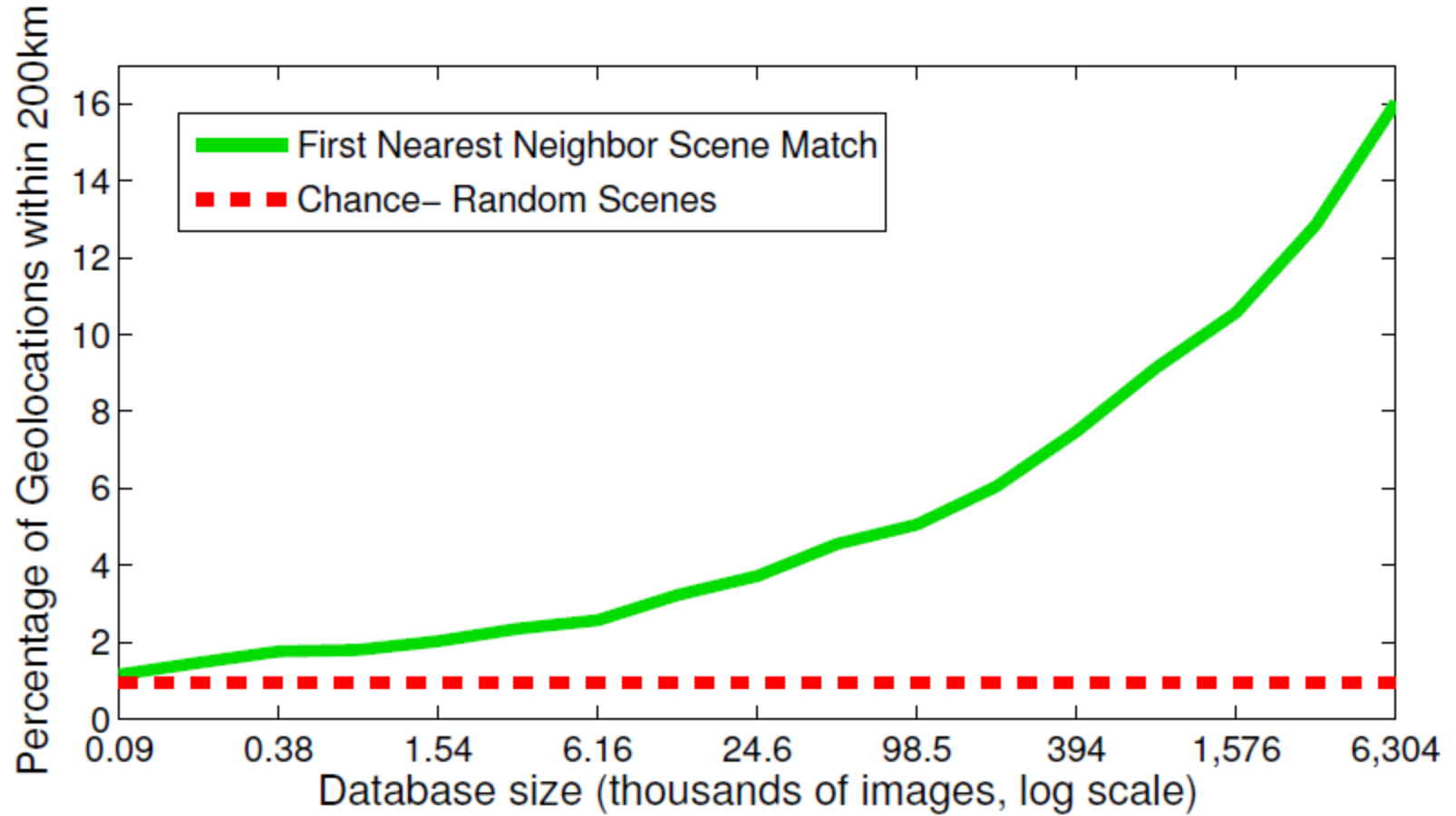
Arkansas



Hawaii



# Effect of Dataset Size





# Population density ranking

## High Predicted Density



## Low Predicted Density

# Where is This?



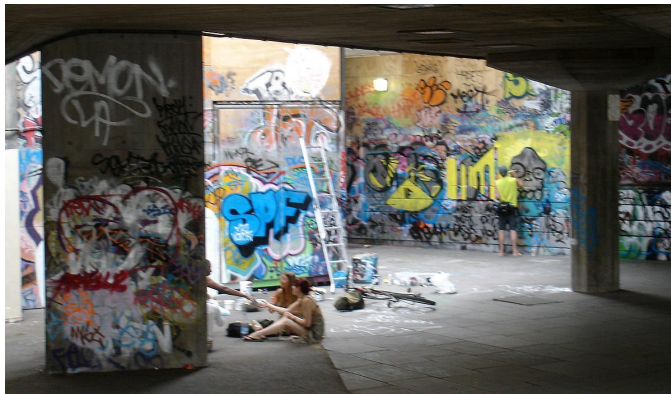
[Olga Vesselova, Vangelis Kalogerakis, Aaron Hertzmann, James Hays, Alexei A. Efros. Image Sequence Geolocation. ICCV'09]

# Where is This?





# Where are These?



15:14,  
June 18<sup>th</sup>, 2006



16:31,  
June 18<sup>th</sup>, 2006

# Where are These?



15:14,  
June 18<sup>th</sup>, 2006



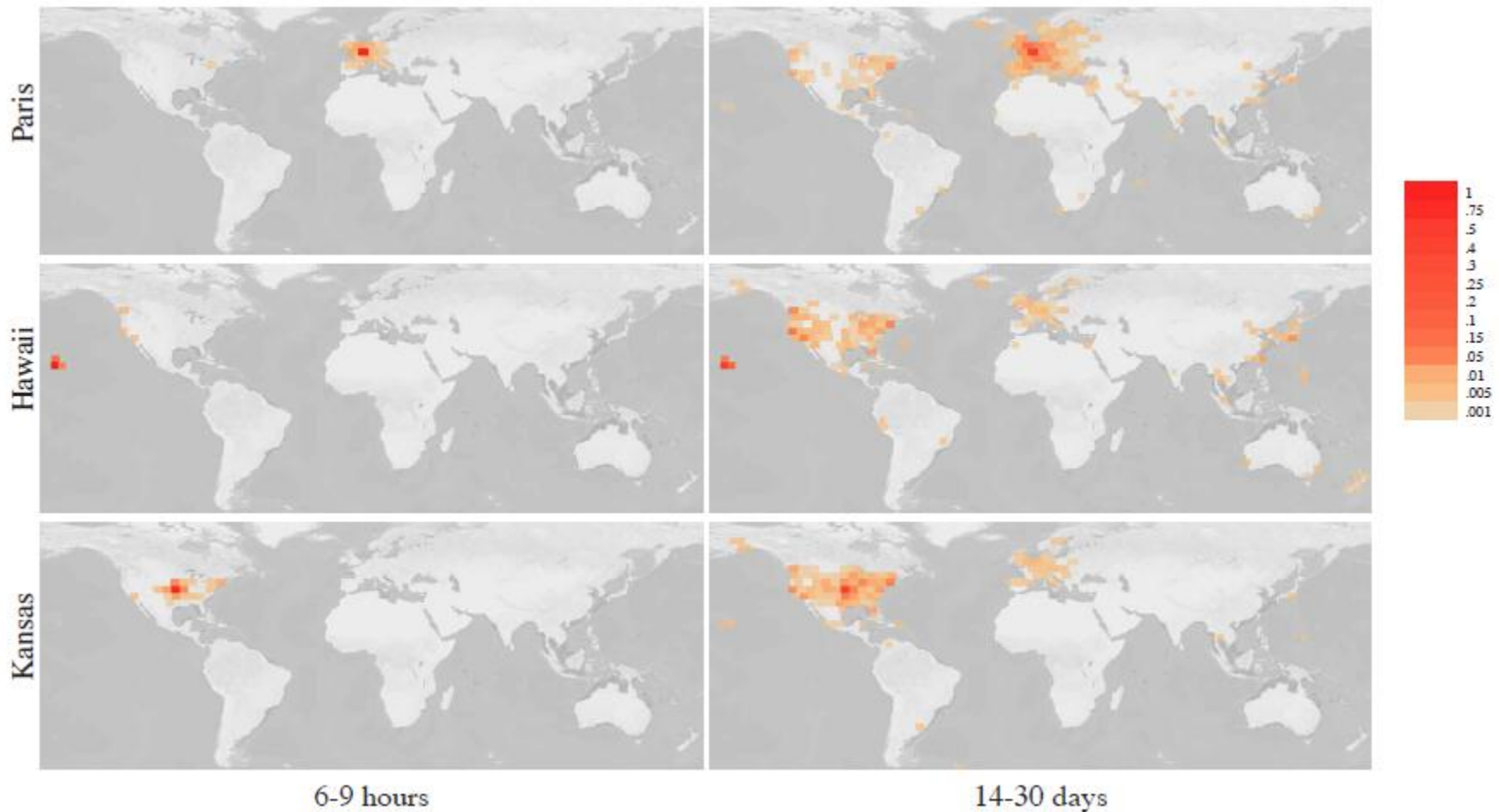
16:31,  
June 18<sup>th</sup>, 2006



17:24,  
June 19<sup>th</sup>, 2006

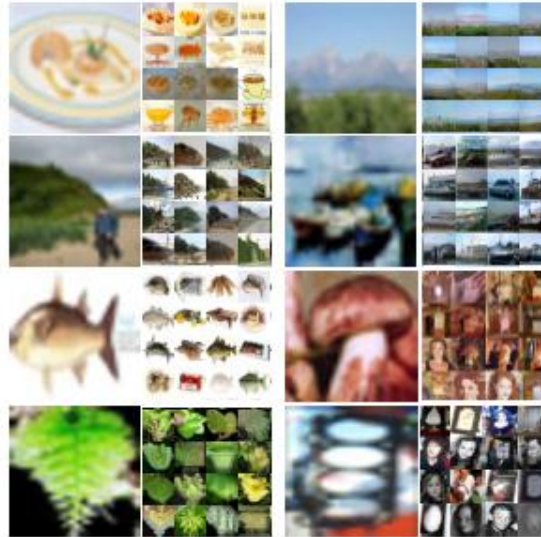
# Results

- im2gps – 10% (geo-loc within 400 km)
- temporal im2gps – 56%





# Tiny Images



80 million tiny images: a large dataset for non-parametric object and scene recognition  
Antonio Torralba, Rob Fergus and William T. Freeman. PAMI 2008.

<http://groups.csail.mit.edu/vision/TinyImages/>

256x256



32x32

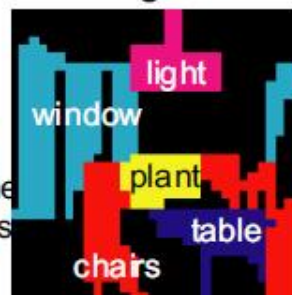
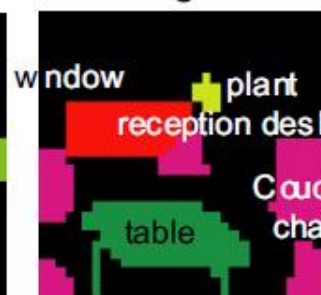
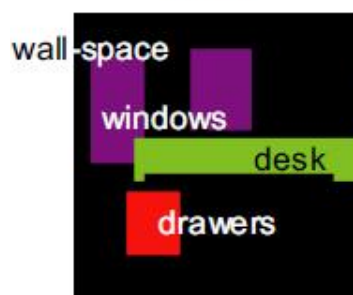


office

waiting area

dining room

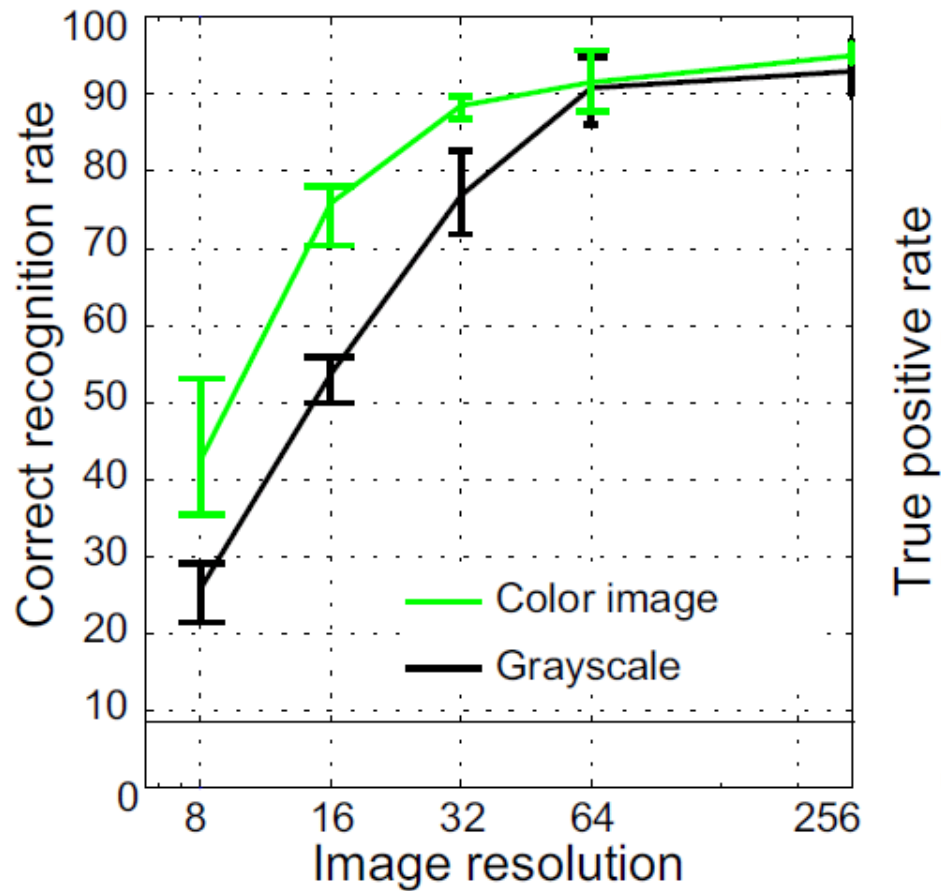
dining room



## c) Segmentation of 32x32 images



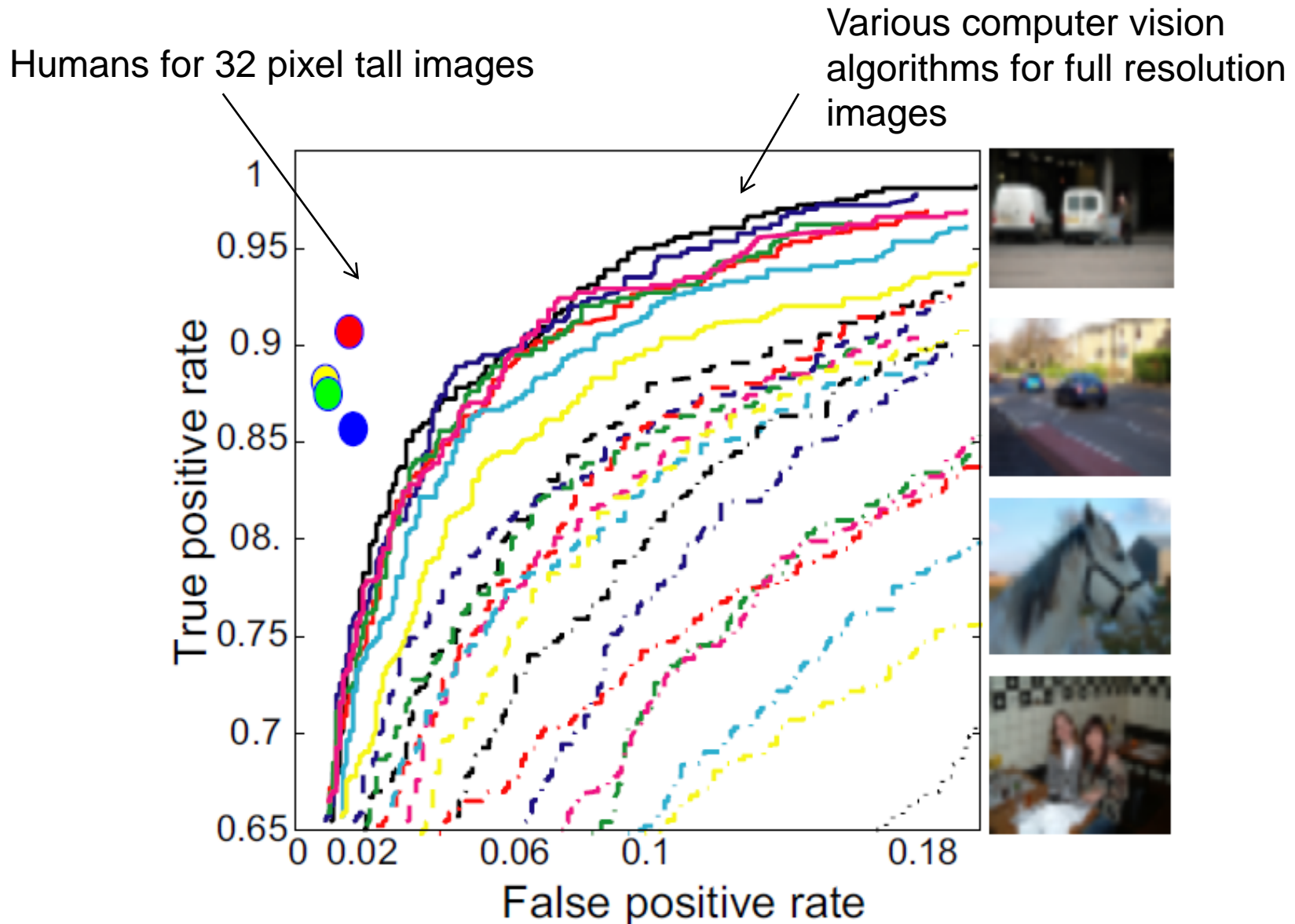
# Human Scene Recognition



a) Scene recognition



# Humans vs. Computers: Car-Image Classification



# Powers of 10

Number of images on my hard drive:

$10^4$



Number of images seen during my first 10 years:

(3 images/second \* 60 \* 60 \* 16 \* 365 \* 10 = 630720000)

$10^8$



Number of images seen by all humanity:

106,456,367,669 humans<sup>1</sup> \* 60 years \* 3 images/second \* 60 \* 60 \* 16 \* 365 =

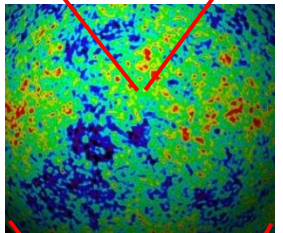
1 from <http://www.prb.org/Articles/2002/HowManyPeopleHaveEverLivedonEarth.aspx>

$10^{20}$



Number of photons in the universe:

$10^{88}$



Number of all 32x32 images:

$256^{32 \times 32 \times 3} \sim 10^{7373}$

$10^{7373}$



# Scenes are unique





# But not all scenes are so original



## 7,900





# Lots Of Images

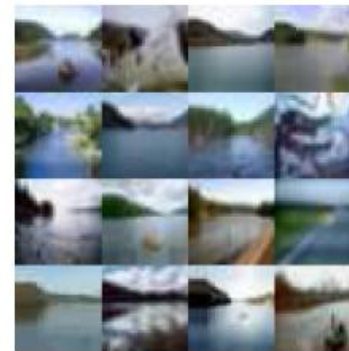
Target



7,900



790,000





# Lots Of Images

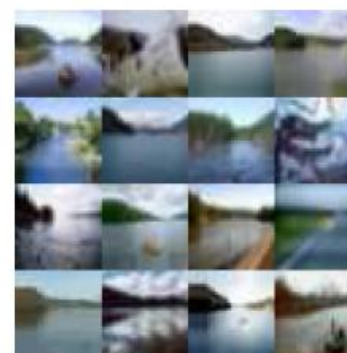
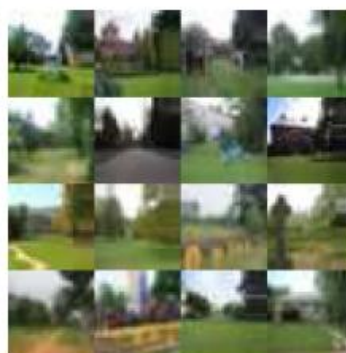
Target



7,900



790,000



79,000,000



# Application: Automatic Colorization



Input



Color Transfer



Color Transfer



Matches (gray)



Matches (w/ color)

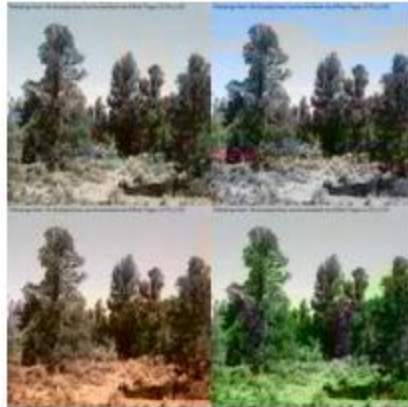


Avg Color of Match

# Application: Automatic Colorization



Input



Color Transfer



Color Transfer



Matches (gray)



Matches (w/ color)



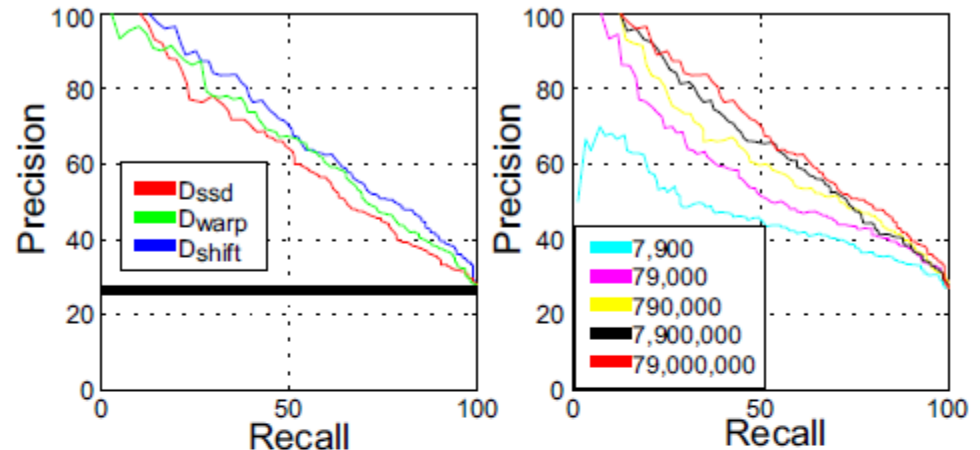
Avg Color of Match



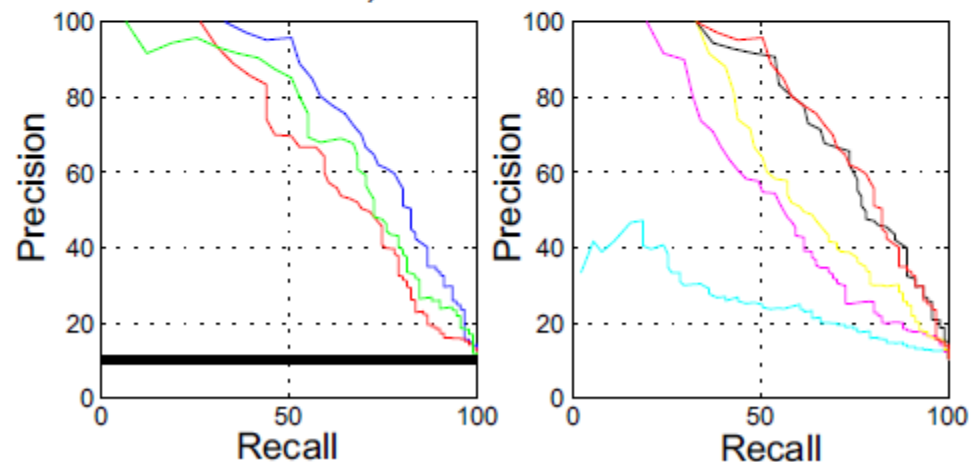
# Application: Person Detection

80 million “tiny images” downloaded by keyword search.

80 nearest neighbors vote for image category.



a) Person detection



b) Person detection (head size > 20%)

# Re-ranking Altavista search for “person”



a) Altavista ranking



b) Sorted by the tiny images

# Recognition by Association



Rather than categorizing objects, associate them with stored examples of objects and transfer the associated labels.

Malisiewicz and Efros (CVPR 2008)



# Training procedure

- Learn a region similarity measure from hand-segmented objects in LabelMe
- Similarity features
  - Shape: region mask, pixel area, bounding box size
  - Texture: normalized texture histogram
  - Color: mean RGB, std RGB, color histogram
  - Position: coarse 8x8 image mask, coords of top/bottom pixels



# Training procedure

- Learn a distance/similarity measure *for each region*
  - Minimize distance to K most similar examples from same category
  - Maximize distance to examples from other categories

$$\{\mathbf{w}^*, \alpha^*\} = \underset{\mathbf{w}, \alpha}{\operatorname{argmin}} f(\mathbf{w}, \alpha)$$

distance weights      distance measures

$$f(\mathbf{w}, \alpha) = \sum_{i \in C} \alpha_i L(-\mathbf{w} \cdot \mathbf{d}_i) + \sum_{i \notin C} L(\mathbf{w} \cdot \mathbf{d}_i)$$

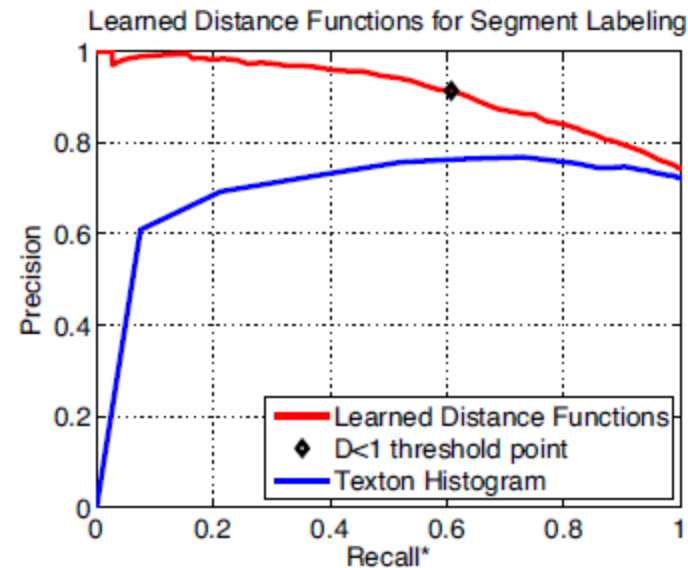
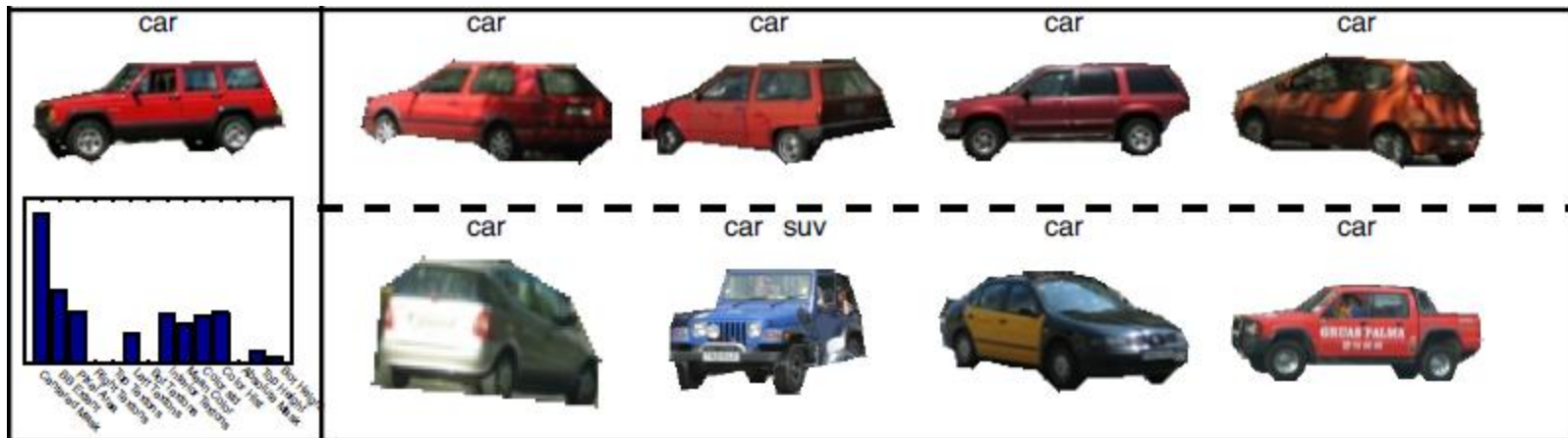
Set to 1 for K nearest examples      Hinge Loss

$$\mathbf{w} \geq 0, \alpha_j \in \{0, 1\}$$
$$\sum_j \alpha_j = K$$

# Learned Similarity Measure

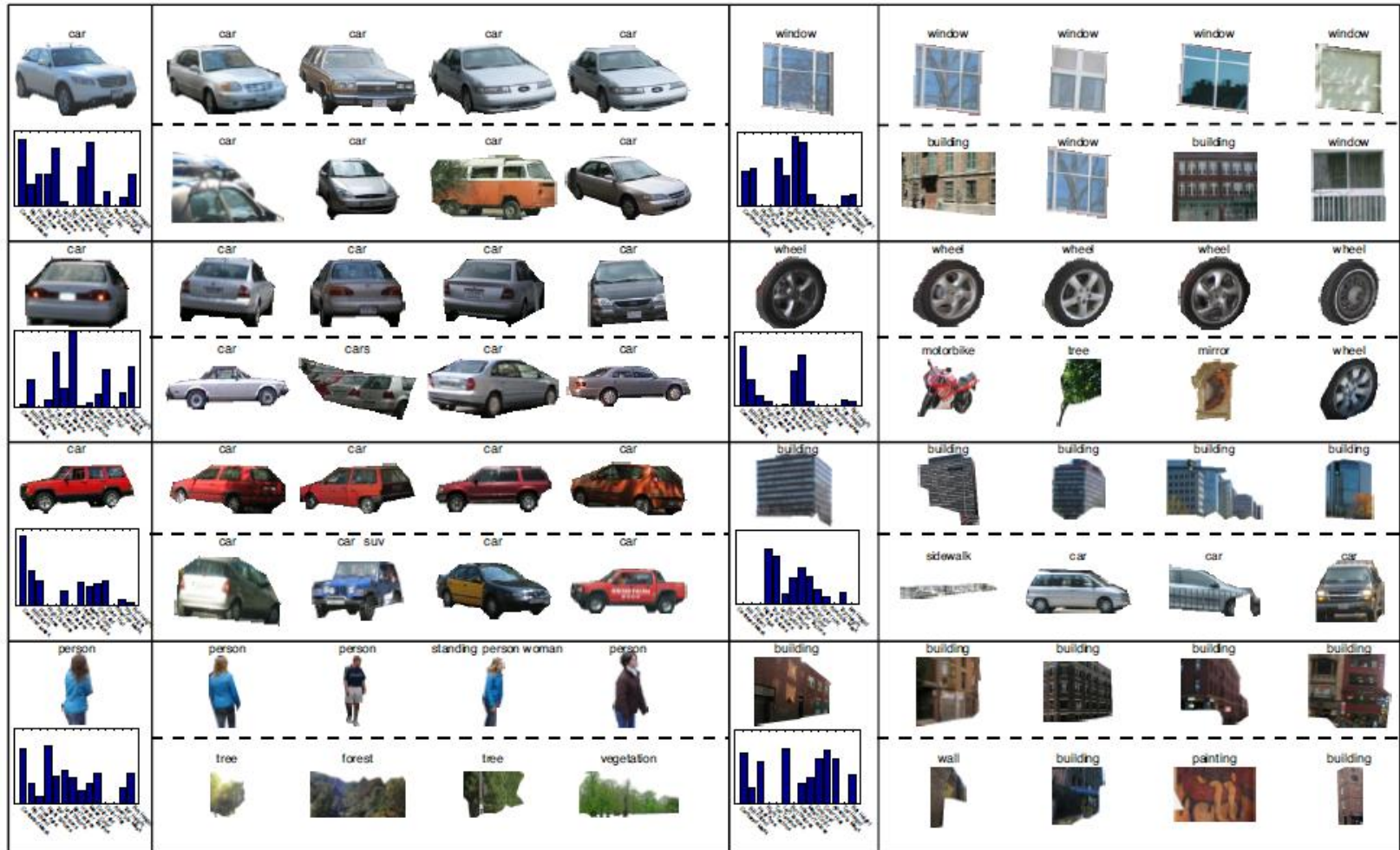
Learned Distance

Texton Distance



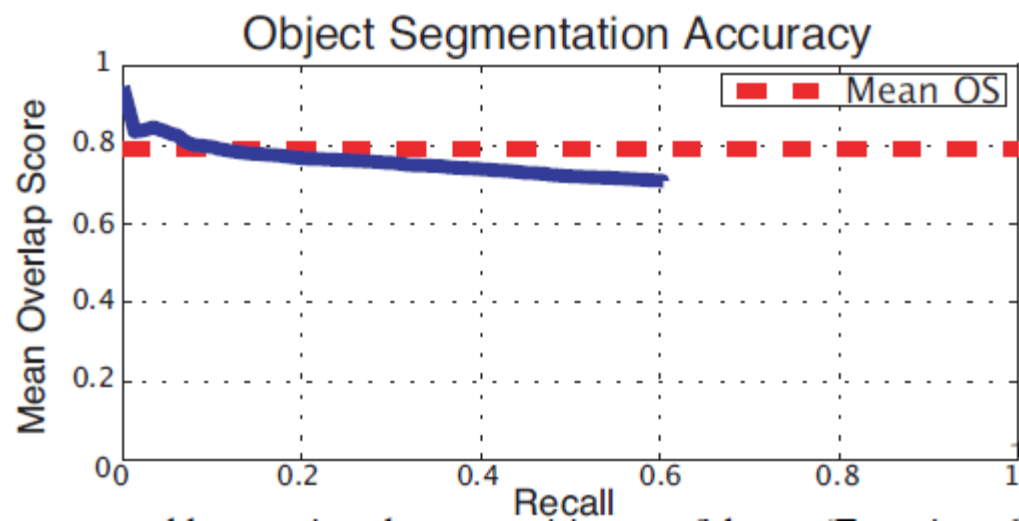
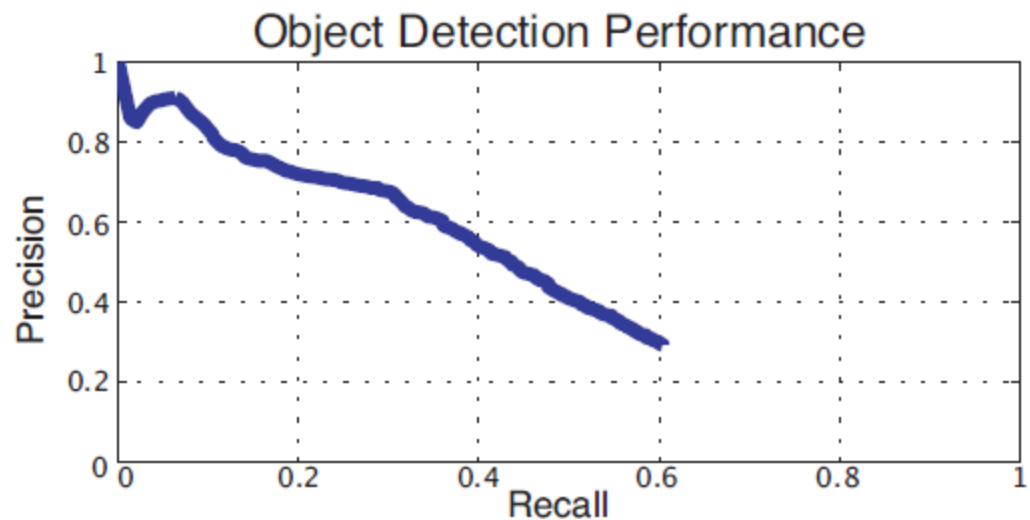


# Learned Similarity Measure



# Testing procedure

- Create multiple segmentations (MeanShift + Ncuts)
- Find similar object regions in training set; each votes for the object label
- What about bad segments?
  - Most of the time, they don't match any objects in the training set
  - Consider only associations with distance  $< 1$





# Automatic Parses



# Summary

- With billions of images on the web, it's often possible to find a close nearest neighbor
- In such cases, we can shortcut hard problems by “looking up” the answer, stealing the labels from our nearest neighbor
- For example, simple (or learned) associations can be used to synthesize background regions, colorize, or recognize objects



# Next class

- Summary and wrap-up
  - Short summary of computer vision
  - Important open problems
- Feedback (important!)
  - Short custom form that goes directly to me
  - ICES forms that go to department, then to me